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SAS/STAT[®] 12.1 User's Guide

The MI Procedure

(Chapter)



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Chapter 57

The MI Procedure

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Overview: MI Procedure

Missing values are an issue in a substantial number of statistical analyses. Most SAS statistical procedures exclude observations with any missing variable values from the analysis. These observations are called incomplete cases. While using only complete cases is simple, you lose information that is in the incomplete cases. Excluding observations with missing values also ignores the possible systematic difference between the complete cases and incomplete cases, and the resulting inference might not be applicable to the population of all cases, especially with a smaller number of complete cases.

Some SAS procedures use all the available cases in an analysis—that is, cases with useful information. For example, the CORR procedure estimates a variable mean by using all cases with nonmissing values for this variable, ignoring the possible missing values in other variables. The CORR procedure also estimates a correlation by using all cases with nonmissing values for this pair of variables. This estimation might make better use of the available data, but the resulting correlation matrix might not be positive definite.

Another strategy is single imputation, in which you substitute a value for each missing value. Standard statistical procedures for complete data analysis can then be used with the filled-in data set. For example, each missing value can be imputed from the variable mean of the complete cases. This approach treats missing values as if they were known in the complete-data analyses. Single imputation does not reflect the uncertainty about the predictions of the unknown missing values, and the resulting estimated variances of the parameter estimates are biased toward zero (Rubin 1987, p. 13).

Instead of filling in a single value for each missing value, multiple imputation replaces each missing value with a set of plausible values that represent the uncertainty about the right value to impute (Rubin 1976, 1987). The multiply imputed data sets are then analyzed by using standard procedures for complete data and combining the results from these analyses. No matter which complete-data analysis is used, the process of combining results from different data sets is essentially the same.

Multiple imputation does not attempt to estimate each missing value through simulated values, but rather to represent a random sample of the missing values. This process results in valid statistical inferences that properly reflect the uncertainty due to missing values; for example, valid confidence intervals for parameters.

Multiple imputation inference involves three distinct phases:

1. The missing data are filled in m times to generate m complete data sets.
2. The m complete data sets are analyzed by using standard procedures.
3. The results from the m complete data sets are combined for the inference.

The MI procedure is a multiple imputation procedure that creates multiply imputed data sets for incomplete p -dimensional multivariate data. It uses methods that incorporate appropriate variability across the m imputations. The imputation method of choice depends on the patterns of missingness in the data and the type of the imputed variable.

A data set with variables Y_1, Y_2, \dots, Y_p (in that order) is said to have a *monotone missing pattern* when the event that a variable Y_j is missing for a particular individual implies that all subsequent variables Y_k , $k > j$, are missing for that individual.

For data sets with monotone missing patterns, the variables with missing values can be imputed sequentially with covariates constructed from their corresponding sets of preceding variables. To impute missing values

for a continuous variable, you can use a regression method (Rubin 1987, pp. 166–167), a predictive mean matching method (Heitjan and Little 1991; Schenker and Taylor 1996), or a propensity score method (Rubin 1987, pp. 124, 158; Lavori, Dawson, and Shera 1995). To impute missing values for a classification variable, you can use a logistic regression method when the classification variable has a binary or ordinal response, or use a discriminant function method when the classification variable has a binary or nominal response.

For data sets with arbitrary missing patterns, you can use either of the following methods to impute missing values: a Markov chain Monte Carlo (MCMC) method (Schafer 1997) that assumes multivariate normality, or a fully conditional specification (FCS) method (Brand 1999; van Buuren 2007) that assumes the existence of a joint distribution for all variables.

You can use the MCMC method to impute either all the missing values or just enough missing values to make the imputed data sets have monotone missing patterns. With a monotone missing data pattern, you have greater flexibility in your choice of imputation models, such as the monotone regression method that do not use Markov chains. You can also specify a different set of covariates for each imputed variable.

An FCS method does not start with an explicitly specified multivariate distribution for all variables, but rather uses a separate conditional distribution for each imputed variable. For each imputation, the process contains two phases: the preliminary filled-in phase followed by the imputation phase. At the filled-in phase, the missing values for all variables are filled in sequentially over the variables taken one at a time. These filled-in values provide starting values for these missing values at the imputation phase. At the imputation phase, the missing values for each variable are imputed sequentially for a number of burn-in iterations before the imputation.

As in methods for data sets with monotone missing patterns, you can use a regression method or a predictive mean matching method to impute missing values for a continuous variable, a logistic regression method to impute missing values for a classification variable with a binary or ordinal response, and a discriminant function method to impute missing values for a classification variable with a binary or nominal response.

After the m complete data sets are analyzed using standard SAS procedures, the MIANALYZE procedure can be used to generate valid statistical inferences about these parameters by combining results from the m analyses.

Often, as few as three to five imputations are adequate in multiple imputation (Rubin 1996, p. 480). The relative efficiency of the small m imputation estimator is high for cases with little missing information (Rubin 1987, p. 114). (Also see the section “[Multiple Imputation Efficiency](#)” on page 4771.)

Multiple imputation inference assumes that the model (variables) you used to analyze the multiply imputed data (the analyst’s model) is the same as the model used to impute missing values in multiple imputation (the imputer’s model). But in practice, the two models might not be the same. The consequences for different scenarios (Schafer 1997, pp. 139–143) are discussed in the section “[Imputer’s Model Versus Analyst’s Model](#)” on page 4771.

Getting Started: MI Procedure

The Fitness data described in the REG procedure are measurements of 31 individuals in a physical fitness course. See Chapter 79, “[The REG Procedure](#),” for more information.

The Fitness1 data set is constructed from the Fitness data set and contains three variables: Oxygen, RunTime, and RunPulse. Some values have been set to missing, and the resulting data set has an arbitrary pattern of missingness in these three variables.

```

*-----Data on Physical Fitness-----*
| These measurements were made on men involved in a physical fitness |
| course at N.C. State University. Certain values have been set to |
| missing and the resulting data set has an arbitrary missing pattern. |
| Only selected variables of |
| Oxygen (intake rate, ml per kg body weight per minute), |
| Runtime (time to run 1.5 miles in minutes), |
| RunPulse (heart rate while running) are used. |
*-----*
data Fitness1;
  input Oxygen RunTime RunPulse @@;
  datalines;
44.609 11.37 178      45.313 10.07 185
54.297 8.65 156      59.571 . .
49.874 9.22 .      44.811 11.63 176
. 11.95 176      . 10.85 .
39.442 13.08 174      60.055 8.63 170
50.541 . .      37.388 14.03 186
44.754 11.12 176      47.273 . .
51.855 10.33 166      49.156 8.95 180
40.836 10.95 168      46.672 10.00 .
46.774 10.25 .      50.388 10.08 168
39.407 12.63 174      46.080 11.17 156
45.441 9.63 164      . 8.92 .
45.118 11.08 .      39.203 12.88 168
45.790 10.47 186      50.545 9.93 148
48.673 9.40 186      47.920 11.50 170
47.467 10.50 170
;

```

Suppose that the data are multivariate normally distributed and the missing data are missing at random (MAR). That is, the probability that an observation is missing can depend on the observed variable values of the individual, but not on the missing variable values of the individual. See the section “[Statistical Assumptions for Multiple Imputation](#)” on page 4745 for a detailed description of the MAR assumption.

The following statements invoke the MI procedure and impute missing values for the Fitness1 data set:

```

proc mi data=Fitness1 seed=501213 mu0=50 10 180 out=outmi;
  mcmc;
  var Oxygen RunTime RunPulse;
run;

```

The “Model Information” table in [Figure 57.1](#) describes the method used in the multiple imputation process. By default, the MCMC statement uses the Markov chain Monte Carlo (MCMC) method with a single chain to create five imputations. The posterior mode, the highest observed-data posterior density, with a noninformative prior, is computed from the expectation-maximization (EM) algorithm and is used as the starting value for the chain.

Figure 57.1 Model Information

The MI Procedure	
Model Information	
Data Set	WORK.FITNESS1
Method	MCMC
Multiple Imputation Chain	Single Chain
Initial Estimates for MCMC	EM Posterior Mode
Start	Starting Value
Prior	Jeffreys
Number of Imputations	5
Number of Burn-in Iterations	200
Number of Iterations	100
Seed for random number generator	501213

The MI procedure takes 200 burn-in iterations before the first imputation and 100 iterations between imputations. In a Markov chain, the information in the current iteration influences the state of the next iteration. The burn-in iterations are iterations in the beginning of each chain that are used both to eliminate the series of dependence on the starting value of the chain and to achieve the stationary distribution. The between-imputation iterations in a single chain are used to eliminate the series of dependence between the two imputations.

The “Missing Data Patterns” table in [Figure 57.2](#) lists distinct missing data patterns with their corresponding frequencies and percentages. An “X” means that the variable is observed in the corresponding group, and a “.” means that the variable is missing. The table also displays group-specific variable means. The MI procedure sorts the data into groups based on whether the analysis variables are observed or missing. For a detailed description of missing data patterns, see the section “[Missing Data Patterns](#)” on page 4746.

Figure 57.2 Missing Data Patterns

Missing Data Patterns					
Group	Oxygen	Run Time	Run Pulse	Freq	Percent
1	X	X	X	21	67.74
2	X	X	.	4	12.90
3	X	.	.	3	9.68
4	.	X	X	1	3.23
5	.	X	.	2	6.45

Missing Data Patterns			
-----Group Means-----			
Group	Oxygen	RunTime	RunPulse
1	46.353810	10.809524	171.666667
2	47.109500	10.137500	.
3	52.461667	.	.
4	.	11.950000	176.000000
5	.	9.885000	.

After the completion of m imputations, the “Variance Information” table in [Figure 57.3](#) displays the between-imputation variance, within-imputation variance, and total variance for combining complete-data inferences. It also displays the degrees of freedom for the total variance. The relative increase in variance due to missing values, the fraction of missing information, and the relative efficiency (in units of variance) for each variable are also displayed. A detailed description of these statistics is provided in the section “Combining Inferences from Multiply Imputed Data Sets” on page 4769.

Figure 57.3 Variance Information

Variance Information				
Variable	-----Variance-----			DF
	Between	Within	Total	
Oxygen	0.056930	0.954041	1.022356	25.549
RunTime	0.000811	0.064496	0.065469	27.721
RunPulse	0.922032	3.269089	4.375528	15.753

Variance Information			
Variable	Relative Increase in Variance	Fraction Missing Information	Relative Efficiency
Oxygen	0.071606	0.068898	0.986408
RunTime	0.015084	0.014968	0.997015
RunPulse	0.338455	0.275664	0.947748

The “Parameter Estimates” table in [Figure 57.4](#) displays the estimated mean and standard error of the mean for each variable. The inferences are based on the t distribution. The table also displays a 95% confidence interval for the mean and a t statistic with the associated p -value for the hypothesis that the population mean is equal to the value specified with the MU0= option. A detailed description of these statistics is provided in the section “Combining Inferences from Multiply Imputed Data Sets” on page 4769.

Figure 57.4 Parameter Estimates

Parameter Estimates					
Variable	Mean	Std Error	95% Confidence Limits		DF
Oxygen	47.094040	1.011116	45.0139	49.1742	25.549
RunTime	10.572073	0.255870	10.0477	11.0964	27.721
RunPulse	171.787793	2.091776	167.3478	176.2278	15.753

Parameter Estimates					
Variable	Minimum	Maximum	Mu0	t for H0: Mean=Mu0	Pr > t
Oxygen	46.783898	47.395550	50.000000	-2.87	0.0081
RunTime	10.526392	10.599616	10.000000	2.24	0.0336
RunPulse	170.774818	173.122002	180.000000	-3.93	0.0012

In addition to the output tables, the procedure also creates a data set with imputed values. The imputed data sets are stored in the outmi data set, with the index variable `_Imputation_` indicating the imputation numbers. The data set can now be analyzed using standard statistical procedures with `_Imputation_` as a BY variable.

The following statements list the first 10 observations of data set outmi:

```
proc print data=outmi (obs=10);
    title 'First 10 Observations of the Imputed Data Set';
run;
```

The table in Figure 57.5 shows that the precision of the imputed values differs from the precision of the observed values. You can use the `ROUND=` option to make the imputed values consistent with the observed values.

Figure 57.5 Imputed Data Set

First 10 Observations of the Imputed Data Set				
Obs	_Imputation_	Oxygen	RunTime	Run Pulse
1	1	44.6090	11.3700	178.000
2	1	45.3130	10.0700	185.000
3	1	54.2970	8.6500	156.000
4	1	59.5710	8.0747	155.925
5	1	49.8740	9.2200	176.837
6	1	44.8110	11.6300	176.000
7	1	42.8857	11.9500	176.000
8	1	46.9992	10.8500	173.099
9	1	39.4420	13.0800	174.000
10	1	60.0550	8.6300	170.000

Syntax: MI Procedure

The following statements are available in the MI procedure:

```
PROC MI < options > ;
    BY variables ;
    CLASS variables ;
    EM < options > ;
    FCS < options > ;
    FREQ variable ;
    MCMC < options > ;
    MONOTONE < options > ;
    TRANSFORM transform (variables< / options >) < ... transform (variables< / options >) > ;
    VAR variables ;
```

The `BY` statement specifies groups in which separate multiple imputation analyses are performed.

The `CLASS` statement lists the classification variables in the `VAR` statement. Classification variables can be either character or numeric.

The EM statement uses the EM algorithm to compute the maximum likelihood estimate (MLE) of the data with missing values, assuming a multivariate normal distribution for the data.

The FREQ statement specifies the variable that represents the frequency of occurrence for other values in the observation.

For a data set with a monotone missing pattern, you can use the MONOTONE statement to specify applicable monotone imputation methods; otherwise, you can use either the MCMC statement assuming multivariate normality or the FCS method assuming a joint distribution for variables exists. Note that you can specify no more than one of these statements. When none of these three statements is specified, the MCMC method with its default options is used.

The FCS statement uses a multivariate imputation by chained equations method to impute values for a data set with an arbitrary missing pattern, assuming a joint distribution exists for the data.

The MCMC statement uses a Markov chain Monte Carlo method to impute values for a data set with an arbitrary missing pattern, assuming a multivariate normal distribution for the data.

The MONOTONE statement specifies monotone methods to impute continuous and classification variables for a data set with a monotone missing pattern.

The TRANSFORM statement specifies the variables to be transformed before the imputation process; the imputed values of these transformed variables are reverse-transformed to the original forms before the imputation.

The VAR statement lists the numeric variables to be analyzed. If you omit the VAR statement, all numeric variables not listed in other statements are used.

The PROC MI statement is the only required statement for the MI procedure. The rest of this section provides detailed syntax information for each of these statements, beginning with the PROC MI statement. The remaining statements are presented in alphabetical order.

PROC MI Statement

PROC MI <options> ;

The PROC MI statement invokes the MI procedure. [Table 57.1](#) summarizes the options available in the PROC MI statement.

Table 57.1 Summary of PROC MI Options

Option	Description
Data Sets	
DATA=	Specifies the input data set
OUT=	Specifies the output data set with imputed values
Imputation Details	
NIMPUTE=	Specifies the number of imputations
SEED=	Specifies the seed to begin random number generator
ROUND=	Specifies units to round imputed variable values
MAXIMUM=	Specifies maximum values for imputed variable values
MINIMUM=	Specifies minimum values for imputed variable values

Table 57.1 *continued*

Option	Description
MINMAXITER=	Specifies the maximum number of iterations to impute values in the specified range
SINGULAR=	Specifies the singularity criterion
Statistical Analysis	
ALPHA=	Specifies the level for the confidence interval, $(1 - \alpha)$
MU0=	Specifies means under the null hypothesis
Printed Output	
NOPRINT	Suppresses all displayed output
SIMPLE	Displays univariate statistics and correlations

The following options can be used in the PROC MI statement. They are listed in alphabetical order.

ALPHA= α

specifies that confidence limits be constructed for the mean estimates with confidence level $100(1 - \alpha)\%$, where $0 < \alpha < 1$. The default is ALPHA=0.05.

DATA=SAS-data-set

names the SAS data set to be analyzed by PROC MI. By default, the procedure uses the most recently created SAS data set.

MAXIMUM=numbers

specifies maximum values for imputed variables. When an intended imputed value is greater than the maximum, PROC MI redraws another value for imputation. If only one number is specified, that number is used for all variables. If more than one number is specified, you must use a VAR statement, and the specified numbers must correspond to variables in the VAR statement. The default number is a missing value, which indicates no restriction on the maximum for the corresponding variable

The MAXIMUM= option is related to the MINIMUM= and ROUND= options, which are used to make the imputed values more consistent with the observed variable values. These options are applicable only if you use the MCMC method or the monotone regression method.

When specifying a maximum for the first variable only, you must also specify a missing value after the maximum. Otherwise, the maximum is used for all variables.

For example, the “MAXIMUM= 100 .” option sets a maximum of 100 for the first analysis variable only and no maximum for the remaining variables. The “MAXIMUM= . 100” option sets a maximum of 100 for the second analysis variable only and no maximum for the other variables.

MINIMUM=numbers

specifies the minimum values for imputed variables. When an intended imputed value is less than the minimum, PROC MI redraws another value for imputation. If only one number is specified, that number is used for all variables. If more than one number is specified, you must use a VAR statement, and the specified numbers must correspond to variables in the VAR statement. The default number is a missing value, which indicates no restriction on the minimum for the corresponding variable

MINMAXITER=number

specifies the maximum number of iterations for imputed values to be in the specified range when the option MINIMUM or MAXIMUM is also specified. The default is MINMAXITER=100.

MU0=numbers**THETA0=numbers**

specifies the parameter values μ_0 under the null hypothesis $\mu = \mu_0$ for the population means corresponding to the analysis variables. Each hypothesis is tested with a t test. If only one number is specified, that number is used for all variables. If more than one number is specified, you must use a VAR statement, and the specified numbers must correspond to variables in the VAR statement. The default is MU0=0.

If a variable is transformed as specified in a TRANSFORM statement, then the same transformation for that variable is also applied to its corresponding specified MU0= value in the t test. If the parameter values μ_0 for a transformed variable are not specified, then a value of zero is used for the resulting μ_0 after transformation.

NIMPUTE=number

specifies the number of imputations. The default is NIMPUTE=5. You can specify NIMPUTE=0 to skip the imputation. In this case, only tables of model information, missing data patterns, descriptive statistics (SIMPLE option), and MLE from the EM algorithm (EM statement) are displayed.

NOPRINT

suppresses the display of all output. Note that this option temporarily disables the Output Delivery System (ODS); see Chapter 20, “[Using the Output Delivery System](#),” for more information.

OUT=SAS-data-set

creates an output SAS data set that contains imputation results. The data set includes an index variable, `_Imputation_`, to identify the imputation number. For each imputation, the data set contains all variables in the input data set with missing values being replaced by the imputed values. See the section “[Output Data Sets](#)” on page 4767 for a description of this data set.

ROUND=numbers

specifies the units to round variables in the imputation. If only one number is specified, that number is used for all continuous variables. If more than one number is specified, you must use a VAR statement, and the specified numbers must correspond to variables in the VAR statement. When the classification variables are listed in the VAR statement, their corresponding roundoff units are not used. The default number is a missing value, which indicates no rounding for imputed variables.

When specifying a roundoff unit for the first variable only, you must also specify a missing value after the roundoff unit. Otherwise, the roundoff unit is used for all variables. For example, the option “ROUND= 10 .” sets a roundoff unit of 10 for the first analysis variable only and no rounding for the remaining variables. The option “ROUND= . 10” sets a roundoff unit of 10 for the second analysis variable only and no rounding for other variables.

The ROUND= option sets the precision of imputed values. For example, with a roundoff unit of 0.001, each value is rounded to the nearest multiple of 0.001. That is, each value has three significant digits after the decimal point. See [Example 57.3](#) for an illustration of this option.

SEED=number

specifies a positive integer to start the pseudo-random number generator. The default is a value generated from reading the time of day from the computer's clock. However, in order to duplicate the results under identical situations, you must use the same value of the seed explicitly in subsequent runs of the MI procedure.

The seed information is displayed in the "Model Information" table so that the results can be reproduced by specifying this seed with the SEED= option. You need to specify the same seed number in the future to reproduce the results.

SIMPLE

displays simple descriptive univariate statistics and pairwise correlations from available cases. For a detailed description of these statistics, see the section "[Descriptive Statistics](#)" on page 4743.

SINGULAR=p

specifies the criterion for determining the singularity of a covariance matrix based on standardized variables, where $0 < p < 1$. The default is SINGULAR=1E-8.

Suppose that \mathbf{S} is a covariance matrix and v is the number of variables in \mathbf{S} . Based on the spectral decomposition $\mathbf{S} = \mathbf{\Gamma}\mathbf{\Lambda}\mathbf{\Gamma}'$, where $\mathbf{\Lambda}$ is a diagonal matrix of eigenvalues λ_j , $j = 1, \dots, v$, where $\lambda_i \geq \lambda_j$ when $i < j$, and $\mathbf{\Gamma}$ is a matrix with the corresponding orthonormal eigenvectors of \mathbf{S} as columns, \mathbf{S} is considered singular when an eigenvalue λ_j is less than $p\bar{\lambda}$, where the average $\bar{\lambda} = \sum_{k=1}^v \lambda_k / v$.

BY Statement

BY variables ;

You can specify a BY statement with PROC MI to obtain separate analyses of observations in groups that are defined by the BY variables. When a BY statement appears, the procedure expects the input data set to be sorted in order of the BY variables. If you specify more than one BY statement, only the last one specified is used.

If your input data set is not sorted in ascending order, use one of the following alternatives:

- Sort the data by using the SORT procedure with a similar BY statement.
- Specify the NOTSORTED or DESCENDING option in the BY statement for the MI procedure. The NOTSORTED option does not mean that the data are unsorted but rather that the data are arranged in groups (according to values of the BY variables) and that these groups are not necessarily in alphabetical or increasing numeric order.
- Create an index on the BY variables by using the DATASETS procedure (in Base SAS software).

For more information about BY-group processing, see the discussion in *SAS Language Reference: Concepts*. For more information about the DATASETS procedure, see the discussion in the *Base SAS Procedures Guide*.

CLASS Statement

CLASS *variables* ;

The CLASS statement specifies the classification variables in the VAR statement. Classification variables can be either character or numeric. The CLASS statement must be used in conjunction with either an FCS or MONOTONE statement.

Classification levels are determined from the formatted values of the classification variables. See “The FORMAT Procedure” in the *Base SAS Procedures Guide* for details.

EM Statement

EM *< options >* ;

The expectation-maximization (EM) algorithm is a technique for maximum likelihood estimation in parametric models for incomplete data. The EM statement uses the EM algorithm to compute the MLE for (μ, Σ) , the means and covariance matrix, of a multivariate normal distribution from the input data set with missing values. Either the means and covariances from complete cases or the means and standard deviations from available cases can be used as the initial estimates for the EM algorithm. You can also specify the correlations for the estimates from available cases.

You can also use the EM statement with the NIMPUTE=0 option in the PROC MI statement to compute the EM estimates without multiple imputation, as shown in [Example 57.1](#).

The following seven options are available with the EM statement (in alphabetical order):

CONVERGE=*p*

XCONV=*p*

sets the convergence criterion. The value must be between 0 and 1. The iterations are considered to have converged when the change in the parameter estimates between iteration steps is less than *p* for each parameter—that is, for each of the means and covariances. For each parameter, the change is a relative change if the parameter is greater than 0.01 in absolute value; otherwise, it is an absolute change. By default, CONVERGE=1E–4.

INITIAL=CC | AC | AC(R=*r*)

sets the initial estimates for the EM algorithm. The INITIAL=CC option uses the means and covariances from complete cases; the INITIAL=AC option uses the means and standard deviations from available cases, and the correlations are set to zero; and the INITIAL=AC(R= *r*) option uses the means and standard deviations from available cases with correlation *r*, where $-1/(p - 1) < r < 1$ and *p* is the number of variables to be analyzed. The default is INITIAL=AC.

ITPRINT

prints the iteration history in the EM algorithm.

MAXITER=*number*

specifies the maximum number of iterations used in the EM algorithm. The default is MAXITER=200.

OUT=SAS-data-set

creates an output SAS data set that contains results from the EM algorithm. The data set contains all variables in the input data set, with missing values being replaced by the expected values from the EM algorithm. See the section “[Output Data Sets](#)” on page 4767 for a description of this data set.

OUTEM=SAS-data-set

creates an output SAS data set of TYPE=COV that contains the MLE of the parameter vector (μ , Σ). These estimates are computed with the EM algorithm. See the section “[Output Data Sets](#)” on page 4767 for a description of this output data set.

OUTITER < (options) > =SAS-data-set

creates an output SAS data set of TYPE=COV that contains parameters for each iteration. The data set includes a variable named `_iteration_` to identify the iteration number. The parameters in the output data set depend on the options specified. You can specify the MEAN and COV options to output the mean and covariance parameters. When no options are specified, the output data set contains the mean parameters for each iteration. See the section “[Output Data Sets](#)” on page 4767 for a description of this data set.

FCS Statement

FCS < options > ;

The FCS statement specifies a multivariate imputation by fully conditional specification methods. If you specify an FCS statement, you must also specify a VAR statement.

Table 57.2 summarizes the options available for the FCS statement.

Table 57.2 Summary of Options in FCS

Option	Description
Imputation Details	
NBITER=	Specifies the number of burn-in iterations
Data Set	
OUTITER=	Outputs parameter estimates used in iterations
ODS Output Graphics	
PLOTS=TRACE	Displays trace plots
Imputation Methods	
DISCRIM	Specifies the discriminant function method
LOGISTIC	Specifies the logistic regression method
REG	Specifies the regression method
REGPMM	Specifies the predictive mean matching method

The following options are available for the FCS statement in addition to the imputation methods specified (in alphabetical order):

NBITER=number

specifies the number of burn-in iterations before each imputation. The default is NBITER=20.

OUTITER <(options)> =SAS-data-set

creates an output SAS data set of TYPE=COV that contains parameters used in the imputation step for each iteration. The data set includes variables named `_Imputation_` and `_Iteration_` to identify the imputation number and iteration number.

The parameters in the output data set depend on the options specified. You can specify the options MEAN and STD to output parameters of means and standard deviations, respectively. When no options are specified, the output data set contains the mean parameters used in the imputation step for each iteration. See the section “[Output Data Sets](#)” on page 4767 for a description of this data set.

PLOTS <(LOG)> <= TRACE <(trace-options)>>

requests statistical graphics of trace plots from iterations via the Output Delivery System (ODS).

ODS Graphics must be enabled before plots can be requested. For example:

```
ods graphics on;
proc mi data=Fitness1 seed=501213 mu0=50 10 180;
  mcmc plots=(trace(mean(Oxygen)) acf(mean(Oxygen)));
  var Oxygen RunTime RunPulse;
run;
ods graphics off;
```

For more information about enabling and disabling ODS Graphics, see the section “[Enabling and Disabling ODS Graphics](#)” on page 600 in Chapter 21, “[Statistical Graphics Using ODS](#).”

The global plot option LOG requests that the logarithmic transformations of parameters be used. The default is PLOTS=TRACE(MEAN).

The available *trace-options* are as follows:

MEAN <(variables)>

displays plots of means for continuous variables in the list. When the MEAN option is specified without variables, all continuous variables are used.

STD <(variables)>

displays plots of standard deviations for continuous variables in the list. When the STD option is specified without variables, all continuous variables are used.

The discriminant function, logistic regression, regression, and predictive mean matching methods are available in the FCS statement. You specify each method with the syntax

```
method < (<imputed <= effects>> </ options>)>
```

That is, for each method, you can specify the imputed variables and, optionally, a set of effects to impute these variables. Each effect is a variable or a combination of variables in the VAR statement. The syntax for the specification of effects is the same as for the GLM procedure. See Chapter 42, “[The GLM Procedure](#),” for more information.

One general form of an effect involving several variables is

$$X1 * X2 * A * B * C (D E)$$

where A, B, C, D, and E are classification variables and X1 and X2 are continuous variables.

When an FCS statement is used without specifying any methods, the regression method is used for all continuous variables and the discriminant function method is used for all classification variables. For each imputed variable, all other variables in the VAR statement are used as the covariates.

When a method for continuous variables is specified without imputed variables, the method is used for all continuous variables in the VAR statement that are not specified in other methods. Similarly, when a method for classification variables is specified without imputed variables, the method is used for all classification variables in the VAR statement that are not specified in other methods.

For each imputed variable, if no covariates are specified, then all other variables in the VAR statement are used as the covariates. That is, each continuous variable is used as a regressor effect, and each classification variable is used as a main effect. For the discriminant function method, only the continuous variables can be used as covariate effects.

With an FCS statement, the variables are imputed sequentially in the order specified in the VAR statement. For a continuous variable, you can use a regression method or a regression predicted mean matching method to impute missing values. For a nominal classification variable, you can use a discriminant function method to impute missing values without using the ordering of the class levels. For an ordinal classification variable, you can use a logistic regression method to impute missing values by using the ordering of the class levels. For a binary classification variable, either a discriminant function method or a logistic regression method can be used. By default, a regression method is used for a continuous variable, and a discriminant function method is used for a classification variable.

Note that except for the regression method, all other methods impute values from the observed values. See the section “[FCS Methods for Data Sets with Arbitrary Missing Patterns](#)” on page 4755 for a detailed description of the FCS methods.

You can specify the following imputation methods in an FCS statement (in alphabetical order):

DISCRIM <(*imputed* <= *effects* > </ *options* >) >

specifies the discriminant function method of classification variables. The available options are DETAILS, PCOV=, PRIOR=, and CLASSEFFECTS=. The DETAILS option displays the group means and pooled covariance matrix used in each imputation. The PCOV= option specifies the pooled covariance used in the discriminant method. Valid values for the PCOV= option are as follows:

FIXED	uses the observed-data pooled covariance matrix for each imputation.
POSTERIOR	draws a pooled covariance matrix from its posterior distribution.

The default is PCOV=POSTERIOR. See the section “[Monotone and FCS Discriminant Function Methods](#)” on page 4752 for a detailed description of the method.

The PRIOR= option specifies the prior probabilities of group membership. Valid values for the PRIOR= option are as follows:

EQUAL	sets the prior probabilities equal for all groups.
PROPORTIONAL	sets the prior probabilities proportion to the group sample sizes.

JEFFREYS < = c > specifies a noninformative prior, $0 < c < 1$. If the number c is not specified, JEFFREYS=0.5.

RIDGE < = d > specifies a ridge prior, $d > 0$. If the number d is not specified, RIDGE=0.25.

The default is PRIOR=JEFFREYS. See the section “[Monotone and FCS Discriminant Function Methods](#)” on page 4752 for a detailed description of the method.

The CLASSEFFECTS= option specifies whether the CLASS variables are used as covariate effects. Valid values for the CLASSEFFECTS= option are as follows:

EXCLUDE excludes the CLASS variables from covariate effects.

INCLUDE includes the CLASS variables as covariate effects.

The default is CLASSEFFECTS=EXCLUDE.

LOGISTIC < (imputed < = effects > < / options >) >

specifies the logistic regression method of classification variables. The available options are DETAILS, ORDER=, and DESCENDING. The DETAILS option displays the regression coefficients in the logistic regression model used in each imputation.

When the imputed variable has more than two response levels, the ordinal logistic regression method is used. The ORDER= option specifies the sort order for the levels of the response variable. Valid values for the ORDER= option are as follows:

DATA sorts by the order of appearance in the input data set.

FORMATTED sorts by their external formatted values.

FREQ sorts by the descending frequency counts.

INTERNAL sorts by the unformatted values.

By default, ORDER=FORMATTED.

The option DESCENDING reverses the sort order for the levels of the response variables.

See the section “[Monotone and FCS Logistic Regression Methods](#)” on page 4754 for a detailed description of the method.

REG | REGRESSION < (imputed < = effects > < / DETAILS >) >

specifies the regression method of continuous variables. The DETAILS option displays the regression coefficients in the regression model used in each imputation.

With a regression method, the MAXIMUM=, MINIMUM=, and ROUND= options can be used to make the imputed values more consistent with the observed variable values.

See the section “[Monotone and FCS Regression Methods](#)” on page 4749 for a detailed description of the method.

REGPMM < (*imputed* < = *effects* > < *options* >) >

REGPREDMEANMATCH < (*imputed* < = *effects* > < *options* >) >

specifies the predictive mean matching method for continuous variables. This method is similar to the regression method except that it imputes a value randomly from a set of observed values whose predicted values are closest to the predicted value for the missing value from the simulated regression model (Heitjan and Little 1991; Schenker and Taylor 1996).

The available options are DETAILS and K=. The DETAILS option displays the regression coefficients in the regression model used in each imputation. The K= option specifies the number of closest observations to be used in the selection. The default is K=5.

See the section “[Monotone and FCS Predictive Mean Matching Methods](#)” on page 4750 for a detailed description of the method.

With an FCS statement, the missing values of variables in the VAR statement are imputed. After the initial filled in, these variables with missing values are imputed sequentially in the order specified in the VAR statement. For example, the following MI procedure statements use the regression method to impute variable y1 from effect y2, the regression method to impute variable y3 from effects y1 and y2, the logistic regression method to impute variable c1 from effects y1, y2, and y1 * y2, and the default regression method for continuous variables to impute variable y2 from effects y1, y3, and c1:

```
proc mi;
  class c1;
  fcs reg(y1= y2) reg(y3= y1 y2) logistic(c1= y1 y2 y1*y2);
  var y1 y2 y3 c1;
run;
```

FREQ Statement

FREQ *variable* ;

To run a procedure on an input data set that contains observations that occur multiple times, you can use a variable in the data set to represent how frequently observations occur and specify a FREQ statement with the name of that variable as its argument (*variable*) when you run the procedure.

When you specify a FREQ statement in other SAS procedures, they treat the data set as if each observation appeared *n* times, where *n* is the value of *variable* in the observation. However, PROC MI treats the data set differently because as PROC MI imputes each missing value in each observation, it generates only one imputed value for that missing value. That is, when you specify a FREQ *variable*, each imputed observation (with its imputed value in place of the missing value) is treated as if it appeared *n* times. In contrast, if an observation actually occurs *n* times in the data set, the missing value at each occurrence is imputed separately, and the resulting *n* observations are not identical.

PROC MI uses only the integer portion of each value of *variable*; if any value is less than 1, PROC MI does not use the corresponding observation in the analysis. When PROC MI calculates significance probabilities, it considers the total number of observations to be equal to the sum of the values of *variable*.

MCMC Statement

MCMC < options > ;

The MCMC statement specifies the details of the MCMC method for imputation.

Table 57.3 summarizes the options available for the MCMC statement.

Table 57.3 Summary of Options in MCMC

Option	Description
Data Sets	
INEST=	Inputs parameter estimates for imputations
OUTEST=	Outputs parameter estimates used in imputations
OUTITER=	Outputs parameter estimates used in iterations
Imputation Details	
IMPUTE=	Specifies monotone or full imputation
CHAIN=	Specifies single or multiple chain
NBITER=	Specifies the number of burn-in iterations for each chain
NITER=	Specifies the number of iterations between imputations in a chain
INITIAL=	Specifies initial parameter estimates for MCMC
PRIOR=	Specifies the prior parameter information
START=	Specifies starting parameters
ODS Output Graphics	
PLOTS=TRACE	Displays trace plots
PLOTS=ACF	Displays autocorrelation plots
Traditional Graphics	
TIMEPLOT	Displays trace plots
ACFPLOT	Displays autocorrelation plots
GOUT=	Specifies the graphics catalog name for saving graphics output
Printed Output	
WLF	Displays the worst linear function
DISPLAYINIT	Displays initial parameter values for MCMC

The following options are available for the MCMC statement (in alphabetical order).

ACFPLOT < (options < / display-options >) >

displays the traditional autocorrelation function plots of parameters from iterations. The ACFPLOT option is applicable only if ODS Graphics is not enabled.

The available options are as follows.

COV <(< *variables* > < *variable1*variable2* > < ... *variable1*variable2* >) >

displays plots of variances for variables in the list and covariances for pairs of variables in the list. When the option COV is specified without variables, variances for all variables and covariances for all pairs of variables are used.

MEAN <(*variables*) >

displays plots of means for variables in the list. When the option MEAN is specified without variables, all variables are used.

WLF

displays the plot for the worst linear function.

When the ACFPLOT is specified without the preceding options, the procedure displays plots of means for all variables that are used.

The display options provide additional information for the autocorrelation function plots. The available display options are as follows:

CCONF=*color*

specifies the color of the displayed confidence limits. The default is CCONF=BLACK.

CFRAME=*color*

specifies the color for filling the area enclosed by the axes and the frame. By default, this area is not filled.

CNEEDLES=*color*

specifies the color of the vertical line segments (needles) that connect autocorrelations to the reference line. The default is CNEEDLES=BLACK.

CREF=*color*

specifies the color of the displayed reference line. The default is CREF=BLACK.

CSYMBOL=*color*

specifies the color of the displayed data points. The default is CSYMBOL=BLACK.

HSYMBOL=*number*

specifies the height of data points in percentage screen units. The default is HSYMBOL=1.

LCONF=*linetype*

specifies the line type for the displayed confidence limits. The default is LCONF=1, a solid line.

LOG

requests that the logarithmic transformations of parameters be used to compute the autocorrelations; it is generally used for the variances of variables. When a parameter has values less than or equal to zero, the corresponding plot is not created.

LREF=*linetype*

specifies the line type for the displayed reference line. The default is LREF=3, a dashed line.

NAME=*'string'*

specifies a descriptive name, up to eight characters, that appears in the name field of the PROC GREPLAY master menu. The default is NAME='MI'.

NLAG=*number*

specifies the maximum lag of the series. The default is NLAG=20. The autocorrelations at each lag are displayed in the graph.

SYMBOL=*value*

specifies the symbol for data points in percentage screen units. The default is SYMBOL=STAR.

TITLE=*'string'*

specifies the title to be displayed in the autocorrelation function plots. The default is TITLE='Autocorrelation Plot'.

WCONF=*number*

specifies the width of the displayed confidence limits in percentage screen units. If you specify the WCONF=0 option, the confidence limits are not displayed. The default is WCONF=1.

WNEEDLES=*number*

specifies the width of the displayed needles that connect autocorrelations to the reference line, in percentage screen units. If you specify the WNEEDLES=0 option, the needles are not displayed. The default is WNEEDLES=1.

WREF=*number*

specifies the width of the displayed reference line in percentage screen units. If you specify the WREF=0 option, the reference line is not displayed. The default is WREF=1.

For example, the following statement requests autocorrelation function plots for the means and variances of the variable *y1*, respectively:

```
acfplot( mean( y1) cov(y1) /log);
```

Logarithmic transformations of both the means and variances are used in the plots. For a detailed description of the autocorrelation function plot, see the section “[Autocorrelation Function Plot](#)” on page 4765; see also Schafer (1997, pp. 120–126) and the *SAS/ETS User's Guide*.

CHAIN=SINGLE | MULTIPLE

specifies whether a single chain is used for all imputations or a separate chain is used for each imputation. The default is CHAIN=SINGLE.

DISPLAYINIT

displays initial parameter values in the MCMC method for each imputation.

GOUT=*graphics-catalog*

specifies the graphics catalog for saving graphics output from PROC MI. The default is WORK.GSEG. For more information, see “The GREPLAY Procedure” in *SAS/GRAPH: Reference*.

IMPUTE=FULL | MONOTONE

specifies whether a full-data imputation is used for all missing values or a monotone-data imputation is used for a subset of missing values to make the imputed data sets have a monotone missing pattern. The default is `IMPUTE=FULL`. When `IMPUTE=MONOTONE` is specified, the order in the `VAR` statement is used to complete the monotone pattern.

INEST=SAS-data-set

names a SAS data set of `TYPE=EST` that contains parameter estimates for imputations. These estimates are used to impute values for observations in the `DATA=` data set. A detailed description of the data set is provided in the section “[Input Data Sets](#)” on page 4766.

INITIAL=EM <(options)>**INITIAL=INPUT=SAS-data-set**

specifies the initial mean and covariance estimates for the MCMC method. The default is `INITIAL=EM`.

You can specify `INITIAL=INPUT=SAS-data-set` to read the initial estimates of the mean and covariance matrix for each imputation from a SAS data set. See the section “[Input Data Sets](#)” on page 4766 for a description of this data set.

With `INITIAL=EM`, PROC MI derives parameter estimates for a posterior mode, the highest observed-data posterior density, from the EM algorithm. The MLE from the EM algorithm is used to start the EM algorithm for the posterior mode, and the resulting EM estimates are used to begin the MCMC method. The prior information specified in the `PRIOR=` option is also used in the process to compute the posterior mode.

The following four options are available with `INITIAL=EM`:

BOOTSTRAP <=number>

requests bootstrap resampling, which uses a simple random sample with replacement from the input data set for the initial estimate. You can explicitly specify the number of observations in the random sample. Alternatively, you can implicitly specify the number of observations in the random sample by specifying the proportion p , $0 < p \leq 1$, to request $[np]$ observations in the random sample, where n is the number of observations in the data set and $[np]$ is the integer part of np . This produces an overdispersed initial estimate that provides different starting values for the MCMC method. If you specify the `BOOTSTRAP` option without the number, $p = 0.75$ is used by default.

CONVERGE= p **XCONV= p**

sets the convergence criterion. The value must be between 0 and 1. The iterations are considered to have converged when the change in the parameter estimates between iteration steps is less than p for each parameter—that is, for each of the means and covariances. For each parameter, the change is a relative change if the parameter is greater than 0.01 in absolute value; otherwise, it is an absolute change. By default, `CONVERGE=1E-4`.

ITPRINT

prints the iteration history in the EM algorithm for the posterior mode.

MAXITER=number

specifies the maximum number of iterations used in the EM algorithm. The default is MAXITER=200.

NBITER=number

specifies the number of burn-in iterations before the first imputation in each chain. The default is NBITER=200.

NITER=number

specifies the number of iterations between imputations in a single chain. The default is NITER=100.

OUTEST=SAS-data-set

creates an output SAS data set of TYPE=EST. The data set contains parameter estimates used in each imputation. The data set also includes a variable named `_Imputation_` to identify the imputation number. See the section “[Output Data Sets](#)” on page 4767 for a description of this data set.

OUTITER < (options) > =SAS-data-set

creates an output SAS data set of TYPE=COV that contains parameters used in the imputation step for each iteration. The data set includes variables named `_Imputation_` and `_Iteration_` to identify the imputation number and iteration number.

The parameters in the output data set depend on the options specified. You can specify the options MEAN, STD, COV, LR, LR_POST, and WLF to output parameters of means, standard deviations, covariances, $-2 \log$ LR statistic, $-2 \log$ LR statistic of the posterior mode, and the worst linear function, respectively. When no options are specified, the output data set contains the mean parameters used in the imputation step for each iteration. See the section “[Output Data Sets](#)” on page 4767 for a description of this data set.

PLOTS < (LOG) > <= plot-request >**PLOTS < (LOG) > <= (plot-request < ... plot-request >) >**

requests statistical graphics via the Output Delivery System (ODS). To request these graphs, ODS Graphics must be enabled and you must specify options in the MCMC statement. For more information about ODS Graphics, see Chapter 21, “[Statistical Graphics Using ODS](#).”

The global plot option LOG requests that the logarithmic transformations of parameters be used. The plot request options include the following:

ACF < (acf-options) >

displays plots of the autocorrelation function of parameters from iterations. The default is ACF(MEAN).

ALL

produces all appropriate plots.

NONE

suppresses all plots.

TRACE < (trace-options) >

displays trace plots of parameters from iterations. The default is TRACE(MEAN).

The available *acf-options* are as follows:

NLAG=*n*

specifies the maximum lag of the series. The default is NLAG=20. The autocorrelations at each lag are displayed in the graph.

COV < (< *variables* > < *variable1*variable2* > ...) >

displays plots of variances for variables in the list and covariances for pairs of variables in the list. When the option COV is specified without variables, variances for all variables and covariances for all pairs of variables are used.

MEAN < (*variables*) >

displays plots of means for variables in the list. When the option MEAN is specified without variables, all variables are used.

WLF

displays the plot for the worst linear function.

The available *trace-options* are as follows:

COV < (< *variables* > < *variable1*variable2* > ...) >

displays plots of variances for variables in the list and covariances for pairs of variables in the list. When the option COV is specified without variables, variances for all variables and covariances for all pairs of variables are used.

MEAN < (*variables*) >

displays plots of means for variables in the list. When the option MEAN is specified without variables, all variables are used.

WLF

displays the plot of the worst linear function.

PRIOR=*name*

specifies the prior information for the means and covariances. Valid values for *name* are as follows:

JEFFREYS specifies a noninformative prior.

RIDGE=*number* specifies a ridge prior.

INPUT=*SAS-data-set* specifies a data set that contains prior information.

For a detailed description of the prior information, see the section “[Bayesian Estimation of the Mean Vector and Covariance Matrix](#)” on page 4759 and the section “[Posterior Step](#)” on page 4759. If you do not specify the PRIOR= option, the default is PRIOR=JEFFREYS.

The PRIOR=INPUT= option specifies a TYPE=COV data set from which the prior information of the mean vector and the covariance matrix is read. See the section “[Input Data Sets](#)” on page 4766 for a description of this data set.

START=VALUE | DIST

specifies that the initial parameter estimates are used either as the starting value (START=VALUE) or as the starting distribution (START=DIST) in the first imputation step of each chain. If the IMPUTE=MONOTONE option is specified, then START=VALUE is used in the procedure. The default is START=VALUE.

TIMEPLOT < (*options* < / *display-options* >) >

displays the traditional trace (time series) plots of parameters from iterations. The TIMEPLOT option is applicable only if ODS Graphics is not enabled.

The available options are as follows:

COV < (< *variables* > < *variable1*variable2* > ...) >

displays plots of variances for variables in the list and covariances for pairs of variables in the list. When the option COV is specified without variables, variances for all variables and covariances for all pairs of variables are used.

MEAN < (*variables*)>

displays plots of means for variables in the list. When the option MEAN is specified without variables, all variables are used.

WLF

displays the plot of the worst linear function.

When the TIMEPLOT is specified without the preceding options, the procedure displays plots of means for all variables that are used.

The display options provide additional information for the trace plots. The available display options are as follows:

CCONNECT=*color*

specifies the color of the line segments that connect data points in the trace plots. The default is CCONNECT=BLACK.

CFRAME=*color*

specifies the color for filling the area enclosed by the axes and the frame. By default, this area is not filled.

CSYMBOL=*color*

specifies the color of the data points to be displayed in the trace plots. The default is CSYMBOL=BLACK.

HSYMBOL=*number*

specifies the height of data points in percentage screen units. The default is HSYMBOL=1.

LCONNECT=*linetype*

specifies the line type for the line segments that connect data points in the trace plots. The default is LCONNECT=1, a solid line.

LOG

requests that the logarithmic transformations of parameters be used; it is generally used for the variances of variables. When a parameter value is less than or equal to zero, the value is not displayed in the corresponding plot.

NAME=*'string'*

specifies a descriptive name, up to eight characters, that appears in the name field of the PROC GREPLAY master menu. The default is NAME='MI'.

SYMBOL=*value*

specifies the symbol for data points in percentage screen units. The default is SYMBOL=PLUS.

TITLE=*'string'*

specifies the title to be displayed in the trace plots. The default is TITLE='Trace Plot'.

WCONNECT=*number*

specifies the width of the line segments that connect data points in the trace plots, in percentage screen units. If you specify the WCONNECT=0 option, the data points are not connected. The default is WCONNECT=1.

For a detailed description of the trace plot, see the section “[Trace Plot](#)” on page 4765 and Schafer (1997, pp. 120–126).

WLF

displays the worst linear function of parameters. This scalar function of parameters μ and Σ is “worst” in the sense that its values from iterations converge most slowly among parameters. For a detailed description of this statistic, see the section “[Worst Linear Function of Parameters](#)” on page 4764.

MONOTONE Statement

MONOTONE <method <(<imputed <= effects>> </options>)>>
<...method <(<imputed <= effects>> </options>)>> ;

The MONOTONE statement specifies imputation methods for data sets with monotone missingness. You must also specify a VAR statement, and the data set must have a monotone missing pattern with variables ordered in the VAR list.

Table 57.4 summarizes the options available for the MONOTONE statement.

Table 57.4 Summary of Imputation Methods in MONOTONE Statement

Option	Description
DISCRIM	Specifies the discriminant function method
LOGISTIC	Specifies the logistic regression method
PROPENSITY	Specifies the propensity scores method
REG	Specifies the regression method
REGPMM	Specifies the predictive mean matching method

For each method, you can specify the imputed variables and, optionally, a set of the effects to impute these variables. Each effect is a variable or a combination of variables preceding the imputed variable in the VAR statement. The syntax for specification of effects is the same as for the GLM procedure. See Chapter 42, “[The GLM Procedure](#),” for more information.

One general form of an effect involving several variables is

$$X1 * X2 * A * B * C (D E)$$

where A, B, C, D, and E are classification variables and X1 and X2 are continuous variables.

If no covariates are specified, then all preceding variables are used as the covariates. That is, each preceding continuous variable is used as a regressor effect, and each preceding classification variable is used as a main effect. For the discriminant function method, only the continuous variables can be used as covariate effects.

When a method for continuous variables is specified without imputed variables, the method is used for all continuous variables in the VAR statement that are not specified in other methods. Similarly, when a method for classification variables is specified without imputed variables, the method is used for all classification variables in the VAR statement that are not specified in other methods.

When a MONOTONE statement is used without specifying any methods, the regression method is used for all continuous variables and the discriminant function method is used for all classification variables. The preceding variables of each imputed variable in the VAR statement are used as the covariates.

With a MONOTONE statement, the variables are imputed sequentially in the order given by the VAR statement. For a continuous variable, you can use a regression method, a regression predicted mean matching method, or a propensity score method to impute missing values.

For a nominal classification variable, you can use a discriminant function method to impute missing values without using the ordering of the class levels. For an ordinal classification variable, you can use a logistic regression method to impute missing values by using the ordering of the class levels. For a binary classification variable, either a discriminant function method or a logistic regression method can be used.

Note that except for the regression method, all other methods impute values from the observed observation values. You can specify the following methods in a MONOTONE statement.

DISCRIM < (*imputed* < = *effects* > < / *options* >) >

specifies the discriminant function method of classification variables. The available options are DETAILS, PCOV=, PRIOR=, and CLASSEFFECTS=. The DETAILS option displays the group means and pooled covariance matrix used in each imputation. The PCOV= option specifies the pooled covariance used in the discriminant method. Valid values for the PCOV= option are as follows:

FIXED	uses the observed-data pooled covariance matrix for each imputation.
POSTERIOR	draws a pooled covariance matrix from its posterior distribution.

The default is PCOV=POSTERIOR. See the section “[Monotone and FCS Discriminant Function Methods](#)” on page 4752 for a detailed description of the method.

The PRIOR= option specifies the prior probabilities of group membership. Valid values for the PRIOR= option are as follows:

EQUAL	sets the prior probabilities equal for all groups.
PROPORTIONAL	sets the prior probabilities proportion to the group sample sizes.

JEFFREYS < =*c* > specifies a noninformative prior, $0 < c < 1$. If the number *c* is not specified, JEFFREYS=0.5.

RIDGE < =*d* > specifies a ridge prior, $d > 0$. If the number *d* is not specified, RIDGE=0.25.

The default is PRIOR=JEFFREYS. See the section “[Monotone and FCS Discriminant Function Methods](#)” on page 4752 for a detailed description of the method.

The CLASSEFFECTS= option specifies whether the CLASS variables are used as covariate effects. Valid values for the CLASSEFFECTS= option are as follows:

EXCLUDE excludes the CLASS variables from covariate effects.

INCLUDE includes the CLASS variables as covariate effects.

The default is CLASSEFFECTS=EXCLUDE.

LOGISTIC < (*imputed* < = *effects* > < / options >) >

specifies the logistic regression method of classification variables. The available options are DETAILS, ORDER=, and DESCENDING. The DETAILS option displays the regression coefficients in the logistic regression model used in each imputation.

When the imputed variable has more than two response levels, the ordinal logistic regression method is used. The ORDER= option specifies the sort order for the levels of the response variable. Valid values for the ORDER= option are as follows:

DATA sorts by the order of appearance in the input data set.

FORMATTED sorts by their external formatted values.

FREQ sorts by the descending frequency counts.

INTERNAL sorts by the unformatted values.

By default, ORDER=FORMATTED.

The option DESCENDING reverses the sort order for the levels of the response variables.

See the section “[Monotone and FCS Logistic Regression Methods](#)” on page 4754 for a detailed description of the method.

PROPENSITY < (*imputed* < = *effects* > < / options >) >

specifies the propensity scores method of variables. Each variable is either a classification variable or a continuous variable. The available options are DETAILS and NGROUPS=. The DETAILS option displays the regression coefficients in the logistic regression model for propensity scores. The NGROUPS= option specifies the number of groups created based on propensity scores. The default is NGROUPS=5.

See the section “[Monotone Propensity Score Method](#)” on page 4751 for a detailed description of the method.

REG | REGRESSION < (*imputed* < = *effects* > < / DETAILS >) >

specifies the regression method of continuous variables. The DETAILS option displays the regression coefficients in the regression model used in each imputation.

With a regression method, the MAXIMUM=, MINIMUM=, and ROUND= options can be used to make the imputed values more consistent with the observed variable values.

See the section “[Monotone and FCS Regression Methods](#)” on page 4749 for a detailed description of the method.

REGPM < (*imputed* < = *effects* > < *options* >) >

REGPREDMEANMATCH < (*imputed* < = *effects* > < *options* >) >

specifies the predictive mean matching method for continuous variables. This method is similar to the regression method except that it imputes a value randomly from a set of observed values whose predicted values are closest to the predicted value for the missing value from the simulated regression model (Heitjan and Little 1991; Schenker and Taylor 1996).

The available options are DETAILS and K=. The DETAILS option displays the regression coefficients in the regression model used in each imputation. The K= option specifies the number of closest observations to be used in the selection. The default is K=5.

See the section “[Monotone and FCS Predictive Mean Matching Methods](#)” on page 4750 for a detailed description of the method.

With a MONOTONE statement, the missing values of a variable are imputed when the variable is either explicitly specified in the method or implicitly specified when a method is specified without imputed variables. These variables are imputed sequentially in the order specified in the VAR statement. For example, the following MI procedure statements use the logistic regression method to impute variable c1 from effects y1, y2, and y1 * y2 first, and then use the regression method to impute variable y3 from effects y1, y2, and c1:

```
proc mi;
  class c1;
  var y1 y2 c1 y3;
  monotone reg(y3= y1 y2 c1) logistic(c1= y1 y2 y1*y2);
run;
```

The variables y1 and y2 are not imputed since y1 is the leading variable in the VAR statement and y2 is not specified as an imputed variable in the MONOTONE statement.

TRANSFORM Statement

TRANSFORM *transform* (*variables* < / *options* >) < ... *transform* (*variables* < / *options* >) > ;

The TRANSFORM statement lists the transformations and their associated variables to be transformed. The options are transformation options that provide additional information for the transformation.

The MI procedure assumes that the data are from a multivariate normal distribution when either the regression method or the MCMC method is used. When some variables in a data set are clearly non-normal, it is useful to transform these variables to conform to the multivariate normality assumption. With a TRANSFORM statement, variables are transformed before the imputation process, and these transformed variable values are displayed in all of the results. When you specify an OUT= option, the variable values are back-transformed to create the imputed data set.

The following transformations can be used in the TRANSFORM statement:

BOXCOX

specifies the Box-Cox transformation of variables. The variable Y is transformed to $\frac{(Y+c)^\lambda - 1}{\lambda}$, where c is a constant such that each value of $Y + c$ must be positive. If the specified constant $\lambda = 0$, the logarithmic transformation is used.

EXP

specifies the exponential transformation of variables. The variable Y is transformed to $e^{(Y+c)}$, where c is a constant.

LOG

specifies the logarithmic transformation of variables. The variable Y is transformed to $\log(Y + c)$, where c is a constant such that each value of $Y + c$ must be positive.

LOGIT

specifies the logit transformation of variables. The variable Y is transformed to $\log(\frac{Y/c}{1-Y/c})$, where the constant $c > 0$ and the values of Y/c must be between 0 and 1.

POWER

specifies the power transformation of variables. The variable Y is transformed to $(Y + c)^\lambda$, where c is a constant such that each value of $Y + c$ must be positive and the constant $\lambda \neq 0$.

The following options provide the constant c and λ values in the transformations.

C=number

specifies the c value in the transformation. The default is $c = 1$ for logit transformation and $c = 0$ for other transformations.

LAMBDA=number

specifies the λ value in the power and Box-Cox transformations. You must specify the λ value for these two transformations.

For example, the following statement requests that variables $\log(y1)$, a logarithmic transformation for the variable $y1$, and $\sqrt{y2 + 1}$, a power transformation for the variable $y2$, be used in the imputation:

```
transform log(y1) power(y2/c=1 lambda=.5);
```

If the MU0= option is used to specify a parameter value μ_0 for a transformed variable, the same transformation for the variable is also applied to its corresponding MU0= value in the t test. Otherwise, $\mu_0 = 0$ is used for the transformed variable. See [Example 57.10](#) for a usage of the TRANSFORM statement.

VAR Statement

VAR *variables* ;

The VAR statement lists the variables to be analyzed. The variables can be either character or numeric. If you omit the VAR statement, all continuous variables not mentioned in other statements are used. The VAR statement is required if you specify either an FCS statement, a MONOTONE statement, an IMPUTE=MONOTONE option in the MCMC statement, or more than one number in the MU0=, MAXIMUM=, MINIMUM=, or ROUND= option.

The classification variables in the VAR statement, which can be either character or numeric, are further specified in the CLASS statement.

Details: MI Procedure

Descriptive Statistics

Suppose $\mathbf{Y} = (\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_n)'$ is the $(n \times p)$ matrix of complete data, which might not be fully observed, n_0 is the number of observations fully observed, and n_j is the number of observations with observed values for variable Y_j .

With complete cases, the sample mean vector is

$$\bar{\mathbf{y}} = \frac{1}{n_0} \sum \mathbf{y}_i$$

and the CSSCP matrix is

$$\sum (\mathbf{y}_i - \bar{\mathbf{y}})(\mathbf{y}_i - \bar{\mathbf{y}})'$$

where each summation is over the fully observed observations.

The sample covariance matrix is

$$\mathbf{S} = \frac{1}{n_0 - 1} \sum (\mathbf{y}_i - \bar{\mathbf{y}})(\mathbf{y}_i - \bar{\mathbf{y}})'$$

and is an unbiased estimate of the covariance matrix.

The correlation matrix \mathbf{R} , which contains the Pearson product-moment correlations of the variables, is derived by scaling the corresponding covariance matrix:

$$\mathbf{R} = \mathbf{D}^{-1} \mathbf{S} \mathbf{D}^{-1}$$

where \mathbf{D} is a diagonal matrix whose diagonal elements are the square roots of the diagonal elements of \mathbf{S} .

With available cases, the corrected sum of squares for variable Y_j is

$$\sum (y_{ji} - \bar{y}_j)^2$$

where $\bar{y}_j = \frac{1}{n_j} \sum y_{ji}$ is the sample mean and each summation is over observations with observed values for variable Y_j .

The variance is

$$s_{jj}^2 = \frac{1}{n_j - 1} \sum (y_{ji} - \bar{y}_j)^2$$

The correlations for available cases contain pairwise correlations for each pair of variables. Each correlation is computed from all observations that have nonmissing values for the corresponding pair of variables.

EM Algorithm for Data with Missing Values

The EM algorithm (Dempster, Laird, and Rubin 1977) is a technique that finds maximum likelihood estimates in parametric models for incomplete data. For a detailed description and applications of the EM algorithm, see the books by Little and Rubin (2002); Schafer (1997); McLachlan and Krishnan (1997).

The EM algorithm is an iterative procedure that finds the MLE of the parameter vector by repeating the following steps:

1. The expectation E-step

Given a set of parameter estimates, such as a mean vector and covariance matrix for a multivariate normal distribution, the E-step calculates the conditional expectation of the complete-data log likelihood given the observed data and the parameter estimates.

2. The maximization M-step

Given a complete-data log likelihood, the M-step finds the parameter estimates to maximize the complete-data log likelihood from the E-step.

The two steps are iterated until the iterations converge.

In the EM process, the observed-data log likelihood is nondecreasing at each iteration. For multivariate normal data, suppose there are G groups with distinct missing patterns. Then the observed-data log likelihood being maximized can be expressed as

$$\log L(\theta|Y_{obs}) = \sum_{g=1}^G \log L_g(\theta|Y_{obs})$$

where $\log L_g(\theta|Y_{obs})$ is the observed-data log likelihood from the g th group, and

$$\log L_g(\theta|Y_{obs}) = -\frac{n_g}{2} \log |\Sigma_g| - \frac{1}{2} \sum_{ig} (\mathbf{y}_{ig} - \boldsymbol{\mu}_g)' \Sigma_g^{-1} (\mathbf{y}_{ig} - \boldsymbol{\mu}_g)$$

where n_g is the number of observations in the g th group, the summation is over observations in the g th group, \mathbf{y}_{ig} is a vector of observed values corresponding to observed variables, $\boldsymbol{\mu}_g$ is the corresponding mean vector, and Σ_g is the associated covariance matrix.

A sample covariance matrix is computed at each step of the EM algorithm. If the covariance matrix is singular, the linearly dependent variables for the observed data are excluded from the likelihood function. That is, for each observation with linear dependency among its observed variables, the dependent variables are excluded from the likelihood function. Note that this can result in an unexpected change in the likelihood between iterations prior to the final convergence.

See Schafer (1997, pp. 163–181) for a detailed description of the EM algorithm for multivariate normal data.

PROC MI uses the means and standard deviations from available cases as the initial estimates for the EM algorithm. The correlations are set to zero. These initial estimates provide a good starting value with positive definite covariance matrix. For a discussion of suggested starting values for the algorithm, see Schafer (1997, p. 169).

You can specify the convergence criterion with the `CONVERGE=` option in the `EM` statement. The iterations are considered to have converged when the maximum change in the parameter estimates between iteration steps is less than the value specified. You can also specify the maximum number of iterations used in the `EM` algorithm with the `MAXITER=` option.

The `MI` procedure displays tables of the initial parameter estimates used to begin the `EM` process and the MLE parameter estimates derived from `EM`. You can also display the `EM` iteration history with the `ITPRINT` option. `PROC MI` lists the iteration number, the likelihood $-2 \log L$, and the parameter values μ at each iteration. You can also save the MLE derived from the `EM` algorithm in a SAS data set by specifying the `OUTEM=` option.

Statistical Assumptions for Multiple Imputation

The `MI` procedure assumes that the data are from a continuous multivariate distribution and contain missing values that can occur for any of the variables. It also assumes that the data are from a multivariate normal distribution when either the regression method or the MCMC method is used.

Suppose \mathbf{Y} is the $n \times p$ matrix of complete data, which is not fully observed, and denote the observed part of \mathbf{Y} by \mathbf{Y}_{obs} and the missing part by \mathbf{Y}_{mis} . The `MI` and `MIANALYZE` procedures assume that the missing data are missing at random (MAR); that is, the probability that an observation is missing can depend on \mathbf{Y}_{obs} , but not on \mathbf{Y}_{mis} (Rubin 1976, 1987, p. 53).

To be more precise, suppose that \mathbf{R} is the $n \times p$ matrix of response indicators whose elements are zero or one depending on whether the corresponding elements of \mathbf{Y} are missing or observed. Then the MAR assumption is that the distribution of \mathbf{R} can depend on \mathbf{Y}_{obs} but not on \mathbf{Y}_{mis} :

$$\text{pr}(\mathbf{R} | \mathbf{Y}_{obs}, \mathbf{Y}_{mis}) = \text{pr}(\mathbf{R} | \mathbf{Y}_{obs})$$

For example, consider a trivariate data set with variables Y_1 and Y_2 fully observed, and a variable Y_3 that has missing values. MAR assumes that the probability that Y_3 is missing for an individual can be related to the individual's values of variables Y_1 and Y_2 , but not to its value of Y_3 . On the other hand, if a complete case and an incomplete case for Y_3 with exactly the same values for variables Y_1 and Y_2 have systematically different values, then there exists a response bias for Y_3 , and MAR is violated.

The MAR assumption is not the same as missing completely at random (MCAR), which is a special case of MAR. Under the MCAR assumption, the missing data values are a simple random sample of all data values; the missingness does not depend on the values of any variables in the data set.

Although the MAR assumption cannot be verified with the data and it can be questionable in some situations, the assumption becomes more plausible as more variables are included in the imputation model (Schafer 1997, pp. 27–28; van Buuren, Boshuizen, and Knook 1999, p. 687).

Furthermore, the `MI` and `MIANALYZE` procedures assume that the parameters θ of the data model and the parameters ϕ of the model for the missing-data indicators are distinct. That is, knowing the values of θ does not provide any additional information about ϕ , and vice versa. If both the MAR and distinctness assumptions are satisfied, the missing-data mechanism is said to be ignorable (Rubin 1987, pp. 50–54; Schafer 1997, pp. 10–11).

Missing Data Patterns

The MI procedure sorts the data into groups based on whether the analysis variables are observed or missing. Note that the input data set does not need to be sorted in any order.

For example, with variables Y_1 , Y_2 , and Y_3 (in that order) in a data set, up to eight groups of observations can be formed from the data set. Figure 57.6 displays the eight groups of observations and an unique missing pattern for each group.

Figure 57.6 Missing Data Patterns

Missing Data Patterns				
Group	Y1	Y2	Y3	
1	X	X	X	
2	X	X	.	
3	X	.	X	
4	X	.	.	
5	.	X	X	
6	.	X	.	
7	.	.	X	
8	.	.	.	

Here, an “X” means that the variable is observed in the corresponding group and a “.” means that the variable is missing.

The variable order is used to derive the order of the groups from the data set, and thus determines the order of missing values in the data to be imputed. If you specify a different order of variables in the VAR statement, then the results are different even if the other specifications remain the same.

A data set with variables Y_1, Y_2, \dots, Y_p (in that order) is said to have a *monotone missing pattern* when the event that a variable Y_j is missing for a particular individual implies that all subsequent variables $Y_k, k > j$, are missing for that individual. Alternatively, when a variable Y_j is observed for a particular individual, it is assumed that all previous variables $Y_k, k < j$, are also observed for that individual.

For example, Figure 57.7 displays a data set of three variables with a monotone missing pattern.

Figure 57.7 Monotone Missing Patterns

Monotone Missing Data Patterns				
Group	Y1	Y2	Y3	
1	X	X	X	
2	X	X	.	
3	X	.	.	

Figure 57.8 displays a data set of three variables with a non-monotone missing pattern.

Figure 57.8 Non-monotone Missing Patterns

Non-monotone Missing Data Patterns				
Group	Y1	Y2	Y3	
1	X	X	X	
2	X	.	X	
3	.	X	.	
4	.	.	X	

A data set with an *arbitrary missing pattern* is a data set with either a monotone missing pattern or a non-monotone missing pattern.

Imputation Methods

This section describes the methods for multiple imputation that are available in the MI procedure. The method of choice depends on the pattern of missingness in the data and the type of the imputed variable, as summarized in Table 57.5.

Table 57.5 Imputation Methods in PROC MI

Pattern of Missingness	Type of Imputed Variable	Type of Covariates	Available Methods
Monotone	Continuous	Arbitrary	<ul style="list-style-type: none"> • Monotone regression • Monotone predicted mean matching • Monotone propensity score
Monotone	Classification (ordinal)	Arbitrary	<ul style="list-style-type: none"> • Monotone logistic regression
Monotone	Classification (nominal)	Arbitrary	<ul style="list-style-type: none"> • Monotone discriminant function
Arbitrary	Continuous	Continuous	<ul style="list-style-type: none"> • MCMC full-data imputation • MCMC monotone-data imputation
Arbitrary	Continuous	Arbitrary	<ul style="list-style-type: none"> • FCS regression • FCS predicted mean matching
Arbitrary	Classification (ordinal)	Arbitrary	<ul style="list-style-type: none"> • FCS logistic regression
Arbitrary	Classification (nominal)	Arbitrary	<ul style="list-style-type: none"> • FCS discriminant function

To impute missing values for a continuous variable in data sets with monotone missing patterns, you should use either a parametric method that assumes multivariate normality or a nonparametric method that uses propensity scores (Rubin 1987, pp. 124, 158; Lavori, Dawson, and Shera 1995). Parametric methods available include the regression method (Rubin 1987, pp. 166–167) and the predictive mean matching method (Heitjan and Little 1991; Schenker and Taylor 1996).

To impute missing values for a classification variable in data sets with monotone missing patterns, you should use the logistic regression method or the discriminant function method. Use the logistic regression method when the classification variable has a binary or ordinal response, and use the discriminant function method when the classification variable has a binary or nominal response.

For data sets with arbitrary missing patterns, you can use either of the following methods to impute missing values: a Markov chain Monte Carlo (MCMC) method (Schafer 1997) that assumes multivariate normality, or a fully conditional specification (FCS) method (van Buuren 2007; Brand 1999) that assumes the existence of a joint distribution for all variables.

For continuous variables in data sets with arbitrary missing patterns, you can use the MCMC method to impute either all the missing values or just enough missing values to make the imputed data sets have monotone missing patterns. With a monotone missing data pattern, you have greater flexibility in your choice of imputation models. In addition to the MCMC method, you can implement other methods, such as the regression method, that do not use Markov chains. You can also specify a different set of covariates for each imputed variable.

Although the regression and MCMC methods assume multivariate normality, inferences based on multiple imputation can be robust to departures from multivariate normality if the amount of missing information is not large, because the imputation model is effectively applied not to the entire data set but only to its missing part (Schafer 1997, pp.147–148).

To impute missing values for both continuous and classification variables in data sets with arbitrary missing patterns, you can use FCS methods to impute missing values for all variables assuming a joint distribution for these variables exists (Brand 1999; van Buuren 2007). Similar to the methods of imputing missing values for variables in data sets with monotone missing patterns, you can use the regression and predictive mean matching methods to impute missing values for a continuous variable, and use the logistic regression method to impute missing values for a classification variable when the variable has a binary or ordinal response, or use the discriminant function method when the variable has a binary or nominal response.

You can also use a TRANSFORM statement to transform variables to conform to the multivariate normality assumption. Variables are transformed before the imputation process and then are reverse-transformed to create the imputed data set. All continuous variables are standardized before the imputation process and then are transformed back to the original scale after the imputation process.

Li (1988) presents a theoretical argument for convergence of the MCMC method in the continuous case and uses it to create imputations for incomplete multivariate continuous data. In practice, however, it is not easy to check the convergence of a Markov chain, especially for a large number of parameters. PROC MI generates statistics and plots that you can use to check for convergence of the MCMC method. The details are described in the section [“Checking Convergence in MCMC”](#) on page 4764.

Monotone Methods for Data Sets with Monotone Missing Patterns

For data sets with monotone missing data patterns, you can use monotone methods to impute missing values for the variables. A monotone method creates multiple imputations by imputing missing values sequentially over the variables taken one at a time.

For example, with variables Y_1, Y_2, \dots, Y_p (in that order) in the VAR statement, a monotone method sequentially simulates a draw for missing values for variables Y_2, \dots, Y_p . That is, the missing values are imputed by using the sequence

$$\begin{aligned}
\theta_2^{(*)} &\sim P(\theta_2 | Y_{1(obs)}, Y_{2(obs)}) \\
Y_2^{(*)} &\sim P(Y_2 | \theta_2^{(*)}) \\
&\dots \\
&\dots \\
\theta_p^{(*)} &\sim P(\theta_p | Y_{1(obs)}, \dots, Y_{p(obs)}) \\
Y_p^{(*)} &\sim P(Y_p | \theta_p^{(*)})
\end{aligned}$$

where $Y_{j(obs)}$ is the set of observed Y_j values, $\theta_j^{(*)}$ is the set of simulated parameters for the conditional distribution of Y_j given covariates constructed from variables Y_1, Y_2, \dots, Y_{j-1} , and $Y_j^{(*)}$ is the set of imputed Y_j values.

The missing values for the leading variable Y_1 are not imputed, and missing values for Y_2, \dots, Y_p are not imputed for those observations with missing Y_1 values. For each subsequent variable Y_j with missing values, the corresponding imputation method is used to fit a model with covariates constructed from its preceding variables Y_1, Y_2, \dots, Y_{j-1} . The observed observations for Y_j , which include only observations with observed values for Y_1, Y_2, \dots, Y_{j-1} , are used in the model fitting. With this resulting model, a new model is drawn and then used to impute missing values for Y_j .

You can specify a separate monotone method for each imputed variable. If a method is not specified for the variable, then the default method is used. That is, a regression method is used for a continuous variable and a discriminant function method is used for a classification variable. For each imputed variable, you can also specify a set of covariates that are constructed from its preceding variables. If a set of covariates is not specified for the variable, all preceding variables in the VAR list are used as covariates.

You can use a regression method, a predictive mean matching method, or a propensity score method to impute missing values for a continuous variable; a logistic regression method for a classification variable with a binary or ordinal response; and a discriminant function method for a classification variable with a binary or nominal response. See the sections “[Monotone and FCS Regression Methods](#)” on page 4749, “[Monotone and FCS Predictive Mean Matching Methods](#)” on page 4750, “[Monotone Propensity Score Method](#)” on page 4751, “[Monotone and FCS Discriminant Function Methods](#)” on page 4752, and “[Monotone and FCS Logistic Regression Methods](#)” on page 4754 for these methods.

Monotone and FCS Regression Methods

The regression method is the default imputation method in the MONOTONE and FCS statements for continuous variables.

In the regression method, a regression model is fitted for a continuous variable with the covariates constructed from a set of effects. Based on the fitted regression model, a new regression model is simulated from the posterior predictive distribution of the parameters and is used to impute the missing values for each variable (Rubin 1987, pp. 166–167). That is, for a continuous variable Y_j with missing values, a model

$$Y_j = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_k X_k$$

is fitted using observations with observed values for the variable Y_j and its covariates X_1, X_2, \dots, X_k .

The fitted model includes the regression parameter estimates $\hat{\beta} = (\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_k)$ and the associated covariance matrix $\hat{\sigma}_j^2 \mathbf{V}_j$, where \mathbf{V}_j is the usual $\mathbf{X}'\mathbf{X}$ inverse matrix derived from the intercept and covariates X_1, X_2, \dots, X_k .

The following steps are used to generate imputed values for each imputation:

1. New parameters $\beta_* = (\beta_{*0}, \beta_{*1}, \dots, \beta_{*(k)})$ and σ_{*j}^2 are drawn from the posterior predictive distribution of the parameters. That is, they are simulated from $(\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_k)$, σ_j^2 , and \mathbf{V}_j . The variance is drawn as

$$\sigma_{*j}^2 = \hat{\sigma}_j^2 (n_j - k - 1) / g$$

where g is a $\chi_{n_j - k - 1}^2$ random variate and n_j is the number of nonmissing observations for Y_j . The regression coefficients are drawn as

$$\beta_* = \hat{\beta} + \sigma_{*j} \mathbf{V}_{hj}' \mathbf{Z}$$

where \mathbf{V}_{hj} is the upper triangular matrix in the Cholesky decomposition, $\mathbf{V}_j = \mathbf{V}_{hj}' \mathbf{V}_{hj}$, and \mathbf{Z} is a vector of $k + 1$ independent random normal variates.

2. The missing values are then replaced by

$$\beta_{*0} + \beta_{*1} x_1 + \beta_{*2} x_2 + \dots + \beta_{*(k)} x_k + z_i \sigma_{*j}$$

where x_1, x_2, \dots, x_k are the values of the covariates and z_i is a simulated normal deviate.

Monotone and FCS Predictive Mean Matching Methods

The predictive mean matching method is also an imputation method available for continuous variables. It is similar to the regression method except that for each missing value, it imputes a value randomly from a set of observed values whose predicted values are closest to the predicted value for the missing value from the simulated regression model (Heitjan and Little 1991; Schenker and Taylor 1996).

Following the description of the model in the section “[Monotone and FCS Regression Methods](#)” on page 4749, the following steps are used to generate imputed values:

1. New parameters $\beta_* = (\beta_{*0}, \beta_{*1}, \dots, \beta_{*(k)})$ and σ_{*j}^2 are drawn from the posterior predictive distribution of the parameters. That is, they are simulated from $(\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_k)$, σ_j^2 , and \mathbf{V}_j . The variance is drawn as

$$\sigma_{*j}^2 = \hat{\sigma}_j^2 (n_j - k - 1) / g$$

where g is a $\chi_{n_j - k - 1}^2$ random variate and n_j is the number of nonmissing observations for Y_j . The regression coefficients are drawn as

$$\beta_* = \hat{\beta} + \sigma_{*j} \mathbf{V}_{hj}' \mathbf{Z}$$

where \mathbf{V}_{hj} is the upper triangular matrix in the Cholesky decomposition, $\mathbf{V}_j = \mathbf{V}_{hj}' \mathbf{V}_{hj}$, and \mathbf{Z} is a vector of $k + 1$ independent random normal variates.

2. For each missing value, a predicted value

$$y_{i*} = \beta_{*0} + \beta_{*1} x_1 + \beta_{*2} x_2 + \dots + \beta_{*(k)} x_k$$

is computed with the covariate values x_1, x_2, \dots, x_k .

3. A set of k_0 observations whose corresponding predicted values are closest to y_{i*} is generated. You can specify k_0 with the K= option.
4. The missing value is then replaced by a value drawn randomly from these k_0 observed values.

The predictive mean matching method requires the number of closest observations to be specified. A smaller k_0 tends to increase the correlation among the multiple imputations for the missing observation and results in a higher variability of point estimators in repeated sampling. On the other hand, a larger k_0 tends to lessen the effect from the imputation model and results in biased estimators (Schenker and Taylor 1996, p. 430).

The predictive mean matching method ensures that imputed values are plausible; it might be more appropriate than the regression method if the normality assumption is violated (Horton and Lipsitz 2001, p. 246).

Monotone Propensity Score Method

The propensity score method is another imputation method available for continuous variables when the data set has a monotone missing pattern.

A propensity score is generally defined as the conditional probability of assignment to a particular treatment given a vector of observed covariates (Rosenbaum and Rubin 1983). In the propensity score method, for a variable with missing values, a propensity score is generated for each observation to estimate the probability that the observation is missing. The observations are then grouped based on these propensity scores, and an approximate Bayesian bootstrap imputation (Rubin 1987, p. 124) is applied to each group (Lavori, Dawson, and Shera 1995).

The propensity score method uses the following steps to impute values for variable Y_j with missing values:

1. Creates an indicator variable R_j with the value 0 for observations with missing Y_j and 1 otherwise.
2. Fits a logistic regression model

$$\text{logit}(p_j) = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_k X_k$$

where X_1, X_2, \dots, X_k are covariates for Y_j , $p_j = \Pr(R_j = 0 | X_1, X_2, \dots, X_k)$, and $\text{logit}(p) = \log(p/(1-p))$.

3. Creates a propensity score for each observation to estimate the probability that it is missing.
4. Divides the observations into a fixed number of groups (typically assumed to be five) based on these propensity scores.
5. Applies an approximate Bayesian bootstrap imputation to each group. In group k , suppose that Y_{obs} denotes the n_1 observations with nonmissing Y_j values and Y_{mis} denotes the n_0 observations with missing Y_j . The approximate Bayesian bootstrap imputation first draws n_1 observations randomly with replacement from Y_{obs} to create a new data set Y_{obs}^* . This is a nonparametric analog of drawing parameters from the posterior predictive distribution of the parameters. The process then draws the n_0 values for Y_{mis} randomly with replacement from Y_{obs}^* .

Steps 1 through 5 are repeated sequentially for each variable with missing values.

The propensity score method was originally designed for a randomized experiment with repeated measures on the response variables. The goal was to impute the missing values on the response variables. The method uses only the covariate information that is associated with whether the imputed variable values are missing; it does not use correlations among variables. It is effective for inferences about the distributions of individual imputed variables, such as a univariate analysis, but it is not appropriate for analyses that involve relationship among variables, such as a regression analysis (Schafer 1999, p. 11). It can also produce badly biased estimates of regression coefficients when data on predictor variables are missing (Allison 2000).

Monotone and FCS Discriminant Function Methods

The discriminant function method is the default imputation method in the MONOTONE and FCS statements for classification variables.

For a nominal classification variable Y_j with responses $1, \dots, g$ and a set of effects from its preceding variables, if the covariates X_1, X_2, \dots, X_k associated with these effects within each group are approximately multivariate normal and the within-group covariance matrices are approximately equal, the discriminant function method (Brand 1999, pp. 95–96) can be used to impute missing values for the variable Y_j .

Denote the group-specific means for covariates X_1, X_2, \dots, X_k by

$$\bar{\mathbf{X}}_t = (\bar{X}_{t1}, \bar{X}_{t2}, \dots, \bar{X}_{tk}), t = 1, 2, \dots, g$$

then the pooled covariance matrix is computed as

$$\mathbf{S} = \frac{1}{n - g} \sum_{t=1}^g (n_t - 1) \mathbf{S}_t$$

where \mathbf{S}_t is the within-group covariance matrix, n_t is the group-specific sample size, and $n = \sum_{t=1}^g n_t$ is the total sample size.

In each imputation, new parameters of the group-specific means (\mathbf{m}_{*t}), pooled covariance matrix (\mathbf{S}_*), and prior probabilities of group membership (q_{*t}) can be drawn from their corresponding posterior distributions (Schafer 1997, p. 356).

Pooled Covariance Matrix and Group-Specific Means

For each imputation, the MI procedure uses either the fixed observed pooled covariance matrix (PCOV=FIXED) or a drawn pooled covariance matrix (PCOV=POSTERIOR) from its posterior distribution with a noninformative prior. That is,

$$\Sigma | \mathbf{X} \sim W^{-1}(n - g, (n - g)\mathbf{S})$$

where W^{-1} is an inverted Wishart distribution.

The group-specific means are then drawn from their posterior distributions with a noninformative prior

$$\mu_t | (\Sigma, \bar{\mathbf{X}}_t) \sim N\left(\bar{\mathbf{X}}_t, \frac{1}{n_t} \Sigma\right)$$

See the section “Bayesian Estimation of the Mean Vector and Covariance Matrix” on page 4759 for a complete description of the inverted Wishart distribution and posterior distributions that use a noninformative prior.

Prior Probabilities of Group Membership

The prior probabilities are computed through the drawing of new group sample sizes. When the total sample size n is considered fixed, the group sample sizes (n_1, n_2, \dots, n_g) have a multinomial distribution. New multinomial parameters (group sample sizes) can be drawn from their posterior distribution by using a Dirichlet prior with parameters $(\alpha_1, \alpha_2, \dots, \alpha_g)$.

After the new sample sizes are drawn from the posterior distribution of (n_1, n_2, \dots, n_g) , the prior probabilities q_{*t} are computed proportionally to the drawn sample sizes.

See Schafer (1997, pp. 247–255) for a complete description of the Dirichlet prior.

Imputation Steps

The discriminant function method uses the following steps in each imputation to impute values for a nominal classification variable Y_j with g responses:

1. Draw a pooled covariance matrix S_* from its posterior distribution if the PCOV=POSTERIOR option is used.
2. For each group, draw group means \mathbf{m}_{*t} from the observed group mean $\bar{\mathbf{X}}_t$ and either the observed pooled covariance matrix (PCOV=FIXED) or the drawn pooled covariance matrix S_* (PCOV=POSTERIOR).
3. For each group, compute or draw q_{*t} , prior probabilities of group membership, based on the PRIOR=option:
 - PRIOR=EQUAL, $q_{*t} = 1/g$, prior probabilities of group membership are all equal.
 - PRIOR=PROPORTIONAL, $q_{*t} = n_t/n$, prior probabilities are proportional to their group sample sizes.
 - PRIOR=JEFFREYS= c , a noninformative Dirichlet prior with $\alpha_t = c$ is used.
 - PRIOR=RIDGE= d , a ridge prior is used with $\alpha_t = d * n_t/n$ for $d \geq 1$ and $\alpha_t = d * n_t$ for $d < 1$.
4. With the group means \mathbf{m}_{*t} , the pooled covariance matrix S_* , and the prior probabilities of group membership q_{*t} , the discriminant function method derives linear discriminant function and computes the posterior probabilities of an observation belonging to each group

$$p_t(\mathbf{x}) = \frac{\exp(-0.5D_t^2(\mathbf{x}))}{\sum_{u=1}^g \exp(-0.5D_u^2(\mathbf{x}))}$$

where $D_t^2(\mathbf{x}) = (\mathbf{x} - \mathbf{m}_{*t})'S_*^{-1}(\mathbf{x} - \mathbf{m}_{*t}) - 2\log(q_{*t})$ is the generalized squared distance from \mathbf{x} to group t .

5. Draw a random uniform variate u , between 0 and 1, for each observation with missing group value. With the posterior probabilities, $p_1(\mathbf{x}) + p_2(\mathbf{x}) + \dots + p_g(\mathbf{x}) = 1$, the discriminant function method imputes $Y_j = 1$ if the value of u is less than $p_1(\mathbf{x})$, $Y_j = 2$ if the value is greater than or equal to $p_1(\mathbf{x})$ but less than $p_1(\mathbf{x}) + p_2(\mathbf{x})$, and so on.

Monotone and FCS Logistic Regression Methods

The logistic regression method is another imputation method available for classification variables. In the logistic regression method, a logistic regression model is fitted for a classification variable with a set of covariates constructed from the effects. For a binary classification variable, based on the fitted regression model, a new logistic regression model is simulated from the posterior predictive distribution of the parameters and is used to impute the missing values for each variable (Rubin 1987, pp. 167–170).

For a binary variable Y_j with responses 1 and 2, a logistic regression model is fitted using observations with observed values for the imputed variable Y_j and its covariates X_1, X_2, \dots, X_k :

$$\text{logit}(p_j) = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_k X_k$$

where X_1, X_2, \dots, X_k are covariates for Y_j , $p_j = \Pr(R_j = 1 | X_1, X_2, \dots, X_k)$, and $\text{logit}(p) = \log(p/(1-p))$.

The fitted model includes the regression parameter estimates $\hat{\beta} = (\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_k)$ and the associated covariance matrix \mathbf{V}_j .

The following steps are used to generate imputed values for a binary variable Y_j with responses 1 and 2:

1. New parameters $\beta_* = (\beta_{*0}, \beta_{*1}, \dots, \beta_{*(k)})$ are drawn from the posterior predictive distribution of the parameters.

$$\beta_* = \hat{\beta} + \mathbf{V}_{hj}' \mathbf{Z}$$

where \mathbf{V}_{hj} is the upper triangular matrix in the Cholesky decomposition, $\mathbf{V}_j = \mathbf{V}_{hj}' \mathbf{V}_{hj}$, and \mathbf{Z} is a vector of $k+1$ independent random normal variates.

2. For an observation with missing Y_j and covariates x_1, x_2, \dots, x_k , compute the expected probability that $Y_j = 1$:

$$p_j = \frac{\exp(\mu_j)}{1 + \exp(\mu_j)}$$

where $\mu_j = \beta_{*0} + \beta_{*1} x_1 + \beta_{*2} x_2 + \dots + \beta_{*(k)} x_k$.

3. Draw a random uniform variate, u , between 0 and 1. If the value of u is less than p_j , impute $Y_j = 1$; otherwise impute $Y_j = 2$.

The preceding logistic regression method can be extended to include the ordinal classification variables with more than two levels of responses. The options ORDER= and DESCENDING can be used to specify the sort order for the levels of the imputed variables.

FCS Methods for Data Sets with Arbitrary Missing Patterns

For a data set with an arbitrary missing data pattern, you can use FCS methods to impute missing values for all variables, assuming the existence of a joint distribution for these variables (Brand 1999; van Buuren 2007). FCS method involves two phases in each imputation: the preliminary filled-in phase followed by the imputation phase.

At the filled-in phase, the missing values for all variables are filled in sequentially over the variables taken one at a time. The missing values for each variable are filled in using the specified method, or the default method for the variable if a method is not specified, with preceding variables serving as the covariates. These filled-in values provide starting values for these missing values at the imputation phase.

At the imputation phase, the missing values for each variable are imputed using the specified method and covariates at each iteration. The default method for the variable is used if a method is not specified, and the remaining variables are used as covariates if the set of covariates is not specified. After a number of iterations, as specified with the NBITER= option, the imputed values in each variable are used for the imputation. At each iteration, the missing values are imputed sequentially over the variables taken one at a time.

The MI procedure orders the variables as they are ordered in the VAR statement. For example, if the order of the p variables in the VAR statement is Y_1, Y_2, \dots, Y_p , then Y_1, Y_2, \dots, Y_p (in that order) are used in the filled-in and imputation phases.

The filled-in phase replaces missing values with filled-in values for each variable. That is, with p variables Y_1, Y_2, \dots, Y_p (in that order), the missing values are filled in by using the sequence,

$$\begin{aligned}
 \theta_1^{(0)} &\sim P(\theta_1 | Y_{1(obs)}) \\
 Y_{1(*)}^{(0)} &\sim P(Y_1 | \theta_1^{(0)}) \\
 Y_1^{(0)} &= (Y_{1(obs)}, Y_{1(*)}^{(0)}) \\
 &\dots \\
 &\dots \\
 \theta_p^{(0)} &\sim P(\theta_p | Y_1^{(0)}, \dots, Y_{p-1}^{(0)}, Y_{p(obs)}) \\
 Y_{p(*)}^{(0)} &\sim P(Y_p | \theta_p^{(0)}) \\
 Y_p^{(0)} &= (Y_{p(obs)}, Y_{p(*)}^{(0)})
 \end{aligned}$$

where $Y_{j(obs)}$ is the set of observed Y_j values, $Y_{j(*)}^{(0)}$ is the set of filled-in Y_j values, $Y_j^{(0)}$ is the set of both observed and filled-in Y_j values, and $\theta_j^{(0)}$ is the set of simulated parameters for the conditional distribution of Y_j given variables Y_1, Y_2, \dots, Y_{j-1} .

For each variable Y_j with missing values, the corresponding imputation method is used to fit the model with covariates Y_1, Y_2, \dots, Y_{j-1} . The observed observations for Y_j , which might include observations with filled-in values for Y_1, Y_2, \dots, Y_{j-1} , are used in the model fitting. With this resulting model, a new model is drawn and then used to impute missing values for Y_j .

The imputation phase replaces these filled-in values $Y_{j(*)}^{(0)}$ with imputed values for each variable sequentially at each iteration. That is, with p variables Y_1, Y_2, \dots, Y_p (in that order), the missing values are imputed with the sequence at iteration $t + 1$,

$$\begin{aligned}\theta_1^{(t+1)} &\sim P(\theta_1 | Y_{1(obs)}, Y_2^{(t)}, \dots, Y_p^{(t)}) \\ Y_{1(*)}^{(t+1)} &\sim P(Y_1 | \theta_1^{(t+1)}) \\ Y_1^{(t+1)} &= (Y_{1(obs)}, Y_{1(*)}^{(t+1)}) \\ &\dots \\ &\dots \\ \theta_p^{(t+1)} &\sim P(\theta_p | Y_1^{(t+1)}, \dots, Y_{p-1}^{(t+1)}, Y_{p(obs)}) \\ Y_{p(*)}^{(t+1)} &\sim P(Y_p | \theta_p^{(t+1)}) \\ Y_p^{(t+1)} &= (Y_{p(obs)}, Y_{p(*)}^{(t+1)})\end{aligned}$$

where $Y_{j(obs)}$ is the set of observed Y_j values, $Y_{j(*)}^{(t+1)}$ is the set of imputed Y_j values at iteration $t + 1$, $Y_{j(*)}^{(t)}$ is the set of filled-in Y_j values ($t = 0$) or the set of imputed Y_j values at iteration t ($t > 0$), $Y_j^{(t+1)}$ is the set of both observed and imputed Y_j values at iteration $t + 1$, and $\theta_j^{(t+1)}$ is the set of simulated parameters for the conditional distribution of Y_j given covariates constructed from $Y_1, \dots, Y_{j-1}, Y_{j+1}, \dots, Y_p$.

At each iteration, a specified model is fitted for each variable with missing values by using observed observations for that variable, which might include observations with imputed values for other variables. With this resulting model, a new model is drawn and then used to impute missing values for the imputed variable.

The steps are iterated long enough for the results to reliably simulate an approximately independent draw of the missing values for an imputed data set.

The imputation methods used in the filled-in and imputation phases are similar to the corresponding monotone methods for monotone missing data. You can use a regression method or a predictive mean matching method to impute missing values for a continuous variable, a logistic regression method for a classification variable with a binary or ordinal response, and a discriminant function method for a classification variable with a binary or nominal response. See the sections “[Monotone and FCS Regression Methods](#)” on page 4749, “[Monotone and FCS Predictive Mean Matching Methods](#)” on page 4750, “[Monotone and FCS Discriminant Function Methods](#)” on page 4752, and “[Monotone and FCS Logistic Regression Methods](#)” on page 4754 for these methods.

The FCS method requires fewer iterations than the MCMC method (van Buuren 2007). Often, as few as five or 10 iterations are enough to produce satisfactory results (van Buuren 2007; Brand 1999).

Checking Convergence in FCS Methods

The parameters used in the imputation step at each iteration can be saved in an output data set with the `OUTITER=` option. These include the means and standard deviations. You can then monitor the convergence by displaying trace plots for those parameter values with the `PLOTS=TRACE` option.

A trace plot for a parameter ξ is a scatter plot of successive parameter estimates ξ_i against the iteration number i . The plot provides a simple way to examine the convergence behavior of the estimation algorithm

for ξ . Long-term trends in the plot indicate that successive iterations are highly correlated and that the series of iterations has not converged.

You can display trace plots for the variable means and standard deviations. You can also request logarithmic transformations for positive parameters in the plots with the LOG option. With the LOG option, if a parameter value is less than or equal to zero, then the value is not displayed in the corresponding plot.

See [Example 57.8](#) for a usage of the trace plot.

MCMC Method for Arbitrary Missing Multivariate Normal Data

The Markov chain Monte Carlo (MCMC) method originated in physics as a tool for exploring equilibrium distributions of interacting molecules. In statistical applications, it is used to generate pseudorandom draws from multidimensional and otherwise intractable probability distributions via Markov chains. A Markov chain is a sequence of random variables in which the distribution of each element depends only on the value of the previous element.

In MCMC simulation, you construct a Markov chain long enough for the distribution of the elements to stabilize to a stationary distribution, which is the distribution of interest. Repeatedly simulating steps of the chain simulates draws from the distribution of interest. See Schafer (1997) for a detailed discussion of this method.

In Bayesian inference, information about unknown parameters is expressed in the form of a posterior probability distribution. This posterior distribution is computed using Bayes' theorem,

$$p(\theta|y) = \frac{p(y|\theta)p(\theta)}{\int p(y|\theta)p(\theta)d\theta}$$

MCMC has been applied as a method for exploring posterior distributions in Bayesian inference. That is, through MCMC, you can simulate the entire joint posterior distribution of the unknown quantities and obtain simulation-based estimates of posterior parameters that are of interest.

In many incomplete-data problems, the observed-data posterior $p(\theta|Y_{obs})$ is intractable and cannot easily be simulated. However, when Y_{obs} is augmented by an estimated or simulated value of the missing data Y_{mis} , the complete-data posterior $p(\theta|Y_{obs}, Y_{mis})$ is much easier to simulate. Assuming that the data are from a multivariate normal distribution, data augmentation can be applied to Bayesian inference with missing data by repeating the following steps:

1. The imputation I-step

Given an estimated mean vector and covariance matrix, the I-step simulates the missing values for each observation independently. That is, if you denote the variables with missing values for observation i by $Y_{i(mis)}$ and the variables with observed values by $Y_{i(obs)}$, then the I-step draws values for $Y_{i(mis)}$ from a conditional distribution for $Y_{i(mis)}$ given $Y_{i(obs)}$.

2. The posterior P-step

Given a complete sample, the P-step simulates the posterior population mean vector and covariance matrix. These new estimates are then used in the next I-step. Without prior information about the parameters, a noninformative prior is used. You can also use other informative priors. For example, a prior information about the covariance matrix can help to stabilize the inference about the mean vector for a near singular covariance matrix.

That is, with a current parameter estimate $\theta^{(t)}$ at the t th iteration, the I-step draws $Y_{mis}^{(t+1)}$ from $p(Y_{mis}|Y_{obs}, \theta^{(t)})$ and the P-step draws $\theta^{(t+1)}$ from $p(\theta|Y_{obs}, Y_{mis}^{(t+1)})$. The two steps are iterated long enough for the results to reliably simulate an approximately independent draw of the missing values for a multiply imputed data set (Schafer 1997).

This creates a Markov chain $(Y_{mis}^{(1)}, \theta^{(1)})$, $(Y_{mis}^{(2)}, \theta^{(2)})$, ..., which converges in distribution to $p(Y_{mis}, \theta|Y_{obs})$. Assuming the iterates converge to a stationary distribution, the goal is to simulate an approximately independent draw of the missing values from this distribution.

To validate the imputation results, you should repeat the process with different random number generators and starting values based on different initial parameter estimates.

The next three sections provide details for the imputation step, Bayesian estimation of the mean vector and covariance matrix, and the posterior step.

Imputation Step

In each iteration, starting with a given mean vector μ and covariance matrix Σ , the imputation step draws values for the missing data from the conditional distribution Y_{mis} given Y_{obs} .

Suppose $\mu = [\mu'_1, \mu'_2]'$ is the partitioned mean vector of two sets of variables, Y_{obs} and Y_{mis} , where μ_1 is the mean vector for variables Y_{obs} and μ_2 is the mean vector for variables Y_{mis} .

Also suppose

$$\Sigma = \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma'_{12} & \Sigma_{22} \end{bmatrix}$$

is the partitioned covariance matrix for these variables, where Σ_{11} is the covariance matrix for variables Y_{obs} , Σ_{22} is the covariance matrix for variables Y_{mis} , and Σ_{12} is the covariance matrix between variables Y_{obs} and variables Y_{mis} .

By using the sweep operator (Goodnight 1979) on the pivots of the Σ_{11} submatrix, the matrix becomes

$$\begin{bmatrix} \Sigma_{11}^{-1} & \Sigma_{11}^{-1}\Sigma_{12} \\ -\Sigma'_{12}\Sigma_{11}^{-1} & \Sigma_{22.1} \end{bmatrix}$$

where $\Sigma_{22.1} = \Sigma_{22} - \Sigma'_{12}\Sigma_{11}^{-1}\Sigma_{12}$ can be used to compute the conditional covariance matrix of Y_{mis} after controlling for Y_{obs} .

For an observation with the preceding missing pattern, the conditional distribution of Y_{mis} given $Y_{obs} = \mathbf{y}_1$ is a multivariate normal distribution with the mean vector

$$\mu_{2.1} = \mu_2 + \Sigma'_{12}\Sigma_{11}^{-1}(\mathbf{y}_1 - \mu_1)$$

and the conditional covariance matrix

$$\Sigma_{22.1} = \Sigma_{22} - \Sigma'_{12}\Sigma_{11}^{-1}\Sigma_{12}$$

Bayesian Estimation of the Mean Vector and Covariance Matrix

Suppose that $\mathbf{Y} = (\mathbf{y}'_1, \mathbf{y}'_2, \dots, \mathbf{y}'_n)'$ is an $(n \times p)$ matrix made up of n ($p \times 1$) independent vectors \mathbf{y}_i , each of which has a multivariate normal distribution with mean zero and covariance matrix $\mathbf{\Lambda}$. Then the SSCP matrix

$$\mathbf{A} = \mathbf{Y}'\mathbf{Y} = \sum_i \mathbf{y}_i \mathbf{y}'_i$$

has a Wishart distribution $W(n, \mathbf{\Lambda})$.

When each observation \mathbf{y}_i is distributed with a multivariate normal distribution with an unknown mean $\boldsymbol{\mu}$, then the CSSCP matrix

$$\mathbf{A} = \sum_i (\mathbf{y}_i - \bar{\mathbf{y}})(\mathbf{y}_i - \bar{\mathbf{y}})'$$

has a Wishart distribution $W(n - 1, \mathbf{\Lambda})$.

If \mathbf{A} has a Wishart distribution $W(n, \mathbf{\Lambda})$, then $\mathbf{B} = \mathbf{A}^{-1}$ has an inverted Wishart distribution $W^{-1}(n, \boldsymbol{\Psi})$, where n is the degrees of freedom and $\boldsymbol{\Psi} = \mathbf{\Lambda}^{-1}$ is the precision matrix (Anderson 1984).

Note that, instead of using the parameter $\boldsymbol{\Psi} = \mathbf{\Lambda}^{-1}$ for the inverted Wishart distribution, Schafer (1997) uses the parameter $\mathbf{\Lambda}$.

Suppose that each observation in the data matrix \mathbf{Y} has a multivariate normal distribution with mean $\boldsymbol{\mu}$ and covariance matrix $\boldsymbol{\Sigma}$. Then with a prior inverted Wishart distribution for $\boldsymbol{\Sigma}$ and a prior normal distribution for $\boldsymbol{\mu}$

$$\begin{aligned} \boldsymbol{\Sigma} &\sim W^{-1}(m, \boldsymbol{\Psi}) \\ \boldsymbol{\mu} | \boldsymbol{\Sigma} &\sim N\left(\boldsymbol{\mu}_0, \frac{1}{\tau} \boldsymbol{\Sigma}\right) \end{aligned}$$

where $\tau > 0$ is a fixed number.

The posterior distribution (Anderson 1984, p. 270; Schafer 1997, p. 152) is

$$\begin{aligned} \boldsymbol{\Sigma} | \mathbf{Y} &\sim W^{-1}\left(n + m, (n - 1)\mathbf{S} + \boldsymbol{\Psi} + \frac{n\tau}{n + \tau}(\bar{\mathbf{y}} - \boldsymbol{\mu}_0)(\bar{\mathbf{y}} - \boldsymbol{\mu}_0)'\right) \\ \boldsymbol{\mu} | (\boldsymbol{\Sigma}, \mathbf{Y}) &\sim N\left(\frac{1}{n + \tau}(n\bar{\mathbf{y}} + \tau\boldsymbol{\mu}_0), \frac{1}{n + \tau}\boldsymbol{\Sigma}\right) \end{aligned}$$

where $(n - 1)\mathbf{S}$ is the CSSCP matrix.

Posterior Step

In each iteration, the posterior step simulates the posterior population mean vector $\boldsymbol{\mu}$ and covariance matrix $\boldsymbol{\Sigma}$ from prior information for $\boldsymbol{\mu}$ and $\boldsymbol{\Sigma}$, and the complete sample estimates.

You can specify the prior parameter information by using one of the following methods:

- PRIOR=JEFFREYS, which uses a noninformative prior
- PRIOR=INPUT=, which provides a prior information for $\boldsymbol{\Sigma}$ in the data set. Optionally, it also provides a prior information for $\boldsymbol{\mu}$ in the data set.
- PRIOR=RIDGE=, which uses a ridge prior

The next four subsections provide details of the posterior step for different prior distributions.

1. A Noninformative Prior

Without prior information about the mean and covariance estimates, you can use a noninformative prior by specifying the PRIOR=JEFFREYS option. The posterior distributions (Schafer 1997, p. 154) are

$$\begin{aligned}\Sigma^{(t+1)}|\mathbf{Y} &\sim W^{-1}(n-1, (n-1)\mathbf{S}) \\ \mu^{(t+1)}|(\Sigma^{(t+1)}, \mathbf{Y}) &\sim N\left(\bar{\mathbf{y}}, \frac{1}{n}\Sigma^{(t+1)}\right)\end{aligned}$$

2. An Informative Prior for μ and Σ

When prior information is available for the parameters μ and Σ , you can provide it with a SAS data set that you specify with the PRIOR=INPUT= option:

$$\begin{aligned}\Sigma &\sim W^{-1}(d^*, d^*\mathbf{S}^*) \\ \mu|\Sigma &\sim N\left(\mu_0, \frac{1}{n_0}\Sigma\right)\end{aligned}$$

To obtain the prior distribution for Σ , PROC MI reads the matrix \mathbf{S}^* from observations in the data set with _TYPE_='COV', and it reads $n^* = d^* + 1$ from observations with _TYPE_='N'.

To obtain the prior distribution for μ , PROC MI reads the mean vector μ_0 from observations with _TYPE_='MEAN', and it reads n_0 from observations with _TYPE_='N_MEAN'. When there are no observations with _TYPE_='N_MEAN', PROC MI reads n_0 from observations with _TYPE_='N'.

The resulting posterior distribution, as described in the section “[Bayesian Estimation of the Mean Vector and Covariance Matrix](#)” on page 4759, is given by

$$\begin{aligned}\Sigma^{(t+1)}|\mathbf{Y} &\sim W^{-1}(n+d^*, (n-1)\mathbf{S} + d^*\mathbf{S}^* + \mathbf{S}_m) \\ \mu^{(t+1)}|(\Sigma^{(t+1)}, \mathbf{Y}) &\sim N\left(\frac{1}{n+n_0}(n\bar{\mathbf{y}} + n_0\mu_0), \frac{1}{n+n_0}\Sigma^{(t+1)}\right)\end{aligned}$$

where

$$\mathbf{S}_m = \frac{nn_0}{n+n_0}(\bar{\mathbf{y}} - \mu_0)(\bar{\mathbf{y}} - \mu_0)'$$

3. An Informative Prior for Σ

When the sample covariance matrix \mathbf{S} is singular or near singular, prior information about Σ can also be used without prior information about μ to stabilize the inference about μ . You can provide it with a SAS data set that you specify with the PRIOR=INPUT= option.

To obtain the prior distribution for Σ , PROC MI reads the matrix \mathbf{S}^* from observations in the data set with _TYPE_='COV', and it reads n^* from observations with _TYPE_='N'.

The resulting posterior distribution for (μ, Σ) (Schafer 1997, p. 156) is

$$\begin{aligned}\Sigma^{(t+1)}|\mathbf{Y} &\sim W^{-1}(n+d^*, (n-1)\mathbf{S} + d^*\mathbf{S}^*) \\ \mu^{(t+1)}|(\Sigma^{(t+1)}, \mathbf{Y}) &\sim N\left(\bar{\mathbf{y}}, \frac{1}{n}\Sigma^{(t+1)}\right)\end{aligned}$$

Note that if the PRIOR=INPUT= data set also contains observations with _TYPE_='MEAN', then a complete informative prior for both μ and Σ will be used.

4. A Ridge Prior

A special case of the preceding adjustment is a ridge prior with $S^* = \text{Diag}(S)$ (Schafer 1997, p. 156). That is, S^* is a diagonal matrix with diagonal elements equal to the corresponding elements in S .

You can request a ridge prior by using the PRIOR=RIDGE= option. You can explicitly specify the number $d^* \geq 1$ in the PRIOR=RIDGE= d^* option. Or you can implicitly specify the number by specifying the proportion p in the PRIOR=RIDGE= p option to request $d^* = (n - 1)p$.

The posterior is then given by

$$\begin{aligned} \Sigma^{(t+1)} | Y &\sim W^{-1} (n + d^*, (n - 1)S + d^* \text{Diag}(S)) \\ \mu^{(t+1)} | (\Sigma^{(t+1)}, Y) &\sim N \left(\bar{y}, \frac{1}{n} \Sigma^{(t+1)} \right) \end{aligned}$$

Producing Monotone Missingness with the MCMC Method

The monotone data MCMC method was first proposed by Li (1988) and Liu (1993) described the algorithm. The method is useful especially when a data set is close to having a monotone missing pattern. In this case, the method needs to impute only a few missing values to the data set to have a monotone missing pattern in the imputed data set. Compared to a full data imputation that imputes all missing values, the monotone data MCMC method imputes fewer missing values in each iteration and achieves approximate stationarity in fewer iterations (Schafer 1997, p. 227).

You can request the monotone MCMC method by specifying the option IMPUTE=MONOTONE in the MCMC statement. The “Missing Data Patterns” table now denotes the variables with missing values by “.” or “O”. The value “.” means that the variable is missing and will be imputed, and the value “O” means that the variable is missing and will not be imputed. The “Variance Information” and “Parameter Estimates” tables are not created.

You must specify the variables in the VAR statement. The variable order in the list determines the monotone missing pattern in the imputed data set. With a different order in the VAR list, the results will be different because the monotone missing pattern to be constructed will be different.

Assuming that the data are from a multivariate normal distribution, then like the MCMC method, the monotone MCMC method repeats the following steps:

1. The imputation I-step

Given an estimated mean vector and covariance matrix, the I-step simulates the missing values for each observation independently. Only a subset of missing values are simulated to achieve a monotone pattern of missingness.

2. The posterior P-step

Given a new sample with a monotone pattern of missingness, the P-step simulates the posterior population mean vector and covariance matrix with a noninformative Jeffreys prior. These new estimates are then used in the next I-step.

Imputation Step

The I-step is almost identical to the I-step described in the section “MCMC Method for Arbitrary Missing Multivariate Normal Data” on page 4757 except that only a subset of missing values need to be simulated. To state this precisely, denote the variables with observed values for observation i by $Y_{i(obs)}$ and the variables with missing values by $Y_{i(mis)} = (Y_{i(m1)}, Y_{i(m2)})$, where $Y_{i(m1)}$ is a subset of the missing variables that will cause a monotone missingness when their values are imputed. Then the I-step draws values for $Y_{i(m1)}$ from a conditional distribution for $Y_{i(m1)}$ given $Y_{i(obs)}$.

Posterior Step

The P-step is different from the P-step described in the section “MCMC Method for Arbitrary Missing Multivariate Normal Data” on page 4757. Instead of simulating the μ and Σ parameters from the full imputed data set, this P-step simulates the μ and Σ parameters through simulated regression coefficients from regression models based on the imputed data set with a monotone pattern of missingness. The step is similar to the process described in the section “Monotone and FCS Regression Methods” on page 4749.

That is, for the variable Y_j , a model

$$Y_j = \beta_0 + \beta_1 Y_1 + \beta_2 Y_2 + \dots + \beta_{j-1} Y_{j-1}$$

is fitted using n_j nonmissing observations for variable Y_j in the imputed data sets.

The fitted model consists of the regression parameter estimates $\hat{\beta} = (\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_{j-1})$ and the associated covariance matrix $\hat{\sigma}_j^2 \mathbf{V}_j$, where \mathbf{V}_j is the usual $\mathbf{X}'\mathbf{X}$ inverse matrix from the intercept and variables Y_1, Y_2, \dots, Y_{j-1} .

For each imputation, new parameters $\beta_* = (\beta_{*0}, \beta_{*1}, \dots, \beta_{*(j-1)})$ and σ_{*j}^2 are drawn from the posterior predictive distribution of the parameters. That is, they are simulated from $(\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_{j-1})$, σ_j^2 , and \mathbf{V}_j . The variance is drawn as

$$\sigma_{*j}^2 = \hat{\sigma}_j^2(n_j - j)/g$$

where g is a $\chi_{n_j - p + j - 1}^2$ random variate and n_j is the number of nonmissing observations for Y_j . The regression coefficients are drawn as

$$\beta_* = \hat{\beta} + \sigma_{*j} \mathbf{V}_{hj}' \mathbf{Z}$$

where \mathbf{V}_{hj} is the upper triangular matrix in the Cholesky decomposition, $\mathbf{V}_j = \mathbf{V}_{hj}' \mathbf{V}_{hj}$, and \mathbf{Z} is a vector of j independent random normal variates.

These simulated values of β_* and σ_{*j}^2 are then used to re-create the parameters μ and Σ . For a detailed description of how to produce monotone missingness with the MCMC method for a multivariate normal data, see Schafer (1997, pp. 226–235).

MCMC Method Specifications

With the MCMC method, you can impute either all missing values (IMPUTE=FULL) or just enough missing values to make the imputed data set have a monotone missing pattern (IMPUTE=MONOTONE). In the process, either a single chain for all imputations (CHAIN=SINGLE) or a separate chain for each imputation

(CHAIN=MULTIPLE) is used. The single chain might be somewhat more precise for estimating a single quantity such as a posterior mean (Schafer 1997, p. 138). See Schafer (1997, pp. 137–138) for a discussion of single versus multiple chains.

You can specify the number of initial burn-in iterations before the first imputation with the NBITER= option. This number is also used for subsequent chains for multiple chains. For a single chain, you can also specify the number of iterations between imputations with the NITER= option.

You can explicitly specify initial parameter values for the MCMC method with the INITIAL=INPUT= data set option. Alternatively, you can use the EM algorithm to derive a set of initial parameter values for MCMC with the option INITIAL=EM. These estimates are used as either the starting value (START=VALUE) or the starting distribution (START=DIST) for the MCMC method. For multiple chains, these estimates are used again as either the starting value (START=VALUE) or the starting distribution (START=DIST) for the subsequent chains.

You can specify the prior parameter information in the PRIOR= option. You can use a noninformative prior (PRIOR=JEFFREYS), a ridge prior (PRIOR=RIDGE), or an informative prior specified in a data set (PRIOR=INPUT).

The parameter estimates used to generate imputed values in each imputation can be saved in a data set with the OUTEST= option. Later, this data set can be read with the INEST= option to provide the reference distribution for imputing missing values for a new data set.

By default, the MCMC method uses a single chain to produce five imputations. It completes 200 burn-in iterations before the first imputation and 100 iterations between imputations. The posterior mode computed from the EM algorithm with a noninformative prior is used as the starting values for the MCMC method.

INITIAL=EM Specifications

The EM algorithm is used to find the maximum likelihood estimates for incomplete data in the EM statement. You can also use the EM algorithm to find a posterior mode, the parameter estimates that maximize the observed-data posterior density. The resulting posterior mode provides a good starting value for the MCMC method.

With the INITIAL=EM option, PROC MI uses the MLE of the parameter vector as the initial estimates in the EM algorithm for the posterior mode. You can use the ITPRINT option within the INITIAL=EM option to display the iteration history for the EM algorithm.

You can use the CONVERGE= option to specify the convergence criterion in deriving the EM posterior mode. The iterations are considered to have converged when the maximum change in the parameter estimates between iteration steps is less than the value specified. By default, CONVERGE=1E-4.

You can also use the MAXITER= option to specify the maximum number of iterations of the EM algorithm. By default, MAXITER=200.

With the BOOTSTRAP option, you can use overdispersed starting values for the MCMC method. In this case, PROC MI applies the EM algorithm to a bootstrap sample, a simple random sample with replacement from the input data set, to derive the initial estimates for each chain (Schafer 1997, p. 128).

Checking Convergence in MCMC

The theoretical convergence of the MCMC method has been explored under various conditions, as described in Schafer (1997, p. 70). However, in practice, verification of convergence is not a simple matter.

The parameters used in the imputation step for each iteration can be saved in an output data set with the OUTITER= option. These include the means, standard deviations, covariances, worst linear function, and observed-data LR statistics. You can then monitor the convergence in a single chain by displaying trace plots and autocorrelations for those parameter values (Schafer 1997, p. 120). The trace and autocorrelation function plots for parameters such as variable means, covariances, and the worst linear function can be displayed by specifying the TIMEPLOT and ACFPLOT options, respectively.

You can apply the EM algorithm to a bootstrap sample to obtain overdispersed starting values for multiple chains (Gelman and Rubin 1992). This provides a conservative estimate of the number of iterations needed before each imputation.

The next four subsections describe useful statistics and plots that can be used to check the convergence of the MCMC method.

LR Statistics

You can save the observed-data likelihood ratio (LR) statistic in each iteration with the LR option in the OUTITER= data set. The statistic is based on the observed-data likelihood with parameter values used in the iteration and the observed-data maximum likelihood derived from the EM algorithm.

In each iteration, the LR statistic is given by

$$-2 \log \left(\frac{f(\hat{\theta}_i)}{f(\hat{\theta})} \right)$$

where $f(\hat{\theta})$ is the observed-data maximum likelihood derived from the EM algorithm and $f(\hat{\theta}_i)$ is the observed-data likelihood for $\hat{\theta}_i$ used in the iteration.

Similarly, you can also save the observed-data LR posterior mode statistic for each iteration with the LR_POST option. This statistic is based on the observed-data posterior density with parameter values used in each iteration and the observed-data posterior mode derived from the EM algorithm for posterior mode.

For large samples, these LR statistics tends to be approximately χ^2 distributed with degrees of freedom equal to the dimension of θ (Schafer 1997, p. 131). For example, with a large number of iterations, if the values of the LR statistic do not behave like a random sample from the described χ^2 distribution, then there is evidence that the MCMC method has not converged.

Worst Linear Function of Parameters

The worst linear function (WLF) of parameters (Schafer 1997, pp. 129–131) is a scalar function of parameters μ and Σ that is “worst” in the sense that its function values converge most slowly among parameters in the MCMC method. The convergence of this function is evidence that other parameters are likely to converge as well.

For linear functions of parameters $\theta = (\mu, \Sigma)$, a worst linear function of θ has the highest asymptotic rate of missing information. The function can be derived from the iterative values of θ near the posterior mode in the EM algorithm. That is, an estimated worst linear function of θ is

$$w(\theta) = \mathbf{v}'(\theta - \hat{\theta})$$

where $\hat{\theta}$ is the posterior mode and the coefficients $\mathbf{v} = \hat{\theta}_{(-1)} - \hat{\theta}$ are the difference between the estimated value of θ one step prior to convergence and the converged value $\hat{\theta}$.

You can display the coefficients of the worst linear function, \mathbf{v} , by specifying the WLF option in the MCMC statement. You can save the function value from each iteration in an OUTITER= data set by specifying the WLF option within the OUTITER option. You can also display the worst linear function values from iterations in an autocorrelation plot or a trace plot by specifying WLF as an ACFPLOT or TIMEPLOT option, respectively.

Note that when the observed-data posterior is nearly normal, the WLF is one of the slowest functions to approach stationarity. When the posterior is not close to normal, other functions might take much longer than the WLF to converge, as described in Schafer (1997, p.130).

Trace Plot

A trace plot for a parameter ξ is a scatter plot of successive parameter estimates ξ_i against the iteration number i . The plot provides a simple way to examine the convergence behavior of the estimation algorithm for ξ . Long-term trends in the plot indicate that successive iterations are highly correlated and that the series of iterations has not converged.

You can display trace plots for worst linear function, variable means, variable variances, and covariances of variables. You can also request logarithmic transformations for positive parameters in the plots with the LOG option. When a parameter value is less than or equal to zero, the value is not displayed in the corresponding plot.

By default, the MI procedure uses solid line segments to connect data points in a trace plot. You can use the CCONNECT=, LCONNECT=, and WCONNECT= options to change the color, line type, and width of the line segments, respectively. When WCONNECT=0 is specified, the data points are not connected, and the procedure uses the plus sign (+) as the plot symbol to display the points with a height of one (percentage screen unit) in a trace plot. You can use the SYMBOL=, CSYMBOL=, and HSYMBOL= options to change the shape, color, and height of the plot symbol, respectively.

By default, the plot title “Trace Plot” is displayed in a trace plot. You can request another title by using the TITLE= option in the TIMEPLOT option. When another title is also specified in a TITLE statement, this title is displayed as the main title and the plot title is displayed as a subtitle in the plot.

You can use options in the GOPTIONS statement to change the color and height of the title. See the chapter “The SAS/GRAPH Statements” in *SAS/GRAPH: Reference* for an illustration of title options. See [Example 57.11](#) for a usage of the trace plot.

Autocorrelation Function Plot

To examine relationships of successive parameter estimates ξ , the autocorrelation function (ACF) can be used. For a stationary series, $\xi_i, i \geq 1$, in trace data, the autocorrelation function at lag k is

$$\rho_k = \frac{\text{Cov}(\xi_i, \xi_{i+k})}{\text{Var}(\xi_i)}$$

The sample k th order autocorrelation is computed as

$$r_k = \frac{\sum_{i=1}^{n-k} (\xi_i - \bar{\xi})(\xi_{i+k} - \bar{\xi})}{\sum_{i=1}^n (\xi_i - \bar{\xi})^2}$$

You can display autocorrelation function plots for the worst linear function, variable means, variable variances, and covariances of variables. You can also request logarithmic transformations for parameters in the plots with the LOG option. When a parameter has values less than or equal to zero, the corresponding plot is not created.

You specify the maximum number of lags of the series with the NLAG= option. The autocorrelations at each lag less than or equal to the specified lag are displayed in the graph. In addition, the plot also displays approximate 95% confidence limits for the autocorrelations. At lag k , the confidence limits indicate a set of approximate 95% critical values for testing the hypothesis $\rho_j = 0$, $j \geq k$.

By default, the MI procedure uses the star (*) as the plot symbol to display the points with a height of one (percentage screen unit) in the plot, a solid line to display the reference line of zero autocorrelation, vertical line segments to connect autocorrelations to the reference line, and a pair of dashed lines to display approximately 95% confidence limits for the autocorrelations.

You can use the SYMBOL=, CSYMBOL=, and HSYMBOL= options to change the shape, color, and height of the plot symbol, respectively, and the CNEEDLES= and WNEEDLES= options to change the color and width of the needles, respectively. You can also use the LREF=, CREF=, and WREF= options to change the line type, color, and width of the reference line, respectively. Similarly, you can use the LCONF=, CCONF=, and WCONF= options to change the line type, color, and width of the confidence limits, respectively.

By default, the plot title “Autocorrelation Plot” is displayed in a autocorrelation function plot. You can request another title by using the TITLE= option within the ACFPLOT option. When another title is also specified in a TITLE statement, this title is displayed as the main title and the plot title is displayed as a subtitle in the plot.

You can use options in the GOPTIONS statement to change the color and height of the title. See the chapter “The SAS/GRAPH Statements” in *SAS/GRAPH: Reference* for a description of title options. See [Example 57.8](#) for an illustration of the autocorrelation function plot.

Input Data Sets

You can specify the input data set with missing values by using the DATA= option in the PROC MI statement. When an MCMC method is used, you can specify the data set that contains the reference distribution information for imputation with the INEST= option, the data set that contains initial parameter estimates for the MCMC method with the INITIAL=INPUT= option, and the data set that contains information for the prior distribution with the PRIOR=INPUT= option in the MCMC statement.

DATA=SAS-data-set

The input DATA= data set is an ordinary SAS data set that contains multivariate data with missing values.

INEST=SAS-data-set

The input INEST= data set is a TYPE=EST data set and contains a variable `_Imputation_` to identify the imputation number. For each imputation, PROC MI reads the point estimate from the observations with `_TYPE_='PARM'` or `_TYPE_='PARMS'` and the associated covariances from the observations with `_TYPE_='COV'` or `_TYPE_='COVB'`. These estimates are used as the reference distribution to impute values for observations in the DATA= data set. When the input INEST= data set also contains observations with `_TYPE_='SEED'`, PROC MI reads the seed information for the random number generator from these observations. Otherwise, the SEED= option provides the seed information.

INITIAL=INPUT=SAS-data-set

The input INITIAL=INPUT= data set is a TYPE=COV or CORR data set and provides initial parameter estimates for the MCMC method. The covariances derived from the TYPE=COV/CORR data set are divided by the number of observations to get the correct covariance matrix for the point estimate (sample mean).

If TYPE=COV, PROC MI reads the number of observations from the observations with `_TYPE_='N'`, the point estimate from the observations with `_TYPE_='MEAN'`, and the covariances from the observations with `_TYPE_='COV'`.

If TYPE=CORR, PROC MI reads the number of observations from the observations with `_TYPE_='N'`, the point estimate from the observations with `_TYPE_='MEAN'`, the correlations from the observations with `_TYPE_='CORR'`, and the standard deviations from the observations with `_TYPE_='STD'`.

PRIOR=INPUT=SAS-data-set

The input PRIOR=INPUT= data set is a TYPE=COV data set that provides information for the prior distribution. You can use the data set to specify a prior distribution for Σ of the form

$$\Sigma \sim W^{-1}(d^*, d^*S^*)$$

where $d^* = n^* - 1$ is the degrees of freedom. PROC MI reads the matrix S^* from observations with `_TYPE_='COV'` and reads n^* from observations with `_TYPE_='N'`.

You can also use this data set to specify a prior distribution for μ of the form

$$\mu \sim N\left(\mu_0, \frac{1}{n_0}\Sigma\right)$$

PROC MI reads the mean vector μ_0 from observations with `_TYPE_='MEAN'` and reads n_0 from observations with `_TYPE_='N_MEAN'`. When there are no observations with `_TYPE_='N_MEAN'`, PROC MI reads n_0 from observations with `_TYPE_='N'`.

Output Data Sets

You can specify the output data set of imputed values with the OUT= option in the PROC MI statement. When an EM statement is used, you can specify the data set that contains the original data set with missing values being replaced by the expected values from the EM algorithm by using the OUT= option in the EM statement. You can also specify the data set that contains MLE computed with the EM algorithm by using the OUTEM= option.

When an MCMC method is used, you can specify the data set that contains parameter estimates used in each imputation with the `OUTEST=` option in the MCMC statement, and you can specify the data set that contains parameters used in the imputation step for each iteration with the `OUTITER` option in the MCMC statement.

OUT=SAS-data-set in the PROC MI statement

The `OUT=` data set contains all the variables in the original data set and a new variable named `_Imputation_` that identifies the imputation. For each imputation, the data set contains all variables in the input `DATA=` data set with missing values being replaced by imputed values. Note that when the `NIMPUTE=1` option is specified, the variable `_Imputation_` is not created.

OUT=SAS-data-set in an EM statement

The `OUT=` data set contains the original data set with missing values being replaced by expected values from the EM algorithm.

OUTEM=SAS-data-set

The `OUTEM=` data set is a `TYPE=COV` data set and contains the MLE computed with the EM algorithm. The observations with `_TYPE_='MEAN'` contain the estimated mean and the observations with `_TYPE_='COV'` contain the estimated covariances.

OUTEST=SAS-data-set

The `OUTEST=` data set is a `TYPE=EST` data set and contains parameter estimates used in each imputation in the MCMC method. It also includes an index variable named `_Imputation_`, which identifies the imputation.

The observations with `_TYPE_='SEED'` contain the seed information for the random number generator. The observations with `_TYPE_='PARM'` or `_TYPE_='PARMS'` contain the point estimate, and the observations with `_TYPE_='COV'` or `_TYPE_='COVB'` contain the associated covariances. These estimates are used as the parameters of the reference distribution to impute values for observations in the `DATA=` dataset.

Note that these estimates are the values used in the I-step before each imputation. These are not the parameter values simulated from the P-step in the same iteration. See [Example 57.12](#) for a usage of this option.

OUTITER <(options)> =SAS-data-set in an EM statement

The `OUTITER=` data set in an EM statement is a `TYPE=COV` data set and contains parameters for each iteration. It also includes a variable `_Iteration_` that provides the iteration number.

The parameters in the output data set depend on the options specified. You can specify the `MEAN` and `COV` options for `OUTITER`. With the `MEAN` option, the output data set contains the mean parameters in observations with the variable `_TYPE_='MEAN'`. Similarly, with the `COV` option, the output data set contains the covariance parameters in observations with the variable `_TYPE_='COV'`. When no options are specified, the output data set contains the mean parameters for each iteration.

OUTITER <(options)> =SAS-data-set in an FCS statement

The OUTITER= data set in an FCS statement is a TYPE=COV data set and contains parameters for each iteration. It also includes variables named `_Imputation_` and `_Iteration_`, which provide the imputation number and iteration number.

The parameters in the output data set depend on the options specified. You can specify the MEAN and STD options for OUTITER. With the MEAN option, the output data set contains the mean parameters used in the imputation in observations with the variable `_TYPE_='MEAN'`. Similarly, with the STD option, the output data set contains the standard deviation parameters used in the imputation in observations with the variable `_TYPE_='STD'`. When no options are specified, the output data set contains the mean parameters for each iteration.

OUTITER <(options)> =SAS-data-set in an MCMC statement

The OUTITER= data set in an MCMC statement is a TYPE=COV data set and contains parameters used in the imputation step for each iteration. It also includes variables named `_Imputation_` and `_Iteration_`, which provide the imputation number and iteration number.

The parameters in the output data set depend on the options specified. [Table 57.6](#) summarizes the options available for OUTITER and the corresponding values for the output variable `_TYPE_`.

Table 57.6 Summary of Options for OUTITER in an MCMC statement

Option	Output Parameters	<code>_TYPE_</code>
MEAN	mean parameters	MEAN
STD	standard deviations	STD
COV	covariances	COV
LR	$-2 \log$ LR statistic	LOG_LR
LR_POST	$-2 \log$ LR statistic of the posterior mode	LOG_POST
WLF	worst linear function	WLF

When no options are specified, the output data set contains the mean parameters used in the imputation step for each iteration. For a detailed description of the worst linear function and LR statistics, see the section “[Checking Convergence in MCMC](#)” on page 4764.

Combining Inferences from Multiply Imputed Data Sets

With m imputations, m different sets of the point and variance estimates for a parameter Q can be computed. Suppose \hat{Q}_i and \hat{W}_i are the point and variance estimates from the i th imputed data set, $i = 1, 2, \dots, m$. Then the combined point estimate for Q from multiple imputation is the average of the m complete-data estimates:

$$\bar{Q} = \frac{1}{m} \sum_{i=1}^m \hat{Q}_i$$

Suppose \overline{W} is the within-imputation variance, which is the average of the m complete-data estimates,

$$\overline{W} = \frac{1}{m} \sum_{i=1}^m \hat{W}_i$$

and B is the between-imputation variance

$$B = \frac{1}{m-1} \sum_{i=1}^m (\hat{Q}_i - \overline{Q})^2$$

Then the variance estimate associated with \overline{Q} is the total variance (Rubin 1987)

$$T = \overline{W} + (1 + \frac{1}{m})B$$

The statistic $(Q - \overline{Q})T^{-(1/2)}$ is approximately distributed as t with v_m degrees of freedom (Rubin 1987), where

$$v_m = (m-1) \left[1 + \frac{\overline{W}}{(1 + m^{-1})B} \right]^2$$

The degrees of freedom v_m depend on m and the ratio

$$r = \frac{(1 + m^{-1})B}{\overline{W}}$$

The ratio r is called the relative increase in variance due to nonresponse (Rubin 1987). When there is no missing information about Q , the values of r and B are both zero. With a large value of m or a small value of r , the degrees of freedom v_m will be large and the distribution of $(Q - \overline{Q})T^{-(1/2)}$ will be approximately normal.

Another useful statistic is the fraction of missing information about Q :

$$\hat{\lambda} = \frac{r + 2/(v_m + 3)}{r + 1}$$

Both statistics r and λ are helpful diagnostics for assessing how the missing data contribute to the uncertainty about Q .

When the complete-data degrees of freedom v_0 are small, and there is only a modest proportion of missing data, the computed degrees of freedom, v_m , can be much larger than v_0 , which is inappropriate. For example, with $m = 5$ and $r = 10\%$, the computed degrees of freedom $v_m = 484$, which is inappropriate for data sets with complete-data degrees of freedom less than 484.

Barnard and Rubin (1999) recommend the use of adjusted degrees of freedom

$$v_m^* = \left[\frac{1}{v_m} + \frac{1}{\hat{v}_{obs}} \right]^{-1}$$

where $\hat{v}_{obs} = (1 - \gamma) v_0 (v_0 + 1) / (v_0 + 3)$ and $\gamma = (1 + m^{-1})B/T$.

Note that the MI procedure uses the adjusted degrees of freedom, v_m^* , for inference.

Multiple Imputation Efficiency

The relative efficiency (RE) of using the finite m imputation estimator, rather than using an infinite number for the fully efficient imputation, in units of variance, is approximately a function of m and λ (Rubin 1987, p. 114):

$$\text{RE} = \left(1 + \frac{\lambda}{m}\right)^{-1}$$

Table 57.7 shows relative efficiencies with different values of m and λ .

Table 57.7 Relative Efficiencies

m	λ				
	10%	20%	30%	50%	70%
3	0.9677	0.9375	0.9091	0.8571	0.8108
5	0.9804	0.9615	0.9434	0.9091	0.8772
10	0.9901	0.9804	0.9709	0.9524	0.9346
20	0.9950	0.9901	0.9852	0.9756	0.9662

The table shows that for situations with little missing information, only a small number of imputations are necessary. In practice, the number of imputations needed can be informally verified by replicating sets of m imputations and checking whether the estimates are stable between sets (Horton and Lipsitz 2001, p. 246).

Imputer's Model Versus Analyst's Model

Multiple imputation inference assumes that the model you used to analyze the multiply imputed data (the analyst's model) is the same as the model used to impute missing values in multiple imputation (the imputer's model). But in practice, the two models might not be the same (Schafer 1997, p. 139).

Schafer (1997, pp. 139–143) provides comprehensive coverage of this topic, and the following example is based on his work.

Consider a trivariate data set with variables Y_1 and Y_2 fully observed, and a variable Y_3 with missing values. An imputer creates multiple imputations with the model $Y_3 = Y_1 Y_2$. However, the analyst can later use the simpler model $Y_3 = Y_1$. In this case, the analyst assumes more than the imputer. That is, the analyst assumes there is no relationship between variables Y_3 and Y_2 .

The effect of the discrepancy between the models depends on whether the analyst's additional assumption is true. If the assumption is true, the imputer's model still applies. The inferences derived from multiple imputations will still be valid, although they might be somewhat conservative because they reflect the additional uncertainty of estimating the relationship between Y_3 and Y_2 .

On the other hand, suppose that the analyst models $Y_3 = Y_1$, and there is a relationship between variables Y_3 and Y_2 . Then the model $Y_3 = Y_1$ will be biased and is inappropriate. Appropriate results can be generated only from appropriate analyst models.

Another type of discrepancy occurs when the imputer assumes more than the analyst. For example, suppose that an imputer creates multiple imputations with the model $Y_3 = Y_1$, but the analyst later fits a model $Y_3 = Y_1 Y_2$. When the assumption is true, the imputer's model is a correct model and the inferences still hold.

On the other hand, suppose there is a relationship between Y_3 and Y_2 . Imputations created under the incorrect assumption that there is no relationship between Y_3 and Y_2 will make the analyst's estimate of the relationship biased toward zero. Multiple imputations created under an incorrect model can lead to incorrect conclusions.

Thus, generally you should include as many variables as you can when doing multiple imputation. The precision you lose with included unimportant predictors is usually a relatively small price to pay for the general validity of analyses of the resultant multiply imputed data set (Rubin 1996). But at the same time, you need to keep the model building and fitting feasible (Barnard and Meng 1999, pp. 19–20).

To produce high-quality imputations for a particular variable, the imputation model should also include variables that are potentially related to the imputed variable and variables that are potentially related to the missingness of the imputed variable (Schafer 1997, p. 143).

Similar suggestions were also given by van Buuren, Boshuizen, and Knook (1999, p. 687). They recommend that the imputation model include three sets of covariates: variables in the analyst's model, variables associated with the missingness of the imputed variable, and variables correlated with the imputed variable. They also recommend the removal of the covariates not in the analyst's model if they have too many missing values for observations with missing imputed variables.

Note that it is good practice to include a description of the imputer's model with the multiply imputed data set (Rubin 1996, p. 479). That way, the analysts will have information about the variables involved in the imputation and which relationships among the variables have been implicitly set to zero.

Parameter Simulation versus Multiple Imputation

As an alternative to multiple imputation, parameter simulation can also be used to analyze the data for many incomplete-data problems. Although the MI procedure does not offer parameter simulation, the trade-offs between the two methods (Schafer 1997, pp. 89–90, 135–136) are examined in this section.

The parameter simulation method simulates random values of parameters from the observed-data posterior distribution and makes simple inferences about these parameters (Schafer 1997, p. 89). When a set of well-defined population parameters θ are of interest, parameter simulation can be used to directly examine and summarize simulated values of θ . This usually requires a large number of iterations, and involves calculating appropriate summaries of the resulting dependent sample of the iterates of the θ . If only a small set of parameters are involved, parameter simulation is suitable (Schafer 1997).

Multiple imputation requires only a small number of imputations. Generating and storing a few imputations can be more efficient than generating and storing a large number of iterations for parameter simulation.

When fractions of missing information are low, methods that average over simulated values of the missing data, as in multiple imputation, can be much more efficient than methods that average over simulated values of θ as in parameter simulation (Schafer 1997).

Summary of Issues in Multiple Imputation

This section summarizes issues that are encountered in applications of the MI procedure.

The MAR Assumption

The missing at random (MAR) assumption is needed for the imputation methods in the MI procedure. Although this assumption cannot be verified with the data, it becomes more plausible as more variables are included in the imputation model (Schafer 1997, pp. 27–28; van Buuren, Boshuizen, and Knook 1999, p. 687).

Number of Imputations

Based on the theory of multiple imputation, only a small number of imputations are needed for a data set with little missing information (Rubin 1987, p. 114). The number of imputations can be informally verified by replicating sets of m imputations and checking whether the estimates are stable (Horton and Lipsitz 2001, p. 246).

Imputation Model

Generally you should include as many variables as you can in the imputation model (Rubin 1996). At the same time, however, it is important to keep the number of variables in control, as discussed by Barnard and Meng (1999, pp. 19–20). For the imputation of a particular variable, the model should include variables in the complete-data model, variables that are correlated with the imputed variable, and variables that are associated with the missingness of the imputed variable (Schafer 1997, p. 143; van Buuren, Boshuizen, and Knook 1999, p. 687).

Multivariate Normality Assumption

Although the regression and MCMC methods assume multivariate normality, inferences based on multiple imputation can be robust to departures from the multivariate normality if the amount of missing information is not large (Schafer 1997, pp. 147–148).

You can use variable transformations to make the normality assumption more tenable. Variables are transformed before the imputation process and then back-transformed to create imputed values.

Monotone Regression Method

With the multivariate normality assumption, either the regression method or the predictive mean matching method can be used to impute continuous variables in data sets with monotone missing patterns.

The predictive mean matching method ensures that imputed values are plausible and might be more appropriate than the regression method if the normality assumption is violated (Horton and Lipsitz 2001, p. 246).

Monotone Propensity Score Method

The propensity score method can also be used to impute continuous variables in data sets with monotone missing patterns.

The propensity score method does not use correlations among variables and is not appropriate for analyses involving relationship among variables, such as a regression analysis (Schafer 1999, p. 11). It can also produce badly biased estimates of regression coefficients when data on predictor variables are missing (Allison 2000).

MCMC Monotone-Data Imputation

The MCMC method is used to impute continuous variables in data sets with arbitrary missing patterns, assuming a multivariate normal distribution for the data. It can also be used to impute just enough missing values to make the imputed data sets have a monotone missing pattern. Then, a more flexible monotone imputation method can be used for the remaining missing values.

Checking Convergence in MCMC

In an MCMC method, parameters are drawn after the MCMC is run long enough to converge to its stationary distribution. In practice, however, it is not simple to verify the convergence of the process, especially for a large number of parameters.

You can check for convergence by examining the observed-data likelihood ratio statistic and worst linear function of the parameters in each iteration. You can also check for convergence by examining a plot of autocorrelation function, as well as a trace plot of parameters (Schafer 1997, p. 120).

EM Estimates

The EM algorithm can be used to compute the MLE of the mean vector and covariance matrix of the data with missing values, assuming a multivariate normal distribution for the data. However, the covariance matrix associated with the estimate of the mean vector cannot be derived from the EM algorithm.

In the MI procedure, you can use the EM algorithm to compute the posterior mode, which provides a good starting value for the MCMC method (Schafer 1997, p. 169).

ODS Table Names

PROC MI assigns a name to each table it creates. You must use these names to reference tables when using the Output Delivery System (ODS). These names are listed in Table 57.8. For more information about ODS, see Chapter 20, “Using the Output Delivery System.”

Table 57.8 ODS Tables Produced by PROC MI

ODS Table Name	Description	Statement	Option
Corr	Pairwise correlations		SIMPLE
EMEstimates	EM (MLE) estimates	EM	
EMInitEstimates	EM initial estimates	EM	
EMIterHistory	EM (MLE) iteration history	EM	ITPRINT
EMPostEstimates	EM (posterior mode) estimates	MCMC	INITIAL=EM
EMPostIterHistory	EM (posterior mode)	MCMC	INITIAL=EM (ITPRINT)

Table 57.8 *continued*

ODS Table Name	Description	Statement	Option
	iteration history		
EMWLF	Worst linear function	MCMC	WLF
FCSDiscrim	Discriminant model	FCS	DISCRIM (/DETAILS)
	group means		
FCSLogistic	Logistic model	FCS	LOGISTIC (/DETAILS)
FCSModel	FCS models	FCS	
FCSReg	Regression model	FCS	REG (/DETAILS)
FCSRegPMM	Predicted mean matching model	FCS	REGPMM (/DETAILS)
MCMCInitEstimates	MCMC initial estimates	MCMC	DISPLAYINIT
MissPattern	Missing data patterns		
ModelInfo	Model information		
MonoDiscrim	Discriminant model	MONOTONE	DISCRIM (/DETAILS)
	group means		
MonoLogistic	Logistic model	MONOTONE	LOGISTIC (/DETAILS)
MonoModel	Monotone models	MONOTONE	
MonoPropensity	Propensity score model	MONOTONE	PROPENSITY (/DETAILS)
	logistic function		
MonoReg	Regression model	MONOTONE	REG (/DETAILS)
MonoRegPMM	Predicted mean matching model	MONOTONE	REGPMM (/DETAILS)
ParameterEstimates	Parameter estimates		
Transform	Variable transformations	TRANSFORM	
Univariate	Univariate statistics		SIMPLE
VarianceInfo	Between, within, and total variances		

ODS Graphics

Statistical procedures use ODS Graphics to create graphs as part of their output. ODS Graphics is described in detail in Chapter 21, “[Statistical Graphics Using ODS.](#)”

Before you create graphs, ODS Graphics must be enabled (for example, by specifying the ODS GRAPHICS ON statement). For more information about enabling and disabling ODS Graphics, see the section “[Enabling and Disabling ODS Graphics](#)” on page 600 in Chapter 21, “[Statistical Graphics Using ODS.](#)”

The overall appearance of graphs is controlled by ODS styles. Styles and other aspects of using ODS Graphics are discussed in the section “[A Primer on ODS Statistical Graphics](#)” on page 599 in Chapter 21, “[Statistical Graphics Using ODS.](#)”

PROC MI assigns a name to each graph it creates using ODS. You can use these names to reference the graphs when using ODS. To request these graphs, ODS Graphics must be enabled and you must specify the options indicated in [Table 57.9](#).

Table 57.9 Graphs Produced by PROC MI

ODS Graph Name	Description	Statement	Option
ACFPlot	ACF plot	MCMC	PLOTS=ACF
TracePlot	Trace plot	MCMC	PLOTS= TRACE
		FCS	PLOTS= TRACE

Examples: MI Procedure

The Fish data described in the STEPDISC procedure are measurements of 159 fish of seven species caught in Finland's lake Laengelmavesi. For each fish, the length, height, and width are measured. Three different length measurements are recorded: from the nose of the fish to the beginning of its tail (Length1), from the nose to the notch of its tail (Length2), and from the nose to the end of its tail (Length3). See Chapter 89, "The STEPDISC Procedure," for more information.

The Fish1 data set is constructed from the Fish data set and contains only one species of the fish and the three length measurements. Some values have been set to missing, and the resulting data set has a monotone missing pattern in the variables Length1, Length2, and Length3. The Fish1 data set is used in [Example 57.2](#) with the propensity score method and in [Example 57.3](#) with the regression method.

The Fish2 data set is also constructed from the Fish data set and contains two species of fish. Some values have been set to missing, and the resulting data set has a monotone missing pattern in the variables Length, Height, Width, and Species. The Fish2 data set is used in [Example 57.4](#) with the logistic regression method and in [Example 57.5](#) with the discriminant function method. Note that some values of the variable Species have also been altered in the data set.

The Fish3 data set is similar to the data set Fish2 except some additional values have been set to missing and the resulting data set has an arbitrary missing pattern. The Fish3 data set is used in [Example 57.7](#) and in [Example 57.8](#).

The Fitness1 data set created in the section "Getting Started: MI Procedure" on page 4716 is used in other examples.

The following statements create the Fish1 data set:

```

*-----Fish1 Data-----*
| The data set contains one species of the fish (Bream) and |
| three measurements: Length1, Length2, Length3.           |
| Some values have been set to missing, and the resulting data set |
| has a monotone missing pattern in the variables           |
| Length1, Length2, and Length3.                             |
*-----*
data Fish1;
  title 'Fish Measurement Data';
  input Length1 Length2 Length3 @@;
  datalines;
23.2 25.4 30.0    24.0 26.3 31.2    23.9 26.5 31.1
26.3 29.0 33.5    26.5 29.0    .    26.8 29.7 34.7
26.8    .    .    27.6 30.0 35.0    27.6 30.0 35.1
28.5 30.7 36.2    28.4 31.0 36.2    28.7    .    .
29.1 31.5    .    29.5 32.0 37.3    29.4 32.0 37.2

```

```

29.4 32.0 37.2    30.4 33.0 38.3    30.4 33.0 38.5
30.9 33.5 38.6    31.0 33.5 38.7    31.3 34.0 39.5
31.4 34.0 39.2    31.5 34.5    .    31.8 35.0 40.6
31.9 35.0 40.5    31.8 35.0 40.9    32.0 35.0 40.6
32.7 36.0 41.5    32.8 36.0 41.6    33.5 37.0 42.6
35.0 38.5 44.1    35.0 38.5 44.0    36.2 39.5 45.3
37.4 41.0 45.9    38.0 41.0 46.5
;

```

The Fish2 data set contains two of the seven species in the Fish data set. For each of the two species (Bream and Pike), the length from the nose of the fish to the end of its tail, the height, and the width of each fish are measured.

The following statements create the Fish2 data set:

```

*-----Fish2 Data-----*
| The data set contains two species of the fish (Bream and Pike) |
| and three measurements: Length, Height, Width.                |
| Some values have been set to missing, and the resulting data set |
| has a monotone missing pattern in the variables                |
| Length, Height, Width, and Species.                            |
*-----*
data Fish2;
  title 'Fish Measurement Data';
  input Species $ Length Height Width @@;
  datalines;
Bream  30.0  11.520  4.020    .    31.2  12.480  4.306
Bream  31.1  12.378  4.696    Bream  33.5  12.730  4.456
.      34.0  12.444    .    Bream  34.7  13.602  4.927
Bream  34.5  14.180  5.279    Bream  35.0  12.670  4.690
Bream  35.1  14.005  4.844    Bream  36.2  14.227  4.959
.      36.2  14.263    .    Bream  36.2  14.371  4.815
Bream  36.4  13.759  4.368    Bream  37.3  13.913  5.073
Bream  37.2  14.954  5.171    Bream  37.2  15.438  5.580
Bream  38.3  14.860  5.285    Bream  38.5  14.938  5.198
.      38.6  15.633  5.134    Bream  38.7  14.474  5.728
Bream  39.5  15.129  5.570    .    39.2  15.994    .
Bream  39.7  15.523  5.280    Bream  40.6  15.469  6.131
.      40.5    .    .    Bream  40.9  16.360  6.053
Bream  40.6  16.362  6.090    Bream  41.5  16.517  5.852
Bream  41.6  16.890  6.198    Bream  42.6  18.957  6.603
Bream  44.1  18.037  6.306    Bream  44.0  18.084  6.292
Bream  45.3  18.754  6.750    Bream  45.9  18.635  6.747
Bream  46.5  17.624  6.371
Pike   34.8    5.568  3.376    Pike   37.8    5.708  4.158
Pike   38.8    5.936  4.384    .    39.8    .    .
Pike   40.5    7.290  4.577    Pike   41.0    6.396  3.977
.      45.5    7.280  4.323    Pike   45.5    6.825  4.459
Pike   45.8    7.786  5.130    Pike   48.0    6.960  4.896
Pike   48.7    7.792  4.870    Pike   51.2    7.680  5.376
Pike   55.1    8.926  6.171    .    59.7   10.686    .
Pike   64.0    9.600  6.144    Pike   64.0    9.600  6.144
Pike   68.0   10.812  7.480
;

```

The following statements create the Fish3 data set:

```

*-----Fish3 Data-----*
| The data set contains two species of the fish (Bream and Pike) |
| and three measurements: Length, Height, Width.                |
| Some values have been set to missing, and the resulting data set |
| has an arbitrary missing pattern.                               |
*-----*
data Fish3;
  title 'Fish Measurement Data';
  input Species $ Length Height Width @@;
  datalines;
Bream  30.0  11.520  4.020      .  31.2  12.480  4.306
Bream  31.1  12.378  4.696      Bream  33.5  12.730  4.456
.      .  12.444  .          Bream  34.7  13.602  4.927
Bream  34.5  14.180  5.279      .  35.0  .  4.690
Bream  35.1  14.005  4.844      Bream  36.2  14.227  4.959
.  36.2  14.263  .          Bream  36.2  14.371  4.815
Bream  36.4  13.759  4.368      Bream  37.3  13.913  5.073
Bream  37.2  14.954  5.171      .  37.2  .  5.580
Bream  38.3  14.860  5.285      Bream  38.5  14.938  5.198
.  38.6  15.633  5.134      Bream  38.7  14.474  5.728
Bream  39.5  15.129  5.570      .  39.2  15.994  .
Bream  39.7  15.523  5.280      Bream  40.6  15.469  6.131
.  40.5  .  .          Bream  40.9  16.360  6.053
Bream  40.6  16.362  6.090      Bream  41.5  16.517  5.852
Bream  41.6  16.890  6.198      Bream  42.6  18.957  6.603
Bream  .  18.037  .          Bream  .  18.084  6.292
Bream  45.3  18.754  6.750      Bream  45.9  18.635  6.747
Bream  46.5  17.624  6.371
Pike   34.8  5.568  3.376      Pike   37.8  5.708  4.158
Pike   38.8  5.936  4.384      .  39.8  .  .
Pike   40.5  7.290  4.577      Pike   41.0  6.396  3.977
.  45.5  7.280  4.323      Pike   45.5  6.825  4.459
Pike   45.8  7.786  5.130      Pike   48.0  6.960  4.896
Pike   48.7  7.792  4.870      Pike   51.2  7.680  5.376
Pike   55.1  8.926  6.171      .  59.7  10.686  .
Pike   64.0  9.600  6.144      Pike   64.0  9.600  6.144
Pike   .  10.812  7.480
;

```

Example 57.1: EM Algorithm for MLE

This example uses the EM algorithm to compute the maximum likelihood estimates for parameters of multivariate normally distributed data with missing values. The following statements invoke the MI procedure and request the EM algorithm to compute the MLE for (μ, Σ) of a multivariate normal distribution from the input data set Fitness1:

```

proc mi data=Fitness1 seed=1518971 simple nimpute=0;
  em itprint outem=outem;
  var Oxygen RunTime RunPulse;
run;

```


Note that when you specify the NIMPUTE=0 option, the missing values are not imputed.

The “Model Information” table in [Output 57.1.1](#) describes the method and options used in the procedure if a positive number is specified in the NIMPUTE= option.

Output 57.1.1 Model Information

The MI Procedure	
Model Information	
Data Set	WORK.FITNESS1
Method	MCMC
Multiple Imputation Chain	Single Chain
Initial Estimates for MCMC	EM Posterior Mode
Start	Starting Value
Prior	Jeffreys
Number of Imputations	0
Number of Burn-in Iterations	200
Number of Iterations	100
Seed for random number generator	1518971

The “Missing Data Patterns” table in [Output 57.1.2](#) lists distinct missing data patterns with corresponding frequencies and percentages. Here, a value of “X” means that the variable is observed in the corresponding group and a value of “.” means that the variable is missing. The table also displays group-specific variable means.

Output 57.1.2 Missing Data Patterns

Missing Data Patterns					
Group	Oxygen	Run Time	Run Pulse	Freq	Percent
1	X	X	X	21	67.74
2	X	X	.	4	12.90
3	X	.	.	3	9.68
4	.	X	X	1	3.23
5	.	X	.	2	6.45

Missing Data Patterns			
-----Group Means-----			
Group	Oxygen	RunTime	RunPulse
1	46.353810	10.809524	171.666667
2	47.109500	10.137500	.
3	52.461667	.	.
4	.	11.950000	176.000000
5	.	9.885000	.

With the SIMPLE option, the procedure displays simple descriptive univariate statistics for available cases in the “Univariate Statistics” table in [Output 57.1.3](#) and correlations from pairwise available cases in the “Pairwise Correlations” table in [Output 57.1.4](#).

Output 57.1.3 Univariate Statistics

Univariate Statistics					
Variable	N	Mean	Std Dev	Minimum	Maximum
Oxygen	28	47.11618	5.41305	37.38800	60.05500
RunTime	28	10.68821	1.37988	8.63000	14.03000
RunPulse	22	171.86364	10.14324	148.00000	186.00000

Univariate Statistics			
---Missing Values---			
Variable	Count	Percent	
Oxygen	3	9.68	
RunTime	3	9.68	
RunPulse	9	29.03	

Output 57.1.4 Pairwise Correlations

Pairwise Correlations				
	Oxygen	RunTime	RunPulse	
Oxygen	1.000000000	-0.849118562	-0.343961742	
RunTime	-0.849118562	1.000000000	0.247258191	
RunPulse	-0.343961742	0.247258191	1.000000000	

When you use the EM statement, the MI procedure displays the initial parameter estimates for the EM algorithm in the “Initial Parameter Estimates for EM” table in [Output 57.1.5](#).

Output 57.1.5 Initial Parameter Estimates for EM

Initial Parameter Estimates for EM				
TYPE	_NAME_	Oxygen	RunTime	RunPulse
MEAN		47.116179	10.688214	171.863636
COV	Oxygen	29.301078	0	0
COV	RunTime	0	1.904067	0
COV	RunPulse	0	0	102.885281

When you use the ITPRINT option in the EM statement, the “EM (MLE) Iteration History” table in [Output 57.1.6](#) displays the iteration history for the EM algorithm.

Output 57.1.6 EM (MLE) Iteration History

EM (MLE) Iteration History				
<u>_Iteration_</u>	<u>-2 Log L</u>	<u>Oxygen</u>	<u>RunTime</u>	<u>RunPulse</u>
0	289.544782	47.116179	10.688214	171.863636
1	263.549489	47.116179	10.688214	171.863636
2	255.851312	47.139089	10.603506	171.538203
3	254.616428	47.122353	10.571685	171.426790
4	254.494971	47.111080	10.560585	171.398296
5	254.483973	47.106523	10.556768	171.389208
6	254.482920	47.104899	10.555485	171.385257
7	254.482813	47.104348	10.555062	171.383345
8	254.482801	47.104165	10.554923	171.382424
9	254.482800	47.104105	10.554878	171.381992
10	254.482800	47.104086	10.554864	171.381796
11	254.482800	47.104079	10.554859	171.381708
12	254.482800	47.104077	10.554858	171.381669

The “EM (MLE) Parameter Estimates” table in [Output 57.1.7](#) displays the maximum likelihood estimates for μ and Σ of a multivariate normal distribution from the data set Fitness1.

Output 57.1.7 EM (MLE) Parameter Estimates

EM (MLE) Parameter Estimates				
<u>_TYPE_</u>	<u>_NAME_</u>	<u>Oxygen</u>	<u>RunTime</u>	<u>RunPulse</u>
MEAN		47.104077	10.554858	171.381669
COV	Oxygen	27.797931	-6.457975	-18.031298
COV	RunTime	-6.457975	2.015514	3.516287
COV	RunPulse	-18.031298	3.516287	97.766857

You can also output the EM (MLE) parameter estimates to an output data set with the OUTEM= option. The following statements list the observations in the output data set outem:

```
proc print data=outem;
  title 'EM Estimates';
run;
```

The output data set outem in [Output 57.1.8](#) is a TYPE=COV data set. The observation with _TYPE_='MEAN' contains the MLE for the parameter μ , and the observations with _TYPE_='COV' contain the MLE for the parameter Σ of a multivariate normal distribution from the data set Fitness1.

Output 57.1.8 EM Estimates

EM Estimates					
Obs	_TYPE_	_NAME_	Oxygen	RunTime	RunPulse
1	MEAN		47.1041	10.5549	171.382
2	COV	Oxygen	27.7979	-6.4580	-18.031
3	COV	RunTime	-6.4580	2.0155	3.516
4	COV	RunPulse	-18.0313	3.5163	97.767

Example 57.2: Monotone Propensity Score Method

This example uses the propensity score method to impute missing values for variables in a data set with a monotone missing pattern. The following statements invoke the MI procedure and request the propensity score method. The resulting data set is named outex2.

```
proc mi data=Fish1 seed=899603 out=outex2;
  monotone propensity;
  var Length1 Length2 Length3;
run;
```

Note that the VAR statement is required and the data set must have a monotone missing pattern with variables as ordered in the VAR statement.

The “Model Information” table in [Output 57.2.1](#) describes the method and options used in the multiple imputation process. By default, five imputations are created for the missing data.

Output 57.2.1 Model Information

The MI Procedure	
Model Information	
Data Set	WORK.FISH1
Method	Monotone
Number of Imputations	5
Seed for random number generator	899603

When monotone methods are used in the imputation, MONOTONE is displayed as the method. The “Monotone Model Specification” table in [Output 57.2.2](#) displays the detailed model specification. By default, the observations are sorted into five groups based on their propensity scores.

Output 57.2.2 Monotone Model Specification

Monotone Model Specification		
Method	Imputed Variables	
Propensity(Groups= 5)	Length2	Length3

Without covariates specified for imputed variables Length2 and Length3, the variable Length1 is used as the covariate for Length2, and the variables Length1 and Length2 are used as covariates for Length3.

The “Missing Data Patterns” table in [Output 57.2.3](#) lists distinct missing data patterns with corresponding frequencies and percentages. Here, values of “X” and “.” indicate that the variable is observed or missing, respectively, in the corresponding group. The table confirms a monotone missing pattern for these three variables.

Output 57.2.3 Missing Data Patterns

Missing Data Patterns					
Group	Length1	Length2	Length3	Freq	Percent
1	X	X	X	30	85.71
2	X	X	.	3	8.57
3	X	.	.	2	5.71

Missing Data Patterns			
Group	-----Group Means-----		
	Length1	Length2	Length3
1	30.603333	33.436667	38.720000
2	29.033333	31.666667	.
3	27.750000	.	.

For the imputation process, first, missing values of Length2 in group 3 are imputed using observed values of Length1. Then the missing values of Length3 in group 2 are imputed using observed values of Length1 and Length2. And finally, the missing values of Length3 in group 3 are imputed using observed values of Length1 and imputed values of Length2.

After the completion of m imputations, the “Variance Information” table in [Output 57.2.4](#) displays the between-imputation variance, within-imputation variance, and total variance for combining complete-data inferences. It also displays the degrees of freedom for the total variance. The relative increase in variance due to missingness, the fraction of missing information, and the relative efficiency for each variable are also displayed. A detailed description of these statistics is provided in the section “[Combining Inferences from Multiply Imputed Data Sets](#)” on page 4769.

Output 57.2.4 Variance Information

Variance Information				
Variable	-----Variance-----			DF
	Between	Within	Total	
Length2	0.001500	0.465422	0.467223	32.034
Length3	0.049725	0.547434	0.607104	27.103

Variance Information				
Variable	Relative Increase in Variance	Fraction Missing Information	Relative Efficiency	
Length2	0.003869	0.003861	0.999228	
Length3	0.108999	0.102610	0.979891	

The “Parameter Estimates” table in [Output 57.2.5](#) displays the estimated mean and standard error of the mean for each variable. The inferences are based on the t distributions. For each variable, the table also displays a 95% mean confidence interval and a t statistic with the associated p -value for the hypothesis that the population mean is equal to the value specified in the MU0= option, which is zero by default.

Output 57.2.5 Parameter Estimates

Parameter Estimates					
Variable	Mean	Std Error	95% Confidence Limits		DF
Length2	33.006857	0.683537	31.61460	34.39912	32.034
Length3	38.361714	0.779169	36.76328	39.96015	27.103

Parameter Estimates					
Variable	Minimum	Maximum	Mu0	t for H0: Mean=Mu0	Pr > t
Length2	32.957143	33.060000	0	48.29	<.0001
Length3	38.080000	38.545714	0	49.23	<.0001

The following statements list the first 10 observations of the data set outex2, as shown in [Output 57.2.6](#). The missing values are imputed from observed values with similar propensity scores.

```
proc print data=outex2(obs=10);
  title 'First 10 Observations of the Imputed Data Set';
run;
```

Output 57.2.6 Imputed Data Set

First 10 Observations of the Imputed Data Set				
Obs	_Imputation_	Length1	Length2	Length3
1	1	23.2	25.4	30.0
2	1	24.0	26.3	31.2
3	1	23.9	26.5	31.1
4	1	26.3	29.0	33.5
5	1	26.5	29.0	38.6
6	1	26.8	29.7	34.7
7	1	26.8	29.0	35.0
8	1	27.6	30.0	35.0
9	1	27.6	30.0	35.1
10	1	28.5	30.7	36.2

Example 57.3: Monotone Regression Method

This example uses the regression method to impute missing values for all variables in a data set with a monotone missing pattern. The following statements invoke the MI procedure and request the regression method for the variable Length2 and the predictive mean matching method for variable Length3. The resulting data set is named outex3.

```
proc mi data=Fish1 round=.1 mu0= 0 35 45
    seed=13951639 out=outex3;
    monotone reg(Length2/ details)
        regpmm(Length3= Length1 Length2 Length1*Length2/ details);
    var Length1 Length2 Length3;
run;
```

The ROUND= option is used to round the imputed values to the same precision as observed values. The values specified with the ROUND= option are matched with the variables Length1, Length2, and Length3 in the order listed in the VAR statement. The MU0= option requests t tests for the hypotheses that the population means corresponding to the variables in the VAR statement are Length2=35 and Length3=45.

The “Missing Data Patterns” table lists distinct missing data patterns with corresponding frequencies and percentages. It is identical to the table in [Output 57.2.3](#) in [Example 57.2](#).

The “Monotone Model Specification” table in [Output 57.3.1](#) displays the model specification.

Output 57.3.1 Monotone Model Specification

The MI Procedure	
Monotone Model Specification	
Method	Imputed Variables
Regression	Length2
Regression-PMM(K= 5)	Length3

When you use the DETAILS option, the parameters estimated from the observed data and the parameters used in each imputation are displayed in [Output 57.3.2](#) and [Output 57.3.3](#).

Output 57.3.2 Regression Model

Regression Models for Monotone Method					
Imputed Variable	Effect	Obs-Data	-----Imputation-----		
			1	2	3
Length2	Intercept	-0.04249	-0.049184	-0.055470	-0.051346
Length2	Length1	0.98587	1.001934	0.995275	0.992294
Regression Models for Monotone Method					
Imputed Variable	Effect		-----Imputation-----		
			4	5	
Length2	Intercept		-0.064193	-0.030719	
Length2	Length1		0.983122	0.995883	

Output 57.3.3 Regression Predicted Mean Matching Model

Regression Models for Monotone Predicted Mean Matching Method					
Imputed Variable	Effect	Obs Data	-----Imputation-----		
			1	2	3
Length3	Intercept	-0.01304	0.004134	-0.011417	-0.034177
Length3	Length1	-0.01332	0.025320	-0.037494	0.308765
Length3	Length2	0.98918	0.955510	1.025741	0.673374
Length3	Length1*Length2	-0.02521	-0.034964	-0.022017	-0.017919

Regression Models for Monotone Predicted Mean Matching Method			
Imputed Variable	Effect	-----Imputation-----	
		4	5
Length3	Intercept	-0.010532	0.004685
Length3	Length1	0.156606	-0.147118
Length3	Length2	0.828384	1.146440
Length3	Length1*Length2	-0.029335	-0.034671

After the completion of five imputations by default, the “Variance Information” table in [Output 57.3.4](#) displays the between-imputation variance, within-imputation variance, and total variance for combining complete-data inferences. The relative increase in variance due to missingness, the fraction of missing information, and the relative efficiency for each variable are also displayed. These statistics are described in the section “[Combining Inferences from Multiply Imputed Data Sets](#)” on page 4769.

Output 57.3.4 Variance Information

Variance Information				
Variable	-----Variance-----			DF
	Between	Within	Total	
Length2	0.000133	0.439512	0.439672	32.15
Length3	0.000386	0.486913	0.487376	32.131

Variance Information			
Variable	Relative Increase in Variance	Fraction Missing Information	Relative Efficiency
Length2	0.000363	0.000363	0.999927
Length3	0.000952	0.000951	0.999810

The “Parameter Estimates” table in [Output 57.3.5](#) displays a 95% mean confidence interval and a t statistic with its associated p -value for each of the hypotheses requested with the MU0= option.

Output 57.3.5 Parameter Estimates

Parameter Estimates					
Variable	Mean	Std Error	95% Confidence Limits		DF
Length2	33.104571	0.663078	31.75417	34.45497	32.15
Length3	38.424571	0.698123	37.00277	39.84637	32.131
Parameter Estimates					
Variable	Minimum	Maximum	Mu0	t for H0: Mean=Mu0	Pr > t
Length2	33.088571	33.117143	35.000000	-2.86	0.0074
Length3	38.397143	38.445714	45.000000	-9.42	<.0001

The following statements list the first 10 observations of the data set outex3 in [Output 57.3.6](#). Note that the imputed values of Length2 are rounded to the same precision as the observed values.

```
proc print data=outex3(obs=10);
  title 'First 10 Observations of the Imputed Data Set';
run;
```

Output 57.3.6 Imputed Data Set

First 10 Observations of the Imputed Data Set				
Obs	_Imputation_	Length1	Length2	Length3
1	1	23.2	25.4	30.0
2	1	24.0	26.3	31.2
3	1	23.9	26.5	31.1
4	1	26.3	29.0	33.5
5	1	26.5	29.0	34.7
6	1	26.8	29.7	34.7
7	1	26.8	28.8	34.7
8	1	27.6	30.0	35.0
9	1	27.6	30.0	35.1
10	1	28.5	30.7	36.2

Example 57.4: Monotone Logistic Regression Method for CLASS Variables

This example uses logistic regression method to impute values for a binary variable in a data set with a monotone missing pattern.

In the following statements, the logistic regression method is used for the binary CLASS variable Species:

```
proc mi data=Fish2 seed=1305417 out=outex4;
  class Species;
  monotone reg( Length Width/ details)
    logistic( Species= Length Height Width Height*Width/ details);
  var Length Height Width Species;
run;
```

The “Model Information” table in [Output 57.4.1](#) describes the method and options used in the multiple imputation process.

Output 57.4.1 Model Information

The MI Procedure	
Model Information	
Data Set	WORK.FISH2
Method	Monotone
Number of Imputations	5
Seed for random number generator	1305417

The “Monotone Model Specification” table in [Output 57.4.2](#) describes methods and imputed variables in the imputation model. The procedure uses the logistic regression method to impute the variable Species in the model. Missing values in other variables are not imputed.

Output 57.4.2 Monotone Model Specification

Monotone Model Specification	
Method	Imputed Variables
Regression	Height Width
Logistic Regression	Species

The “Missing Data Patterns” table in [Output 57.4.3](#) lists distinct missing data patterns with corresponding frequencies and percentages. The table confirms a monotone missing pattern for these variables.

Output 57.4.3 Missing Data Patterns

Missing Data Patterns						
Group	Length	Height	Width	Species	Freq	Percent
1	X	X	X	X	43	82.69
2	X	X	X	.	3	5.77
3	X	X	.	.	4	7.69
4	X	.	.	.	2	3.85

Missing Data Patterns				
-----Group Means-----				
Group	Length	Height	Width	
1	41.997674	12.819512	5.359860	
2	38.433333	11.797667	4.587667	
3	42.275000	13.346750	.	
4	40.150000	.	.	

When you use the DETAILS option, parameters estimated from the observed data and the parameters used in each imputation are displayed in the “Logistic Models for Monotone Method” table in [Output 57.4.4](#).

Output 57.4.4 Regression Model

Regression Models for Monotone Method					
Imputed Variable	Effect	Obs-Data	-----Imputation-----		
			1	2	3
Width	Intercept	0.00682	0.054140	0.018049	-0.015137
Width	Length	0.75519	0.838485	0.768945	0.789577
Width	Height	0.73890	0.832117	0.831748	0.809482

Regression Models for Monotone Method			
Imputed Variable	Effect	-----Imputation-----	
		4	5
Width	Intercept	0.024027	0.084643
Width	Length	0.728779	0.631217
Width	Height	0.747734	0.745232

Output 57.4.5 Logistic Regression Model

Logistic Models for Monotone Method					
Imputed Variable	Effect	Obs-Data	-----Imputation-----		
			1	2	3
Species	Intercept	22.80713	22.807129	22.807129	22.807129
Species	Length	-14.44698	-14.446980	-14.446980	-14.446980
Species	Height	43.11236	43.112363	43.112363	43.112363
Species	Width	-9.64352	-9.643524	-9.643524	-9.643524
Species	Height*Width	-9.73015	-9.730154	-9.730154	-9.730154

Logistic Models for Monotone Method					
Imputed Variable	Effect		-----Imputation-----		
			4	5	
Species	Intercept		22.807129	22.807129	
Species	Length		-14.446980	-14.446980	
Species	Height		43.112363	43.112363	
Species	Width		-9.643524	-9.643524	
Species	Height*Width		-9.730154	-9.730154	

The following statements list the first 10 observations of the data set outex4 in [Output 57.4.5](#):

```
proc print data=outex4(obs=10);
  title 'First 10 Observations of the Imputed Data Set';
run;
```

Output 57.4.6 Imputed Data Set

First 10 Observations of the Imputed Data Set					
Obs	_Imputation_	Species	Length	Height	Width
1	1	Bream	30.0	11.520	4.02000
2	1	Bream	31.2	12.480	4.30600
3	1	Bream	31.1	12.378	4.69600
4	1	Bream	33.5	12.730	4.45600
5	1	Bream	34.0	12.444	4.62964
6	1	Bream	34.7	13.602	4.92700
7	1	Bream	34.5	14.180	5.27900
8	1	Bream	35.0	12.670	4.69000
9	1	Bream	35.1	14.005	4.84400
10	1	Bream	36.2	14.227	4.95900

Note that a missing value of the variable Species is not imputed if the corresponding covariates are missing and not imputed, as shown by observation 4 in the table.

Example 57.5: Monotone Discriminant Function Method for CLASS Variables

This example uses discriminant monotone methods to impute values of a CLASS variable from the observed observation values in a data set with a monotone missing pattern.

The following statements impute the continuous variables Height and Width with the regression method and the classification variable Species with the discriminant function method:

```
proc mi data=Fish2 seed=7545417 nimpute=3 out=outex5;
  class Species;
  monotone reg( Height Width)
           discrim( Species= Length Height Width/ details);
  var Length Height Width Species;
run;
```

The “Model Information” table in [Output 57.5.1](#) describes the method and options used in the multiple imputation process.

Output 57.5.1 Model Information

The MI Procedure	
Model Information	
Data Set	WORK.FISH2
Method	Monotone
Number of Imputations	3
Seed for random number generator	7545417

The “Monotone Model Specification” table in [Output 57.5.2](#) describes methods and imputed variables in the imputation model. The procedure uses the regression method to impute the variables Height and Width, and uses the logistic regression method to impute the variable Species in the model.

Output 57.5.2 Monotone Model Specification

Monotone Model Specification	
Method	Imputed Variables
Regression	Height Width
Discriminant Function	Species

The “Missing Data Patterns” table in [Output 57.5.3](#) lists distinct missing data patterns with corresponding frequencies and percentages. The table confirms a monotone missing pattern for these variables.

Output 57.5.3 Missing Data Patterns

Missing Data Patterns						
Group	Length	Height	Width	Species	Freq	Percent
1	X	X	X	X	43	82.69
2	X	X	X	.	3	5.77
3	X	X	.	.	4	7.69
4	X	.	.	.	2	3.85

Missing Data Patterns						
-----Group Means-----						
Group	Length	Height	Width			
1	41.997674	12.819512	5.359860			
2	38.433333	11.797667	4.587667			
3	42.275000	13.346750	.			
4	40.150000	.	.			

When you use the DETAILS option, the parameters estimated from the observed data and the parameters used in each imputation are displayed in [Output 57.5.4](#).

Output 57.5.4 Discriminant Model

Group Means for Monotone Discriminant Method					
Species	Variable	Obs-Data	-----Imputation-----		
			1	2	3
Bream	Length	-0.36712	-0.198907	-0.375696	-0.307771
Bream	Height	0.64051	0.756448	0.684845	0.658337
Bream	Width	0.20882	0.465034	0.254438	0.252637
Pike	Length	0.85554	0.656521	0.677957	1.024069
Pike	Height	-1.31185	-1.431954	-1.436355	-1.119520
Pike	Width	-0.25768	-0.381503	-0.420441	-0.136188

The following statements list the first 10 observations of the data set outex5 in [Output 57.5.5](#). Note that all missing values of the variables Width and Species are imputed.

```
proc print data=outex5(obs=10);
  title 'First 10 Observations of the Imputed Data Set';
run;
```

Output 57.5.5 Imputed Data Set

First 10 Observations of the Imputed Data Set					
Obs	_Imputation_	Species	Length	Height	Width
1	1	Bream	30.0	11.520	4.02000
2	1	Bream	31.2	12.480	4.30600
3	1	Bream	31.1	12.378	4.69600
4	1	Bream	33.5	12.730	4.45600
5	1	Bream	34.0	12.444	4.46687
6	1	Bream	34.7	13.602	4.92700
7	1	Bream	34.5	14.180	5.27900
8	1	Bream	35.0	12.670	4.69000
9	1	Bream	35.1	14.005	4.84400
10	1	Bream	36.2	14.227	4.95900

Example 57.6: FCS Method for Continuous Variables

This example uses FCS regression methods to impute values for all continuous variables in a data set with an arbitrary missing pattern.

The following statements invoke the MI procedure and impute missing values for the Fitness1 data set:

```
proc mi data=Fitness1 seed=1213 nimpute=4 mu0=50 10 180 out=outex6;
  fcs nbiter=20 reg(/details);
  var Oxygen RunTime RunPulse;
run;
```

The NIMPUTE=4 option specifies the total number of imputations. The FCS statement requests multivariate imputations by FCS methods, and the NBITER=20 option (which is the default) specifies the number of burn-in iterations before each imputation.

The “Model Information” table in [Output 57.6.1](#) describes the method and options used in the multiple imputation process.

Output 57.6.1 Model Information

The MI Procedure	
Model Information	
Data Set	WORK.FITNESS1
Method	FCS
Number of Imputations	4
Number of Burn-in Iterations	20
Seed for random number generator	1213

The “FCS Model Specification” table in [Output 57.6.2](#) describes methods and imputed variables in the imputation model. With the REG option in the FCS statement, the procedure uses the regression method to

impute variables RunTime, RunPulse, and Oxygen in the model.

Output 57.6.2 FCS Model Specification

FCS Model Specification			
Method	Imputed Variables		
Regression	Oxygen	RunTime	RunPulse

The “Missing Data Patterns” table in [Output 57.6.3](#) lists distinct missing data patterns with corresponding frequencies and percentages.

Output 57.6.3 Missing Data Patterns

Missing Data Patterns					
Group	Oxygen	Run Time	Run Pulse	Freq	Percent
1	X	X	X	21	67.74
2	X	X	.	4	12.90
3	X	.	.	3	9.68
4	.	X	X	1	3.23
5	.	X	.	2	6.45

Missing Data Patterns			
Group	-----Group Means-----		
	Oxygen	RunTime	RunPulse
1	46.353810	10.809524	171.666667
2	47.109500	10.137500	.
3	52.461667	.	.
4	.	11.950000	176.000000
5	.	9.885000	.

When you use the DETAILS option, the parameters used in each imputation are displayed in [Output 57.6.4](#), [Output 57.6.5](#), and [Output 57.6.6](#).

Output 57.6.4 FCS Regression Model for Oxygen

Regression Models for FCS Method					
Imputed Variable	Effect	-----Imputation-----			
		1	2	3	4
Oxygen	Intercept	-0.132359	0.093555	0.078587	0.063256
Oxygen	RunTime	-0.908663	-0.753423	-1.125549	-0.634844
Oxygen	RunPulse	-0.134745	0.052640	-0.135864	-0.158692

Output 57.6.5 FCS Regression Model for RunTime

The MI Procedure					
Regression Models for FCS Method					
Imputed Variable	Effect	-----Imputation-----			
		1	2	3	4
RunTime	Intercept	-0.127880	-0.125666	-0.074802	0.058724
RunTime	Oxygen	-0.592047	-1.067554	-1.020216	-0.827592
RunTime	RunPulse	0.110865	-0.311273	-0.158049	0.060715

Output 57.6.6 FCS Regression Model for RunPulse

The MI Procedure					
Regression Models for FCS Method					
Imputed Variable	Effect	-----Imputation-----			
		1	2	3	4
RunPulse	Intercept	-0.072862	-0.089964	0.049778	0.082088
RunPulse	Oxygen	0.226951	-0.439850	-0.440705	-0.353438
RunPulse	RunTime	0.545914	0.067482	0.234528	-0.273761

The following statements list the first 10 observations of the data set outex6 in [Output 57.6.7](#). Note that all missing values of all variables are imputed.

```
proc print data=outex6(obs=10);
  title 'First 10 Observations of the Imputed Data Set';
run;
```

Output 57.6.7 Imputed Data Set

First 10 Observations of the Imputed Data Set				
Obs	_Imputation_	Oxygen	RunTime	Run Pulse
1	1	44.6090	11.3700	178.000
2	1	45.3130	10.0700	185.000
3	1	54.2970	8.6500	156.000
4	1	59.5710	10.1985	185.842
5	1	49.8740	9.2200	173.379
6	1	44.8110	11.6300	176.000
7	1	44.6299	11.9500	176.000
8	1	47.4258	10.8500	183.926
9	1	39.4420	13.0800	174.000
10	1	60.0550	8.6300	170.000

After the completion of the specified four imputations, the “Variance Information” table in [Output 57.6.8](#) displays the between-imputation variance, within-imputation variance, and total variance for combining complete-data inferences. The relative increase in variance due to missingness, the fraction of missing information, and the relative efficiency for each variable are also displayed. These statistics are described in the section “Combining Inferences from Multiply Imputed Data Sets” on page 4769.

Output 57.6.8 Variance Information

Variance Information				
Variable	-----Variance-----			DF
	Between	Within	Total	
Oxygen	0.044012	0.936794	0.991809	25.911
RunTime	0.002518	0.063583	0.066730	26.328
RunPulse	3.552893	3.488832	7.929948	5.3995

Variance Information			
Variable	Relative Increase in Variance	Fraction Missing Information	Relative Efficiency
Oxygen	0.058727	0.057401	0.985853
RunTime	0.049500	0.048575	0.988002
RunPulse	1.272952	0.630073	0.863917

The “Parameter Estimates” table in [Output 57.6.9](#) displays a 95% mean confidence interval and a t statistic with its associated p -value for each of the hypotheses requested with the MU0= option.

Output 57.6.9 Parameter Estimates

Parameter Estimates					
Variable	Mean	Std Error	95% Confidence Limits		DF
Oxygen	47.200681	0.995896	45.1532	49.2481	25.911
RunTime	10.578418	0.258322	10.0478	11.1091	26.328
RunPulse	171.368390	2.816016	164.2877	178.4490	5.3995

Parameter Estimates					
Variable	Minimum	Maximum	Mu0	t for H0:	Pr > t
				Mean=Mu0	
Oxygen	47.075129	47.512585	50.000000	-2.81	0.0093
RunTime	10.526891	10.627704	10.000000	2.24	0.0338
RunPulse	168.633931	172.932612	180.000000	-3.07	0.0253

Example 57.7: FCS Method for CLASS Variables

This example uses FCS methods to impute missing values in both continuous and CLASS variables in a data set with an arbitrary missing pattern. The following statements invoke the MI procedure and impute missing values for the Fish3 data set:

```
proc mi data=Fish3 seed=1305417 out=outex7;
  class Species;
  fcs nbiter=10 discrim(Species/details) reg(Height/details);
  var Species Length Height Width;
run;
```

The DISCRIM option uses the discriminant function method to impute the classification variable *Species*, and the REG option uses the regression method to impute the continuous variable *Height*. By default, the regression method is also used to impute other continuous variables, *Length* and *Width*.

The “Model Information” table in [Output 57.7.1](#) describes the method and options used in the multiple imputation process.

Output 57.7.1 Model Information

The MI Procedure	
Model Information	
Data Set	WORK.FISH3
Method	FCS
Number of Imputations	5
Number of Burn-in Iterations	10
Seed for random number generator	1305417

The “FCS Model Specification” table in [Output 57.7.2](#) describes methods and imputed variables in the imputation model. The procedure uses the discriminant function method to impute the variable *Species*, and the regression method to impute other variables.

Output 57.7.2 FCS Model Specification

FCS Model Specification		
Method	Imputed Variables	
Regression	Length	Height Width
Discriminant Function	Species	

The “Missing Data Patterns” table in [Output 57.7.3](#) lists distinct missing data patterns with corresponding frequencies and percentages.

Output 57.7.3 Missing Data Patterns

Missing Data Patterns						
Group	Species	Length	Height	Width	Freq	Percent
1	X	X	X	X	38	73.08
2	X	.	X	X	2	3.85
3	X	.	X	.	1	1.92
4	.	X	X	X	3	5.77
5	.	X	X	.	3	5.77
6	.	X	.	X	2	3.85
7	.	X	.	.	2	3.85
8	.	.	X	.	1	1.92

Missing Data Patterns			
-----Group Means-----			
Group	Length	Height	Width
1	41.515789	12.531526	5.266474
2	.	14.448000	6.886000
3	.	18.037000	.
4	38.433333	11.797667	4.587667
5	45.033333	13.647667	.
6	36.100000	.	5.135000
7	40.150000	.	.
8	.	12.444000	.

With the specified DETAILS option for variables Species and Height, parameters used in each imputation for these two variables are displayed in the “Group Means for FCS Discriminant Method” table in [Output 57.7.4](#) and in the “Regression Models for FCS Method” table in [Output 57.7.5](#).

Output 57.7.4 FCS Discrim Model for Species

Group Means for FCS Discriminant Method					
Species	Variable	-----Imputation-----			
		1	2	3	4
Bream	Length	-0.635560	-0.539102	-0.183231	-0.312298
Bream	Height	0.505922	0.540880	0.761373	0.736716
Bream	Width	-0.203055	0.030787	0.403116	0.422214
Pike	Length	1.074270	0.904169	0.409041	1.234640
Pike	Height	-1.293411	-1.359962	-1.418251	-1.177828
Pike	Width	0.060791	-0.463132	-0.702662	0.004479

Group Means for FCS Discriminant Method			
Species	Variable	-----Imputation-----	
		5	
Bream	Length	-0.501390	
Bream	Height	0.582379	
Bream	Width	0.080807	
Pike	Length	0.479436	
Pike	Height	-1.428490	
Pike	Width	-0.659505	

Output 57.7.5 FCS Regression Model for Height

Regression Models for FCS Method					
Imputed Variable	Effect	Species	-----Imputation-----		
			1	2	3
Height	Intercept		-0.366066	-0.359325	-0.272079
Height	Species	Bream	0.973036	0.980092	0.818649
Height	Length		0.170407	0.099879	-0.018424
Height	Width		0.242966	0.382906	0.430107

Regression Models for FCS Method			
Imputed Variable	Effect	-----Imputation-----	
		4	5
Height	Intercept	-0.353772	-0.357781
Height	Species	1.035374	0.963826
Height	Length	0.187469	0.090964
Height	Width	0.299173	0.325195

The following statements list the first 10 observations of the data set outex7 in [Output 57.7.6](#):

```
proc print data=outex7(obs=10);
  title 'First 10 Observations of the Imputed Data Set';
run;
```

Output 57.7.6 Imputed Data Set

First 10 Observations of the Imputed Data Set					
Obs	_Imputation_	Species	Length	Height	Width
1	1	Bream	30.0000	11.5200	4.02000
2	1	Bream	31.2000	12.4800	4.30600
3	1	Bream	31.1000	12.3780	4.69600
4	1	Bream	33.5000	12.7300	4.45600
5	1	Pike	68.6009	12.4440	7.65040
6	1	Bream	34.7000	13.6020	4.92700
7	1	Bream	34.5000	14.1800	5.27900
8	1	Pike	35.0000	5.7684	4.69000
9	1	Bream	35.1000	14.0050	4.84400
10	1	Bream	36.2000	14.2270	4.95900

After the completion of five imputations by default, the “Variance Information” table in [Output 57.7.7](#) displays the between-imputation variance, within-imputation variance, and total variance for combining complete-data inferences for continuous variables. The relative increase in variance due to missingness, the fraction of missing information, and the relative efficiency for each variable are also displayed. These statistics are described in the section “[Combining Inferences from Multiply Imputed Data Sets](#)” on page 4769.

Output 57.7.7 Variance Information

Variance Information				
Variable	-----Variance-----			DF
	Between	Within	Total	
Length	0.076551	1.351968	1.443828	43.942
Height	0.024597	0.311347	0.340863	41.379
Width	0.000307	0.015361	0.015730	47.645
Variance Information				
Variable	Relative Increase in Variance	Fraction Missing Information	Relative Efficiency	
Length	0.067946	0.065513	0.987067	
Height	0.094801	0.089997	0.982319	
Width	0.024018	0.023723	0.995278	

The “Parameter Estimates” table in [Output 57.7.8](#) displays a 95% mean confidence interval and a t statistic with its associated p -value for each of the hypotheses requested with the default MU0=0 option.

Output 57.7.8 Parameter Estimates

Parameter Estimates					
Variable	Mean	Std Error	95% Confidence Limits		DF
Length	41.952213	1.201594	39.53047	44.37396	43.942
Height	12.785938	0.583835	11.60719	13.96469	41.379
Width	5.345132	0.125420	5.09291	5.59735	47.645
Parameter Estimates					
Variable	Minimum	Maximum	t for H0:		
			Mu0	Mean=Mu0	Pr > t
Length	41.702410	42.286360	0	34.91	<.0001
Height	12.555560	12.988405	0	21.90	<.0001
Width	5.324639	5.366759	0	42.62	<.0001

Example 57.8: FCS Method with Trace Plot

This example uses FCS methods to impute missing values in both continuous and classification variables in a data set with an arbitrary missing pattern. The following statements use a logistic regression method to impute values of the classification variable Species:

```
ods graphics on;
proc mi data=Fish3 seed=1305417 out=outex8;
  class Species;
  fcs plots=trace
    logistic(Species= Height Width Height*Width /details);
  var Species Height Width;
run;
ods graphics off;
```

The “Model Information” table in [Output 57.8.1](#) describes the method and options used in the multiple imputation process. By default, a regression method is used to impute missing values in each continuous variable.

Output 57.8.1 Model Information

The MI Procedure	
Model Information	
Data Set	WORK.FISH3
Method	FCS
Number of Imputations	5
Number of Burn-in Iterations	20
Seed for random number generator	1305417

The “FCS Model Specification” table in [Output 57.8.2](#) describes methods and imputed variables in the imputation model. The procedure uses the logistic regression method to impute the variable Species, and the regression method to impute variables Height and Width.

Output 57.8.2 FCS Model Specification

FCS Model Specification	
Method	Imputed Variables
Regression	Height Width
Logistic Regression	Species

The “Missing Data Patterns” table in [Output 57.8.3](#) lists distinct missing data patterns with corresponding frequencies and percentages.

Output 57.8.3 Missing Data Patterns

Missing Data Patterns							
Group	Species	Height	Width	Freq	Percent	-----Group Means-----	
						Height	Width
1	X	X	X	40	76.92	12.627350	5.347450
2	X	X	.	1	1.92	18.037000	.
3	.	X	X	3	5.77	11.797667	4.587667
4	.	X	.	4	7.69	13.346750	.
5	.	.	X	2	3.85	.	5.135000
6	O	O	O	2	3.85	.	.

When you use the DETAILS keyword in the LOGISTIC option, parameters estimated from the observed data and the parameters used in each imputation are displayed in the “Logistic Models for FCS Method” table in [Output 57.8.4](#).

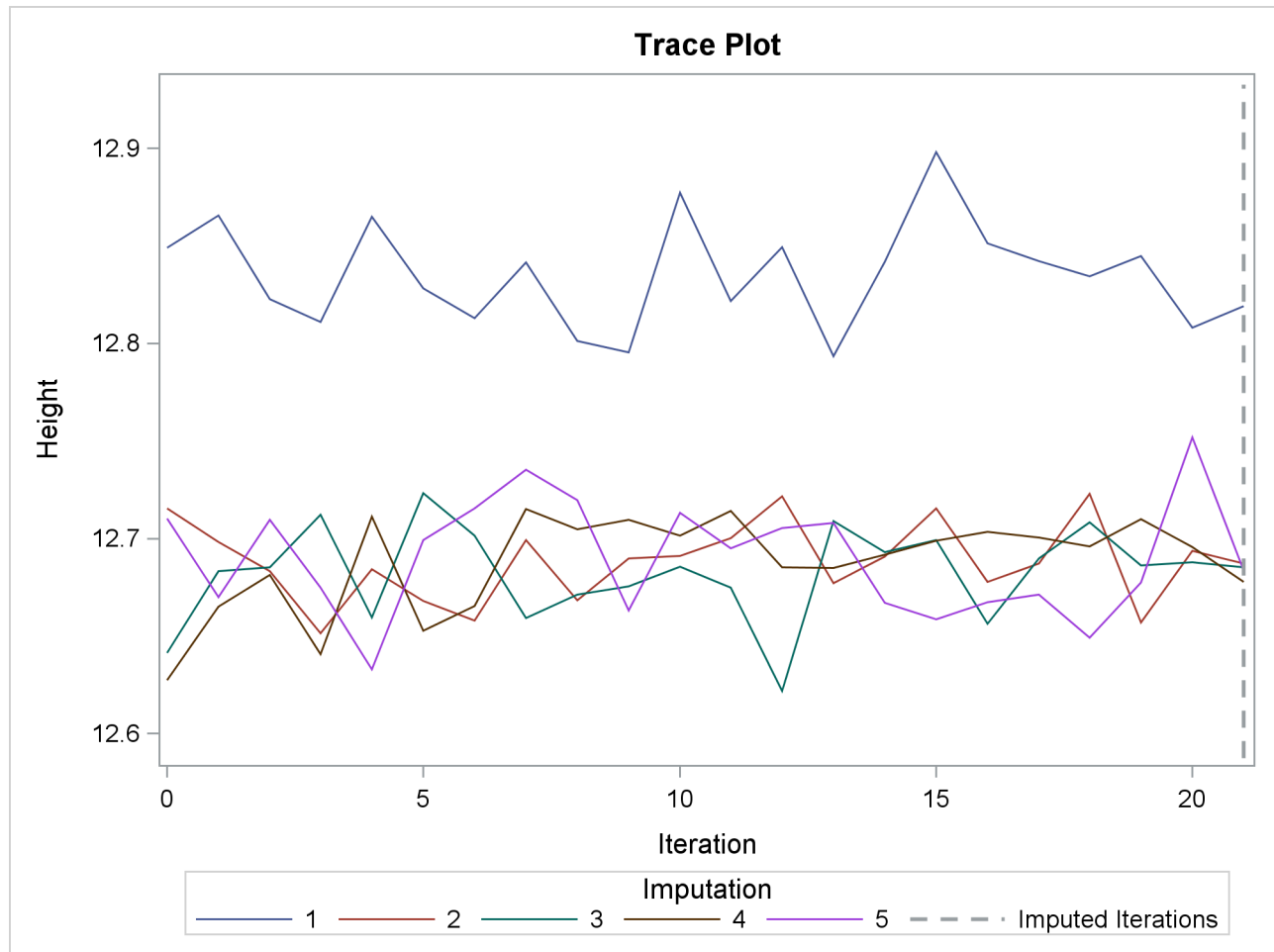
Output 57.8.4 FCS Logistic Regression Model for Species

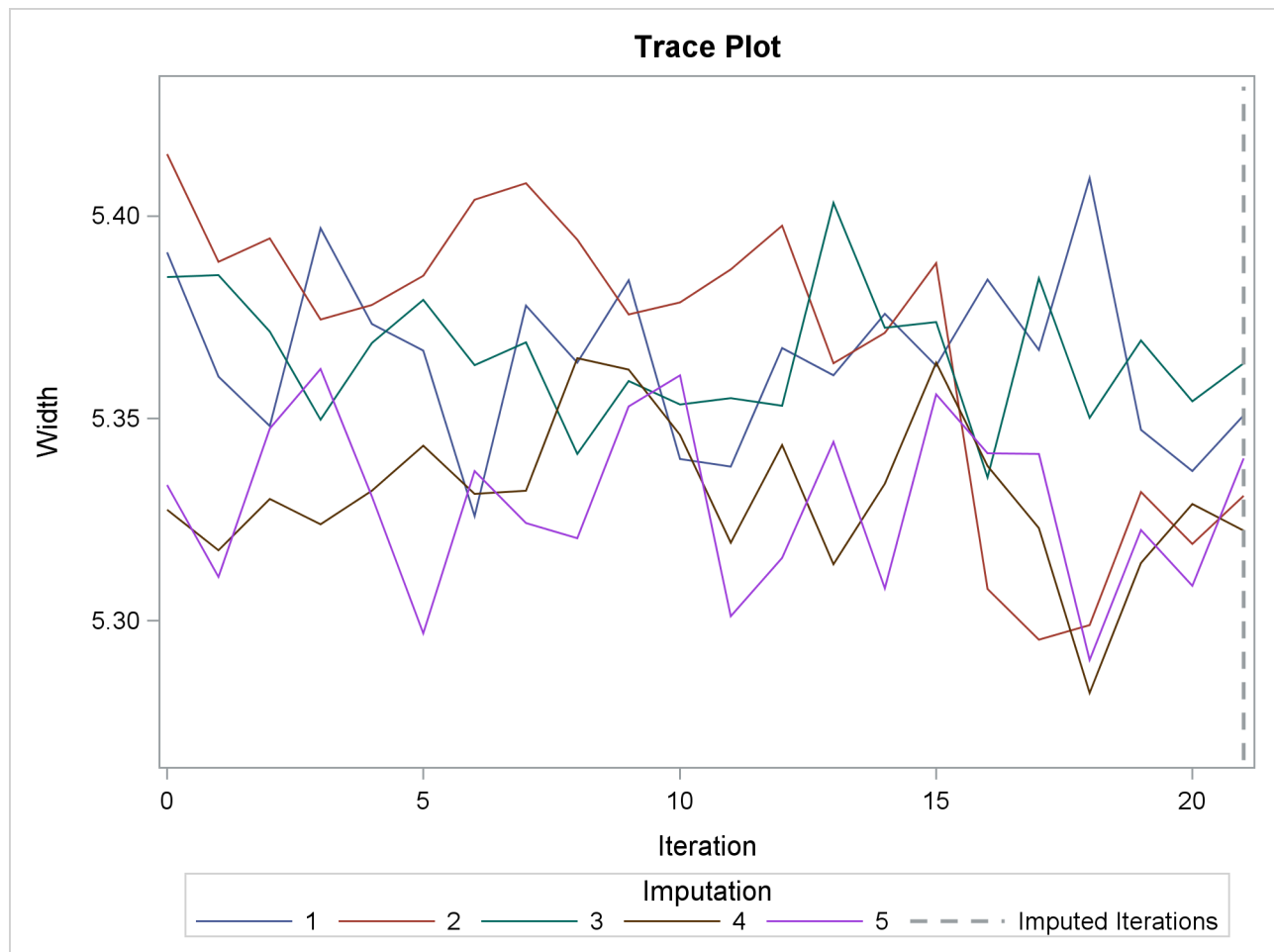
Logistic Models for FCS Method					
Imputed Variable	Effect	-----Imputation-----			
		1	2	3	4
Species	Intercept	27.250540	27.240843	27.242699	27.254682
Species	Height	59.970974	59.962249	59.964027	59.980855
Species	Width	-26.032805	-26.021304	-26.023556	-26.028866
Species	Height*Width	-6.760308	-6.739118	-6.742934	-6.754780

Logistic Models for FCS Method		
Imputed Variable	Effect	-Imputation- 5
Species	Intercept	27.251468
Species	Height	59.971742
Species	Width	-26.033865
Species	Height*Width	-6.762477

With ODS Graphics enabled, the PLOTS=TRACE option displays trace plots of means for all continuous variables by default, as shown in [Output 57.8.5](#) and [Output 57.8.6](#). The dashed vertical lines indicate the imputed iterations—that is, the variable values used in the imputations. The plot shows no apparent trends for the two variables.

Output 57.8.5 Trace Plot for Height



Output 57.8.6 Trace Plot for Width

The following statements list the first 10 observations of the data set outex8 in [Output 57.8.7](#):

```
proc print data=outex8(obs=10);
  title 'First 10 Observations of the Imputed Data Set';
run;
```

Output 57.8.7 Imputed Data Set

First 10 Observations of the Imputed Data Set					
Obs	_Imputation_	Species	Length	Height	Width
1	1	Bream	30.0000	11.5200	4.02000
2	1	Bream	31.2000	12.4800	4.30600
3	1	Bream	31.1000	12.3780	4.69600
4	1	Bream	33.5000	12.7300	4.45600
5	1	Pike	68.0455	12.4440	6.46920
6	1	Bream	34.7000	13.6020	4.92700
7	1	Bream	34.5000	14.1800	5.27900
8	1	Pike	35.0000	4.9290	4.69000
9	1	Bream	35.1000	14.0050	4.84400
10	1	Bream	36.2000	14.2270	4.95900

After the completion of five imputations by default, the “Variance Information” table in [Output 57.8.8](#) displays the between-imputation variance, within-imputation variance, and total variance for combining complete-data inferences for continuous variables. The relative increase in variance due to missingness, the fraction of missing information, and the relative efficiency for each variable are also displayed. These statistics are described in the section “[Combining Inferences from Multiply Imputed Data Sets](#)” on page 4769.

Output 57.8.8 Variance Information

Variance Information				
Variable	-----Variance-----			DF
	Between	Within	Total	
Height	0.003691	0.318783	0.323212	46.369
Width	0.001464	0.017777	0.019534	39.458
Variance Information				
Variable	Relative Increase in Variance	Fraction Missing Information	Relative Efficiency	
Height	0.013894	0.013797	0.997248	
Width	0.098807	0.093580	0.981628	

The “Parameter Estimates” table in [Output 57.8.9](#) displays a 95% mean confidence interval and a t statistic with its associated p -value for each of the hypotheses requested with the default MU0=0 option.

Output 57.8.9 Parameter Estimates

Parameter Estimates					
Variable	Mean	Std Error	95% Confidence Limits		DF
Height	12.710577	0.568517	11.56646	13.85470	46.369
Width	5.331652	0.139764	5.04906	5.61425	39.458
Parameter Estimates					
Variable	Minimum	Maximum	t for H0: Mean=Mu0 Pr > t		
Height	12.677842	12.819080	0	22.36	<.0001
Width	5.287861	5.393360	0	38.15	<.0001

Example 57.9: MCMC Method

This example uses the MCMC method to impute missing values for a data set with an arbitrary missing pattern. The following statements invoke the MI procedure and specify the MCMC method with six imputations:

```
proc mi data=Fitness1 seed=21355417 nimpute=6 mu0=50 10 180 ;
  mcmc chain=multiple displayinit initial=em(itprint);
  var Oxygen RunTime RunPulse;
run;
```

The “Model Information” table in [Output 57.9.1](#) describes the method used in the multiple imputation process. When you use the CHAIN=MULTIPLE option, the procedure uses multiple chains and completes the default 200 burn-in iterations before each imputation. The 200 burn-in iterations are used to make the iterations converge to the stationary distribution before the imputation.

Output 57.9.1 Model Information

The MI Procedure	
Model Information	
Data Set	WORK.FITNESS1
Method	MCMC
Multiple Imputation Chain	Multiple Chains
Initial Estimates for MCMC	EM Posterior Mode
Start	Starting Value
Prior	Jeffreys
Number of Imputations	6
Number of Burn-in Iterations	200
Seed for random number generator	21355417

By default, the procedure uses a noninformative Jeffreys prior to derive the posterior mode from the EM algorithm as the starting values for the MCMC method.

The “Missing Data Patterns” table in [Output 57.9.2](#) lists distinct missing data patterns with corresponding statistics.

Output 57.9.2 Missing Data Patterns

Missing Data Patterns					
Group	Oxygen	Run Time	Run Pulse	Freq	Percent
1	X	X	X	21	67.74
2	X	X	.	4	12.90
3	X	.	.	3	9.68
4	.	X	X	1	3.23
5	.	X	.	2	6.45

Missing Data Patterns			
-----Group Means-----			
Group	Oxygen	RunTime	RunPulse
1	46.353810	10.809524	171.666667
2	47.109500	10.137500	.
3	52.461667	.	.
4	.	11.950000	176.000000
5	.	9.885000	.

When you use the ITPRINT option within the INITIAL=EM option, the procedure displays the “EM (Posterior Mode) Iteration History” table in [Output 57.9.3](#).

Output 57.9.3 EM (Posterior Mode) Iteration History

EM (Posterior Mode) Iteration History				
Iteration	-2 Log L	-2 Log Posterior	Oxygen	RunTime
0	254.482800	282.909549	47.104077	10.554858
1	255.081168	282.051584	47.104077	10.554857
2	255.271408	282.017488	47.104077	10.554857
3	255.318622	282.015372	47.104002	10.554523
4	255.330259	282.015232	47.103861	10.554388
5	255.333161	282.015222	47.103797	10.554341
6	255.333896	282.015222	47.103774	10.554325
7	255.334085	282.015222	47.103766	10.554320

EM (Posterior Mode) Iteration History	
Iteration	RunPulse
0	171.381669
1	171.381652
2	171.381644
3	171.381842
4	171.382053
5	171.382150
6	171.382185
7	171.382196

When you use the `DISPLAYINIT` option in the MCMC statement, the “Initial Parameter Estimates for MCMC” table in [Output 57.9.4](#) displays the starting mean and covariance estimates used in the MCMC method. The same starting estimates are used in the MCMC method for multiple chains because the EM algorithm is applied to the same data set in each chain. You can explicitly specify different initial estimates for different imputations, or you can use the bootstrap method to generate different parameter estimates from the EM algorithm for the MCMC method.

Output 57.9.4 Initial Parameter Estimates

Initial Parameter Estimates for MCMC				
TYPE	_NAME_	Oxygen	RunTime	RunPulse
MEAN		47.103766	10.554320	171.382196
COV	Oxygen	24.549967	-5.726112	-15.926036
COV	RunTime	-5.726112	1.781407	3.124798
COV	RunPulse	-15.926036	3.124798	83.164045

[Output 57.9.5](#) and [Output 57.9.6](#) display variance information and parameter estimates, respectively, from the multiple imputation.

Output 57.9.5 Variance Information

Variance Information				
Variable	-----Variance-----			DF
	Between	Within	Total	
Oxygen	0.051560	0.928170	0.988323	25.958
RunTime	0.003979	0.070057	0.074699	25.902
RunPulse	4.118578	4.260631	9.065638	7.5938

Variance Information			
Variable	Relative Increase in Variance	Fraction Missing Information	Relative Efficiency
Oxygen	0.064809	0.062253	0.989731
RunTime	0.066262	0.063589	0.989513
RunPulse	1.127769	0.575218	0.912517

Output 57.9.6 Parameter Estimates

Parameter Estimates					
Variable	Mean	Std Error	95% Confidence Limits		DF
Oxygen	47.164819	0.994145	45.1212	49.2085	25.958
RunTime	10.549936	0.273312	9.9880	11.1118	25.902
RunPulse	170.969836	3.010920	163.9615	177.9782	7.5938

Parameter Estimates					
Variable	Minimum	Maximum	Mu0	t for H0: Mean=Mu0	Pr > t
Oxygen	46.858020	47.363540	50.000000	-2.85	0.0084
RunTime	10.476886	10.659412	10.000000	2.01	0.0547
RunPulse	168.252615	172.894991	180.000000	-3.00	0.0182

Example 57.10: Producing Monotone Missingness with MCMC

This example uses the MCMC method to impute just enough missing values for a data set with an arbitrary missing pattern so that each imputed data set has a monotone missing pattern based on the order of variables in the VAR statement.

The following statements invoke the MI procedure and specify the IMPUTE=MONOTONE option to create the imputed data set with a monotone missing pattern. You must specify a VAR statement to provide the order of variables in order for the imputed data to achieve a monotone missing pattern.

```
proc mi data=Fitness1 seed=17655417 out=outex10;
  mcmc impute=monotone;
  var Oxygen RunTime RunPulse;
run;
```

The “Model Information” table in [Output 57.10.1](#) describes the method used in the multiple imputation process.

Output 57.10.1 Model Information

The MI Procedure	
Model Information	
Data Set	WORK.FITNESS1
Method	Monotone-data MCMC
Multiple Imputation Chain	Single Chain
Initial Estimates for MCMC	EM Posterior Mode
Start	Starting Value
Prior	Jeffreys
Number of Imputations	5
Number of Burn-in Iterations	200
Number of Iterations	100
Seed for random number generator	17655417

The “Missing Data Patterns” table in [Output 57.10.2](#) lists distinct missing data patterns with corresponding statistics. Here, an “X” means that the variable is observed in the corresponding group, a “.” means that the variable is missing and will be imputed to achieve the monotone missingness for the imputed data set, and an “O” means that the variable is missing and will not be imputed. The table also displays group-specific variable means.

Output 57.10.2 Missing Data Patterns

Missing Data Patterns					
Group	Oxygen	Run Time	Run Pulse	Freq	Percent
1	X	X	X	21	67.74
2	X	X	O	4	12.90
3	X	O	O	3	9.68
4	.	X	X	1	3.23
5	.	X	O	2	6.45

Missing Data Patterns			
-----Group Means-----			
Group	Oxygen	RunTime	RunPulse
1	46.353810	10.809524	171.666667
2	47.109500	10.137500	.
3	52.461667	.	.
4	.	11.950000	176.000000
5	.	9.885000	.

As shown in the table in [Output 57.10.2](#), the MI procedure needs to impute only three missing values from group 4 and group 5 to achieve a monotone missing pattern for the imputed data set.

When you use the MCMC method to produce an imputed data set with a monotone missing pattern, tables of variance information and parameter estimates are not created.

The following statements are used just to show the monotone missingness of the output data set outex10:

```
proc mi data=outex10 seed=15541 nimpute=0;
  var Oxygen RunTime RunPulse;
run;
```

The “Missing Data Patterns” table in [Output 57.10.3](#) displays a monotone missing data pattern.

Output 57.10.3 Monotone Missing Data Patterns

The MI Procedure					
Missing Data Patterns					
Group	Oxygen	Run Time	Run Pulse	Freq	Percent
1	X	X	X	110	70.97
2	X	X	.	30	19.35
3	X	.	.	15	9.68
Missing Data Patterns					
-----Group Means-----					
Group	Oxygen	RunTime	RunPulse		
1	46.152428	10.861364	171.863636		
2	47.796038	10.053333	.		
3	52.461667	.	.		

The following statements impute one value for each missing value in the monotone missingness data set outex10:

```
proc mi data=outex10 nimpute=1 seed=51343672 out=outex10a;
  monotone method=reg;
  var Oxygen RunTime RunPulse;
  by _Imputation_;
run;
```

You can then analyze these data sets by using other SAS procedures and combine these results by using the MIANALYZE procedure. Note that the VAR statement is required with a MONOTONE statement to provide the variable order for the monotone missing pattern.

Example 57.11: Checking Convergence in MCMC

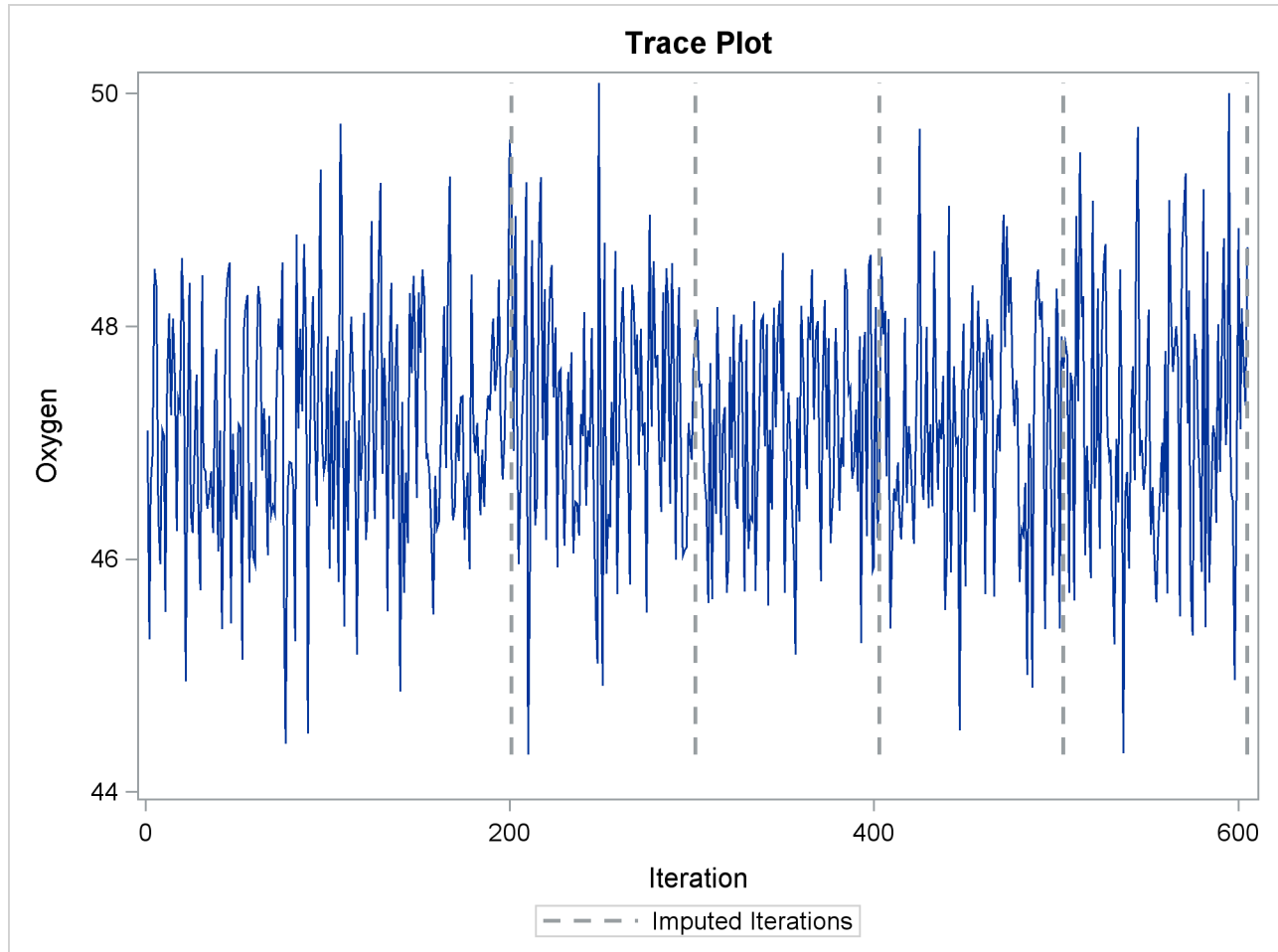
This example uses the MCMC method with a single chain. It also displays trace and autocorrelation plots to check convergence for the single chain.

The following statements use the MCMC method to create an iteration plot for the successive estimates of the mean of Oxygen. These statements also create an autocorrelation function plot for the variable Oxygen.

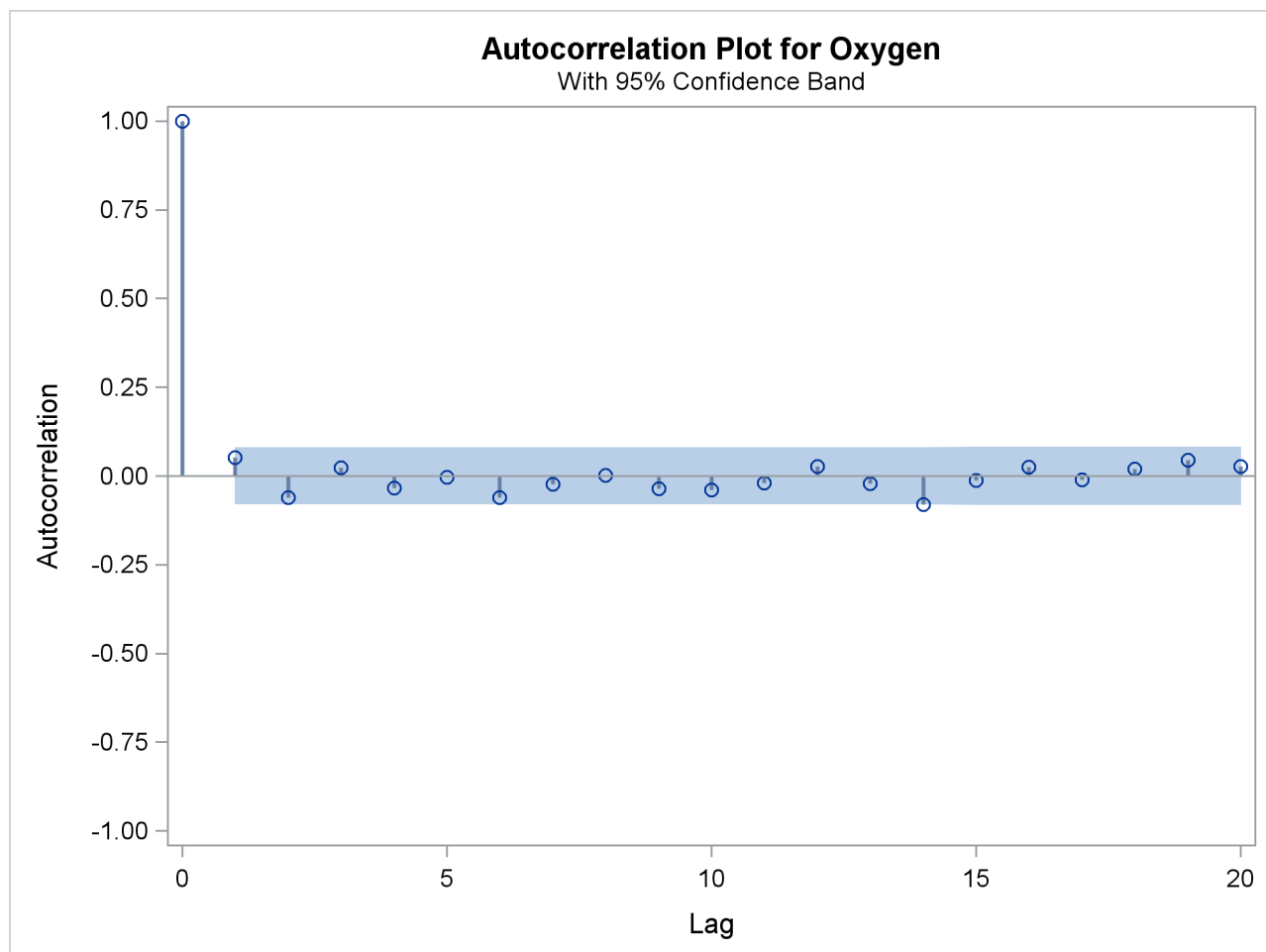
```
ods graphics on;
proc mi data=Fitness1 seed=501213 mu0=50 10 180;
  mcmc plots=(trace(mean(Oxygen)) acf(mean(Oxygen))) ;
  var Oxygen RunTime RunPulse;
run;
ods graphics off;
```

With ODS Graphics enabled, the TRACE(MEAN(OXYGEN)) option in the PLOTS= option displays the trace plot of means for the variable Oxygen, as shown in [Output 57.11.1](#). The dashed vertical lines indicate the imputed iterations—that is, the Oxygen values used in the imputations. The plot shows no apparent trends for the variable Oxygen.

Output 57.11.1 Trace Plot for Oxygen



The ACF(MEAN(OXYGEN)) option in the PLOTS= option displays the autocorrelation plot of means for the variable Oxygen, as shown in [Output 57.11.2](#). The autocorrelation function plot shows no significant positive or negative autocorrelation.

Output 57.11.2 Autocorrelation Function Plot for Oxygen

You can also create plots for the worst linear function, the means of other variables, the variances of variables, and the covariances between variables. Alternatively, you can use the OUTITER option to save statistics such as the means, standard deviations, covariances, $-2 \log LR$ statistic, $-2 \log LR$ statistic of the posterior mode, and worst linear function from each iteration in an output data set. Then you can do a more in-depth trace (time series) analysis of the iterations with other procedures, such as PROC AUTOREG and PROC ARIMA in the *SAS/ETS User's Guide*.

For general information about ODS Graphics, see Chapter 21, “[Statistical Graphics Using ODS](#).” For specific information about the graphics available in the MI procedure, see the section “[ODS Graphics](#)” on page 4775.

Example 57.12: Saving and Using Parameters for MCMC

This example uses the MCMC method with multiple chains as specified in [Example 57.9](#). It saves the parameter values used for each imputation in an output data set of type EST called `miest`. This output data set can then be used to impute missing values in other similar input data sets. The following statements invoke the MI procedure and specify the MCMC method with multiple chains to create three imputations:

```
proc mi data=Fitness1 seed=21355417 nimpute=6 mu0=50 10 180;
  mcmc chain=multiple initial=em outest=miest;
  var Oxygen RunTime RunPulse;
run;
```

The following statements list the parameters used for the imputations in [Output 57.12.1](#). Note that the data set includes observations with `_TYPE_='SEED'` which contains the seed to start the next random number generator.

```
proc print data=miest(obs=15);
  title 'Parameters for the Imputations';
run;
```

Output 57.12.1 OUTEST Data Set

Parameters for the Imputations						
Obs	_Imputation_	_TYPE_	_NAME_	Oxygen	RunTime	RunPulse
1	1	SEED		825240167.00	825240167.00	825240167.00
2	1	PARM		46.77	10.47	169.41
3	1	COV	Oxygen	30.59	-8.32	-50.99
4	1	COV	RunTime	-8.32	2.90	17.03
5	1	COV	RunPulse	-50.99	17.03	200.09
6	2	SEED		1895925872.00	1895925872.00	1895925872.00
7	2	PARM		47.41	10.37	173.34
8	2	COV	Oxygen	22.35	-4.44	-21.18
9	2	COV	RunTime	-4.44	1.76	1.25
10	2	COV	RunPulse	-21.18	1.25	125.67
11	3	SEED		137653011.00	137653011.00	137653011.00
12	3	PARM		48.21	10.36	170.52
13	3	COV	Oxygen	23.59	-5.25	-19.76
14	3	COV	RunTime	-5.25	1.66	5.00
15	3	COV	RunPulse	-19.76	5.00	110.99

The following statements invoke the MI procedure and use the `INEST=` option in the MCMC statement:

```
proc mi data=Fitness1 mu0=50 10 180;
  mcmc inest=miest;
  var Oxygen RunTime RunPulse;
run;
```

The “Model Information” table in [Output 57.12.2](#) describes the method used in the multiple imputation process. The remaining tables for the example are identical to the tables in [Output 57.9.2](#), [Output 57.9.4](#), [Output 57.9.5](#), and [Output 57.9.6](#) in [Example 57.9](#).

Output 57.12.2 Model Information

The MI Procedure	
Model Information	
Data Set	WORK.FITNESS1
Method	MCMC
INEST Data Set	WORK.MIEST
Number of Imputations	6

Example 57.13: Transforming to Normality

This example applies the MCMC method to the Fitness1 data set in which the variable Oxygen is transformed. Assume that Oxygen is skewed and can be transformed to normality with a logarithmic transformation. The following statements invoke the MI procedure and specify the transformation. The TRANSFORM statement specifies the log transformation for Oxygen. Note that the values displayed for Oxygen in all of the results correspond to transformed values.

```
proc mi data=Fitness1 seed=32937921 mu0=50 10 180 out=outex13;
  transform log(Oxygen);
  mcmc chain=multiple displayinit;
  var Oxygen RunTime RunPulse;
run;
```

The “Missing Data Patterns” table in [Output 57.13.1](#) lists distinct missing data patterns with corresponding statistics for the Fitness1 data. Note that the values of Oxygen shown in the tables are transformed values.

Output 57.13.1 Missing Data Patterns

The MI Procedure					
Missing Data Patterns					
Group	Oxygen	Run Time	Run Pulse	Freq	Percent
1	X	X	X	21	67.74
2	X	X	.	4	12.90
3	X	.	.	3	9.68
4	.	X	X	1	3.23
5	.	X	.	2	6.45

Transformed Variables: Oxygen

Missing Data Patterns			
-----Group Means-----			
Group	Oxygen	RunTime	RunPulse
1	3.829760	10.809524	171.666667
2	3.851813	10.137500	.
3	3.955298	.	.
4	.	11.950000	176.000000
5	.	9.885000	.

Transformed Variables: Oxygen

The “Variable Transformations” table in [Output 57.13.2](#) lists the variables that have been transformed.

Output 57.13.2 Variable Transformations

Variable Transformations	
Variable	_Transform_
Oxygen	LOG

The “Initial Parameter Estimates for MCMC” table in [Output 57.13.3](#) displays the starting mean and covariance estimates used in the MCMC method.

Output 57.13.3 Initial Parameter Estimates

Initial Parameter Estimates for MCMC				
<u>_TYPE_</u>	<u>_NAME_</u>	Oxygen	RunTime	RunPulse
MEAN		3.846122	10.557605	171.382949
COV	Oxygen	0.010827	-0.120891	-0.328772
COV	RunTime	-0.120891	1.744580	3.011180
COV	RunPulse	-0.328772	3.011180	82.747609
Transformed Variables: Oxygen				

[Output 57.13.4](#) displays variance information from the multiple imputation.

Output 57.13.4 Variance Information

Variance Information				
Variable	-----Variance-----			DF
	Between	Within	Total	
* Oxygen	0.000016175	0.000401	0.000420	26.499
RunTime	0.001762	0.065421	0.067536	27.118
RunPulse	0.205979	3.116830	3.364004	25.222
* Transformed Variables				
Variance Information				
Variable	Relative Increase in Variance	Fraction Missing Information	Relative Efficiency	
* Oxygen	0.048454	0.047232	0.990642	
RunTime	0.032318	0.031780	0.993684	
RunPulse	0.079303	0.075967	0.985034	
* Transformed Variables				

[Output 57.13.5](#) displays parameter estimates from the multiple imputation. Note that the parameter value of μ_0 has also been transformed using the logarithmic transformation.

Output 57.13.5 Parameter Estimates

Parameter Estimates					
Variable	Mean	Std Error	95% Confidence Limits		DF
* Oxygen	3.845175	0.020494	3.8031	3.8873	26.499
RunTime	10.560131	0.259876	10.0270	11.0932	27.118
RunPulse	171.802181	1.834122	168.0264	175.5779	25.222
* Transformed Variables					
Parameter Estimates					
Variable	Minimum	Maximum	Mu0	t for H0: Mean=Mu0	Pr > t
* Oxygen	3.838599	3.848456	3.912023	-3.26	0.0030
RunTime	10.493031	10.600498	10.000000	2.16	0.0402
RunPulse	171.251777	172.498626	180.000000	-4.47	0.0001
* Transformed Variables					

The following statements list the first 10 observations of the data set outex13 in [Output 57.13.6](#). Note that the values for Oxygen are in the original scale.

```
proc print data=outex13(obs=10);
  title 'First 10 Observations of the Imputed Data Set';
run;
```

Output 57.13.6 Imputed Data Set in Original Scale

First 10 Observations of the Imputed Data Set				
Obs	_Imputation_	Oxygen	RunTime	Run Pulse
1	1	44.6090	11.3700	178.000
2	1	45.3130	10.0700	185.000
3	1	54.2970	8.6500	156.000
4	1	59.5710	7.1440	167.012
5	1	49.8740	9.2200	170.092
6	1	44.8110	11.6300	176.000
7	1	38.5834	11.9500	176.000
8	1	43.7376	10.8500	158.851
9	1	39.4420	13.0800	174.000
10	1	60.0550	8.6300	170.000

Note that the results in [Output 57.13.6](#) can also be produced from the following statements without using a TRANSFORM statement. A transformed value of $\log(50)=3.91202$ is used in the MU0= option.

```
data temp;
    set Fitness1;
    LogOxygen= log(Oxygen);
run;
proc mi data=temp seed=14337921 mu0=3.91202 10 180 out=outtemp;
    mcmc chain=multiple displayinit;
    var LogOxygen RunTime RunPulse;
run;
data outex13;
    set outtemp;
    Oxygen= exp(LogOxygen);
run;
```

Example 57.14: Multistage Imputation

This example uses two separate imputation procedures to complete the imputation process. In the first case, the MI procedure statements use the MCMC method to impute just enough missing values for a data set with an arbitrary missing pattern so that each imputed data set has a monotone missing pattern. In the second case, the MI procedure statements use a MONOTONE statement to impute missing values for data sets with monotone missing patterns.

The following statements are identical to those in [Example 57.10](#). The statements invoke the MI procedure and specify the IMPUTE=MONOTONE option to create the imputed data set with a monotone missing pattern.

```
proc mi data=Fitness1 seed=17655417 out=outex14;
    mcmc impute=monotone;
    var Oxygen RunTime RunPulse;
run;
```

The “Missing Data Patterns” table in [Output 57.14.1](#) lists distinct missing data patterns with corresponding statistics. Here, an “X” means that the variable is observed in the corresponding group, a “.” means that the variable is missing and will be imputed to achieve the monotone missingness for the imputed data set, and an “O” means that the variable is missing and will not be imputed. The table also displays group-specific variable means.

Output 57.14.1 Missing Data Patterns

The MI Procedure					
Missing Data Patterns					
Group	Oxygen	Run Time	Run Pulse	Freq	Percent
1	X	X	X	21	67.74
2	X	X	O	4	12.90
3	X	O	O	3	9.68
4	.	X	X	1	3.23
5	.	X	O	2	6.45

Missing Data Patterns			
-----Group Means-----			
Group	Oxygen	RunTime	RunPulse
1	46.353810	10.809524	171.666667
2	47.109500	10.137500	.
3	52.461667	.	.
4	.	11.950000	176.000000
5	.	9.885000	.

As shown in the table, the MI procedure needs to impute only three missing values from group 4 and group 5 to achieve a monotone missing pattern for the imputed data set. When the MCMC method is used to produce an imputed data set with a monotone missing pattern, tables of variance information and parameter estimates are not created.

The following statements impute one value for each missing value in the monotone missingness data set outex14:

```
proc mi data=outex14
  nimpute=1 seed=51343672
  out=outex14a;
  monotone reg;
  var Oxygen RunTime RunPulse;
  by _Imputation_;
run;
```

You can then analyze these data sets by using other SAS procedures and combine these results by using the MIANALYZE procedure. Note that the VAR statement is required with a MONOTONE statement to provide the variable order for the monotone missing pattern.

The “Model Information” table in [Output 57.14.2](#) shows that a monotone method is used to generate imputed values in the first BY group.

Output 57.14.2 Model Information

----- Imputation Number=1 -----	
The MI Procedure	
Model Information	
Data Set	WORK.OUTEX14
Method	Monotone
Number of Imputations	1
Seed for random number generator	51343672

The “Monotone Model Specification” table in [Output 57.14.3](#) describes methods and imputed variables in the imputation model. The MI procedure uses the regression method to impute the variables RunTime and RunPulse in the model.

Output 57.14.3 Monotone Model Specification

----- Imputation Number=1 -----		
Monotone Model Specification		
Method	Imputed Variables	
Regression	RunTime	RunPulse

The “Missing Data Patterns” table in [Output 57.14.4](#) lists distinct missing data patterns with corresponding statistics. It shows a monotone missing pattern for the imputed data set.

Output 57.14.4 Missing Data Patterns

----- Imputation Number=1 -----					
Missing Data Patterns					
Group	Oxygen	Run Time	Run Pulse	Freq	Percent
1	X	X	X	22	70.97
2	X	X	.	6	19.35
3	X	.	.	3	9.68
Missing Data Patterns					
-----Group Means-----					
Group	Oxygen	RunTime	RunPulse		
1	46.057479	10.861364	171.863636		
2	46.745227	10.053333	.		
3	52.461667	.	.		

The following statements list the first 10 observations of the data set outex14a in [Output 57.14.5](#):

```
proc print data=outex14a(obs=10);
  title 'First 10 Observations of the Imputed Data Set';
run;
```

Output 57.14.5 Imputed Data Set

First 10 Observations of the Imputed Data Set				
Obs	_Imputation_	Oxygen	RunTime	Run Pulse
1	1	44.6090	11.3700	178.000
2	1	45.3130	10.0700	185.000
3	1	54.2970	8.6500	156.000
4	1	59.5710	7.1569	169.914
5	1	49.8740	9.2200	159.315
6	1	44.8110	11.6300	176.000
7	1	39.8345	11.9500	176.000
8	1	45.3196	10.8500	151.252
9	1	39.4420	13.0800	174.000
10	1	60.0550	8.6300	170.000

This example presents an alternative to the full-data MCMC imputation, in which imputation of only a few missing values is needed to achieve a monotone missing pattern for the imputed data set. The example uses a monotone MCMC method that imputes fewer missing values in each iteration and achieves approximate stationarity in fewer iterations (Schafer 1997, p. 227). The example also demonstrates how to combine the monotone MCMC method with a method for monotone missing data, which does not rely on iterations of steps.

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