SAS/OR® 13.2 User’s Guide: Mathematical Programming Legacy Procedures
The NETFLOW Procedure
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Chapter 6
The NETFLOW Procedure

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Overview: NETFLOW Procedure

Introduction

Constrained network models can be used to describe a wide variety of real-world applications ranging from production, inventory, and distribution problems to financial applications. These problems can be solved with the NETFLOW procedure.

These models are conceptually easy since they are based on network diagrams that represent the problem pictorially. PROC NETFLOW accepts the network specification in a format that is particularly suited to networks. This not only simplifies problem description but also aids in the interpretation of the solution.

Certain algebraic features of networks are exploited by a specialized version of the simplex method so that solution times are reduced. Another optimization algorithm, the interior point algorithm, has been implemented in PROC NETFLOW and can be used as an alternative to the simplex algorithm to solve network problems.

Should PROC NETFLOW detect there are no arcs and nodes in the model’s data, (that is, there is no network component), it assumes it is dealing with a linear programming (LP) problem. The interior point algorithm is automatically selected to perform the optimization.

You can also solve LP problems by using the OPTLP procedure. The OPTLP procedure requires a linear program to be specified by using a SAS data set that adheres to the MPS format, a widely accepted format in the optimization community. You can use the MPSOUT= option in the NETFLOW procedure to convert typical PROC NETFLOW format data sets into MPS-format SAS data sets.
Network Models

A network consists of a collection of nodes joined by a collection of arcs. The arcs connect nodes and convey flow of one or more commodities that are supplied at supply nodes and demanded at demand nodes in the network. Each arc has a cost per unit of flow, a flow capacity, and a lower flow bound associated with it. An important concept in network modeling is conservation of flow.

Conservation of flow means that the total flow in arcs directed toward a node, plus the supply at the node, minus the demand at the node, equals the total flow in arcs directed away from the node.

A network and its associated data can be described in SAS data sets. PROC NETFLOW uses this description and finds the flow through each arc in the network that minimizes the total cost of flow, meets the demand at demand nodes using the supply at supply nodes so that the flow through each arc is on or between the arc’s lower flow bound and its capacity, and satisfies the conservation of flow.

One class of network models is the production-inventory-distribution problem. The diagram in Figure 6.1 illustrates this problem. The subscripts on the Production, Inventory, and Sales nodes indicate the time period. Notice that if you replicate sections of the model, the notion of time can be included.

Figure 6.1  Production-Inventory-Distribution Problem

In this type of model, the nodes can represent a wide variety of facilities. Several examples are suppliers, spot markets, importers, farmers, manufacturers, factories, parts of a plant, production lines, waste disposal facilities, workstations, warehouses, coolstores, depots, wholesalers, export markets, ports, rail junctions, airports, road intersections, cities, regions, shops, customers, and consumers. The diversity of this selection demonstrates the richness of potential applications of this model.

Depending upon the interpretation of the nodes, the objectives of the modeling exercise can vary widely. Some common types of objectives are

- to reduce collection or purchase costs of raw materials
- to reduce inventory holding or backorder costs. Warehouses and other storage facilities sometimes have capacities, and there can be limits on the amount of goods that can be placed on backorder.
• to decide where facilities should be located and what the capacity of these should be. Network models have been used to help decide where factories, hospitals, ambulance and fire stations, oil and water wells, and schools should be sited.

• to determine the assignment of resources (machines, production capability, workforce) to tasks, schedules, classes, or files

• to determine the optimal distribution of goods or services. This usually means minimizing transportation costs, and reducing time in transit or distances covered.

• to find the shortest path from one location to another

• to ensure that demands (for example, production requirements, market demands, contractual obligations) are met

• to maximize profits from the sale of products or the charge for services

• to maximize production by identifying bottlenecks

Some specific applications are

• car distribution models. These help determine which models and numbers of cars should be manufactured in which factories and where to distribute cars from these factories to zones in the United States in order to meet customer demand at least cost.

• models in the timber industry. These help determine when to plant and mill forests, schedule production of pulp, paper and wood products, and distribute products for sale or export.

• military applications. The nodes can be theatres, bases, ammunition dumps, logistical suppliers, or radar installations. Some models are used to find the best ways to mobilize personnel and supplies and to evacuate the wounded in the least amount of time.

• communications applications. The nodes can be telephone exchanges, transmission lines, satellite links, and consumers. In a model of an electrical grid, the nodes can be transformers, powerstations, watersheds, reservoirs, dams, and consumers. Of concern might be the effect of high loads or outages.

### Side Constraints

Often all the details of a problem cannot be specified in a network model alone. In many of these cases, these details can be represented by the addition of side constraints to the model. Side constraints are a linear function of arc variables (variables containing flow through an arc) and nonarc variables (variables that are not part of the network). This enhancement to the basic network model allows for very general problems. In fact, any linear program can be represented with network models having these types of side constraints. The examples that follow help to clarify the notion of side constraints.

PROC NETFLOW enables you to specify side constraints. The data for a side constraint consist of coefficients of arcs and coefficients of nonarc variables, a constraint type (that is, ≤, =, or ≥) and a right-hand-side value (rhs). A nonarc variable has a name, an objective function coefficient analogous to an arc cost, an upper bound analogous to an arc capacity, and a lower bound analogous to an arc lower flow bound. PROC
NETFLOW finds the flow through the network and the values of any nonarc variables that minimize the total cost of the solution. Flow conservation is met, flow through each arc is on or between the arc’s lower flow bound and capacity, the value of each nonarc variable is on or between the nonarc’s lower and upper bounds, and the side constraints are satisfied. Note that, since many linear programs have large embedded networks, PROC NETFLOW is an attractive alternative to the LP procedure in many cases.

In order for arcs to be specified in side constraints, they must be named. By default, PROC NETFLOW names arcs using the names of the nodes at the head and tail of the arc. An arc is named with its tail node name followed by an underscore and its head node name. For example, an arc from node from to node to is called from_to.

**Proportionality Constraints**

Side constraints in network models fall into several categories that have special structure. They are frequently used when the flow through an arc must be proportional to the flow through another arc. Such constraints are called proportionality constraints and are useful in models where production is subject to refining or modification into different materials. The amount of each output, or any waste, evaporation, or reduction can be specified as a proportion of input.

Typically the arcs near the supply nodes carry raw materials and the arcs near the demand nodes carry refined products. For example, in a model of the milling industry, the flow through some arcs may represent quantities of wheat. After the wheat is processed, the flow through other arcs might be flour. For others it might be bran. The side constraints model the relationship between the amount of flour or bran produced as a proportion of the amount of wheat milled. Some of the wheat can end up as neither flour, bran, nor any useful product, so this waste is drained away via arcs to a waste node.

**Figure 6.2** Proportionality Constraints

Consider the network fragment in Figure 6.2. The arc Wheat_Mill conveys the wheat milled. The cost of flow on this arc is the milling cost. The capacity of this arc is the capacity of the mill. The lower flow bound on this arc is the minimum quantity that must be milled for the mill to operate economically. The constraints

\[
0.3 \text{Wheat}_\text{Mill} - \text{Mill}_\text{Flour} = 0.0
\]

\[
0.2 \text{Wheat}_\text{Mill} - \text{Mill}_\text{Bran} = 0.0
\]
force every unit of wheat that is milled to produce 0.3 units of flour and 0.2 units of bran. Note that it is not necessary to specify the constraint

\[ 0.5 \text{Wheat} - \text{Mill} - \text{Mill} \text{Other} = 0.0 \]

since flow conservation implies that any flow that does not traverse through Mill\_Flour or Mill\_Bran must be conveyed through Mill\_Other. And, computationally, it is better if this constraint is not specified, since there is one less side constraint and fewer problems with numerical precision. Notice that the sum of the proportions must equal 1.0 exactly; otherwise, flow conservation is violated.

**Blending Constraints**

Blending or quality constraints can also influence the recipes or proportions of ingredients that are mixed. For example, different raw materials can have different properties. In an application of the oil industry, the amount of products that are obtained could be different for each type of crude oil. Furthermore, fuel might have a minimum octane requirement or limited sulphur or lead content, so that a blending of crudes is needed to produce the product.

The network fragment in Figure 6.3 shows an example of this.

![Figure 6.3 Blending Constraints](image)

The arcs MidEast\_Port and USA\_Port convey crude oil from the two sources. The arc Port\_Refinery represents refining while the arcs Refinery\_Gasoline and Refinery\_Diesel carry the gas and diesel produced. The proportionality constraints

\[ 0.4 \text{Port} - \text{Refinery} - \text{Refinery} \text{Gasoline} = 0.0 \]

\[ 0.2 \text{Port} - \text{Refinery} - \text{Refinery} \text{Diesel} = 0.0 \]

capture the restrictions for producing gasoline and diesel from crude. Suppose that, if only crude from the Middle East is used, the resulting diesel would contain 5 units of sulphur per liter. If only crude from the
USA is used, the resulting diesel would contain 4 units of sulphur per liter. Diesel can have at most 4.75 units of sulphur per liter. Some crude from the USA must be used if Middle East crude is used in order to meet the 4.75 sulphur per liter limit. The side constraint to model this requirement is

$$5 \text{MidEast}_\text{Port} + 4 \text{USA}_\text{Port} - 4.75 \text{Port}_\text{Refinery} \leq 0.0$$

Since $\text{Port}_\text{Refinery} = \text{MidEast}_\text{Port} + \text{USA}_\text{Port}$, flow conservation allows this constraint to be simplified to

$$1 \text{MidEast}_\text{Port} - 3 \text{USA}_\text{Port} \leq 0.0$$

If, for example, 120 units of crude from the Middle East is used, then at least 40 units of crude from the USA must be used. The preceding constraint is simplified because you assume that the sulphur concentration of diesel is proportional to the sulphur concentration of the crude mix. If this is not the case, the relation

$$0.2 \text{Port}_\text{Refinery} = \text{Refinery}_\text{Diesel}$$

is used to obtain

$$5 \text{MidEast}_\text{Port} + 4 \text{USA}_\text{Port} - 4.75 (1.0/0.2 \text{ Refinery}_\text{Diesel}) \leq 0.0$$

which equals

$$5 \text{MidEast}_\text{Port} + 4 \text{USA}_\text{Port} - 23.75 \text{Refinery}_\text{Diesel} \leq 0.0$$

An example similar to this Oil Industry problem is solved in the section “Introductory Example” on page 315.

**Multicommodity Problems**

Side constraints are also used in models in which there are capacities on transportation or some other shared resource, or there are limits on overall production or demand in multicommodity, multidivisional or multiperiod problems. Each commodity, division or period can have a separate network coupled to one main system by the side constraints. Side constraints are used to combine the outputs of subdivisions of a problem (either commodities, outputs in distinct time periods, or different process streams) to meet overall demands or to limit overall production or expenditures. This method is more desirable than doing separate local optimizations for individual commodity, process, or time networks and then trying to establish relationships between each when determining an overall policy if the global constraint is not satisfied. Of course, to make models more realistic, side constraints may be necessary in the local problems.
Figure 6.4 shows two network fragments. They represent identical production and distribution sites of two different commodities. Suffix *com1* represents commodity 1 and suffix *com2* represents commodity 2. The nodes Factorycom1 and Factorycom2 model the same factory, and nodes City1com1 and City1com2 model the same location, city 1. Similarly, City2com1 and City2com2 are the same location, city 2. Suppose that commodity 1 occupies 2 cubic meters, commodity 2 occupies 3 cubic meters, the truck dispatched to city 1 has a capacity of 200 cubic meters, and the truck dispatched to city 2 has a capacity of 250 cubic meters. How much of each commodity can be loaded onto each truck? The side constraints for this case are

\[
2 \text{Factorycom1\_City1com1} + 3 \text{Factorycom2\_City1com2} \leq 200
\]

\[
2 \text{Factorycom1\_City2com1} + 3 \text{Factorycom2\_City2com2} \leq 250
\]

**Large Modeling Strategy**

In many cases, the flow through an arc might actually represent the flow or movement of a commodity from place to place or from time period to time period. However, sometimes an arc is included in the network as a method of capturing some aspect of the problem that you would not normally think of as part of a network model. For example, in a multiprocess, multiproduct model (Figure 6.5), there might be subnetworks for each process and each product. The subnetworks can be joined together by a set of arcs that have flows that represent the amount of product *j* produced by process *i*. To model an upper limit constraint on the total amount of product *j* that can be produced, direct all arcs carrying product *j* to a single node and from there through a single arc. The capacity of this arc is the upper limit of product *j* production. It is preferable to model this structure in the network rather than to include it in the side constraints because the efficiency of the optimizer is affected less by a reasonable increase in the size of the network.
Figure 6.5  Multiprocess, Multiproduct Example

It is often a good strategy when starting a project to use a small network formulation and then use that model as a framework upon which to add detail. For example, in the multiprocess, multiproduct model, you might start with the network depicted in Figure 6.5. Then, for example, the process subnetwork can be enhanced to include the distribution of products. Other phases of the operation could be included by adding more subnetworks. Initially, these subnetworks can be single nodes, but in subsequent studies they can be expanded to include greater detail.

The NETFLOW procedure accepts the side constraints in the same dense and sparse formats that the LP procedure provides. Although PROC LP can solve network problems, the NETFLOW procedure generally solves network flow problems more efficiently than PROC LP.

Advantages of Network Models over LP Models

Many linear programming problems have large embedded network structures. Such problems often result when modeling manufacturing processes, transportation or distribution networks, or resource allocation, or when deciding where to locate facilities. Often, some commodity is to be moved from place to place, so the more natural formulation in many applications is that of a constrained network rather than a linear program.

Using a network diagram to visualize a problem makes it possible to capture the important relationships in an easily understood picture form. The network diagram aids the communication between model builder and model user, making it easier to comprehend how the model is structured, how it can be changed, and how results can be interpreted.

If a network structure is embedded in a linear program, the problem is a network programming problem with side constraints (NPSC). When the network part of the problem is large compared to the nonnetwork part, especially if the number of side constraints is small, it is worthwhile to exploit this structure in the solution process. This is what PROC NETFLOW does. It uses a variant of the revised primal simplex algorithm that exploits the network structure to reduce solution time.
Mathematical Description of NPSC

If a network programming problem with side constraints has \( n \) nodes, \( a \) arcs, \( g \) nonarc variables, and \( k \) side constraints, then the formal statement of the problem solved by PROC NETFLOW is

\[
\text{minimize} \quad c^T x + d^T z \\
\text{subject to} \quad F x = b \\
H x + Q z \geq, =, \leq r \\
l \leq x \leq u \\
m \leq z \leq v
\]

where

- \( c \) is the \( a \times 1 \) arc variable objective function coefficient vector (the cost vector)
- \( x \) is the \( a \times 1 \) arc variable value vector (the flow vector)
- \( d \) is the \( g \times 1 \) nonarc variable objective function coefficient vector
- \( z \) is the \( g \times 1 \) nonarc variable value vector
- \( F \) is the \( n \times a \) node-arc incidence matrix of the network, where
  \[
  F_{i,j} = \begin{cases} 
  -1, & \text{if arc } j \text{ is directed from node } i \\
  1, & \text{if arc } j \text{ is directed toward node } i \\
  0, & \text{otherwise}
  \end{cases}
  \]
- \( b \) is the \( n \times 1 \) node supply/demand vector, where
  \[
  b_i = \begin{cases} 
  s, & \text{if node } i \text{ has supply capability of } s \text{ units of flow} \\
  -d, & \text{if node } i \text{ has demand of } d \text{ units of flow} \\
  0, & \text{if node } i \text{ is a trans-shipment node}
  \end{cases}
  \]
- \( H \) is the \( k \times a \) side constraint coefficient matrix for arc variables, where \( H_{i,j} \) is the coefficient of arc \( j \) in the \( i \)th side constraint
- \( Q \) is the \( k \times g \) side constraint coefficient matrix for nonarc variables, where \( Q_{i,j} \) is the coefficient of nonarc \( j \) in the \( i \)th side constraint
- \( r \) is the \( k \times 1 \) side constraint right-hand-side vector
- \( l \) is the \( a \times 1 \) arc lower flow bound vector
- \( u \) is the \( a \times 1 \) arc capacity vector
- \( m \) is the \( g \times 1 \) nonarc variable lower bound vector
- \( v \) is the \( g \times 1 \) nonarc variable upper bound vector
Flow Conservation Constraints

The constraints $Fx = b$ are referred to as the nodal flow conservation constraints. These constraints algebraically state that the sum of the flow through arcs directed toward a node plus that node’s supply, if any, equals the sum of the flow through arcs directed away from that node plus that node’s demand, if any. The flow conservation constraints are implicit in the network model and should not be specified explicitly in side constraint data when using PROC NETFLOW. The constrained problems most amenable to being solved by the NETFLOW procedure are those that, after the removal of the flow conservation constraints, have very few constraints. PROC NETFLOW is superior to linear programming optimizers when the network part of the problem is significantly larger than the nonnetwork part.

The NETFLOW procedure can also be used to solve an unconstrained network problem, that is, one in which $H, Q, d, r,$ and $z$ do not exist.

Nonarc Variables

If the constrained problem to be solved has no nonarc variables, then $Q, d,$ and $z$ do not exist. However, nonarc variables can be used to simplify side constraints. For example, if a sum of flows appears in many constraints, it may be worthwhile to equate this expression with a nonarc variable and use this in the other constraints. By assigning a nonarc variable a nonzero objective function, it is then possible to incur a cost for using resources above some lowest feasible limit. Similarly, a profit (a negative objective function coefficient value) can be made if all available resources are not used.

In some models, nonarc variables are used in constraints to absorb excess resources or supply needed resources. Then, either the excess resource can be used or the needed resource can be supplied to another component of the model.

For example, consider a multicommodity problem of making television sets that have either 19- or 25-inch screens. In their manufacture, 3 and 4 chips, respectively, are used. Production occurs at 2 factories during March and April. The supplier of chips can supply only 2600 chips to factory 1 and 3750 chips to factory 2 each month. The names of arcs are in the form $Prodn_s_m$, where $n$ is the factory number, $s$ is the screen size, and $m$ is the month. For example, $Prod1_25_Apr$ is the arc that conveys the number of 25-inch TVs produced in factory 1 during April. You might have to determine similar systematic naming schemes for your application.

As described, the constraints are

$$3 \text{Prod1}_{19}\_\text{Mar} + 4 \text{Prod1}_{25}\_\text{Mar} \leq 2600$$

$$3 \text{Prod2}_{19}\_\text{Mar} + 4 \text{Prod2}_{25}\_\text{Mar} \leq 3750$$

$$3 \text{Prod1}_{19}\_\text{Apr} + 4 \text{Prod1}_{25}\_\text{Apr} \leq 2600$$

$$3 \text{Prod2}_{19}\_\text{Apr} + 4 \text{Prod2}_{25}\_\text{Apr} \leq 3750$$
If there are chips that could be obtained for use in March but not used for production in March, why not keep these unused chips until April? Furthermore, if the March excess chips at factory 1 could be used either at factory 1 or factory 2 in April, the model becomes

\[
\begin{align*}
3 \text{Prod1}_19\text{Mar} + & 4 \text{Prod1}_25\text{Mar} + \text{F1}_{\text{Unused\_Mar}} = 2600 \\
3 \text{Prod2}_19\text{Mar} + & 4 \text{Prod2}_25\text{Mar} + \text{F2}_{\text{Unused\_Mar}} = 3750 \\
3 \text{Prod1}_19\text{Apr} + & 4 \text{Prod1}_25\text{Apr} - \text{F1}_{\text{Kept\_Since\_Mar}} = 2600 \\
3 \text{Prod2}_19\text{Apr} + & 4 \text{Prod2}_25\text{Apr} - \text{F2}_{\text{Kept\_Since\_Mar}} = 3750 \\
\text{F1}_{\text{Unused\_Mar}} + & \text{F2}_{\text{Unused\_Mar}} \text{ (continued)} \\
- & \text{F1}_{\text{Kept\_Since\_Mar}} - \text{F2}_{\text{Kept\_Since\_Mar}} \geq 0.0
\end{align*}
\]

where \(\text{F1}_{\text{Kept\_Since\_Mar}}\) is the number of chips used during April at factory 1 that were obtained in March at either factory 1 or factory 2 and \(\text{F2}_{\text{Kept\_Since\_Mar}}\) is the number of chips used during April at factory 2 that were obtained in March. The last constraint ensures that the number of chips used during April that were obtained in March does not exceed the number of chips not used in March. There may be a cost to hold chips in inventory. This can be modeled having a positive objective function coefficient for the nonarc variables \(\text{F1}_{\text{Kept\_Since\_Mar}}\) and \(\text{F2}_{\text{Kept\_Since\_Mar}}\). Moreover, nonarc variable upper bounds represent an upper limit on the number of chips that can be held in inventory between March and April.

See Example 6.4 through Example 6.8 for a series of examples that use this TV problem. The use of nonarc variables as described previously is illustrated.

---

**Warm Starts**

If you have a problem that has already been partially solved and is to be solved further to obtain a better, optimal solution, information describing the solution now available may be used as an initial solution. This is called *warm starting* the optimization, and the supplied solution data are called the *warm start*.

Some data can be changed between the time when a warm start is created and when it is used as a warm start for a subsequent PROC NETFLOW run. Elements in the arc variable cost vector, the nonarc variable objective function coefficient vector, and sometimes capacities, upper value bounds, and side constraint data can be changed between PROC NETFLOW calls. See the section “Warm Starts” on page 406. Also, see Example 6.4 through Example 6.8 (the TV problem) for a series of examples that show the use of warm starts.
Getting Started: NETFLOW Procedure

To solve network programming problems with side constraints using PROC NETFLOW, you save a representation of the network and the side constraints in three SAS data sets. These data sets are then passed to PROC NETFLOW for solution. There are various forms that a problem’s data can take. You can use any one or a combination of several of these forms.

The NODEDATA= data set contains the names of the supply and demand nodes and the supply or demand associated with each. These are the elements in the column vector \( b \) in problem (NPSC).

The ARCDATA= data set contains information about the variables of the problem. Usually these are arcs, but there can also be data related to nonarc variables in the ARCDATA= data set.

An arc is identified by the names of its tail node (where it originates) and head node (where it is directed). Each observation can be used to identify an arc in the network and, optionally, the cost per flow unit across the arc, the arc’s capacity, lower flow bound, and name. These data are associated with the matrix \( F \) and the vectors \( c, l, \) and \( u \) in problem (NPSC).

**NOTE:** Although \( F \) is a node-arc incidence matrix, it is specified in the ARCDATA= data set by arc definitions.

In addition, the ARCDATA= data set can be used to specify information about nonarc variables, including objective function coefficients, lower and upper value bounds, and names. These data are the elements of the vectors \( d, m, \) and \( v \) in problem (NPSC). Data for an arc or nonarc variable can be given in more than one observation.

Supply and demand data also can be specified in the ARCDATA= data set. In such a case, the NODEDATA= data set may not be needed.

The CONDATA= data set describes the side constraints and their right-hand sides. These data are elements of the matrices \( H \) and \( Q \) and the vector \( r \). Constraint types are also specified in the CONDATA= data set. You can include in this data set upper bound values or capacities, lower flow or value bounds, and costs or objective function coefficients. It is possible to give all information about some or all nonarc variables in the CONDATA= data set.

An arc is identified in this data set by its name. If you specify an arc’s name in the ARCDATA= data set, then this name is used to associate data in the CONDATA= data set with that arc. Each arc also has a default name that is the name of the tail and head node of the arc concatenated together and separated by an underscore character; `tail_head`, for example.

If you use the dense side constraint input format (described in the section “CONDATA= Data Set” on page 380) and want to use the default arc names, these arc names are names of SAS variables in the VAR list of the CONDATA= data set.

If you use the sparse side constraint input format (see the section “CONDATA= Data Set” on page 380) and want to use the default arc names, these arc names are values of the COLUMN list SAS variable of the CONDATA= data set.
The execution of PROC NETFLOW has three stages. In the preliminary (zeroth) stage, the data are read from the NODEDATA= data set, the ARCDATA= data set, and the CONDATA= data set. Error checking is performed, and an initial basic feasible solution is found. If an unconstrained solution warm start is being used, then an initial basic feasible solution is obtained by reading additional data containing that information in the NODEDATA= data set and the ARCDATA= data set. In this case, only constraint data and nonarc variable data are read from the CONDATA= data set.

In the first stage, an optimal solution to the network flow problem neglecting any side constraints is found. The primal and dual solutions for this relaxed problem can be saved in the ARCOUt= data set and the NODEOUT= data set, respectively. These data sets are named in the PROC NETFLOW, RESET, and SAVE statements.

In the second stage, an optimal solution to the network flow problem with side constraints is found. The primal and dual solutions for this side constrained problem are saved in the CONOUT= data set and the DUALOUT= data set, respectively. These data sets are also named in the PROC NETFLOW, RESET, and SAVE statements.

If a constrained solution warm start is being used, PROC NETFLOW does not perform the zeroth and first stages. This warm start can be obtained by reading basis data containing additional information in the NODEDATA= data set (also called the DUALIN= data set) and the ARCDATA= data set.

If warm starts are to be used in future optimizations, the FUTURE1 and FUTURE2 options must be used in addition to specifying names for the data sets that contain the primal and dual solutions in stages one and two. Then, most of the information necessary for restarting problems is available in the output data sets containing the primal and dual solutions of both the relaxed and side constrained network programs.

Introductory Example

Consider the following trans-shipment problem for an oil company. Crude oil is shipped to refineries where it is processed into gasoline and diesel fuel. The gasoline and diesel fuel are then distributed to service stations. At each stage, there are shipping, processing, and distribution costs. Also, there are lower flow bounds and capacities.

In addition, there are two sets of side constraints. The first set is that two times the crude from the Middle East cannot exceed the throughput of a refinery plus 15 units. (The phrase “plus 15 units” that finishes the last sentence is used to enable some side constraints in this example to have a nonzero rhs.) The second set of constraints are necessary to model the situation that one unit of crude mix processed at a refinery yields three-fourths of a unit of gasoline and one-fourth of a unit of diesel fuel.

Because there are two products that are not independent in the way in which they flow through the network, a network programming problem with side constraints is an appropriate model for this example (see Figure 6.6). The side constraints are used to model the limitations on the amount of Middle Eastern crude that can be processed by each refinery and the conversion proportions of crude to gasoline and diesel fuel.
To solve this problem with PROC NETFLOW, save a representation of the model in three SAS data sets. In the NODEDATA= data set, you name the supply and demand nodes and give the associated supplies and demands. To distinguish demand nodes from supply nodes, specify demands as negative quantities. For the oil example, the NODEDATA= data set can be saved as follows:

```sas
title 'Oil Industry Example';
title3 'Setting Up Nodedata = Noded For Proc Netflow';
data noded;
  input _node_ &$15. _sd_;
datalines;
middle east  100
u.s.a.       80
servstn1 gas -95
servstn1 diesel -30
servstn2 gas -40
servstn2 diesel -15
;
```

The ARCDATA= data set contains the rest of the information about the network. Each observation in the data set identifies an arc in the network and gives the cost per flow unit across the arc, the capacities of the arc, the lower bound on flow across the arc, and the name of the arc.
title3 'Setting Up Arcdata = Arcd1 For Proc Netflow';
data arcd1;
    input _from_&$11._to_&$15._cost_ _capac_ _lo_ _name_ $;
datalines;
middle east refinery 1 63 95 20 m_e_ref1
middle east refinery 2 81 80 10 m_e_ref2
u.s.a. refinery 1 55 . . .
u.s.a. refinery 2 49 . . .
refinery 1 r1 200 175 50 thruput1
refinery 2 r2 220 100 35 thruput2
r1 ref1 gas . 140 . r1_gas
r1 ref1 diesel . 75 . .
r2 ref2 gas . 100 . r2_gas
r2 ref2 diesel . 75 . .
ref1 gas servstn1 gas 15 70 . .
ref1 gas servstn2 gas 22 60 . .
ref1 diesel servstn1 diesel 18 . .
ref1 diesel servstn2 diesel 17 . .
ref2 gas servstn1 gas 17 35 5 .
ref2 gas servstn2 gas 31 . .
ref2 diesel servstn1 diesel 36 . .
ref2 diesel servstn2 diesel 23 . .
;
Finally, the CONDATA= data set contains the side constraints for the model.

title3 'Setting Up Condata = Cond1 For Proc Netflow';
data cond1;
    input m_e_ref1 m_e_ref2 thruput1 r1_gas thruput2 r2_gas
        _type_ $ _rhs_;
datalines;
-2 . 1 . . . >= -15
 -2 . . 1 . GE -15
 . .-3 4 . . EQ 0
 . . . -3 4 = 0
;
Note that the SAS variable names in the CONDATA= data set are the names of arcs given in the ARCDATA= data set. These are the arcs that have nonzero constraint coefficients in side constraints. For example, the proportionality constraint that specifies that one unit of crude at each refinery yields three-fourths of a unit of gasoline and one-fourth of a unit of diesel fuel is given for REFINERY 1 in the third observation and for REFINERY 2 in the last observation. The third observation requires that each unit of flow on arc THRUPUT1 equals three-fourths of a unit of flow on arc R1_GAS. Because all crude processed at REFINERY 1 flows through THRUPUT1 and all gasoline produced at REFINERY 1 flows through R1_GAS, the constraint models the situation. It proceeds similarly for REFINERY 2 in the last observation.
To find the minimum cost flow through the network that satisfies the supplies, demands, and side constraints, invoke PROC NETFLOW as follows:

```
proc netflow
  nodedata=noded  /* the supply and demand data */
  arcdata=arcd1  /* the arc descriptions */
  conddata=cond1  /* the side constraints */
  conout=solution; /* the solution data set */
run;
```

The following messages, which appear on the SAS log, summarize the model as read by PROC NETFLOW and note the progress toward a solution:

```
NOTE: Number of nodes= 14.
NOTE: Number of supply nodes= 2.
NOTE: Number of demand nodes= 4.
NOTE: Total supply= 180, total demand= 180.
NOTE: Number of arcs= 18.
NOTE: Number of iterations performed (neglecting any constraints)= 14.
NOTE: Of these, 0 were degenerate.
NOTE: Optimum (neglecting any constraints) found.
NOTE: Minimal total cost= 50600.
NOTE: Number of <= side constraints= 0.
NOTE: Number of == side constraints= 2.
NOTE: Number of >= side constraints= 2.
NOTE: Number of arc and nonarc variable side constraint coefficients= 8.
NOTE: Number of iterations, optimizing with constraints= 4.
NOTE: Of these, 0 were degenerate.
NOTE: Optimum reached.
NOTE: Minimal total cost= 50875.
NOTE: The data set WORK.SOLUTION has 18 observations and 14 variables.
```

Unlike PROC LP, which displays the solution and other information as output, PROC NETFLOW saves the optimum in output SAS data sets that you specify. For this example, the solution is saved in the SOLUTION data set. It can be displayed with the PRINT procedure as

```
proc print data=solution;
  var _from_ _to_ _cost_ _capac_ _lo_ _name_
    _supply_ _demand_ _flow_ _fcost_ _rcost_;  
  sum _fcost_;  
  title3 'Constrained Optimum';
run;
```
Notice that, in CONOUT=SOLUTION (Figure 6.7), the optimal flow through each arc in the network is given in the variable named `_FLOW_`, and the cost of flow through each arc is given in the variable `_FCOST_`. 

```
Obs  _from_   _to_  _cost_  _capac_ _lo_ _name_  _SUPPLY_ _DEMAND_ _FLOW_  _FCOST_  _RCOST_
1    refinery 1 r1    200  175  50  thruput1    .        .    145.00    29000.00  .
2    refinery 2 r2    220  100  35  thruput2    .        .    35.00     7700.00  29
3    r1    ref1 diesel 0    75  0        .        .    36.25    0.00    .
4    r1    ref1 gas    0    140  0  r1_gas    .        .    108.75    0.00    .
5    r2    ref2 diesel 0    75  0        .        .    8.75     0.00    .
6    r2    ref2 gas    0    100  0  r2_gas    .        .    26.25    0.00    .
7    middle east refinery 1 63    95  20  m_e_ref1 100        .    80.00    5040.00  .
8    u.s.a.   refinery 1 55 999999999 0        .        .    65.00    3575.00  .
9    middle east refinery 2 81    80  10  m_e_ref2 100        .    20.00    1620.00  .
10   u.s.a.   refinery 2 49 999999999 0        .        .    15.00    735.00    .
11   ref1 diesel servst1 diesel 18 999999999 0        .        .    30.00    540.00    .
12   ref2 diesel servst1 diesel 36 999999999 0        .        .    30.00    0.00    0.00    12
13   ref1 gas   servst1 gas 15    70  0        .        .    95.00    68.75    1031.25  .
14   ref2 gas   servst1 gas 17    35  5        .        .    95.00    26.25    446.25  .
15   ref1 diesel servst2 diesel 17 999999999 0        .        .    15.00    6.25    106.25  .
16   ref2 diesel servst2 diesel 23 999999999 0        .        .    15.00    8.75    201.25  .
17   ref1 gas   servst2 gas 22    60  0        .        .    40.00    40.00    880.00  .
18   ref2 gas   servst2 gas 31 999999999 0        .        .    40.00    0.00    0.00    7

50875.00
```
Figure 6.8  Oil Industry Solution

\[
\begin{array}{c}
\text{middle east} \quad 80 \quad \text{refinery1} \quad 145 \quad \text{ref2} \\
\quad 65 \quad \text{us.a.} \quad 80 \quad \text{refinery2} \quad 35 \quad \text{r2} \\
100 \quad 15 \\
\end{array}
\]

\[
\begin{array}{c}
\text{ref1 gas} \quad 108.75 \quad 40 \quad 26.25 \\
\text{ref1 diesel} \quad 36.25 \quad 30 \\
\text{ref2 gas} \quad 26.25 \\
\text{ref2 diesel} \quad 8.75 \\
\text{servstn1 gas} \quad 68.75 \\
\text{servstn1 diesel} \quad -95 \\
\text{servstn2 gas} \quad -40 \\
\text{servstn2 diesel} \quad -15
\end{array}
\]
Syntax: NETFLOW Procedure

Below are statements used in PROC NETFLOW, listed in alphabetical order as they appear in the text that follows.

```plaintext
PROC NETFLOW options ;
   CAPACITY variable ;
   COEF variables ;
   COLUMN variable ;
   CONOPT ;
   COST variable ;
   DEMAND variable ;
   HEADNODE variable ;
   ID variables ;
   LO variable ;
   NAME variable ;
   NODE variable ;
   PIVOT ;
   PRINT options ;
   QUIT ;
   RESET options ;
   RHS variables ;
   ROW variables ;
   RUN ;
   SAVE options ;
   SHOW options ;
   SUPDEM variable ;
   SUPPLY variable ;
   TAILNODE variable ;
   TYPE variable ;
   VAR variables ;
```

Functional Summary

The following table outlines the options available for the NETFLOW procedure classified by function.

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input Data Set Options:</td>
<td>PROC NETFLOW</td>
<td>ARCDATA=</td>
</tr>
<tr>
<td>Arcs input data set</td>
<td>PROC NETFLOW</td>
<td>NODEDATA=</td>
</tr>
<tr>
<td>Nodes input data set</td>
<td>PROC NETFLOW</td>
<td>CONDATA=</td>
</tr>
<tr>
<td>Constraint input data set</td>
<td>PROC NETFLOW</td>
<td></td>
</tr>
<tr>
<td>Output Data Set Options:</td>
<td>PROC NETFLOW</td>
<td>ARCOUT=</td>
</tr>
<tr>
<td>Unconstrained primal solution data set</td>
<td>PROC NETFLOW</td>
<td></td>
</tr>
</tbody>
</table>
Chapter 6: The NETFLOW Procedure

### Description

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Unconstrained dual solution data set</td>
<td>PROC NETFLOW</td>
<td>NODEOUT=</td>
</tr>
<tr>
<td>Constrained primal solution data set</td>
<td>PROC NETFLOW</td>
<td>CONOUT=</td>
</tr>
<tr>
<td>Constrained dual solution data set</td>
<td>PROC NETFLOW</td>
<td>DUALOUT=</td>
</tr>
<tr>
<td>Convert sparse or dense format input data set into MPS format output data set</td>
<td>PROC NETFLOW</td>
<td>MPSOUT=</td>
</tr>
</tbody>
</table>

### Data Set Read Options:

- **CONDATA** has sparse data format
- Default constraint type
- Special `COLUMN` variable value
- Special `COLUMN` variable value
- Used to interpret arc and nonarc variable names
- No new nonarc variables
- No nonarc data in `ARCDATA`
- Data for an arc found once in `ARCDATA`
- Data for a constraint found once in `CONDATA`
- Data for a coefficient found once in `CONDATA`
- Data are grouped, exploited during data read

### Problem Size Specification Options:

- Approximate number of nodes
- Approximate number of arcs
- Approximate number of nonarc variables
- Approximate number of coefficients
- Approximate number of constraints

### Network Options:

- Default arc cost
- Default arc capacity
- Default arc lower flow bound
- Network’s only supply node
- Network’s only demand node
- SINK’s demand
- Convey excess supply/demand through network
- Find maximal flow between SOURCE and SINK
- Cost of bypass arc for MAXFLOW problem
- Find shortest path from SOURCE to SINK
- Specify generalized networks
- Specify excess demand or supply

### Memory Control Options:

- Issue memory usage messages to SAS log
- Number of bytes to use for main memory
- Proportion of memory for arrays
<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Memory allocated for LU factors</td>
<td>PROC NETFLOW</td>
<td>DWIA=</td>
</tr>
<tr>
<td>Linked list for updated column</td>
<td>PROC NETFLOW</td>
<td>SPARSEP2</td>
</tr>
<tr>
<td>Use 2-dimensional array for basis matrix</td>
<td>PROC NETFLOW</td>
<td>INVD_2D</td>
</tr>
<tr>
<td>Maximum bytes for a single array</td>
<td>PROC NETFLOW</td>
<td>MAXARRAYBYTES=</td>
</tr>
<tr>
<td><strong>Simplex Options:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Use big-M instead of two-phase method, stage 1</td>
<td>RESET</td>
<td>BIGM1</td>
</tr>
<tr>
<td>Use Big-M instead of two-phase method, stage 2</td>
<td>RESET</td>
<td>BIGM2</td>
</tr>
<tr>
<td>Anti-cycling option</td>
<td>RESET</td>
<td>CYCLEMULT1=</td>
</tr>
<tr>
<td>Interchange first nonkey with leaving key arc</td>
<td>RESET</td>
<td>INTFIRST</td>
</tr>
<tr>
<td>Controls working basis matrix inversions</td>
<td>RESET</td>
<td>INVFREQ=</td>
</tr>
<tr>
<td>Maximum number of L row operations allowed before refactorization</td>
<td>RESET</td>
<td>MAXL=</td>
</tr>
<tr>
<td>Maximum number of LU factor column updates</td>
<td>RESET</td>
<td>MAXLUUPDATES=</td>
</tr>
<tr>
<td>Anti-cycling option</td>
<td>RESET</td>
<td>MINBLOCK1=</td>
</tr>
<tr>
<td>Use first eligible leaving variable, stage 1</td>
<td>RESET</td>
<td>LRATIO1</td>
</tr>
<tr>
<td>Use first eligible leaving variable, stage 2</td>
<td>RESET</td>
<td>LRATIO2</td>
</tr>
<tr>
<td>Negates INTFIRST</td>
<td>RESET</td>
<td>NINTFIRST</td>
</tr>
<tr>
<td>Negates LRATIO1</td>
<td>RESET</td>
<td>NLRATIO1</td>
</tr>
<tr>
<td>Negates LRATIO2</td>
<td>RESET</td>
<td>NLRATIO2</td>
</tr>
<tr>
<td>Negates PERTURB1</td>
<td>RESET</td>
<td>NOPERTURB1</td>
</tr>
<tr>
<td>Anti-cycling option</td>
<td>RESET</td>
<td>PERTURB1</td>
</tr>
<tr>
<td>Controls working basis matrix refactorization</td>
<td>RESET</td>
<td>REFACTFREQ=</td>
</tr>
<tr>
<td>Use two-phase instead of big-M method, stage 1</td>
<td>RESET</td>
<td>TWOPHASE1</td>
</tr>
<tr>
<td>Use two-phase instead of big-M method, stage 2</td>
<td>RESET</td>
<td>TWOPHASE2</td>
</tr>
<tr>
<td>Pivot element selection parameter</td>
<td>RESET</td>
<td>U=</td>
</tr>
<tr>
<td>Zero tolerance, stage 1</td>
<td>RESET</td>
<td>ZERO1=</td>
</tr>
<tr>
<td>Zero tolerance, stage 2</td>
<td>RESET</td>
<td>ZERO2=</td>
</tr>
<tr>
<td>Zero tolerance, real number comparisons</td>
<td>RESET</td>
<td>ZEROTOL=</td>
</tr>
<tr>
<td><strong>Pricing Options:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Frequency of dual value calculation</td>
<td>RESET</td>
<td>DUALFREQ=</td>
</tr>
<tr>
<td>Pricing strategy, stage 1</td>
<td>RESET</td>
<td>PRICETYPE1=</td>
</tr>
<tr>
<td>Pricing strategy, stage 2</td>
<td>RESET</td>
<td>PRICETYPE2=</td>
</tr>
<tr>
<td>Used when P1SCAN=PARTIAL</td>
<td>RESET</td>
<td>P1NPARTIAL=</td>
</tr>
<tr>
<td>Controls search for entering candidate, stage 1</td>
<td>RESET</td>
<td>P1SCAN=</td>
</tr>
<tr>
<td>Used when P2SCAN=PARTIAL</td>
<td>RESET</td>
<td>P2NPARTIAL=</td>
</tr>
<tr>
<td>Controls search for entering candidate, stage 2</td>
<td>RESET</td>
<td>P2SCAN=</td>
</tr>
<tr>
<td>Initial queue size, stage 1</td>
<td>RESET</td>
<td>QSIZE1=</td>
</tr>
<tr>
<td>Initial queue size, stage 2</td>
<td>RESET</td>
<td>QSIZE2=</td>
</tr>
<tr>
<td>Used when Q1FILLSCAN=PARTIAL</td>
<td>RESET</td>
<td>Q1FILLNPARTIAL=</td>
</tr>
<tr>
<td>Controls scan when filling queue, stage 1</td>
<td>RESET</td>
<td>Q1FILLSCAN=</td>
</tr>
<tr>
<td>Used when Q2FILLSCAN=PARTIAL</td>
<td>RESET</td>
<td>Q2FILLNPARTIAL=</td>
</tr>
<tr>
<td>Controls scan when filling queue, stage 2</td>
<td>RESET</td>
<td>Q2FILLSCAN=</td>
</tr>
<tr>
<td>Queue size reduction factor, stage 1</td>
<td>RESET</td>
<td>REDUCEQSIZE1=</td>
</tr>
</tbody>
</table>
### Chapter 6: The NETFLOW Procedure

**Description Statement Option**

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Queue size reduction factor, stage 2</td>
<td>RESET</td>
<td>REDUCEQSIZE2=</td>
</tr>
<tr>
<td>Frequency of refreshing queue, stage 1</td>
<td>RESET</td>
<td>REFRESHQ1=</td>
</tr>
<tr>
<td>Frequency of refreshing queue, stage 2</td>
<td>RESET</td>
<td>REFRESHQ2=</td>
</tr>
</tbody>
</table>

**Optimization Termination Options:**

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pause after stage 1; do not start stage 2</td>
<td>RESET</td>
<td>ENDPAUSE1</td>
</tr>
<tr>
<td>Pause when feasible, stage 1</td>
<td>RESET</td>
<td>FEASIBLEPAUSE1</td>
</tr>
<tr>
<td>Pause when feasible, stage 2</td>
<td>RESET</td>
<td>FEASIBLEPAUSE2</td>
</tr>
<tr>
<td>Maximum number of iterations, stage 1</td>
<td>RESET</td>
<td>MAXIT1=</td>
</tr>
<tr>
<td>Maximum number of iterations, stage 2</td>
<td>RESET</td>
<td>MAXIT2=</td>
</tr>
<tr>
<td>Negates ENDPAUSE1</td>
<td>RESET</td>
<td>NOENDPAUSE1</td>
</tr>
<tr>
<td>Negates FEASIBLEPAUSE1</td>
<td>RESET</td>
<td>NOFEASIBLEPAUSE1</td>
</tr>
<tr>
<td>Negates FEASIBLEPAUSE2</td>
<td>RESET</td>
<td>NOFEASIBLEPAUSE2</td>
</tr>
<tr>
<td>Pause every PAUSE1 iterations, stage 1</td>
<td>RESET</td>
<td>PAUSE1=</td>
</tr>
<tr>
<td>Pause every PAUSE2 iterations, stage 2</td>
<td>RESET</td>
<td>PAUSE2=</td>
</tr>
</tbody>
</table>

**Interior Point Algorithm Options:**

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Use interior point algorithm</td>
<td>PROC NETFLOW</td>
<td>INTPOINT</td>
</tr>
<tr>
<td>Factorization method</td>
<td>RESET</td>
<td>FACT_METHOD=</td>
</tr>
<tr>
<td>Allowed amount of dual infeasibility</td>
<td>RESET</td>
<td>TOLDINF=</td>
</tr>
<tr>
<td>Allowed amount of primal infeasibility</td>
<td>RESET</td>
<td>TOLPINF=</td>
</tr>
<tr>
<td>Allowed total amount of dual infeasibility</td>
<td>RESET</td>
<td>TOLTOTDINF=</td>
</tr>
<tr>
<td>Allowed total amount of primal infeasibility</td>
<td>RESET</td>
<td>TOLTOTPINF=</td>
</tr>
<tr>
<td>Cut-off tolerance for Cholesky factorization</td>
<td>RESET</td>
<td>CHOLTINYTOL=</td>
</tr>
<tr>
<td>Density threshold for Cholesky processing</td>
<td>RESET</td>
<td>DENSETHR=</td>
</tr>
<tr>
<td>Step-length multiplier</td>
<td>RESET</td>
<td>PDSTEPMULT=</td>
</tr>
<tr>
<td>Preprocessing type</td>
<td>RESET</td>
<td>PRSLTYPE=</td>
</tr>
<tr>
<td>Print optimization progress on SAS log</td>
<td>RESET</td>
<td>PRINTLEVEL2=</td>
</tr>
</tbody>
</table>

**Interior Point Stopping Criteria Options:**

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Maximum number of interior point iterations</td>
<td>RESET</td>
<td>MAXITERB=</td>
</tr>
<tr>
<td>Primal-dual (duality) gap tolerance</td>
<td>RESET</td>
<td>PDGAPTOL=</td>
</tr>
<tr>
<td>Stop because of complementarity</td>
<td>RESET</td>
<td>STOP_C=</td>
</tr>
<tr>
<td>Stop because of duality gap</td>
<td>RESET</td>
<td>STOP_DG=</td>
</tr>
<tr>
<td>Stop because of $\text{infeas}_b$</td>
<td>RESET</td>
<td>STOP_IB=</td>
</tr>
<tr>
<td>Stop because of $\text{infeas}_c$</td>
<td>RESET</td>
<td>STOP_IC=</td>
</tr>
<tr>
<td>Stop because of $\text{infeas}_d$</td>
<td>RESET</td>
<td>STOP_ID=</td>
</tr>
<tr>
<td>Stop because of complementarity</td>
<td>RESET</td>
<td>AND_STOP_C=</td>
</tr>
<tr>
<td>Stop because of duality gap</td>
<td>RESET</td>
<td>AND_STOP_DG=</td>
</tr>
<tr>
<td>Stop because of $\text{infeas}_b$</td>
<td>RESET</td>
<td>AND_STOP_IB=</td>
</tr>
<tr>
<td>Stop because of $\text{infeas}_c$</td>
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<td>AND_STOP_IC=</td>
</tr>
<tr>
<td>Stop because of $\text{infeas}_d$</td>
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<td>AND_STOP_ID=</td>
</tr>
<tr>
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<td>KEEPGOING_C=</td>
</tr>
<tr>
<td>Stop because of duality gap</td>
<td>RESET</td>
<td>KEEPGOING_DG=</td>
</tr>
<tr>
<td>Stop because of $\text{infeas}_b$</td>
<td>RESET</td>
<td>KEEPGOING_IB=</td>
</tr>
<tr>
<td>Description</td>
<td>Statement</td>
<td>Option</td>
</tr>
<tr>
<td>-------------------------------------------------</td>
<td>-----------</td>
<td>----------------------</td>
</tr>
<tr>
<td>Stop because of $infeas_c$</td>
<td>RESET</td>
<td>KEEPGOING_IC=</td>
</tr>
<tr>
<td>Stop because of $infeas_d$</td>
<td>RESET</td>
<td>KEEPGOING_ID=</td>
</tr>
<tr>
<td>Stop because of complementarity</td>
<td>RESET</td>
<td>AND_KEEPGOING_C=</td>
</tr>
<tr>
<td>Stop because of duality gap</td>
<td>RESET</td>
<td>AND_KEEPGOING_DG=</td>
</tr>
<tr>
<td>Stop because of $infeas_b$</td>
<td>RESET</td>
<td>AND_KEEPGOING_IB=</td>
</tr>
<tr>
<td>Stop because of $infeas_c$</td>
<td>RESET</td>
<td>AND_KEEPGOING_IC=</td>
</tr>
<tr>
<td>Stop because of $infeas_d$</td>
<td>RESET</td>
<td>AND_KEEPGOING_ID=</td>
</tr>
</tbody>
</table>

**PRINT Statement Options:**
- Display everything: PRINT PROBLEM
- Display arc information: PRINT ARCS
- Display nonarc variable information: PRINT NONARCS
- Display variable information: PRINT VARIABLES
- Display constraint information: PRINT CONSTRAINTS
- Display information for some arcs: PRINT SOME_ARCS
- Display information for some nonarc variables: PRINT SOME_NONARCS
- Display information for some variables: PRINT SOME_VARIABLES
- Display information for some constraints: PRINT SOME_CONS
- Display information for some constraints associated with some arcs: PRINT CON_ARCS
- Display information for some constraints associated with some nonarc variables: PRINT CON_NONARCS
- Display information for some constraints associated with some variables: PRINT CON_VARIABLES

**PRINT Statement Qualifiers:**
- Produce a short report: PRINT / SHORT
- Produce a long report: PRINT / LONG
- Display arcs/variables with zero flow/value: PRINT / ZERO
- Display arcs/variables with nonzero flow/value: PRINT / NONZERO
- Display basic arcs/variables: PRINT / BASIC
- Display nonbasic arcs/variables: PRINT / NONBASIC

**SHOW Statement Options:**
- Show problem, optimization status: SHOW STATUS
- Show network model parameters: SHOW NETSTMT
- Show data sets that have been or will be created: SHOW DATASETS
- Show options that pause optimization: SHOW PAUSE
- Show simplex algorithm options: SHOW SIMPLEX
- Show pricing strategy options: SHOW PRICING
- Show miscellaneous options: SHOW MISC

**SHOW Statement Qualifiers:**
- Display information only on relevant options: SHOW / RELEVANT
- Display options for current stage only: SHOW / STAGE
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## Miscellaneous Options:

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
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<tr>
<td>Infinity value</td>
<td>PROC NETFLOW</td>
<td>INFINITY=</td>
</tr>
<tr>
<td>Scale constraint row, nonarc variable column coefficients, or both</td>
<td>PROC NETFLOW</td>
<td>SCALE=</td>
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<td>Maximization instead of minimization</td>
<td>PROC NETFLOW</td>
<td>MAXIMIZE</td>
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<td>Use warm start solution</td>
<td>PROC NETFLOW</td>
<td>WARM</td>
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<td>PROC NETFLOW</td>
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<td>Output complete basis information to ARCOU7= and NODEOUT= data sets</td>
<td>RESET</td>
<td>FUTURE1</td>
</tr>
<tr>
<td>Output complete basis information to CONOUT= and DUALOUT= data sets</td>
<td>RESET</td>
<td>FUTURE2</td>
</tr>
<tr>
<td>Turn off infeasibility or optimality flags</td>
<td>RESET</td>
<td>MOREOPT</td>
</tr>
<tr>
<td>Negates FUTURE1</td>
<td>RESET</td>
<td>NOFUTURE1</td>
</tr>
<tr>
<td>Negates FUTURE2</td>
<td>RESET</td>
<td>NOFUTURE2</td>
</tr>
<tr>
<td>Negates SCRATCH</td>
<td>RESET</td>
<td>NOSCRATCH</td>
</tr>
<tr>
<td>Negates ZTOL1</td>
<td>RESET</td>
<td>NOZTOL1</td>
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<tr>
<td>Negates ZTOL2</td>
<td>RESET</td>
<td>NOZTOL2</td>
</tr>
<tr>
<td>Write optimization time to SAS log</td>
<td>RESET</td>
<td>OPTIM_TIMER</td>
</tr>
<tr>
<td>No stage 1 optimization; do stage 2 optimization</td>
<td>RESET</td>
<td>SCRATCH</td>
</tr>
<tr>
<td>Suppress similar SAS log messages</td>
<td>RESET</td>
<td>VERBOSE=</td>
</tr>
<tr>
<td>Use zero tolerance, stage 1</td>
<td>RESET</td>
<td>ZTOL1</td>
</tr>
<tr>
<td>Use zero tolerance, stage 2</td>
<td>RESET</td>
<td>ZTOL2</td>
</tr>
</tbody>
</table>

## Interactivity

PROC NETFLOW can be used interactively. You begin by giving the PROC NETFLOW statement, and you must specify the ARCDATA= data set. The CONDATA= data set must also be specified if the problem has side constraints. If necessary, specify the NODEDATA= data set.

The variable lists should be given next. If you have variables in the input data sets that have special names (for example, a variable in the ARCDATA= data set named _TAIL_ that has tail nodes of arcs as values), it may not be necessary to have many or any variable lists.

The CONOPT, PIVOT, PRINT, QUIT, SAVE, SHOW, RESET, and RUN statements follow and can be listed in any order. The CONOPT and QUIT statements can be used only once. The others can be used as many times as needed.

Use the RESET or SAVE statement to change the names of the output data sets. With RESET, you can also indicate the reasons why optimization should stop (for example, you can indicate the maximum number of stage 1 or stage 2 iterations that can be performed). PROC NETFLOW then has a chance to either execute the next statement, or, if the next statement is one that PROC NETFLOW does not recognize (the next PROC or DATA step in the SAS session), do any allowed optimization and finish. If no new statement has been
submitted, you are prompted for one. Some options of the RESET statement enable you to control aspects of
the primal simplex algorithm. Specifying certain values for these options can reduce the time it takes to solve
a problem. Note that any of the RESET options can be specified in the PROC NETFLOW statement.

The RUN statement starts or resumes optimization. The PIVOT statement makes PROC NETFLOW perform
one simplex iteration. The QUIT statement immediately stops PROC NETFLOW. The CONOPT statement
forces PROC NETFLOW to consider constraints when it next performs optimization. The SAVE statement
has options that enable you to name output data sets; information about the current solution is put in these
output data sets. Use the SHOW statement if you want to examine the values of options of other statements.
Information about the amount of optimization that has been done and the STATUS of the current solution can
also be displayed using the SHOW statement.

The PRINT statement instructs PROC NETFLOW to display parts of the problem. PRINT ARCS produces
information on all arcs. PRINT SOME_ARCS limits this output to a subset of arcs. There are similar PRINT
statements for nonarc variables and constraints:

    print nonarcs;
    print some_nonarcs;
    print constraints;
    print some_cons;

PRINT CON_ARCS enables you to limit constraint information that is obtained to members of a set of arcs
that have nonzero constraint coefficients in a set of constraints. PRINT CON_NONARCS is the corresponding
statement for nonarc variables.

For example, an interactive PROC NETFLOW run might look something like this:

proc netflow arcdata= data set
    other options;
    variable list specifications; /* if necessary */
    reset options;
    print options; /* look at problem */
    run; /* do some optimization */
    /* suppose that optimization stopped for */
    /* some reason or you manually stopped it */
    print options; /* look at the current solution */
    save options; /* keep current solution */
    show options; /* look at settings */
    reset options; /* change some settings, those that */
        /* caused optimization to stop */
    run; /* do more optimization */
    print options; /* look at the optimal solution */
    save options; /* keep optimal solution */

If you are interested only in finding the optimal solution, have used SAS variables that have special names in
the input data sets, and want to use default settings for everything, then the following statement is all you
need:

    PROC NETFLOW ARCDATA= data set ;
PROC NETFLOW Statement

PROC NETFLOW options;

This statement invokes the procedure. The following options and the options listed with the RESET statement can appear in the PROC NETFLOW statement.

Data Set Options

This section briefly describes all the input and output data sets used by PROC NETFLOW. The ARCDATA= data set, NODEDATA= data set, and CONDATA= data set can contain SAS variables that have special names, for instance _CAPAC_, _COST_, and _HEAD_. PROC NETFLOW looks for such variables if you do not give explicit variable list specifications. If a SAS variable with a special name is found and that SAS variable is not in another variable list specification, PROC NETFLOW determines that values of the SAS variable are to be interpreted in a special way. By using SAS variables that have special names, you may not need to have any variable list specifications.

ARCDATA=SAS-data-set

names the data set that contains arc and, optionally, nonarc variable information and nodal supply/demand data. The ARCDATA= data set must be specified in all PROC NETFLOW statements.

ARCOUt=SAS-data-set

names the output data set that receives all arc and nonarc variable data, including flows or values, and other information concerning the unconstrained optimal solution. The supply and demand information can also be found in the ARCOUt= data set. Once optimization that considers side constraints starts, you are not able to obtain an ARCOUt= data set. Instead, use the CONOUT= data set to get the current solution. See the section “ARCOUt= and CONOUT= Data Sets” on page 389 for more information.

CONDATA=SAS-data-set

names the data set that contains the side constraint data. The data set can also contain other data such as arc costs, capacities, lower flow bounds, nonarc variable upper and lower bounds, and objective function coefficients. PROC NETFLOW needs a CONDATA= data set to solve a constrained problem or a linear programming problem. See the section “CONDATA= Data Set” on page 380 for more information.

CONOUT=SAS-data-set

names the output data set that receives an optimal primal solution to the problem obtained by performing optimization that considers the side constraints. See the section “ARCOUt= and CONOUT= Data Sets” on page 389 for more information.

DUALOUT=SAS-data-set

names the output data set that receives an optimal dual solution to the problem obtained by performing optimization that considers the side constraints. See the section “NODEOUT= and DUALOUT= Data Sets” on page 390 for more information.
**PROC NETFLOW Statement**

**NODEDATA=SAS-data-set**
names the data set that contains the node supply and demand specifications. You do not need observations in the NODEDATA= data set for trans-shipment nodes. (Trans-shipment nodes neither supply nor demand flow.) All nodes are assumed to be trans-shipment nodes unless supply or demand data indicate otherwise. It is acceptable for some arcs to be directed toward supply nodes or away from demand nodes.

The use of the NODEDATA= data set is optional in the PROC NETFLOW statement provided that, if the NODEDATA= data set is not used, supply and demand details are specified by other means. Other means include using the MAXFLOW or SHORTPATH option, SUPPLY or DEMAND list variables (or both) in the ARCDATA= data set, and the SOURCE=, SUPPLY=, SINK=, or DEMAND= option in the PROC NETFLOW statement.

**NODEOUT=SAS-data-set**
names the output data set that receives all information about nodes (supply and demand and nodal dual variable values) and other information concerning the optimal solution found by the optimizer when neglecting side constraints. Once optimization that considers side constraints starts, you are not able to obtain a NODEOUT= data set. Instead, use the DUALOUT= data set to get the current solution dual information. See the section “NODEOUT= and DUALOUT= Data Sets” on page 390 for a more complete description.

**MPSOUT=SAS-data-set**
names the SAS data set that contains converted sparse or dense format input data in MPS format. Invoking this option directs the NETFLOW procedure to halt before attempting optimization. For more information about the MPSOUT= option, see the section “Converting Any PROC NETFLOW Format to an MPS-Format SAS Data Set” on page 391. For more information about the MPS-format SAS data set, see Chapter 17, “The MPS-Format SAS Data Set” (SAS/OR User’s Guide: Mathematical Programming).

**General Options**

The following is a list of options you can use with PROC NETFLOW. The options are listed in alphabetical order.

**ALLART**
indicates that PROC NETFLOW uses an all artificial initial solution (Kennington and Helgason 1980, p. 68) instead of the default good path method for determining an initial solution (Kennington and Helgason 1980, p. 245). The ALLART initial solution is generally not as good; more iterations are usually required before the optimal solution is obtained. However, because less time is used when setting up an ALLART start, it can offset the added expenditure of CPU time in later computations.

**ARCS_ONLY_ARCDATA**
indicates that data for only arcs are in the ARCDATA= data set. When PROC NETFLOW reads the data in ARCDATA= data set, memory would not be wasted to receive data for nonarc variables. The read might then be performed faster. See the section “How to Make the Data Read of PROC NETFLOW More Efficient” on page 410.
**ARC_SINGLE_OBS** indicates that for all arcs and nonarc variables, data for each arc or nonarc variable is found in only one observation of the ARCDATA= data set. When reading the data in the ARCDATA= data set, PROC NETFLOW knows that the data in an observation is for an arc or a nonarc variable that has not had data previously read that needs to be checked for consistency. The read might then be performed faster.

If you specify ARC_SINGLE_OBS, PROC NETFLOW automatically works as if GROUPED=ARCDATA is also specified. See the section “How to Make the Data Read of PROC NETFLOW More Efficient” on page 410.

**BYPASSDIVIDE=b**

**BYPASSDIV=b**

**BPD=b** should be used only when the MAXFLOW option has been specified; that is, PROC NETFLOW is solving a maximal flow problem. PROC NETFLOW prepares to solve maximal flow problems by setting up a bypass arc. This arc is directed from the SOURCE to the SINK and will eventually convey flow equal to INFINITY minus the maximal flow through the network. The cost of the bypass arc must be expensive enough to drive flow through the network, rather than through the bypass arc. However, the cost of the bypass arc must be less than the cost of artificial variables (otherwise these might have nonzero optimal value and a false infeasibility error will result). Also, the cost of the bypass arc must be greater than the eventual total cost of the maximal flow, which can be nonzero if some network arcs have nonzero costs. The cost of the bypass is set to the value of the INFINITY= option. Valid values for the BYPASSDIVIDE= option must be greater than or equal to 1.1.

If there are no nonzero costs of arcs in the MAXFLOW problem, the cost of the bypass arc is set to 1.0 (-1.0 if maximizing) if you do not specify the BYPASSDIVIDE= option. The reduced costs in the ARCOUT= data set and the CONOUT= data set will correctly reflect the value that would be added to the maximal flow if the capacity of the arc is increased by one unit. If there are nonzero costs, or if you specify the BYPASSDIVIDE= option, the reduced costs may be contaminated by the cost of the bypass arc and no economic interpretation can be given to reduced cost values. The default value for the BYPASSDIVIDE= option (in the presence of nonzero arc costs) is 100.0.

**BYTES=b**

indicates the size of the main working memory (in bytes) that PROC NETFLOW will allocate. The default value for the BYTES= option is near to the number of bytes of the largest contiguous memory that can be allocated for this purpose. The working memory is used to store all the arrays and buffers used by PROC NETFLOW. If this memory has a size smaller than what is required to store all arrays and buffers, PROC NETFLOW uses various schemes that page information between memory and disk.

PROC NETFLOW uses more memory than the main working memory. The additional memory requirements cannot be determined at the time when the main working memory is allocated. For example, every time an output data set is created, some additional memory is required. Do not specify a value for the BYTES= option equal to the size of available memory.

**CON_SINGLE_OBS** improves how the CONDATA= data set is read. How it works depends on whether the CONDATA has a dense or sparse format.

If CONDATA has the dense format, specifying CON_SINGLE_OBS indicates that, for each constraint, data can be found in only one observation of CONDATA.
If `CONDATA` has a sparse format, and data for each arc and nonarc variable can be found in only one observation of `CONDATA`, then specify the `CON_SINGLE_OBS` option. If there are `n` SAS variables in the `ROW` and `COEF` list, then each arc or nonarc can have at most `n` constraint coefficients in the model. See the section “How to Make the Data Read of PROC NETFLOW More Efficient” on page 410.

`COREFACTOR=c`  
`CF=c`

enables you to specify the maximum proportion of memory to be used by the arrays frequently accessed by PROC NETFLOW. PROC NETFLOW strives to maintain all information required during optimization in core. If the amount of available memory is not great enough to store the arrays completely in core, either initially or as memory requirements grow, PROC NETFLOW can change the memory management scheme it uses. Large problems can still be solved. When necessary, PROC NETFLOW transfers data from random access memory (RAM) or core that can be accessed quickly but is of limited size to slower access large capacity disk memory. This is called *paging*.

Some of the arrays and buffers used during constrained optimization either vary in size, are not required as frequently as other arrays, or are not required throughout the simplex iteration. Let `a` be the amount of memory in bytes required to store frequently accessed arrays of nonvarying size. Specify the `MEMREP` option in the PROC NETFLOW statement to get the value for `a` and a report of memory usage. If the size of the main working memory `BYTES=b` multiplied by `COREFACTOR=c` is greater than `a`, PROC NETFLOW keeps the frequently accessed arrays of nonvarying size resident in core throughout the optimization. If the other arrays cannot fit into core, they are paged in and out of the remaining part of the main working memory.

If `b` multiplied by `c` is less than `a`, PROC NETFLOW uses a different memory scheme. The working memory is used to store only the arrays needed in the part of the algorithm being executed. If necessary, these arrays are read from disk into the main working area. Paging, if required, is done for all these arrays, and sometimes information is written back to disk at the end of that part of the algorithm. This memory scheme is not as fast as the other memory schemes. However, problems can be solved with memory that is too small to store every array.

PROC NETFLOW is capable of solving very large problems in a modest amount of available memory. However, as more time is spent doing input/output operations, the speed of PROC NETFLOW decreases. It is important to choose the value of the `COREFACTOR=` option carefully. If the value is too small, the memory scheme that needs to be used might not be as efficient as another that could have been used had a larger value been specified. If the value is too large, too much of the main working memory is occupied by the frequently accessed, nonvarying sized arrays, leaving too little for the other arrays. The amount of input/output operations for these other arrays can be so high that another memory scheme might have been used more beneficially.

The valid values of `COREFACTOR=c` are between 0.0 and 0.95, inclusive. The default value for `c` is 0.75 when there are over 200 side constraints, and 0.9 when there is only one side constraint. When the problem has between 2 and 200 constraints, the value of `c` lies between the two points (1, 0.9) and (201, 0.75).

`DEFCAPACITY=c`  
`DC=c`

requests that the default arc capacity and the default nonarc variable value upper bound be `c`. If this option is not specified, then `DEFCAPACITY= INFINITY`. 


DEFCONTYPE=c
DEFTYPE=c
DCT=c

specifies the default constraint type. This default constraint type is either less than or equal to or is the type indicated by DEFCONTYPE=c. Valid values for this option are

LE, le, <= for less than or equal to
EQ, eq, = for equal to
GE, ge, >= for greater than or equal to

The values do not need to be enclosed in quotes.

DEFCOST=c
requests that the default arc cost and the default nonarc variable objective function coefficient be c. If this option is not specified, then DEFCOST=0.0.

DEFMINFLOW=m
DMF=m
requests that the default lower flow bound through arcs and the default lower value bound of nonarc variables be m. If a value is not specified, then DEFMINFLOW=0.0.

DEMAND=d
specifies the demand at the SINK node specified by the SINK= option. The DEMAND= option should be used only if the SINK= option is given in the PROC NETFLOW statement and neither the SHORTPATH option nor the MAXFLOW option is specified. If you are solving a minimum cost network problem and the SINK= option is used to identify the sink node, but the DEMAND= option is not specified, then the demand at the sink node is made equal to the network’s total supply.

DWIA=i
controls the initial amount of memory to be allocated to store the LU factors of the working basis matrix. DWIA stands for $D_W$ initial allocation and i is the number of nonzeros and matrix row operations in the LU factors that can be stored in this memory. Due to fill-in in the U factor and the growth in the number of row operations, it is often necessary to move information about elements of a particular row or column to another location in the memory allocated for the LU factors. This process leaves some memory temporarily unoccupied. Therefore, DWIA=i must be greater than the memory required to store only the LU factors.

Occasionally, it is necessary to compress the U factor so that it again occupies contiguous memory. Specifying too large a value for DWIA means that more memory is required by PROC NETFLOW. This might cause more expensive memory mechanisms to be used than if a smaller but adequate value had been specified for DWIA=. Specifying too small a value for the DWIA= option can make time-consuming compressions more numerous. The default value for the DWIA= option is eight times the number of side constraints.

EXCESS=option
enables you to specify how to handle excess supply or demand in a network, if it exists.

For pure networks EXCESS=ARCS and EXCESS=SLACKS are valid options. By default EXCESS=ARCS is used. Note that if you specify EXCESS=SLACKS, then the interior point solver is
used and you need to specify the output data set using the CONOUT= data set. For more details see the section “Using the New EXCESS= Option in Pure Networks: NETFLOW Procedure” on page 454.

For generalized networks you can either specify EXCESS=DEMAND or EXCESS=SUPPLY to indicate that the network has excess demand or excess supply, respectively. For more details see the section “Using the New EXCESS= Option in Generalized Networks: NETFLOW Procedure” on page 461.

**GENNET**

This option is necessary if you need to solve a generalized network flow problem and there are no arc multipliers specified in the ARCDATA= data set.

**GROUPED=**

PROC NETFLOW can take a much shorter time to read data if the data have been grouped prior to the PROC NETFLOW call. This enables PROC NETFLOW to conclude that, for instance, a new NAME list variable value seen in an ARCDATA= data set grouped by the values of the NAME list variable before PROC NETFLOW was called is new. PROC NETFLOW does not need to check that the NAME has been read in a previous observation. See the section “How to Make the Data Read of PROC NETFLOW More Efficient” on page 410.

- **GROUPED=ARCDATA** indicates that the ARCDATA= data set has been grouped by values of the NAME list variable. If _NAME_ is the name of the NAME list variable, you could use PROC SORT DATA=ARCDATA; BY _NAME_; prior to calling PROC NETFLOW. Technically, you do not have to sort the data, only ensure that all similar values of the NAME list variable are grouped together. If you specify the ARCS_ONLY_ARCDATA option, PROC NETFLOW automatically works as if GROUPED=ARCDATA is also specified.

- **GROUPED=CONDATA** indicates that the CONDATA= data set has been grouped.
  If the CONDATA= data set has a dense format, GROUPED=CONDATA indicates that the CONDATA= data set has been grouped by values of the ROW list variable. If _ROW_ is the name of the ROW list variable, you could use PROC SORT DATA=CONDATA; BY _ROW_; prior to calling PROC NETFLOW. Technically, you do not have to sort the data, only ensure that all similar values of the ROW list variable are grouped together. If you specify the CON_SINGLE_OBS option, or if there is no ROW list variable, PROC NETFLOW automatically works as if GROUPED=CONDATA has been specified.

  If the CONDATA= data set has the sparse format, GROUPED=CONDATA indicates that the CONDATA= data set has been grouped by values of the COLUMN list variable. If _COL_ is the name of the COLUMN list variable, you could use PROC SORT DATA=CONDATA; BY _COL_; prior to calling PROC NETFLOW. Technically, you do not have to sort the data, only ensure that all similar values of the COLUMN list variable are grouped together.

- **GROUPED=BOTH** indicates that both GROUPED=ARCDATA and GROUPED=CONDATA are TRUE.

- **GROUPED=NONE** indicates that the data sets have not been grouped, that is, neither GROUPED=ARCDATA nor GROUPED=CONDATA is TRUE. This is the default, but it is much better if GROUPED=ARCDATA, or GROUPED=CONDATA, or GROUPED=BOTH.
A data set like

\[
\ldots \_XXXXX\_ \ldots
\]

bbb
bbb
aaa
ccc
ccc

is a candidate for the `GROUPED=` option. Similar values are grouped together. When PROC NETFLOW is reading the \textit{i}th observation, either the value of the \_XXXXX\_ variable is the same as the \((i - 1)\)st (that is, the previous observation’s) \_XXXXX\_ value, or it is a new \_XXXXX\_ value not seen in any previous observation. This also means that if the \textit{i}th \_XXXXX\_ value is different from the \((i - 1)\)st \_XXXXX\_ value, the value of the \((i - 1)\)st \_XXXXX\_ variable will not be seen in any observations \(i, i + 1, \ldots\).

**INFINITY=i**

**INF=i**

is the largest number used by PROC NETFLOW in computations. A number too small can adversely affect the solution process. You should avoid specifying an enormous value for the `INFINITY=` option because numerical roundoff errors can result. If a value is not specified, then `INFINITY=99999999`. The `INFINITY=` option cannot be assigned a value less than 9999.

**INTPOINT**

indicates that the interior point algorithm is to be used. The `INTPOINT` option must be specified if you want the interior point algorithm to be used for solving network problems, otherwise the simplex algorithm is used instead. For linear programming problems (problems with no network component), PROC NETFLOW must use the interior point algorithm, so you need not specify the `INTPOINT` option.

**INVD_2D**

controls the way in which the inverse of the working basis matrix is stored. How this matrix is stored affects computations as well as how the working basis or its inverse is updated. The working basis matrix is defined in the section “Details: NETFLOW Procedure” on page 380. If `INVD_2D` is specified, the working basis matrix inverse is stored as a matrix. Typically, this memory scheme is best when there are few side constraints or when the working basis is dense.

If `INVD_2D` is not specified, lower (\(L\)) and upper (\(U\)) factors of the working basis matrix are used. \(U\) is an upper triangular matrix and \(L\) is a lower triangular matrix corresponding to a sequence of elementary matrix row operations. The sparsity-exploiting variant of the Bartels-Golub decomposition is used to update the \(LU\) factors. This scheme works well when the side constraint coefficient matrix is sparse or when many side constraints are nonbinding.

**MAXARRAYBYTES=m**

specifies the maximum number of bytes an individual array can occupy. This option is of most use when solving large problems and the amount of available memory is insufficient to store all arrays at once. Specifying the `MAXARRAYBYTES=` option ensures that arrays that need a large amount of memory do not consume too much memory at the expense of other arrays.

There is one array that contains information about nodes and the network basis spanning tree description. This tree description enables computations involving the network part of the basis to be performed
very quickly and is the reason why PROC NETFLOW is more suited to solving constrained network problems than PROC LP. It is beneficial that this array be stored in core when possible, otherwise this array must be paged, slowing down the computations. Try not to specify a MAXARRAYBYTES=m value smaller than the amount of memory needed to store the main node array. You are told what this memory amount is on the SAS log if you specify the MEMREP option in the PROC NETFLOW statement.

MAXFLOW
MF
specifies that PROC NETFLOW solve a maximum flow problem. In this case, the PROC NETFLOW procedure finds the maximum flow from the node specified by the SOURCE= option to the node specified by the SINK= option. PROC NETFLOW automatically assigns an INFINITY= option supply to the SOURCE= option node and the SINK= option is assigned the INFINITY= option demand. In this way, the MAXFLOW option sets up a maximum flow problem as an equivalent minimum cost problem.

You can use the MAXFLOW option when solving any flow problem (not necessarily a maximum flow problem) when the network has one supply node (with infinite supply) and one demand node (with infinite demand). The MAXFLOW option can be used in conjunction with all other options (except SHORTPATH, SUPPLY=, and DEMAND=) and capabilities of PROC NETFLOW.

MAXIMIZE
MAX
specifies that PROC NETFLOW find the maximum cost flow through the network. If both the MAXIMIZE and the SHORTPATH options are specified, the solution obtained is the longest path between the SOURCE= and SINK= nodes. Similarly, MAXIMIZE and MAXFLOW together cause PROC NETFLOW to find the minimum flow between these two nodes; this is zero if there are no nonzero lower flow bounds.

MEMREP
indicates that information on the memory usage and paging schemes (if necessary) is reported by PROC NETFLOW on the SAS log. As optimization proceeds, you are informed of any changes in the memory requirements and schemes used by PROC NETFLOW.

NAMECTRL=i
is used to interpret arc and nonarc variable names in the CONDATA= data set.

In the ARCDATA= data set, an arc is identified by its tail and head node. In the CONDATA= data set, arcs are identified by names. You can give a name to an arc by having a NAME list specification that indicates a SAS variable in the ARCDATA= data set that has names of arcs as values.

PROC NETFLOW requires arcs that have information about them in the CONDATA= data set to have names, but arcs that do not have information about them in the CONDATA= data set can also have names. Unlike a nonarc variable whose name uniquely identifies it, an arc can have several different names. An arc has a default name in the form tail_head, that is, the name of the arc’s tail node followed by an underscore and the name of the arc’s head node.

In the CONDATA= data set, if the dense data format is used, (described in the section “CONDATA= Data Set” on page 380) a name of an arc or a nonarc variable is the name of a SAS variable listed in the VAR list specification. If the sparse data format of the CONDATA= data set is used, a name of an arc or a nonarc variable is a value of the SAS variable listed in the COLUMN list specification.
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The NAMECTRL= option is used when a name of an arc or nonarc variable in the CONDATA= data set (either a VAR list SAS variable name or value of the COLUMN list SAS variable) is in the form tail_head and there exists an arc with these end nodes. If tail_head has not already been tagged as belonging to an arc or nonarc variable in the ARCDATA= data set, PROC NETFLOW needs to know whether tail_head is the name of the arc or the name of a nonarc variable.

If you specify NAMECTRL=1, a name that is not defined in the ARCDATA= data set is assumed to be the name of a nonarc variable. NAMECTRL=2 treats tail_head as the name of the arc with these endnodes, provided no other name is used to associate data in the CONDATA= data set with this arc. If the arc does have other names that appear in the CONDATA= data set, tail_head is assumed to be the name of a nonarc variable. If you specify NAMECTRL=3, tail_head is assumed to be a name of the arc with these end nodes, whether the arc has other names or not. The default value of NAMECTRL is 3. Note that if you use the dense side constraint input format, the default arc name tail_head is not recognized (regardless of the NAMECTRL value) unless the head node and tail node names contain no lowercase letters.

If the dense format is used for the CONDATA= data set, the SAS System converts SAS variable names in a SAS program to uppercase. The VAR list variable names are uppercased. Because of this, PROC NETFLOW automatically uppercases names of arcs and nonarc variables (the values of the NAME list variable) in the ARCDATA= data set. The names of arcs and nonarc variables (the values of the NAME list variable) appear upcased in the ARCOUT= data set and the CONOUT= data set, and in the PRINT statement output.

Also, if the dense format is used for the CONDATA= data set, be careful with default arc names (names in the form tailnode_headnode). Node names (values in the TAILNODE and HEADNODE list variables) in the ARCDATA= data set are not uppercased by PROC NETFLOW. Consider the following code:

```sas
data arcdata;
  input _from_ $ _to_ $ _name $ ;
datalines;
  from to1 .
  from to2 arc2
  TAIL TO3 .
;
data densecon;
  input from_to1 from_to2 arc2 tail_to3;
datalines;
  2 3 3 5
;
proc netflow
  arcedata=arcdata condata=densecon;
run;
```

The SAS System does not uppercase character string values. PROC NETFLOW never uppercases node names, so the arcs in observations 1, 2, and 3 in the preceding ARCDATA= data set have the default names “from_to1”, “from_to2”, and “TAIL_TO3”, respectively. When the dense format of the CONDATA= data set is used, PROC NETFLOW does uppercase values of the NAME list variable, so the name of the arc in the second observation of the ARCDATA= data set is “ARC2”. Thus, the second arc has two names: its default “from_to2” and the other that was specified “ARC2”.
As the SAS System does uppercase program code, you must think of the input statement

```
input from_to1 from_to2 arc2 tail_to3;
```

as really being

```
INPUT FROM_TO1 FROM_TO2 ARC2 TAIL_TO3;
```

The SAS variables named “FROM_TO1” and “FROM_TO2” are not associated with any of the arcs in the preceding ARCDATA= data set. The values “FROM_TO1” and “FROM_TO2” are different from all of the arc names “from_to1”, “from_to2”, “TAIL_TO3”, and “ARC2”. “FROM_TO1” and “FROM_TO2” could end up being the names of two nonarc variables. It is sometimes useful to specify PRINT NONARCS; before commencing optimization to ensure that the model is correct (has the right set of nonarc variables).

The SAS variable named “ARC2” is the name of the second arc in the ARCDATA= data set, even though the name specified in the ARCDATA= data set looks like “arc2”. The SAS variable named “TAIL_TO3” is the default name of the third arc in the ARCDATA= data set.

**NARCS=n**

specifies the approximate number of arcs. See the section “How to Make the Data Read of PROC NETFLOW More Efficient” on page 410.

**NCOEFS=n**

specifies the approximate number of constraint coefficients. See the section “How to Make the Data Read of PROC NETFLOW More Efficient” on page 410.

**NCONS=n**

specifies the approximate number of constraints. See the section “How to Make the Data Read of PROC NETFLOW More Efficient” on page 410.

**NNAS=n**

specifies the approximate number of nonarc variables. See the section “How to Make the Data Read of PROC NETFLOW More Efficient” on page 410.

**NNODES=n**

specifies the approximate number of nodes. See the section “How to Make the Data Read of PROC NETFLOW More Efficient” on page 410.

**NON_REPLIC=non_replic**

prevents PROC NETFLOW from doing unnecessary checks of data previously read.

- **NON_REPLIC=COEFS** indicates that each constraint coefficient is specified once in the CONDATA= data set.
- **NON_REPLIC=NONE** indicates that constraint coefficients can be specified more than once in the CONDATA= data set. NON_REPLIC=NONE is the default.

See the section “How to Make the Data Read of PROC NETFLOW More Efficient” on page 410.
**RHSOBS=charstr**

specifies the keyword that identifies a right-hand-side observation when using the `sparse` format for data in the `CONDATA=` data set. The keyword is expected as a value of the SAS variable in the `CONDATA=` data set named in the `COLUMN` list specification. The default value of the `RHSOBS=` option is `_RHS_` or `_rhs_`. If `charstr` is not a valid SAS variable name, enclose it in single quotes.

**SAME_NONARC_DATA**

If all nonarc variable data are given in the `ARCDATA=` data set, or if the problem has no nonarc variables, the unconstrained warm start can be read more quickly if the option `SAME_NONARC_DATA` is specified. `SAME_NONARC_DATA` indicates that any nonconstraint nonarc variable data in the `CONDATA=` data set is to be ignored. Only side constraint data in the `CONDATA=` data set are read.

If you use an unconstrained warm start and `SAME_NONARC_DATA` is not specified, any nonarc variable objective function coefficient, upper bound, or lower bound can be changed. Any nonarc variable data in the `CONDATA=` data set overrides (without warning messages) corresponding data in the `ARCDATA=` data set. You can possibly introduce new nonarc variables to the problem, that is, nonarc variables that were not in the problem when the warm start was generated.

`SAME_NONARC_DATA` should be specified if nonarc variable data in the `CONDATA=` data set are to be deliberately ignored. Consider

```sas
proc netflow options arcdata=arc0 nodedata=node0
   condata=con0
   /* this data set has nonarc variable */
   /* objective function coefficient data */
   future1 arcout=arc1 nodeout=node1;
run;

data arc2;
   reset arc1; /* this data set has nonarc variable obs */
   if _cost_<50.0 then _cost_=_cost_*1.25;
   /* some objective coefficients of nonarc */
   /* variable might be changed */
proc netflow options
   warm arcdata=arc2 nodedata=node1
   condata=con0 same_nonarc_data
   /* This data set has old nonarc variable */
   /* obj, fn. coefficients. same_nonarc_data */
   /* indicates that the "new" coefs in the */
   /* arcdata=arc2 are to be used. */
run;
```

**SCALE=scale**

indicates that the side constraints are to be scaled. Scaling is useful when some coefficients of a constraint or nonarc variable are either much larger or much smaller than other coefficients. Scaling might make all coefficients have values that have a smaller range, and this can make computations more stable numerically. Try the `SCALE=` option if PROC NETFLOW is unable to solve a problem because of numerical instability. Specify

- `SCALE=ROW`, `SCALE=CON`, or `SCALE=CONSTRAINT` if the largest absolute value of coefficients in each constraint is about 1.0
• SCALE=COL, SCALE=COLUMN, or SCALE=NONARC if nonarc variable columns are scaled so that the absolute value of the largest constraint coefficient of a nonarc variable is near to 1

• SCALE=BOTH if the largest absolute value of coefficients in each constraint, and the absolute value of the largest constraint coefficient of a nonarc variable is near to 1. This is the default.

• SCALE=NONE if no scaling should be done

**SHORTPATH**

**SP**
specifies that PROC NETFLOW solve a shortest path problem. The NETFLOW procedure finds the shortest path between the nodes specified in the SOURCE= option and the SINK= option. The costs of arcs are their *lengths*. PROC NETFLOW automatically assigns a supply of one flow unit to the SOURCE= node, and the SINK= node is assigned to have a one flow unit demand. In this way, the SHORTPATH option sets up a shortest path problem as an equivalent minimum cost problem.

If a network has one supply node (with supply of one unit) and one demand node (with demand of one unit), you could specify the SHORTPATH option, with the SOURCE= and SINK= nodes, even if the problem is not a shortest path problem. You then should not provide any supply or demand data in the NODEDATA= data set or the ARCDATA= data set.

**SINK=** *sinkname*

**SINKNODE=** *sinkname*

identifies the demand node. The SINK= option is useful when you specify the MAXFLOW option or the SHORTPATH option and need to specify toward which node the shortest path or maximum flow is directed. The SINK= option also can be used when a minimum cost problem has only one demand node. Rather than having this information in the ARCDATA= data set or the NODEDATA= data set, use the SINK= option with an accompanying DEMAND= specification for this node. The SINK= option must be the name of a head node of at least one arc; thus, it must have a character value. If the value of the SINK= option is not a valid SAS character variable name, it must be enclosed in single quotes and can contain embedded blanks.

**SOURCE=** *sourcename*

**SOURCENODE=** *sourcename*

identifies a supply node. The SOURCE= option is useful when you specify the MAXFLOW or the SHORTPATH option and need to specify from which node the shortest path or maximum flow originates. The SOURCE= option also can be used when a minimum cost problem has only one supply node. Rather than having this information in the ARCDATA= data set or the NODEDATA= data set, use the SOURCE= option with an accompanying SUPPLY= amount of supply at this node. The SOURCE= option must be the name of a tail node of at least one arc; thus, it must have a character value. If the value of the SOURCE= option is not a valid SAS character variable name, it must be enclosed in single quotes and can contain embedded blanks.

**SPARSECONDATA**

**SCDATA**

indicates that the CONDATA= data set has data in the sparse data format. Otherwise, it is assumed that the data are in the dense format.

**NOTE:** If the SPARSECONDATA option is not specified, and you are running SAS software Version 6 or you have specified options validvarname=v6; all NAME list variable values in the ARCDATA= data set are uppercased. See the section “Case Sensitivity” on page 392.
SPARSEP2

SP2 indicates that the new column of the working basis matrix that replaces another column be held in a linked list. If the SPARSEP2 option is not specified, a one-dimensional array is used to store this column’s information, that can contain elements that are 0.0 and use more memory than the linked list. The linked list mechanism requires more work if the column has numerous nonzero elements in many iterations. Otherwise, it is superior. Sometimes, specifying SPARSEP2 is beneficial when the side constrained coefficient matrix is very sparse or when some paging is necessary.

SUPPLY=s

specifies the supply at the source node specified by the SOURCE= option. The SUPPLY= option should be used only if the SOURCE= option is given in the PROC NETFLOW statement and neither the SHORTPATH option nor the MAXFLOW option is specified. If you are solving a minimum cost network problem and the SOURCE= option is used to identify the source node and the SUPPLY= option is not specified, then by default the supply at the source node is made equal to the network’s total demand.

THRUNET

tells PROC NETFLOW to force through the network any excess supply (the amount by which total supply exceeds total demand) or any excess demand (the amount by which total demand exceeds total supply) as is required. If a network problem has unequal total supply and total demand and the THRUNET option is not specified, PROC NETFLOW drains away the excess supply or excess demand in an optimal manner. The consequences of specifying or not specifying THRUNET are discussed in the section “Balancing Total Supply and Total Demand” on page 405.

TYPEOBS=charstr

specifies the keyword that identifies a type observation when using the sparse format for data in the CONDATA= data set. The keyword is expected as a value of the SAS variable in the CONDATA= data set named in the COLUMN list specification. The default value of the TYPEOBS= option is _TYPE_ or _type_. If charstr is not a valid SAS variable name, enclose it in single quotes.

WARM

indicates that the NODEDATA= data set or the DUALIN= data set and the ARCDATA= data set contain extra information of a warm start to be used by PROC NETFLOW. See the section “Warm Starts” on page 406.

CAPACITY Statement

CAPACITY variable ;
CAPAC variable ;
UPPERBD variable ;

The CAPACITY statement identifies the SAS variable in the ARCDATA= data set that contains the maximum feasible flow or capacity of the network arcs. If an observation contains nonarc variable information, the CAPACITY list variable is the upper value bound for the nonarc variable named in the NAME list variable in that observation. The CAPACITY list variable must have numeric values. It is not necessary to have a CAPACITY statement if the name of the SAS variable is _CAPAC_, _UPPER_, _UPPERBD_, or _HI_.

**COEF Statement**

```latex
COEF variables ;
```

The COEF list is used with the sparse input format of the CONDATA= data set. The COEF list can contain more than one SAS variable, each of which must have numeric values. If the COEF statement is not specified, the CONDATA= data set is searched and SAS variables with names beginning with _COE are used. The number of SAS variables in the COEF list must be no greater than the number of SAS variables in the ROW list.

The values of the COEF list variables in an observation can be interpreted differently than these variables’ values in other observations. The values can be coefficients in the side constraints, costs and objective function coefficients, bound data, constraint type data, or rhs data. If the COLUMN list variable has a value that is a name of an arc or nonarc variable, the $i$th COEF list variable is associated with the constraint or special row name named in the $i$th ROW list variable. Otherwise, the COEF list variables indicate type values, rhs values, or missing values.

**COLUMN Statement**

```latex
COLUMN variable ;
```

The COLUMN list is used with the sparse input format of side constraints. This list consists of one SAS variable in the CONDATA= data set that has as values the names of arc variables, nonarc variables, or missing values. Some, if not all of these values, also can be values of the NAME list variables of the ARCDATA= data set. The COLUMN list variable can have other special values (refer to the TYPEOBS= and RHSOBS= options). If the COLUMN list is not specified after the PROC NETFLOW statement, the CONDATA= data set is searched and a SAS variable named _COLUMN_ is used. The COLUMN list variable must have character values.

**CONOPT Statement**

```latex
CONOPT ;
```

The CONOPT statement has no options. It is equivalent to specifying RESET SCRATCH;. The CONOPT statement should be used before stage 2 optimization commences. It indicates that the optimization performed next should consider the side constraints.

Usually, the optimal unconstrained network solution is used as a starting solution for constrained optimization. Finding the unconstrained optimum usually reduces the amount of stage 2 optimization. Furthermore, the unconstrained optimum is almost always “closer” to the constrained optimum than the initial basic solution determined before any optimization is performed. However, as the optimum is approached during stage 1 optimization, the flow change candidates become scarcer and a solution good enough to start stage 2 optimization may already be at hand. You should then specify the CONOPT statement.
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COST Statement

COST variable;
OBJFN variable;

The COST statement identifies the SAS variable in the ARCDATA= data set that contains the per unit flow cost through an arc. If an observation contains nonarc variable information, the value of the COST list variable is the objective function coefficient of the nonarc variable named in the NAME list variable in that observation. The COST list variable must have numeric values. It is not necessary to specify a COST statement if the name of the SAS variable is _COST_ or _LENGTH_.

DEMAND Statement

DEMAND variable;

The DEMAND statement identifies the SAS variable in the ARCDATA= data set that contains the demand at the node named in the corresponding HEADNODE list variable. The DEMAND list variable must have numeric values. It is not necessary to have a DEMAND statement if the name of this SAS variable is _DEMAND_.

HEADNODE Statement

HEADNODE variable;
HEAD variable;
TONODE variable;
TO variable;

The HEADNODE statement specifies the SAS variable that must be present in the ARCDATA= data set that contains the names of nodes toward which arcs are directed. It is not necessary to have a HEADNODE statement if the name of the SAS variable is _HEAD_ or _TO_. The HEADNODE variable must have character values.

ID Statement

ID variables;

The ID statement specifies SAS variables containing values for pre- and post-optimal processing and analysis. These variables are not processed by PROC NETFLOW but are read by the procedure and written in the ARCOUT= and CONOUT= data sets and the output of PRINT statements. For example, imagine a network used to model a distribution system. The SAS variables listed on the ID statement can contain information on type of vehicle, transportation mode, condition of road, time to complete journey, name of driver, or other ancillary information useful for report writing or describing facets of the operation that do not have bearing on the optimization. The ID variables can be character, numeric, or both.
If no ID list is specified, the procedure forms an ID list of all SAS variables not included in any other implicit or explicit list specification. If the ID list is specified, any SAS variables in the ARCDATA= data set not in any list are dropped and do not appear in the ARCOOUT= or CONOUT= data sets, or in the PRINT statement output.

---

**LO Statement**

\[
\text{LO \ variable} \\
\text{LOWERBD \ variable} \\
\text{MINFLOW \ variable}
\]

The LO statement identifies the SAS variable in the ARCDATA= data set that contains the minimum feasible flow or lower flow bound for arcs in the network. If an observation contains nonarc variable information, the LO list variable has the value of the lower bound for the nonarc variable named in the NAME list variable. The LO list variables must have numeric values. It is not necessary to have a LO statement if the name of this SAS variable is \_LOWER\_, \_LO\_, \_LOWERBD\_, or \_MINFLOW\_.

---

**MULT Statement**

\[
\text{MULT \ variables} \\
\text{MULTIPLIER \ variables}
\]

The MULT statement identifies the SAS variable in the ARCDATA= data set associated with the values of arc multipliers in the network. These values must be positive real numbers. It is not necessary to have a MULT statement if the name of this SAS variable is \_MULT\_.

---

**NAME Statement**

\[
\text{NAME \ variable} \\
\text{ARCNAME \ variable} \\
\text{VARNAME \ variable}
\]

Each arc and nonarc variable that has data in the CONDATA= data set must have a unique name. This variable is identified in the ARCDATA= data set. The NAME list variable must have character values (see the NAMECTRL= option in the PROC NETFLOW statement for more information). It is not necessary to have a NAME statement if the name of this SAS variable is \_NAME\_.

---
**NODE Statement**

```
NODE variable;
```

The NODE list variable, which must be present in the NODEDATA= data set, has names of nodes as values. These values must also be values of the TAILNODE list variable, the HEADNODE list variable, or both. If this list is not explicitly specified, the NODEDATA= data set is searched for a SAS variable with the name `_NODE_`. The NODE list variable must have character values.

---

**PIVOT Statement**

```
PIVOT;
```

The PIVOT statement has no options. It indicates that one simplex iteration is to be performed. The PIVOT statement forces a simplex iteration to be performed in spite of the continued presence of any reasons or solution conditions that caused optimization to be halted. For example, if the number of iterations performed exceeds the value of the MAXIT1= or MAXIT2= option and you issue a PIVOT statement, the iteration is performed even though the MAXIT1= or MAXIT2= value has not yet been changed using a RESET statement.

---

**PRINT Statement**

```
PRINT options / qualifiers;
```

The options available with the PRINT statement of PROC NETFLOW are summarized by purpose in the following table.

**Table 6.2  Functional Summary, PRINT Statement**

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>PRINT Statement Options:</td>
<td>PRINTER</td>
<td>PROBLEM</td>
</tr>
<tr>
<td>Display everything</td>
<td>PRINT</td>
<td>ARCS</td>
</tr>
<tr>
<td>Display arc information</td>
<td>PRINT</td>
<td>NONARCS</td>
</tr>
<tr>
<td>Display nonarc variable information</td>
<td>PRINT</td>
<td>VARIABLES</td>
</tr>
<tr>
<td>Display variable information</td>
<td>PRINT</td>
<td>CONSTRAINTS</td>
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<tr>
<td>Display constraint information</td>
<td>PRINT</td>
<td>SOME_ARCS</td>
</tr>
<tr>
<td>Display information for some arcs</td>
<td>PRINT</td>
<td>SOME_NONARCS</td>
</tr>
<tr>
<td>Display information for some nonarc variables</td>
<td>PRINT</td>
<td>SOME_VARIABLES</td>
</tr>
<tr>
<td>Display information for some variables</td>
<td>PRINT</td>
<td>SOMECONS</td>
</tr>
<tr>
<td>Display information for some constraints</td>
<td>PRINT</td>
<td>CON_ARCS</td>
</tr>
<tr>
<td>Display information for some constraints associated with some arcs</td>
<td>PRINT</td>
<td>CON_NONARCS</td>
</tr>
</tbody>
</table>
PRINT Statement

The PRINT statement enables you to examine part or all of the problem. You can limit the amount of information displayed when a PRINT statement is processed by specifying PRINT statement options. The name of the PRINT option indicates what part of the problem is to be examined. If no options are specified, or PRINT PROBLEM is specified, information about the entire problem is produced.

The amount of displayed information can be limited further by following any PRINT statement options with a slash (/) and one or more of the qualifiers SHORT or LONG, ZERO or NONZERO, BASIC or NONBASIC.

Some of the PRINT statement options require you to specify a list of some type of entity, thereby enabling you to indicate what entities are of interest. The entities of interest are the ones you want to display. These entities might be tail node names, head node names, nonarc variable names, or constraint names. The entity list is made up of one or more of the following constructs. Each construct can add none, one, or more entities to the set of entities to be displayed.

- **_ALL_**
  Display all entities in the required list.

- **entity**
  Display the named entity that is interesting.

- **entity1 - entity2** (one hyphen)
  Display all entities with names on or between the suffixes of entity1 and entity2.

- **entity1 - CHARACTER - entity2** or **entity1 - CHAR - entity2**
  Display all entities with names made up of the same character string prefix followed by a numeric suffix. The suffixes of both entity1 and entity2 have the same number of numerals but can have different values. A specification of entity1 - entity2 indicates that all entities with the same prefix and suffixes with values on or between the suffixes of entity1 and entity2 are to be put in the set of entities to be displayed. The numeric suffix of both entity1 and entity2 can be followed by a character string. For example, _OBS07_ - _OBS13_ is a valid construct of the forms entity1 - entity2.

- **part_of_entity_name:**
  Display all entities in the required list that have names beginning with the character string preceding the colon.
The following options can appear in the PRINT statement:

**ARCS**
indicates that you want to have displayed information about all arcs.

**SOME_ARCS (taillist, headlist)**
is similar to the statement PRINT ARCS except that, instead of displaying information about all arcs, only arcs directed from nodes in a specified set of tail nodes to nodes in a specified set of head nodes are included. The nodes or node constructs belonging to the taillist list are separated by blanks. The nodes or node constructs belonging to the headlist list are also separated by blanks. The lists are separated by a comma.

**NONARCS VARIABLES**
indicates that information is to be displayed about all nonarc variables.

**SOME_NONARCS (nonarclist)**
is similar to the PRINT NONARCS statement except that, instead of displaying information about all nonarc variables, only those belonging to a specified set of nonarc variables have information displayed. The nonarc variables or nonarc variable constructs belonging to the nonarclist list are separated by blanks.

**CONSTRAINTS**
indicates that you want to have displayed information about all constraint coefficients.

**SOME_CONS (conlist)**
displays information for coefficients in a specified set of constraints. The constraints or constraint constructs belonging to the conlist list are separated by blanks.

**CON_ARCS (taillist, headlist)**
is similar to the PRINT SOME_CONS (conlist) statement except that, instead of displaying information about all coefficients in specified constraints, information about only those coefficients that are associated with arcs directed from a set of specified tail nodes toward a set of specified head nodes is displayed. The constraints or constraint constructs belonging to the conlist list are separated by blanks; so too are the nodes or node constructs belonging to the taillist list and the nodes or node constructs belonging to the headlist list. The lists are separated by commas.

**CON_NONARCS (conlist, nonarclist)**
**CON_VARIABLES (conlist, variablelist)**
is similar to the PRINT SOME_CONS (conlist) statement except that, instead of displaying information about all coefficients in specified constraints, information about only those coefficients that are associated with nonarc variables in a specified set is displayed. The constraints or constraint constructs belonging to the conlist list are separated by blanks. The nonarc variables or nonarc variable constructs belonging to the nonarclist list are separated by blanks. The lists are separated by a comma.

**PROBLEM**
is equivalent to the statement PRINT ARCS NONARCS CONSTRAINTS.
Following a slash (/), the qualifiers SHORT or LONG, ZERO or NONZERO, BASIC or NONBASIC can appear in any PRINT statement. These qualifiers are described below.

- **BASIC**
  Only rows that are associated with arcs or nonarc variables that are basic are displayed. The _STATUS_ column values are KEY_ARC BASIC or NONKEY ARC BASIC for arcs, and NONKEY_BASIC for nonarc variables.

- **LONG**
  All table columns are displayed (the default when no qualifier is used).

- **NONBASIC**
  Only rows that are associated with arcs or nonarc variables that are nonbasic are displayed. The _STATUS_ column values are LOWERBD NONBASIC or UPPERBD NONBASIC.

- **NONZERO**
  Only rows that have nonzero _FLOW_ column values (nonzero arc flows, nonzero nonarc variable values) are displayed.

- **SHORT**
  The table columns are _N_, _FROM_, _TO_, _COST_, _CAPAC_, _LO_, _NAME_, and _FLOW_, or the names of the SAS variables specified in the corresponding variable lists (TAILNODE, HEADNODE, COST, CAPACITY, LO, and NAME lists). _COEF_ or the name of the SAS variable in the COEF list specification will head a column when the SHORT qualifier is used in PRINT CONSTRAINTS, SOMECONS, CON_ARCS, or CON_NONARCS.

- **ZERO**
  Only rows that have zero _FLOW_ column values (zero arc flows, zero nonarc variable values) are displayed.

The default qualifiers are BASIC, NONBASIC, ZERO, NONZERO, and LONG.

**Displaying Information On All Constraints**

In the oil refinery problem, if you had entered

```plaintext
print constraints;
```

after the RUN statement, the output in Figure 6.9 would have been produced.

**Displaying Information About Selected Arcs**

In the oil refinery problem, if you had entered

```plaintext
print some_arcs(refin:,_all_)/short;
```

after the RUN statement, the output in Figure 6.10 would have been produced.
Figure 6.9 PRINT CONSTRAINTS

Constrained Optimum

The NETFLOW Procedure

<table>
<thead>
<tr>
<th>N</th>
<th><em>CON</em></th>
<th>type</th>
<th><em>rhs</em></th>
<th><em>name</em></th>
<th><em>from</em></th>
<th>to</th>
<th><em>cost</em></th>
<th><em>capac</em></th>
<th><em>lo</em></th>
<th><em>SUPPLY</em></th>
<th>DEMAND</th>
<th><em>FLOW</em></th>
<th><em>COEF</em></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td><em>OBS1</em></td>
<td>GE</td>
<td>-15</td>
<td>m_e_ref</td>
<td>middle</td>
<td>refinery 1</td>
<td>63</td>
<td>95</td>
<td>20</td>
<td>100</td>
<td>.</td>
<td>80</td>
<td>-2</td>
</tr>
<tr>
<td>2</td>
<td><em>OBS1</em></td>
<td>GE</td>
<td>-15</td>
<td>thruput1</td>
<td>refinery 1</td>
<td>r1</td>
<td>200</td>
<td>175</td>
<td>50</td>
<td>.</td>
<td>.</td>
<td>145</td>
<td>1</td>
</tr>
<tr>
<td>3</td>
<td><em>OBS2</em></td>
<td>GE</td>
<td>-15</td>
<td>m_e_ref</td>
<td>middle</td>
<td>refinery 2</td>
<td>81</td>
<td>80</td>
<td>10</td>
<td>100</td>
<td>.</td>
<td>20</td>
<td>-2</td>
</tr>
<tr>
<td>4</td>
<td><em>OBS2</em></td>
<td>GE</td>
<td>-15</td>
<td>thruput2</td>
<td>refinery 2</td>
<td>r2</td>
<td>220</td>
<td>100</td>
<td>35</td>
<td>.</td>
<td>.</td>
<td>35</td>
<td>1</td>
</tr>
<tr>
<td>5</td>
<td><em>OBS3</em></td>
<td>EQ</td>
<td>0</td>
<td>thruput1</td>
<td>refinery 1</td>
<td>r1</td>
<td>200</td>
<td>175</td>
<td>50</td>
<td>.</td>
<td>.</td>
<td>145</td>
<td>-3</td>
</tr>
<tr>
<td>6</td>
<td><em>OBS3</em></td>
<td>EQ</td>
<td>0</td>
<td>r1_gas</td>
<td>ref1gas</td>
<td>r1</td>
<td>0</td>
<td>140</td>
<td>0</td>
<td>.</td>
<td>.</td>
<td>108.75</td>
<td>4</td>
</tr>
<tr>
<td>7</td>
<td><em>OBS4</em></td>
<td>EQ</td>
<td>0</td>
<td>thruput2</td>
<td>refinery 2</td>
<td>r2</td>
<td>220</td>
<td>100</td>
<td>35</td>
<td>.</td>
<td>.</td>
<td>35</td>
<td>-3</td>
</tr>
<tr>
<td>8</td>
<td><em>OBS4</em></td>
<td>EQ</td>
<td>0</td>
<td>r2_gas</td>
<td>ref2gas</td>
<td>r2</td>
<td>0</td>
<td>100</td>
<td>0</td>
<td>.</td>
<td>.</td>
<td>26.25</td>
<td>4</td>
</tr>
</tbody>
</table>

Figure 6.10 PRINT SOME_ARCS

Constrained Optimum

The NETFLOW Procedure

<table>
<thead>
<tr>
<th>N</th>
<th><em>from</em></th>
<th>to</th>
<th><em>cost</em></th>
<th><em>capac</em></th>
<th><em>lo</em></th>
<th><em>name</em></th>
<th><em>FLOW</em></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>refinery 1</td>
<td>r1</td>
<td>200</td>
<td>175</td>
<td>50</td>
<td>thruput1</td>
<td>145</td>
</tr>
<tr>
<td>2</td>
<td>refinery 2</td>
<td>r2</td>
<td>220</td>
<td>100</td>
<td>35</td>
<td>thruput2</td>
<td>35</td>
</tr>
</tbody>
</table>

Displaying Information About Selected Constraints

In the oil refinery problem, if you had entered

```
print some_cons(_obs3_-_obs4_)/nonzero short;
```

after the RUN statement, the output in Figure 6.11 would have been produced.
If you had entered

    print con_arcs(_all_,r1 r2,_all_)/short;

after the RUN statement, the output in Figure 6.12 would have been produced. Constraint information about arcs directed from selected tail nodes is displayed.

### Cautions

This subsection has two parts; the first part is applicable if you are running Version 7 or later of the SAS System, and the second part is applicable if you are running Version 6. You can get later versions to “act” like Version 6 by specifying

    options validvarname=v6;

For Version 7 onward, PROC NETFLOW strictly respects case sensitivity. The PRINT statements of PROC NETFLOW that require lists of entities will work properly only if the entities have the same case as in the input data sets. Entities that contain blanks must be enclosed in single or double quotes. For example,

    print some_arcs (_all_,”Ref1 Gas”);

In this example, a head node of an arc in the model is “Ref1 Gas” (without the quotes). If you omit the quotes, PROC NETFLOW issues a message on the SAS log:

**WARNING:** The node Ref1 in the list of head nodes in the PRINT SOME_ARCS or PRINT CON_ARCS is not a node in the problem. This statement will be ignored.
If you had specified

```plaintext
print some_arcs (_all_,"ref1 Gas");
```

(note the small r), you would have been warned

```
WARNING: The node ref1 Gas in the list of head nodes in the PRINT
SOME_ARCS or PRINT CON_ARCS is not a node in the
problem. This statement will be ignored.
```

If you are running Version 6, or if you are running a later version and you have specified

```plaintext
options validvarname=v6;
```

when information is parsed to procedures, the SAS System converts the text that makes up statements into uppercase. The PRINT statements of PROC NETFLOW that require lists of entities will work properly only if the entities are uppercase in the input data sets. If you do not want this upercasing to occur, you must enclose the entity in single or double quotes.

```plaintext
print some_arcs('lowercase tail','lowercase head');
print some_cons('factory07'-'factory12');
print some_cons('_factory07_'-_factory12_');
print some_nonarcs("CO2 content");
```

Entities that contain blanks must be enclosed in single or double quotes.

---

**QUIT Statement**

```
QUIT ;
```

The QUIT statement indicates that PROC NETFLOW is to be terminated immediately. The solution is not saved in the current output data sets. The QUIT statement has no options.

---

**RESET Statement**

```
RESET options ;
SET options ;
```

The RESET statement is used to change options after PROC NETFLOW has started execution. Any of the following options can appear in the PROC NETFLOW statement.

Another name for the RESET statement is SET. You can use RESET when you are resetting options and SET when you are setting options for the first time. The following options fall roughly into five categories:

- output data set specifications
- options that indicate conditions under which optimization is to be halted temporarily, giving you an opportunity to use PROC NETFLOW interactively
• options that control aspects of the operation of the network primal simplex optimization
• options that control the pricing strategies of the network simplex optimizer
• miscellaneous options

If you want to examine the setting of any options, use the SHOW statement. If you are interested in looking at only those options that fall into a particular category, the SHOW statement has options that enable you to do this.

The execution of PROC NETFLOW has three stages. In stage zero the problem data are read from the NODEDATA=, ARCDATA=, and CONDATA= data sets. If a warm start is not available, an initial basic feasible solution is found. Some options of the PROC NETFLOW statement control what occurs in stage zero. By the time the first RESET statement is processed, stage zero has already been completed.

In the first stage, an optimal solution to the network flow problem neglecting any side constraints is found. The primal and dual solutions for this relaxed problem can be saved in the ARCP= data set and the NODEOUT= data set, respectively.

In the second stage, the side constraints are examined and some initializations occur. Some preliminary work is also needed to commence optimization that considers the constraints. An optimal solution to the network flow problem with side constraints is found. The primal and dual solutions for this side-constrained problem are saved in the CONOUT= data set and the DUALOUT= data set, respectively.

Many options in the RESET statement have the same name except that they have as a suffix the numeral 1 or 2. Such options have much the same purpose, but option1 controls what occurs during the first stage when optimizing the network neglecting any side constraints and option2 controls what occurs in the second stage when PROC NETFLOW is performing constrained optimization.

Some options can be turned off by the option prefixed by the word NO. For example, FEASIBLEPAUSE1 may have been specified in a RESET statement and in a later RESET statement, you can specify NOFEASIBLEPAUSE1. In a later RESET statement, you can respecify FEASIBLEPAUSE1 and, in this way, toggle this option.

The options available with the RESET statement are summarized by purpose in the following table.

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output Data Set Options:</td>
<td>RESET</td>
<td>ARCP=</td>
</tr>
<tr>
<td>Unconstrained primal solution data set</td>
<td>RESET</td>
<td>NODEOUT=</td>
</tr>
<tr>
<td>Unconstrained dual solution data set</td>
<td>RESET</td>
<td>CONOUT=</td>
</tr>
<tr>
<td>Constrained primal solution data set</td>
<td>RESET</td>
<td>DUALOUT=</td>
</tr>
<tr>
<td>Constrained dual solution data set</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Simplex Options:

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Use big-M instead of two-phase method, stage 1</td>
<td>RESET</td>
<td>BIGM1</td>
</tr>
<tr>
<td>Use Big-M instead of two-phase method, stage 2</td>
<td>RESET</td>
<td>BIGM2</td>
</tr>
<tr>
<td>Anti-cycling option</td>
<td>RESET</td>
<td>CYCLEMULT1=</td>
</tr>
<tr>
<td>Interchange first nonkey with leaving key arc</td>
<td>RESET</td>
<td>INTFIRST</td>
</tr>
</tbody>
</table>
### Description

- Controls working basis matrix inversions
- Maximum number of L row operations allowed before refactorization
- Maximum number of LU factor column updates
- Anti-cycling option
- Use first eligible leaving variable, stage 1
- Use first eligible leaving variable, stage 2
- Negates INTFIRST
- Negates LRATIO1
- Negates LRATIO2
- Negates PERTURB1
- Anti-cycling option
- Controls working basis matrix refactorization
- Use two-phase instead of big-M method, stage 1
- Use two-phase instead of big-M method, stage 2
- Pivot element selection parameter
- Zero tolerance, stage 1
- Zero tolerance, stage 2
- Zero tolerance, real number comparisons

### Statement Option

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Controls working basis matrix inversions</td>
<td>RESET</td>
<td>INVFREQ=</td>
</tr>
<tr>
<td>Maximum number of L row operations allowed before refactorization</td>
<td>RESET</td>
<td>MAXL=</td>
</tr>
<tr>
<td>Maximum number of LU factor column updates</td>
<td>RESET</td>
<td>MAXLUUPDATE=</td>
</tr>
<tr>
<td>Anti-cycling option</td>
<td>RESET</td>
<td>MINBLOCK1=</td>
</tr>
<tr>
<td>Use first eligible leaving variable, stage 1</td>
<td>RESET</td>
<td>LRATIO1=</td>
</tr>
<tr>
<td>Use first eligible leaving variable, stage 2</td>
<td>RESET</td>
<td>LRATIO2=</td>
</tr>
<tr>
<td>Negates INTFIRST</td>
<td>RESET</td>
<td>NOINTFIRST=</td>
</tr>
<tr>
<td>Negates LRATIO1</td>
<td>RESET</td>
<td>NOLRATIO1=</td>
</tr>
<tr>
<td>Negates LRATIO2</td>
<td>RESET</td>
<td>NOLRATIO2=</td>
</tr>
<tr>
<td>Negates PERTURB1</td>
<td>RESET</td>
<td>NOPERTURB1=</td>
</tr>
<tr>
<td>Anti-cycling option</td>
<td>RESET</td>
<td>PERTURB1=</td>
</tr>
<tr>
<td>Controls working basis matrix refactorization</td>
<td>RESET</td>
<td>REFACTFREQ=</td>
</tr>
<tr>
<td>Use two-phase instead of big-M method, stage 1</td>
<td>RESET</td>
<td>TWOPHASE1=</td>
</tr>
<tr>
<td>Use two-phase instead of big-M method, stage 2</td>
<td>RESET</td>
<td>TWOPHASE2=</td>
</tr>
<tr>
<td>Pivot element selection parameter</td>
<td>RESET</td>
<td>U=</td>
</tr>
<tr>
<td>Zero tolerance, stage 1</td>
<td>RESET</td>
<td>ZERO1=</td>
</tr>
<tr>
<td>Zero tolerance, stage 2</td>
<td>RESET</td>
<td>ZERO2=</td>
</tr>
<tr>
<td>Zero tolerance, real number comparisons</td>
<td>RESET</td>
<td>ZEROTOL=</td>
</tr>
</tbody>
</table>

### Pricing Options:

- Frequency of dual value calculation
- Pricing strategy, stage 1
- Pricing strategy, stage 2
- Used when P1SCAN=PARTIAL
- Controls search for entering candidate, stage 1
- Used when P2SCAN=PARTIAL
- Controls search for entering candidate, stage 2
- Initial queue size, stage 1
- Initial queue size, stage 2
- Used when Q1FILLSCAN=PARTIAL
- Controls scan when filling queue, stage 1
- Used when Q2FILLSCAN=PARTIAL
- Controls scan when filling queue, stage 2
- Queue size reduction factor, stage 1
- Queue size reduction factor, stage 2
- Frequency of refreshing queue, stage 1
- Frequency of refreshing queue, stage 2

### Statement Option

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Frequency of dual value calculation</td>
<td>RESET</td>
<td>DUALFREQ=</td>
</tr>
<tr>
<td>Pricing strategy, stage 1</td>
<td>RESET</td>
<td>PRICETYPE1=</td>
</tr>
<tr>
<td>Pricing strategy, stage 2</td>
<td>RESET</td>
<td>PRICETYPE2=</td>
</tr>
<tr>
<td>Used when P1SCAN=PARTIAL</td>
<td>RESET</td>
<td>P1NPARTIAL=</td>
</tr>
<tr>
<td>Controls search for entering candidate, stage 1</td>
<td>RESET</td>
<td>P1SCAN=</td>
</tr>
<tr>
<td>Used when P2SCAN=PARTIAL</td>
<td>RESET</td>
<td>P2NPARTIAL=</td>
</tr>
<tr>
<td>Controls search for entering candidate, stage 2</td>
<td>RESET</td>
<td>P2SCAN=</td>
</tr>
<tr>
<td>Initial queue size, stage 1</td>
<td>RESET</td>
<td>QSIZE1=</td>
</tr>
<tr>
<td>Initial queue size, stage 2</td>
<td>RESET</td>
<td>QSIZE2=</td>
</tr>
<tr>
<td>Used when Q1FILLSCAN=PARTIAL</td>
<td>RESET</td>
<td>Q1FILLNPARTIAL=</td>
</tr>
<tr>
<td>Controls scan when filling queue, stage 1</td>
<td>RESET</td>
<td>Q1FILLSCAN=</td>
</tr>
<tr>
<td>Used when Q2FILLSCAN=PARTIAL</td>
<td>RESET</td>
<td>Q2FILLNPARTIAL=</td>
</tr>
<tr>
<td>Controls scan when filling queue, stage 2</td>
<td>RESET</td>
<td>Q2FILLSCAN=</td>
</tr>
<tr>
<td>Queue size reduction factor, stage 1</td>
<td>RESET</td>
<td>REDUCEQSIZE1=</td>
</tr>
<tr>
<td>Queue size reduction factor, stage 2</td>
<td>RESET</td>
<td>REDUCEQSIZE2=</td>
</tr>
<tr>
<td>Frequency of refreshing queue, stage 1</td>
<td>RESET</td>
<td>REFRESHQ1=</td>
</tr>
<tr>
<td>Frequency of refreshing queue, stage 2</td>
<td>RESET</td>
<td>REFRESHQ2=</td>
</tr>
</tbody>
</table>

### Optimization Termination Options:

- Pause after stage 1; do not start stage 2
- Pause when feasible, stage 1
- Pause when feasible, stage 2
- Maximum number of iterations, stage 1
- Maximum number of iterations, stage 2

### Statement Option

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pause after stage 1; do not start stage 2</td>
<td>RESET</td>
<td>ENDPAUSE1</td>
</tr>
<tr>
<td>Pause when feasible, stage 1</td>
<td>RESET</td>
<td>FEASIBLEPAUSE1</td>
</tr>
<tr>
<td>Pause when feasible, stage 2</td>
<td>RESET</td>
<td>FEASIBLEPAUSE2</td>
</tr>
<tr>
<td>Maximum number of iterations, stage 1</td>
<td>RESET</td>
<td>MAXIT1=</td>
</tr>
<tr>
<td>Maximum number of iterations, stage 2</td>
<td>RESET</td>
<td>MAXIT2=</td>
</tr>
<tr>
<td>Description</td>
<td>Statement</td>
<td>Option</td>
</tr>
<tr>
<td>-----------------------------------------------------------------------------</td>
<td>-----------</td>
<td>----------------</td>
</tr>
<tr>
<td>Negates ENDPAUSE1</td>
<td>RESET</td>
<td>NOENDPAUSE1</td>
</tr>
<tr>
<td>Negates FEASIBLEPAUSE1</td>
<td>RESET</td>
<td>NOFEASIBLEPAUSE1</td>
</tr>
<tr>
<td>Negates FEASIBLEPAUSE2</td>
<td>RESET</td>
<td>NOFEASIBLEPAUSE2</td>
</tr>
<tr>
<td>Pause every PAUSE1 iterations, stage 1</td>
<td>RESET</td>
<td>PAUSE1=</td>
</tr>
<tr>
<td>Pause every PAUSE2 iterations, stage 2</td>
<td>RESET</td>
<td>PAUSE2=</td>
</tr>
</tbody>
</table>

**Interior Point Algorithm Options:**
- Factorization method: RESET FACT_METHOD=
- Allowed amount of dual infeasibility: RESET TOLDINF=
- Allowed amount of primal infeasibility: RESET TOLPINF=
- Allowed total amount of dual infeasibility: RESET TOLTOTDINF=
- Allowed total amount of primal infeasibility: RESET TOLTOTPINF=
- Cut-off tolerance for Cholesky factorization: RESET CHOLTINYTOL=
- Density threshold for Cholesky processing: RESET DENSETHR=
- Step-length multiplier: RESET PDSTEPMULT=
- Preprocessing type: RESET PRSLTYPE=
- Print optimization progress on SAS log: RESET PRINTLEVEL2=

**Interior Point Stopping Criteria Options:**
- Maximum number of interior point iterations: RESET MAXITERB=
- Primal-dual (duality) gap tolerance: RESET PDGAPTOL=
- Stop because of complementarity: RESET STOP_C=
- Stop because of duality gap: RESET STOP_DG=
- Stop because of $\text{infeas}_b$: RESET STOP_IB=
- Stop because of $\text{infeas}_c$: RESET STOP_IC=
- Stop because of $\text{infeas}_d$: RESET STOP_ID=
- Stop because of complementarity: RESET AND_STOP_C=
- Stop because of duality gap: RESET AND_STOP_DG=
- Stop because of $\text{infeas}_b$: RESET AND_STOP_IB=
- Stop because of $\text{infeas}_c$: RESET AND_STOP_IC=
- Stop because of $\text{infeas}_d$: RESET AND_STOP_ID=
- Stop because of complementarity: RESET KEEPGOING_C=
- Stop because of duality gap: RESET KEEPGOING_DG=
- Stop because of $\text{infeas}_b$: RESET KEEPGOING_IB=
- Stop because of $\text{infeas}_c$: RESET KEEPGOING_IC=
- Stop because of $\text{infeas}_d$: RESET KEEPGOING_ID=
- Stop because of complementarity: RESET AND_KEEPGOING_C=
- Stop because of duality gap: RESET AND_KEEPGOING_DG=
- Stop because of $\text{infeas}_b$: RESET AND_KEEPGOING_IB=
- Stop because of $\text{infeas}_c$: RESET AND_KEEPGOING_IC=
- Stop because of $\text{infeas}_d$: RESET AND_KEEPGOING_ID=

**Miscellaneous Options:**
- Output complete basis information to ARCOOUT= and NODEOUT= data sets: RESET FUTURE1
### Description Statement Option

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output complete basis information to CONOUT= and DUALOUT= data sets</td>
<td>RESET</td>
<td>FUTURE2</td>
</tr>
<tr>
<td>Turn off infeasibility or optimality flags</td>
<td>RESET</td>
<td>MOREOPT</td>
</tr>
<tr>
<td>Negates FUTURE1</td>
<td>RESET</td>
<td>NOFUTURE1</td>
</tr>
<tr>
<td>Negates FUTURE2</td>
<td>RESET</td>
<td>NOFUTURE2</td>
</tr>
<tr>
<td>Negates SCRATCH</td>
<td>RESET</td>
<td>NOSCRATCH</td>
</tr>
<tr>
<td>Negates ZTOL1</td>
<td>RESET</td>
<td>NOZTOL1</td>
</tr>
<tr>
<td>Negates ZTOL2</td>
<td>RESET</td>
<td>NOZTOL2</td>
</tr>
<tr>
<td>Write optimization time to SAS log</td>
<td>RESET</td>
<td>OPTIM_TIMER</td>
</tr>
<tr>
<td>No stage 1 optimization; do stage 2 optimization</td>
<td>RESET</td>
<td>SCRATCH</td>
</tr>
<tr>
<td>Suppress similar SAS log messages</td>
<td>RESET</td>
<td>VERBOSE=</td>
</tr>
<tr>
<td>Use zero tolerance, stage 1</td>
<td>RESET</td>
<td>ZTOL1</td>
</tr>
<tr>
<td>Use zero tolerance, stage 2</td>
<td>RESET</td>
<td>ZTOL2</td>
</tr>
</tbody>
</table>

### Output Data Set Specifications

In a RESET statement, you can specify an ARCOUT= data set, a NODEOUT= data set, a CONOUT= data set, or a DUALOUT= data set. You are advised to specify these output data sets early because if you make a syntax error when using PROC NETFLOW interactively or, for some other reason, PROC NETFLOW encounters or does something unexpected, these data sets will contain information about the solution that was reached. If you had specified the FUTURE1 or FUTURE2 option in a RESET statement, PROC NETFLOW may be able to resume optimization in a subsequent run.

You can turn off these current output data set specifications by specifying ARCOUT=NULL, NODEOUT=NULL, CONOUT=NULL, or DUALOUT=NULL.

If PROC NETFLOW is outputting observations to an output data set and you want this to stop, press the keys used to stop SAS procedures. PROC NETFLOW waits, if necessary, and then executes the next statement.

**ARCOUT=SAS-data-set**

**AOUT=SAS-data-set**

names the output data set that receives all information concerning arc and nonarc variables, including flows and other information concerning the current solution and the supply and demand information. The current solution is the latest solution found by the optimizer when the optimization neglecting side constraints is halted or the unconstrained optimum is reached.

You can specify an ARCOUT= data set in any RESET statement before the unconstrained optimum is found (even at commencement). Once the unconstrained optimum has been reached, use the SAVE statement to produce observations in an ARCOUT= data set. Once optimization that considers constraints starts, you will be unable to obtain an ARCOUT= data set. Instead, use a CONOUT= data set to get the current solution. See the section “ARCOUT= and CONOUT= Data Sets” on page 389 for more information.
CONOUT=SAS-data-set

names the output data set that contains the primal solution obtained after optimization considering side constraints reaches the optimal solution. You can specify a CONOUT= data set in any RESET statement before the constrained optimum is found (even at commencement or while optimizing neglecting constraints). Once the constrained optimum has been reached, or during stage 2 optimization, use the SAVE statement to produce observations in a CONOUT= data set. See the section “ARCOUT= and CONOUT= Data Sets” on page 389 for more information.

DUALOUT=SAS-data-set

names the output data set that contains the dual solution obtained after doing optimization that considers side constraints reaches the optimal solution. You can specify a DUALOUT= data set in any RESET statement before the constrained optimum is found (even at commencement or while optimizing neglecting constraints). Once the constrained optimum has been reached, or during stage 2 optimization, use the SAVE statement to produce observations in a DUALOUT= data set. See the section “NODEOUT= and DUALOUT= Data Sets” on page 390 for more information.

NODEOUT=SAS-data-set

NOUT=SAS-data-set

names the output data set that receives all information about nodes (supply/demand and nodal dual variable values) and other information concerning the unconstrained optimal solution.

You can specify a NODEOUT= data set in any RESET statement before the unconstrained optimum is found (even at commencement). Once the unconstrained optimum has been reached, or during stage 1 optimization, use the SAVE statement to produce observations in a NODEOUT= data set. Once optimization that considers constraints starts, you will not be able to obtain a NODEOUT= data set. Instead use a DUALOUT= data set to get the current solution. See the section “NODEOUT= and DUALOUT= Data Sets” on page 390 for more information.

Options to Halt Optimization

The following options indicate conditions when optimization is to be halted. You then have a chance to use PROC NETFLOW interactively. If the NETFLOW procedure is optimizing and you want optimization to halt immediately, press the CTRL-BREAK key combination used to stop SAS procedures. Doing this is equivalent to PROC NETFLOW finding that some prespecified condition of the current solution under which optimization should stop has occurred.

If optimization does halt, you may need to change the conditions for when optimization should stop again. For example, if the number of iterations exceeded MAXIT2, use the RESET statement to specify a larger value for the MAXIT2= option before the next RUN statement. Otherwise, PROC NETFLOW will immediately find that the number of iterations still exceeds MAXIT2 and halt without doing any additional optimization.

ENDPAUSE1

indicates that PROC NETFLOW will pause after the unconstrained optimal solution has been obtained and information about this solution has been output to the current ARCOUT= data set, NODEOUT= data set, or both. The procedure then executes the next statement, or waits if no subsequent statement has been specified.
FEASIBLEPAUSE1

FP1
indicates that unconstrained optimization should stop once a feasible solution is reached. PROC NETFLOW checks for feasibility every 10 iterations. A solution is feasible if there are no artificial arcs having nonzero flow assigned to be conveyed through them. The presence of artificial arcs with nonzero flows means that the current solution does not satisfy all the nodal flow conservation constraints implicit in network problems.

MAXIT1=m
specifies the maximum number of primal simplex iterations PROC NETFLOW is to perform in stage 1. The default value for the MAXIT1= option is 1000. If MAXIT1=m iterations are performed and you want to continue unconstrained optimization, reset MAXIT1= to a number larger than the number of iterations already performed and issue another RUN statement.

NOENDPAUSE1
NOEP1
negates the ENDPAUSE1 option.

NOFEASIBLEPAUSE1
NOFP1
negates the FEASIBLEPAUSE1 option.

PAUSE1=p
indicates that PROC NETFLOW will halt unconstrained optimization and pause when the remainder of the number of stage 1 iterations divided by the value of the PAUSE1= option is zero. If present, the next statement is executed; if not, the procedure waits for the next statement to be specified. The default value for PAUSE1= is 999999.

FEASIBLEPAUSE2
FP2
NOFEASIBLEPAUSE2
NOFP2
PAUSE2=p
MAXIT2=m
are the stage 2 constrained optimization counterparts of the options described previously and having as a suffix the numeral 1.

Options Controlling the Network Simplex Optimization

BIGM1
NOTWOPHASE1
TWOPHASE1
NOBIGM1
BIGM1 indicates that the “big-M” approach to optimization is used. Artificial variables are treated like real arcs, slacks, surpluses and nonarc variables. Artificials have very expensive costs. BIGM1 is the default.
TWOPHASE1 indicates that the two-phase approach is used instead of the big-M approach. At first, artificial variables are the only variables to have nonzero objective function coefficients. An artificial variable’s objective function coefficient is temporarily set to 1 and PROC NETFLOW minimizes. When all artificial variables have zero value, PROC NETFLOW has found a feasible solution, and phase 2 commences. Arcs and nonarc variables have their real costs and objective function coefficients.

Before all artificial variables are driven to have zero value, you can toggle between the big-M and the two-phase approaches by specifying BIGM1 or TWOPHASE1 in a RESET statement. The option NOTWOPHASE1 is synonymous with BIGM1, and NOBIGM1 is synonymous with TWOPHASE1.

CYCLEMULT1 = c
MINBLOCK1 = m
NOPERTURB1
PERTURB1

In an effort to reduce the number of iterations performed when the problem is highly degenerate, PROC NETFLOW has in stage 1 optimization adopted an algorithm outlined in Ryan and Osborne (1988). If the number of consecutive degenerate pivots (those with no progress toward the optimum) performed equals the value of the CYCLEMULT1 = option times the number of nodes, the arcs that were “blocking” (can leave the basis) are added to a list. In subsequent iterations, of the arcs that now can leave the basis, the one chosen to leave is an arc on the list of arcs that could have left in the previous iteration. In other words, preference is given to arcs that “block” many iterations. After several iterations, the list is cleared.

If the number of blocking arcs is less than the value of the MINBLOCK1 = option, a list is not kept. Otherwise, if PERTURB1 is specified, the arc flows are perturbed by a random quantity, so that arcs on the list that block subsequent iterations are chosen to leave the basis randomly. Although perturbation often pays off, it is computationally expensive. Periodically, PROC NETFLOW has to clear out the lists and un-perturb the solution. You can specify NOPERTURB1 to prevent perturbation.

Defaults are CYCLEMULT1 = 0.15, MINBLOCK1 = 2, and NOPERTURB1.

LRATIO1

specifies the type of ratio test to use in determining which arc leaves the basis in stage 1. In some iterations, more than one arc is eligible to leave the basis. Of those arcs that can leave the basis, the leaving arc is the first encountered by the algorithm if the LRATIO1 option is specified. Specifying the LRATIO1 option can decrease the chance of cycling but can increase solution times. The alternative to the LRATIO1 option is the NOLRATIO1 option, which is the default.

LRATIO2

specifies the type of ratio test to use in determining what leaves the basis in stage 2. In some iterations, more than one arc, constraint slack, surplus, or nonarc variable is eligible to leave the basis. If the LRATIO2 option is specified, the leaving arc, constraint slack, surplus, or nonarc variable is the one that is eligible to leave the basis first encountered by the algorithm. Specifying the LRATIO2 option can decrease the chance of cycling but can increase solution times. The alternative to the LRATIO2 option is the NOLRATIO2 option, which is the default.
NOLRATIO1

specifies the type of ratio test to use in determining which arc leaves the basis in stage 1. If the NOLRATIO1 option is specified, of those arcs that can leave the basis, the leaving arc has the minimum (maximum) cost if the leaving arc is to be nonbasic with flow capacity equal to its capacity (lower flow bound). If more than one possible leaving arc has the minimum (maximum) cost, the first such arc encountered is chosen. Specifying the NOLRATIO1 option can decrease solution times, but can increase the chance of cycling. The alternative to the NOLRATIO1 option is the LRATIO1 option. The NOLRATIO1 option is the default.

NOLRATIO2

specifies the type of ratio test to use in determining which arc leaves the basis in stage 2. If the NOLRATIO2 option is specified, the leaving arc, constraint slack, surplus, or nonarc variable is the one eligible to leave the basis with the minimum (maximum) cost or objective function coefficient if the leaving arc, constraint slack or nonarc variable is to be nonbasic with flow or value equal to its capacity or upper value bound (lower flow or value bound), respectively. If several possible leaving arcs, constraint slacks, surpluses, or nonarc variables have the minimum (maximum) cost or objective function coefficient, then the first encountered is chosen. Specifying the NOLRATIO2 option can decrease solution times, but can increase the chance of cycling. The alternative to the NOLRATIO2 option is the LRATIO2 option. The NOLRATIO2 option is the default.

Options Applicable to Constrained Optimization

The INVFRQ= option is relevant only if INVD_2D is specified in the PROC NETFLOW statement; that is, the inverse of the working basis matrix is being stored and processed as a two-dimensional array. The REFACTFRQ=, U=, MAXLUUPDATES=, and MAXL= options are relevant if the INVD_2D option is not specified in the PROC NETFLOW statement; that is, if the working basis matrix is LU factored.

BIGM2
NOTWOPHASE2
TWOPHASE2
NOBIGM2

are the stage 2 constrained optimization counterparts of the options BIGM1, NOTWOPHASE1, TWOPHASE1, and NOBIGM1.

The TWOPHASE2 option is often better than the BIGM2 option when the problem has many side constraints.

INVFRQ=n

recalculates the working basis matrix inverse whenever n iterations have been performed where n is the value of the INVFRQ= option. Although a relatively expensive task, it is prudent to do as roundoff errors accumulate, especially affecting the elements of this matrix inverse. The default is INVFRQ=50. The INVFRQ= option should be used only if the INVD_2D option is specified in the PROC NETFLOW statement.
INTFIRST

In some iterations, it is found that what must leave the basis is an arc that is part of the spanning tree representation of the network part of the basis (called a *key* arc). It is necessary to interchange another basic arc not part of the tree (called a *nonkey* arc) with the tree arc that leaves to permit the basis update to be performed efficiently. Specifying the INTFIRST option indicates that of the nonkey arcs eligible to be swapped with the leaving key arc, the one chosen to do so is the first encountered by the algorithm. If the INTFIRST option is not specified, all such arcs are examined and the one with the best cost is chosen.

The terms *key* and *nonkey* are used because the algorithm used by PROC NETFLOW for network optimization considering side constraints (GUB-based, Primal Partitioning, or Factorization) is a variant of an algorithm originally developed to solve linear programming problems with generalized upper bounding constraints. The terms *key* and *nonkey* were coined then. The STATUS SAS variable in the ARCOOUT= and CONOUT= data sets and the STATUS column in tables produced when PRINT statements are processed indicate whether basic arcs are key or nonkey. Basic nonarc variables are always nonkey.

MAXL=\(m\)

If the working basis matrix is \(LU\) factored, \(U\) is an upper triangular matrix and \(L\) is a lower triangular matrix corresponding to a sequence of elementary matrix row operations required to change the working basis matrix into \(U\). \(L\) and \(U\) enable substitution techniques to be used to solve the linear systems of the simplex algorithm. Among other things, the \(LU\) processing strives to keep the number of \(L\) elementary matrix row operation matrices small. A buildup in the number of these could indicate that fill-in is becoming excessive and the computations involving \(L\) and \(U\) will be hampered. Refactorization should be performed to restore \(U\) sparsity and reduce \(L\) information. When the number of \(L\) matrix row operations exceeds the value of the MAXL= option, a refactorization is done rather than one or more updates. The default value for MAXL= option should not be used if INVD_2D is specified in the PROC NETFLOW statement.

MAXLUUPDATES=\(m\)

MLUU=\(m\)

In some iterations, PROC NETFLOW must either perform a series of single column updates or a complete refactorization of the working basis matrix. More than one column of the working basis matrix must change before the next simplex iteration can begin. The single column updates can often be done faster than a complete refactorization, especially if few updates are necessary, the working basis matrix is sparse, or a refactorization has been performed recently. If the number of columns that must change is less than the value specified in the MAXLUUPDATES= option, the updates are attempted; otherwise, a refactorization is done. Refactorization also occurs if the sum of the number of columns that must be changed and the number of \(LU\) updates done since the last refactorization exceeds the value of the REFACTFREQ= option. The MAXLUUPDATES= option should not be used if the INVD_2D option is specified in the PROC NETFLOW statement.

In some iterations, a series of single column updates are not able to complete the changes required for a working basis matrix because, ideally, all columns should change at once. If the update cannot be completed, PROC NETFLOW performs a refactorization. The default value is 5.
**NOINTFIRST**
indicates that of the arcs eligible to be swapped with the leaving arc, the one chosen to do so has the best cost. See the **INTFIRST** option.

**REFACTFREQ=\(r\)**
**RFF=\(r\)**
specifies the maximum number of L and U updates between refactorization of the working basis matrix to reinitialize LU factors. In most iterations, one or several Bartels-Golub updates can be performed. An update is performed more quickly than a complete refactorization. However, after a series of updates, the sparsity of the U factor is degraded. A refactorization is necessary to regain sparsity and to make subsequent computations and updates more efficient. The default value is 50. The **REFACTFREQ=** option should not be used if **INVD_2D** is specified in the **PROC NETFLOW** statement.

**U=\(u\)**
controls the choice of pivot during LU decomposition or Bartels-Golub update. When searching for a pivot, any element less than the value of the U= option times the largest element in its matrix row is excluded, or matrix rows are interchanged to improve numerical stability. The U= option should have values on or between ZERO2 and 1.0. Decreasing the value of the U= option biases the algorithm toward maintaining sparsity at the expense of numerical stability and vice-versa. Reid (1975) suggests that the value of 0.01 is acceptable and this is the default for the U= option. This option should not be used if **INVD_2D** is specified in the **PROC NETFLOW** statement.

**Pricing Strategy Options**

There are three main types of pricing strategies:

- **PRICETYPE\(x\)=NOQ**
- **PRICETYPE\(x\)=BLAND**
- **PRICETYPE\(x\)=Q**

The one that usually performs better than the others is **PRICETYPE\(x\)=Q**, so this is the default. Because the pricing strategy takes a lot of computational time, you should experiment with the following options to find the optimum specification. These options influence how the pricing step of the simplex iteration is performed. See the section “Pricing Strategies” on page 393 for further information.

- **PRICETYPE\(x\)=BLAND or PTYPE\(x\)=BLAND**
- **PRICETYPE\(x\)=NOQ or PTYPE\(x\)=NOQ**
  - **P\(x\)SCAN=BEST**
  - **P\(x\)SCAN=FIRST**
  - **P\(x\)SCAN=PARTIAL** and **P\(x\)NPARTIAL=\(p\)**
PRICETYPE\textsubscript{x}=Q or PTYPE\textsubscript{x}=Q
QSIZE\textsubscript{x}=q or Q\textsubscript{x}=q
REFRESHQ\textsubscript{x}=r
REDUCEQSIZE\textsubscript{x}=r
REDUCEQ\textsubscript{x}=r

- P\textsubscript{x}SCAN=BEST
- P\textsubscript{x}SCAN=FIRST
- P\textsubscript{x}SCAN=PARTIAL and P\textsubscript{x}NPARTIAL=p
- Q\textsubscript{x}FILLSCAN=BEST
- Q\textsubscript{x}FILLSCAN=FIRST
- Q\textsubscript{x}FILLSCAN=PARTIAL and Q\textsubscript{x}FILLNPARTIAL=q

For stage 2 optimization, you can specify P2SCAN=ANY, which is used in conjunction with the DUAL-FREQ= option.

**Miscellaneous Options**

**FUTURE1**
signals that PROC NETFLOW must output extra observations to the NODEOUT= and ARCUOT= data sets. These observations contain information about the solution found by doing optimization neglecting any side constraints. These two data sets then can be used as the NODEDATA= and ARCDATA= data sets, respectively, in subsequent PROC NETFLOW runs with the WARM option specified. See the section “Warm Starts” on page 406.

**FUTURE2**
signals that PROC NETFLOW must output extra observations to the DUALOUT= and CONOUT= data sets. These observations contain information about the solution found by optimization that considers side constraints. These two data sets can then be used as the NODEDATA= data set (also called the DUALIN= data set) and the ARCDATA= data sets, respectively, in subsequent PROC NETFLOW runs with the WARM option specified. See the section “Warm Starts” on page 406.

**MOREOPT**
The MOREOPT option turns off all optimality and infeasibility flags that may have been raised. Unless this is done, PROC NETFLOW will not do any optimization when a RUN statement is specified.

If PROC NETFLOW determines that the problem is infeasible, it will not do any more optimization unless you specify MOREOPT in a RESET statement. At the same time, you can try resetting options (particularly zero tolerances) in the hope that the infeasibility was raised incorrectly.

Consider the following example:

```plaintext
proc netflow
  nodedata=noded /* supply and demand data */
  arcdata=arcd1 /* the arc descriptions */
  condata=cond1 /* the side constraints */
  conout=solution; /* output the solution */
run;
/* Netflow states that the problem is infeasible. */
```
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/* You suspect that the zero tolerance is too large */
reset zero2=1.0e-10 moreopt;
run;

/* Netflow will attempt more optimization. */
/* After this, if it reports that the problem is */
/* infeasible, the problem really might be infeasible */

If PROC NETFLOW finds an optimal solution, you might want to do additional optimization to confirm that an optimum has really been reached. Specify the MOREOPT option in a RESET statement. Reset options, but in this case tighten zero tolerances.

**NOFUTURE1**

negates the FUTURE1 option.

**NOFUTURE2**

negates the FUTURE2 option.

**NOSCRATCH**

negates the SCRATCH option.

**NOZTOL1**

indicates that the majority of tests for roundoff error should not be done. Specifying the NOZTOL1 option and obtaining the same optimal solution as when the NOZTOL1 option is not specified in the PROC NETFLOW statement (or the ZTOL1 option is specified), verifies that the zero tolerances were not too high. Roundoff error checks that are critical to the successful functioning of PROC NETFLOW and any related readjustments are always done.

**NOZTOL2**

indicates that the majority of tests for roundoff error are not to be done during an optimization that considers side constraints. The reasons for specifying the NOZTOL2 option are the same as those for specifying the NOZTOL1 option for stage 1 optimization (see the NOZTOL1 option).

**OPTIM_TIMER**

indicates that the procedure is to issue a message to the SAS log giving the CPU time spent doing optimization. This includes the time spent preprocessing, performing optimization, and postprocessing. Not counted in that time is the rest of the procedure execution, which includes reading the data and creating output SAS data sets.

The time spent optimizing can be small compared to the total CPU time used by the procedure. This is especially true when the problem is quite small (e.g., fewer than 10,000 variables).

**SCRATCH**

specifies that you do not want PROC NETFLOW to enter or continue stage 1 of the algorithm. Rather than specify RESET SCRATCH, you can use the CONOPT statement.

**VERBOSE=v**

limits the number of similar messages that are displayed on the SAS log.

For example, when reading the ARCDATA= data set, PROC NETFLOW might have cause to issue the following message many times:
**ERROR: The HEAD list variable value in obs i in ARCDATA is missing and the TAIL list variable value of this obs is nonmissing. This is an incomplete arc specification.**

If there are many observations that have this fault, messages that are similar are issued for only the first VERBOSEQ=such observations. After the ARCDATA= data set has been read, PROC NETFLOW will issue the message

**NOTE: More messages similar to the ones immediately above could have been issued but were suppressed as VERBOSEQ=v.**

If observations in the ARCDATA= data set have this error, PROC NETFLOW stops and you have to fix the data. Imagine that this error is only a warning and PROC NETFLOW proceeded to other operations such as reading the CONDATA= data set. If PROC NETFLOW finds there are numerous errors when reading that data set, the number of messages issued to the SAS log are also limited by the VERBOSEQ= option.

If you have a problem with a large number of side constraints and for some reason you stop stage 2 optimization early, PROC NETFLOW indicates that constraints are violated by the current solution. Specifying VERBOSEQ=v allows at most v violated constraints to be written to the log. If there are more, these are not displayed.

When PROC NETFLOW finishes and messages have been suppressed, the message

**NOTE: To see all messages, specify VERBOSEQ=vmin.**

is issued. The value of vmin is the smallest value that should be specified for the VERBOSEQ= option so that all messages are displayed if PROC NETFLOW is run again with the same data and everything else (except the VERBOSEQ= option) unchanged. No messages are suppressed.

The default value for the VERBOSEQ= option is 12.

**ZERO1=z**

**Z1=z**

specifies the zero tolerance level in stage 1. If the NOZTOL1 option is not specified, values within z of zero are set to 0.0, where z is the value of the ZERO1= option. Flows close to the lower flow bound or capacity of arcs are reassigned those exact values. Two values are deemed to be close if one is within z of the other. The default value for the ZERO1= option is 0.000001. Any value specified for the ZERO1= option that is < 0.0 or > 0.0001 is invalid.

**ZERO2=z**

**Z2=z**

specifies the zero tolerance level in stage 2. If the NOZTOL2 option is not specified, values within z of zero are set to 0.0, where z is the value of the ZERO2= option. Flows close to the lower flow bound or capacity of arcs are reassigned those exact values. If there are nonarc variables, values close to the lower or upper value bound of nonarc variables are reassigned those exact values. Two values are deemed to be close if one is within z of the other. The default value for the ZERO2= option is 0.000001. Any value specified for the ZERO2= option that is < 0.0 or > 0.0001 is invalid.
**ZEROTOL=z**
specifies the zero tolerance used when PROC NETFLOW must compare any real number with another real number, or zero. For example, if x and y are real numbers, then for x to be considered greater than y, x must be at least y + z. The ZEROTOL= option is used throughout any PROC NETFLOW run.

ZEROTOL=z controls the way PROC NETFLOW performs all double precision comparisons; that is, whether a double precision number is equal to, not equal to, greater than (or equal to), or less than (or equal to) zero or some other double precision number. A double precision number is deemed to be the same as another such value if the absolute difference between them is less than or equal to the value of the ZEROTOL= option.

The default value for the ZEROTOL= option is 1.0E–14. You can specify the ZEROTOL= option in the NETFLOW or RESET statement. Valid values for the ZEROTOL= option must be > 0.0 and < 0.0001. Do not specify a value too close to zero as this defeats the purpose of the ZEROTOL= option. Neither should the value be too large, as comparisons might be incorrectly performed.

The ZEROTOL= option is different from the ZERO1= and ZERO2= options in that ZERO1= and ZERO2= options work when determining whether optimality has been reached, whether an entry in the updated column in the ratio test of the simplex method is zero, whether a flow is the same as the arc’s capacity or lower bound, or whether the value of a nonarc variable is at a bound. The ZEROTOL= option is used in all other general double precision number comparisons.

**ZTOL1**
indicates that all tests for roundoff error are performed during stage 1 optimization. Any alterations are carried out. The opposite of the ZTOL1 option is the NOZTOL1 option.

**ZTOL2**
indicates that all tests for roundoff error are performed during stage 2 optimization. Any alterations are carried out. The opposite of the ZTOL2 option is the NOZTOL2 option.

**Interior Point Algorithm Options**

**FACT_METHOD=f**
enables you to choose the type of algorithm used to factorize and solve the main linear systems at each iteration of the interior point algorithm.

FACT_METHOD=LEFT_LOOKING is new for SAS 9.1.2. It uses algorithms described in George, Liu, and Ng (2001). Left looking is one of the main methods used to perform Cholesky optimization and, along with some recently developed implementation approaches, can be faster and require less memory than other algorithms.

Specify FACT_METHOD=USE_OLD if you want the procedure to use the only factorization available prior to SAS 9.1.2.

**TOLDINF=t**
**RTOLDINF=t**
specifies the allowed amount of dual infeasibility. In the section “Interior Point Algorithmic Details” on page 429, the vector $\text{infeas}_d$ is defined. If all elements of this vector are $\leq t$, the solution is deemed feasible. $\text{infeas}_d$ is replaced by a zero vector, making computations faster. This option is the dual equivalent to the TOLPINF= option. Valid values for $t$ are greater than 1.0E–12. The default is 1.0E–7.
RESET Statement

\( \text{TOLPINF}=t \)

RTOLPINF=\( t \)

specifies the allowed amount of primal infeasibility. This option is the primal equivalent to the \( \text{TOLDINF}= \) option. In the section “Interior Point: Upper Bounds” on page 436, the vector \( \text{infeas}_b \) is defined. In the section “Interior Point Algorithmic Details” on page 429, the vector \( \text{infeas}_c \) is defined. If all elements in these vectors are \( \leq t \), the solution is deemed feasible. \( \text{infeas}_b \) and \( \text{infeas}_c \) are replaced by zero vectors, making computations faster. Increasing the value of the TOLPINF= option too much can lead to instability, but a modest increase can give the algorithm added flexibility and decrease the iteration count. Valid values for \( t \) are greater than 1.0E\(-12\). The default is 1.0E\(-7\).

\( \text{TOLTOTDINF}=t \)

RTOLTOTDINF=\( t \)

specifies the allowed total amount of dual infeasibility. In the section “Interior Point Algorithmic Details” on page 429, the vector \( \text{infeas}_d \) is defined. If \( \sum_{i=1}^{n} \text{infeas}_{di} \leq t \), the solution is deemed feasible. \( \text{infeas}_d \) is replaced by a zero vector, making computations faster. This option is the dual equivalent to the TOLTOTPINF= option. Valid values for \( t \) are greater than 1.0E\(-12\). The default is 1.0E\(-7\).

\( \text{TOLTOTPINF}=t \)

RTOLTOTPINF=\( t \)

specifies the allowed total amount of primal infeasibility. This option is the primal equivalent to the \( \text{TOLTOTDINF}= \) option. In the section “Interior Point: Upper Bounds” on page 436, the vector \( \text{infeas}_b \) is defined. In the section “Interior Point Algorithmic Details” on page 429, the vector \( \text{infeas}_c \) is defined. If \( \sum_{i=1}^{n} \text{infeas}_{bi} \leq t \) and \( \sum_{i=1}^{m} \text{infeas}_{ci} \leq t \), the solution is deemed feasible. \( \text{infeas}_b \) and \( \text{infeas}_c \) are replaced by zero vectors, making computations faster. Increasing the value of the TOLTOTPINF= option too much can lead to instability, but a modest increase can give the algorithm added flexibility and decrease the iteration count. Valid values for \( t \) are greater than 1.0E\(-12\). The default is 1.0E\(-7\).

\( \text{CHOLTINYTOL}=c \)

RCHOLTINYTOL=\( c \)

specifies the cut-off tolerance for Cholesky factorization of the \( A\Theta A^{-1} \). If a diagonal value drops below \( c \), the row is essentially treated as dependent and is ignored in the factorization. Valid values for \( c \) are between 1.0E\(-30\) and 1.0E\(-6\). The default value is 1.0E\(-8\).

\( \text{DENSETHR}=d \)

RDENSETHR=\( d \)

specifies the density threshold for Cholesky processing. When the symbolic factorization encounters a column of \( L \) that has DENSETHR= \( d \) proportion of nonzeros and the remaining part of \( L \) is at least 12 \( \times \) 12, the remainder of \( L \) is treated as dense. In practice, the lower right part of the Cholesky triangular factor \( L \) is quite dense and it can be computationally more efficient to treat it as 100\% dense. The default value for \( d \) is 0.7. A specification of \( d \leq 0.0 \) causes all dense processing; \( d \geq 1.0 \) causes all sparse processing.
PDSTEPMULT=$p$
RPDSTEPMULT=$p$

specifies the step-length multiplier. The maximum feasible step-length chosen by the Primal-Dual with Predictor-Corrector algorithm is multiplied by the value of the PDSTEPMULT= option. This number must be less than 1 to avoid moving beyond the barrier. An actual step length greater than 1 indicates numerical difficulties. Valid values for $p$ are between 0.01 and 0.999999. The default value is 0.99995.

In the section “Interior Point Algorithmic Details” on page 429, the solution of the next iteration is obtained by moving along a direction from the current iteration’s solution:

$$(x^{k+1}, y^{k+1}, s^{k+1}) = (x^k, y^k, s^k) + \alpha(\Delta x^k, \Delta y^k, \Delta s^k)$$

where $\alpha$ is the maximum feasible step-length chosen by the interior point algorithm. If $\alpha \leq 1$, then $\alpha$ is reduced slightly by multiplying it by $p$. $\alpha$ is a value as large as possible but $\leq 1.0$ and not so large that an $x^{k+1}_i$ or $s^{k+1}_i$ of some variable $i$ is “too close” to zero.

PRSLTYPE=$p$
IPRSLTYPE=$p$

Preprocessing the linear programming problem often succeeds in allowing some variables and constraints to be temporarily eliminated from the LP that must be solved. This reduces the solution time and possibly also the chance that the optimizer will run into numerical difficulties. The task of preprocessing is inexpensive to do.

You control how much preprocessing to do by specifying PRSLTYPE=$p$, where $p$ can be –1, 0, 1, 2, or 3.

-1 Do not perform preprocessing. For most problems, specifying PRSLTYPE=–1 is not recommended.
0 Given upper and lower bounds on each variable, the greatest and least contribution to the row activity of each variable is computed. If these are within the limits set by the upper and lower bounds on the row activity, then the row is redundant and can be discarded. Try to tighten the bounds on any of the variables it can. For example, if all coefficients in a constraint are positive and all variables have zero lower bounds, then the row’s smallest contribution is zero. If the rhs value of this constraint is zero, then if the constraint type is $=$ or $\leq$, all the variables in that constraint can be fixed to zero. These variables and the constraint can be removed. If the constraint type is $\geq$, the constraint is redundant. If the rhs is negative and the constraint is $\leq$, the problem is infeasible. If just one variable in a row is not fixed, use the row to impose an implicit upper or lower bound on the variable and then eliminate the row. The preprocessor also tries to tighten the bounds on constraint right-hand sides.
1 When there are exactly two unfixed variables with coefficients in an equality constraint, solve for one in terms of the other. The problem will have one less variable. The new matrix will have at least two fewer coefficients and one less constraint. In other constraints where both variables appear, two coefs are combined into one. PRSLTYPE=0 reductions are also done.
It may be possible to determine that an equality constraint is not constraining a variable. That is, if all variables are nonnegative, then \( x - \sum_i y_i = 0 \) does not constrain \( x \), since it must be nonnegative if all the \( y_i \)'s are nonnegative. In this case, eliminate \( x \) by subtracting this equation from all others containing \( x \). This is useful when the only other entry for \( x \) is in the objective function. Perform this reduction if there is at most one other nonobjective coefficient. PRSLTYPE=0 reductions are also done.

All possible reductions are performed. PRSLTYPE=3 is the default.

Preprocessing is iterative. As variables are fixed and eliminated, and constraints are found to be redundant and they too are eliminated, and as variable bounds and constraint right-hand sides are tightened, the LP to be optimized is modified to reflect these changes. Another iteration of preprocessing of the modified LP may reveal more variables and constraints that can be eliminated.

**PRINTLEVEL2=p**

is used when you want to see PROC NETFLOW's progress to the optimum. PROC NETFLOW will produce a table on the SAS log. A row of the table is generated during each iteration and may consist of values of

- the affine step complementarity
- the complementarity of the solution for the next iteration
- the total bound infeasibility \( \sum_{i=1}^{n} \text{infeas}_{bi} \) (see the \( \text{infeas}_b \) array in the section “Interior Point: Upper Bounds” on page 436)
- the total constraint infeasibility \( \sum_{i=1}^{m} \text{infeas}_{ci} \) (see the \( \text{infeas}_c \) array in the section “Interior Point Algorithmic Details” on page 429)
- the total dual infeasibility \( \sum_{i=1}^{n} \text{infeas}_{di} \) (see the \( \text{infeas}_d \) array in the section “Interior Point Algorithmic Details” on page 429)

As optimization progresses, the values in all columns should converge to zero. If you specify PRINTLEVEL2=2, all columns will appear in the table. If PRINTLEVEL2=1 is specified, only the affine step complementarity and the complementarity of the solution for the next iteration will appear. Some time is saved by not calculating the infeasibility values.

**Interior Point Algorithm Options: Stopping Criteria**

**MAXITERB=m**

**IMAXITERB=m**

specifies the maximum number of iterations of the interior point algorithm that can be performed. The default value for \( m \) is 100. One of the most remarkable aspects of the interior point algorithm is that for most problems, it usually needs to do a small number of iterations, no matter the size of the problem.

**PDGAPTOL=p**

**RPDGAPTOL=p**

specifies the primal-dual gap or duality gap tolerance. Duality gap is defined in the section “Interior Point Algorithmic Details” on page 429. If the relative gap \((\text{duality gap}/c^T x)\) between the primal and dual objectives is smaller than the value of the PDGAPTOL= option and both the primal and dual problems are feasible, then PROC NETFLOW stops optimization with a solution that is deemed optimal. Valid values for \( p \) are between 1.0E−12 and 1.0E−1. The default is 1.0E−7.
STOP_C=s
is used to determine whether optimization should stop. At the beginning of each iteration, if complementarity (the value of the Complem-ity column in the table produced when you specify PRINTLEVEL2=1 or PRINTLEVEL2=2) is \( \leq s \), optimization will stop. This option is discussed in the section “Stopping Criteria” on page 433.

STOP_DG=s
is used to determine whether optimization should stop. At the beginning of each iteration, if the duality gap (the value of the Duality_gap column in the table produced when you specify PRINTLEVEL2=1 or PRINTLEVEL2=2) is \( \leq s \), optimization will stop. This option is discussed in the section “Stopping Criteria” on page 433.

STOP_IB=s
is used to determine whether optimization should stop. At the beginning of each iteration, if total bound infeasibility \( \sum_{i=1}^{n} infeas_{bi} \) (see the infeas_{b} array in the section “Interior Point: Upper Bounds” on page 436; this value appears in the Tot_infeasb column in the table produced when you specify PRINTLEVEL2=1 or PRINTLEVEL2=2) is \( \leq s \), optimization will stop. This option is discussed in the section “Stopping Criteria” on page 433.

STOP_IC=s
is used to determine whether optimization should stop. At the beginning of each iteration, if total constraint infeasibility \( \sum_{i=1}^{m} infeas_{ci} \) (see the infeas_{c} array in the section “Interior Point Algorithmic Details” on page 429; this value appears in the Tot_infeasc column in the table produced when you specify PRINTLEVEL2=2) is \( \leq s \), optimization will stop. This option is discussed in the section “Stopping Criteria” on page 433.

STOP_ID=s
is used to determine whether optimization should stop. At the beginning of each iteration, if total dual infeasibility \( \sum_{i=1}^{n} infeas_{di} \) (see the infeas_{d} array in the section “Interior Point Algorithmic Details” on page 429; this value appears in the Tot_infeasd column in the table produced when you specify PRINTLEVEL2=2) is \( \leq s \), optimization will stop. This option is discussed in the section “Stopping Criteria” on page 433.

AND_STOP_C=s
is used to determine whether optimization should stop. At the beginning of each iteration, if complementarity (the value of the Complem-ity column in the table produced when you specify PRINTLEVEL2=1 or PRINTLEVEL2=2) is \( \leq s \), and the conditions related to other AND_STOP parameters are also satisfied, optimization will stop. This option is discussed in the section “Stopping Criteria” on page 433.

AND_STOP_DG=s
is used to determine whether optimization should stop. At the beginning of each iteration, if the duality gap (the value of the Duality_gap column in the table produced when you specify PRINTLEVEL2=1 or PRINTLEVEL2=2) is \( \leq s \), and the conditions related to other AND_STOP parameters are also satisfied, optimization will stop. This option is discussed in the section “Stopping Criteria” on page 433.

AND_STOP_IB=s
is used to determine whether optimization should stop. At the beginning of each iteration, if total bound infeasibility \( \sum_{i=1}^{n} infeas_{bi} \) (see the infeas_{b} array in the section “Interior Point: Upper Bounds” on page 436; this value appears in the Tot_infeasb column in the table produced when you specify PRINTLEVEL2=1 or PRINTLEVEL2=2) is \( \leq s \), and the conditions related to other AND_STOP
parameters are also satisfied, optimization will stop. This option is discussed in the section “Stopping Criteria” on page 433.

**AND_STOP_IC=s**

is used to determine whether optimization should stop. At the beginning of each iteration, if total constraint infeasibility $\sum_{i=1}^{m} \text{infeas}_{ci}$ (see the $\text{infeas}_{c}$ array in the section “Interior Point Algorithmic Details” on page 429; this value appears in the Tot_infeasc column in the table produced when you specify PRINTLEVEL2=2) is $\leq s$, and the conditions related to other AND_STOP parameters are also satisfied, optimization will stop. This option is discussed in the section “Stopping Criteria” on page 433.

**AND_STOP_ID=s**

is used to determine whether optimization should stop. At the beginning of each iteration, if total dual infeasibility $\sum_{i=1}^{n} \text{infeas}_{di}$ (see the $\text{infeas}_{d}$ array in the section “Interior Point Algorithmic Details” on page 429; this value appears in the Tot_infeasd column in the table produced when you specify PRINTLEVEL2=2) is $\leq s$, and the conditions related to other AND_STOP parameters are also satisfied, optimization will stop. This option is discussed in the section “Stopping Criteria” on page 433.

**KEEPGOING_C=s**

is used to determine whether optimization should stop. If a stopping condition is met, if complementarity (the value of the Complementarity column in the table produced when you specify PRINTLEVEL2=1 or PRINTLEVEL2=2) is $> s$, optimization will continue. This option is discussed in the section “Stopping Criteria” on page 433.

**KEEPGOING_DG=s**

is used to determine whether optimization should stop. If a stopping condition is met, if the duality gap (the value of the Duality_gap column in the table produced when you specify PRINTLEVEL2=1 or PRINTLEVEL2=2) is $> s$, optimization will continue. This option is discussed in the section “Stopping Criteria” on page 433.

**KEEPGOING_IB=s**

is used to determine whether optimization should stop. If a stopping condition is met, if total bound infeasibility $\sum_{i=1}^{n} \text{infeas}_{bi}$ (see the $\text{infeas}_{b}$ array in the section “Interior Point: Upper Bounds” on page 436; this value appears in the Tot_infeasb column in the table produced when you specify PRINTLEVEL2=1 or PRINTLEVEL2=2) is $> s$, optimization will continue. This option is discussed in the section “Stopping Criteria” on page 433.

**KEEPGOING_IC=s**

is used to determine whether optimization should stop. If a stopping condition is met, if total constraint infeasibility $\sum_{i=1}^{m} \text{infeas}_{ci}$ (see the $\text{infeas}_{c}$ array in the section “Interior Point Algorithmic Details” on page 429; this value appears in the Tot_infeasc column in the table produced when you specify PRINTLEVEL2=2) is $> s$, optimization will continue. This option is discussed in the section “Stopping Criteria” on page 433.

**KEEPGOING_ID=s**

is used to determine whether optimization should stop. If a stopping condition is met, if total dual infeasibility $\sum_{i=1}^{n} \text{infeas}_{di}$ (see the $\text{infeas}_{d}$ array in the section “Interior Point Algorithmic Details” on page 429; this value appears in the Tot_infeasd column in the table produced when you specify PRINTLEVEL2=2) is $> s$, optimization will continue. This option is discussed in the section “Stopping Criteria” on page 433.
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AND_KEEPGOING_C=s

is used to determine whether optimization should stop. If a stopping condition is met, if complementarity (the value of the Complement-ity column in the table produced when you specify PRINTLEVEL2=1 or PRINTLEVEL2=2) is > s, and the conditions related to other AND_KEEPGOING parameters are also satisfied, optimization will continue. This option is discussed in the section “Stopping Criteria” on page 433.

AND_KEEPGOING_DG=s

is used to determine whether optimization should stop. If a stopping condition is met, if the duality gap (the value of the Duality_gap column in the table produced when you specify PRINTLEVEL2=1 or PRINTLEVEL2=2) is > s, and the conditions related to other AND_KEEPGOING parameters are also satisfied, optimization will continue. This option is discussed in the section “Stopping Criteria” on page 433.

AND_KEEPGOING_IB=s

is used to determine whether optimization should stop. If a stopping condition is met, if total bound infeasibility \( \sum_{i=1}^{n} \text{feas}_b i \) (see the \text{feas}_b array in the section “Interior Point: Upper Bounds” on page 436; this value appears in the Tot_feasb column in the table produced when you specify PRINTLEVEL2=2) is > s, and the conditions related to other AND_KEEPGOING parameters are also satisfied, optimization will continue. This option is discussed in the section “Stopping Criteria” on page 433.

AND_KEEPGOING_IC=s

is used to determine whether optimization should stop. If a stopping condition is met, if total constraint infeasibility \( \sum_{i=1}^{m} \text{feas}_c i \) (see the \text{feas}_c array in the section “Interior Point Algorithmic Details” on page 429; this value appears in the Tot_feasc column in the table produced when you specify PRINTLEVEL2=2) is > s, and the conditions related to other AND_KEEPGOING parameters are also satisfied, optimization will continue. This option is discussed in the section “Stopping Criteria” on page 433.

AND_KEEPGOING_ID=s

is used to determine whether optimization should stop. If a stopping condition is met, if total dual infeasibility \( \sum_{i=1}^{n} \text{feas}_d i \) (see the \text{feas}_d array in the section “Interior Point Algorithmic Details” on page 429; this value appears in the Tot_feasd column in the table produced when you specify PRINTLEVEL2=2) is > s, and the conditions related to other AND_KEEPGOING parameters are also satisfied, optimization will continue. This option is discussed in the section “Stopping Criteria” on page 433.

### RHS Statement

RHS variable ;

The RHS variable list is used when the dense format of the CONDATA= data set is used. The values of the SAS variable specified in the RHS list are constraint right-hand-side values. If the RHS list is not specified, the CONDATA= data set is searched and a SAS variable with the name _RHS_/ is used. If there is no RHS list and no SAS variable named _RHS_/ all constraints are assumed to have zero right-hand-side values. The RHS list variable must have numeric values.
**ROW Statement**

```plaintext
ROW variables ;
```

The ROW list is used when either the **sparse** or the **dense** format of side constraints is being used. SAS variables in the ROW list have values that are constraint or special row names. The SAS variables in the ROW list must have character values.

If the **dense** data format is used, there must be only one SAS variable in this list. In this case, if a ROW list is not specified, the CONDATA= data set is searched and the SAS variable with the name `_ROW_` or `_CON_` is used.

If the **sparse** data format is used and the ROW statement is not specified, the CONDATA= data set is searched and SAS variables with names beginning with `_ROW` or `_CON` are used. The number of SAS variables in the ROW list must not be less than the number of SAS variables in the COEF list. The `i`th ROW list variable is paired with the `i`th COEF list variable. If the number of ROW list variables is greater than the number of COEF list variables, the last ROW list variables have no COEF partner. These ROW list variables that have no corresponding COEF list variable are used in observations that have a TYPE list variable value. All ROW list variable values are tagged as having the type indicated. If there is no TYPE list variable, all ROW list variable values are constraint names.

**RUN Statement**

```plaintext
RUN ;
```

The RUN statement causes optimization to be started or resumed. The RUN statement has no options. If PROC NETFLOW is called and is not terminated because of an error or a QUIT statement, and you have not used a RUN statement, a RUN statement is assumed implicitly as the last statement of PROC NETFLOW. Therefore, PROC NETFLOW always performs optimization and saves the obtained (optimal) solution in the current output data sets.

**SAVE Statement**

```plaintext
SAVE options ;
```

The options available with the SAVE statement of PROC NETFLOW are summarized by purpose in the following table.

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output Data Set Options:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Unconstrained primal solution data set</td>
<td>SAVE</td>
<td>ARCOU T=</td>
</tr>
<tr>
<td>Unconstrained dual solution data set</td>
<td>SAVE</td>
<td>NODEOUT=</td>
</tr>
<tr>
<td>Constrained primal solution data set</td>
<td>SAVE</td>
<td>CONOUT=</td>
</tr>
<tr>
<td>Constrained dual solution data set</td>
<td>SAVE</td>
<td>DUALOUT=</td>
</tr>
</tbody>
</table>
The SAVE statement can be used to specify output data sets and create observations in these data sets. Use the SAVE statement if no optimization is to be performed before these output data sets are created.

The SAVE statement must be used to save solutions in data sets if there is no more optimization to do. If more optimization is to be performed, after which you want to save the solution, then do one of the following:

- Submit a RUN statement followed by a SAVE statement.
- Use the PROC NETFLOW or RESET statement to specify current output data sets. After optimization, output data sets are created and observations are automatically sent to the current output data sets.

Consider the following example:

```plaintext
proc netflow options; lists;
  reset maxit1=10 maxit2=25
    arcout=arcout0  nodeout=nodeout0
    conout=conout0  dualout=dualout0;
  run;
  /* Stage 1 optimization stops after iteration 10. */
  /* No output data sets are created yet. */
  save arcout=arcout1 nodeout=nodeout1;
  /* arcout1 and nodeout1 are created. */
  reset arcout=arcout2 maxit1=999999;
  run;
  /* The stage 1 optimum is reached. */
  /* Arcout2 and nodeout0 are created. */
  /* Arcout0 is not created as arcout=arcout2 over- */
  /* rides the arcout=arcout0 specified earlier. */
  /* Stage 2 optimization stops after 25 iterations */
  /* as MAXIT2=25 was specified. */
  save conout=conout1;
  /* Conout1 is created. */
  reset maxit2=999999 dualout=null;
  run;
  /* The stage 2 optimum is reached. */
  /* Conout0 is created. */
  /* No dualout is created as the last NETFLOW or */
  /* reset statements dualout=data set specification*/
  /* was dualout=null. */
```

The data sets specified in the PROC NETFLOW and RESET statements are created when an optimal solution is found. The data sets specified in SAVE statements are created immediately.

The data sets in the preceding example are all distinct, but this need not be the case. The only exception to this is that the ARCOUT= data set and the NODEOUT= data set (or the CONOUT= data set and the DUALOUT= data set) that are being created at the same time must be distinct. Use the SHOW DATASETS statement to examine what data sets are current and when they were created.

The following options can appear in the SAVE statement:

- **ARCOUT=SAS-data-set** (or **AOUT=SAS-data-set**)
- **NODEOUT=SAS-data-set** (or **NOUT=SAS-data-set**)

SHOW Statement

SHOW options / qualifiers ;

The options available with the SHOW statement of PROC NETFLOW are summarized by purpose in the following table.

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>SHOW Statement Options:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Show problem, optimization status</td>
<td>SHOW</td>
<td>STATUS</td>
</tr>
<tr>
<td>Show network model parameters</td>
<td>SHOW</td>
<td>NETSTMT</td>
</tr>
<tr>
<td>Show data sets that have been or will be created</td>
<td>SHOW</td>
<td>DATASETS</td>
</tr>
<tr>
<td>Show options that pause optimization</td>
<td>SHOW</td>
<td>PAUSE</td>
</tr>
<tr>
<td>Show simplex algorithm options</td>
<td>SHOW</td>
<td>SIMPLEX</td>
</tr>
<tr>
<td>Show pricing strategy options</td>
<td>SHOW</td>
<td>PRICING</td>
</tr>
<tr>
<td>Show miscellaneous options</td>
<td>SHOW</td>
<td>MISC</td>
</tr>
<tr>
<td>SHOW Statement Qualifiers:</td>
<td>SHOW</td>
<td>/ RELEVANT</td>
</tr>
<tr>
<td>Display information only on relevant options</td>
<td>SHOW</td>
<td>/ STAGE</td>
</tr>
<tr>
<td>Display options for current stage only</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The SHOW statement enables you to examine the status of the problem and values of the RESET statement options. All output of the SHOW statement appears on the SAS log. The amount of information displayed when a SHOW statement is processed can be limited if some of the options of the SHOW statement are specified. These options indicate whether the problem status or a specific category of the RESET options is of interest. If no options are specified, the problem status and information on all RESET statement options in every category is displayed. The amount of displayed information can be limited further by following any SHOW statement options with a slash (/) and one or both qualifiers, RELEVANT and STAGE.

STATUS

produces one of the following optimization status reports, whichever is applicable. The warning messages are issued only if the network or entire problem is infeasible.

NOTE: Optimization Status.
Optimization has not started yet.

NOTE: Optimization Status.
Optimizing network (ignoring any side constraints).
Number of iterations=17
Of these, 3 were degenerate
WARNING: This optimization has detected that the network is infeasible.

NOTE: Optimization Status.
Found network optimum (ignoring side constraints)
Number of iterations=23
Of these, 8 were degenerate

NOTE: Optimization Status.
Optimizing side constrained network.
Number of iterations=27
Of these, 9 were degenerate
WARNING: This optimization has detected that the problem is infeasible.

NOTE: Optimization Status.
Found side constrained network optimum
Number of iterations=6
Of these, 0 were degenerate

DATASETS
produces a report on output data sets.

NOTE: Current output SAS data sets
No output data sets have been specified

NOTE: Current output SAS data sets
ARCOUT=libname.memname
NODEOUT=libname.memname
CONOUT=libname.memname
DUALOUT=libname.memname

NOTE: Other SAS data sets specified in previous ARCOUT=, NODEOUT=, CONOUT=, or DUALOUT=.
libname.memname
.
.
.

NOTE: Current output SAS data sets (SHOW DATASETS)
libname.memname
.
.
.

NOTE: SAS data sets specified as ARCOUT= NODEOUT= CONOUT= or DUALOUT= data sets in previous PROC NETFLOW, SET, RESET and SAVE statements.
The number following the data set specification was the iteration number when observations were placed into the data set.
libname.memname iteration_number
.
.
.
PAUSE

produces a report on the current settings of options used to make optimization pause.

NOTE: Options and parameters that stop optimization for reasons other than infeasibility or optimality (SHOW PAUSE)
FEASIBLEPAUSE1=FALSE
ENDPAUSE1=FALSE
PAUSE1=999999
MAXIT1=1000
FEASIBLEPAUSE2=FALSE
PAUSE2=999999
MAXIT2=999999

SIMPLEX

produces the following:

NOTE: Options and parameters that control the primal simplex network algorithm (excluding those that affect the pricing strategies) (SHOW SIMPLEX)
LRATIO1=FALSE
BIGM1=NOTWOPHASE1=TRUE, TWOPHASE1=NOBIGM1=FALSE
CYCLEMULT1=0.15
PERTURB1=FALSE
MINBLOCK1=2
INTFIRST=TRUE
LRATIO2=FALSE
BIGM2=NOTWOPHASE2=TRUE, TWOPHASE2=NOBIGM2=FALSE
REFACTFREQ=50
U=0.1
MAXLUUPDATES=6
MAXL=40

PRICING

produces the following:

NOTE: Options and parameters that control the primal simplex network algorithm pricing strategies (SHOW PRICING)
PRICETYPE1=Q
P1SCAN=FIRST
P1NPARTIAL=10
Q1FILLSCAN=FIRST
QSIZE1=24
REFRESHQ1=0.75
REDUCEQSIZE1=1
Q1FILLN Partial=10
PRICETYPE2=Q
P2SCAN=FIRST
P2NPARTIAL=10
DUALFREQ=4
Q2FILLSCAN=FIRST
QSIZE2=24
REFRESHQ2=0.75
REDUCEQSIZE2=1
Q2FILLNPARTIAL=10

MISC

produces the following:

NOTE: Miscellaneous options and parameters (SHOW MISC)

VERBOSE=12
ZTOL1=TRUE
ZERO1=1E-6
FUTURE1=FALSE
ZTOL2=TRUE
ZERO2=1E-6
FUTURE2=FALSE

Following a slash (/), the qualifiers below can appear in any SHOW statement.

RELEVANT

indicates that you want information only on relevant options of the RESET statement. The following will not be displayed if / RELEVANT is specified:

• information on noncurrent data sets
• the options that control the reasons why stage 1 optimization should be halted and the options that control the simplex algorithm during stage 1 optimization, if the unconstrained optimum has been reached or constrained optimization has been performed
• if P1SCAN=BEST or P1SCAN=FIRST, the P1NPARTIAL= option is irrelevant
• if PRICETYPE1=BLAND or PRICETYPE1=NOQ, the options QSIZE1=, Q1FILLSCAN=, REFRESHQ1=, and REDUCEQSIZE1= are irrelevant
• if Q1FILLSCAN=BEST or Q1FILLSCAN=FIRST, the Q1FILLNPARTIAL= option is irrelevant
• the options that control the reasons stage 2 optimization should be halted, the options that control the simplex algorithm during stage 2 optimization, if the constrained optimum has been reached
• if P2SCAN=BEST or P2SCAN=FIRST, the P2NPARTIAL= option is irrelevant
• if PRICETYPE2=BLAND or PRICETYPE2=NOQ, the options QSIZE2=, Q2FILLSCAN=, REFRESHQ2=, and REDUCEQSIZE2= are irrelevant
• if Q2FILLSCAN=BEST or Q2FILLSCAN=FIRST, the Q2FILLNPARTIAL= option is irrelevant

STAGE

indicates that you want to examine only the options that affect the optimization that is performed if a RUN statement is executed next. Before any optimization has been done, only stage 2 options are displayed if the problem has side constraints and the SCRATCH option is used, or if the CONOPT statement is specified. Otherwise, stage 1 options are displayed. If still optimizing neglecting constraints, only stage 1 options will be displayed. If the unconstrained optimum has been reached and
optimization that considers constraints has not been performed, stage 1 options are displayed. If the problem has constraints, stage 2 options are displayed. If any optimization that considers constraints has been performed, only stage 2 options are displayed.

**SUPDEM Statement**

```
SUPDEM variable ;
```

The SAS variable in this list, which must be present in the **NODEDATA=** data set, contains supply and demand information for the nodes in the **NODE** list. A positive SUPDEM list variable value \( s \ (s > 0) \) denotes that the node named in the **NODE** list variable can supply \( s \) units of flow. A negative SUPDEM list variable value \( -d \ (d > 0) \) means that this node demands \( d \) units of flow. If a SAS variable is not explicitly specified, a SAS variable with the name `_SUPDEM_` or `_SD_` in the **NODEDATA=** data set is used as the SUPDEM variable. If a node is a transshipment node (neither a supply nor a demand node), an observation associated with this node need not be present in the **NODEDATA=** data set. If present, the SUPDEM list variable value must be zero or a missing value.

**SUPPLY Statement**

```
SUPPLY variable ;
```

The **SUPPLY** statement identifies the SAS variable in the **ARCDATA=** data set that contains the supply at the node named in that observation’s **TAILNODE** list variable. If a tail node does not supply flow, use zero or a missing value for the observation’s **SUPPLY** list variable value. If a tail node has supply capability, a missing value indicates that the supply quantity is given in another observation. It is not necessary to have a **SUPPLY** statement if the name of this SAS variable is `_SUPPLY_`.

**TAILNODE Statement**

```
TAILNODE variable ;
TAIL variable ;
FROMNODE variable ;
FROM variable ;
```

The **TAILNODE** statement specifies the SAS variable that must be present in the **ARCDATA=** data set that has as values the names of tail nodes of arcs. The **TAILNODE** variable must have character values. It is not necessary to have a **TAILNODE** statement if the name of the SAS variable is `_TAIL_` or `_FROM_`. If the **TAILNODE** list variable value is missing, it is assumed that the observation of **ARCDATA=** data set contains information concerning a nonarc variable.
**TYPE Statement**

```
TYPE variable ;
CONTYPE variable ;
```

The TYPE list, which is optional, names the variable that has as values keywords that indicate either the constraint type for each constraint or the type of special rows in the CONDATA= data set. The values of the TYPE list variable also indicate, in each observation of the CONDATA= data set, how values of the VAR or COEF list variables are to be interpreted and how the type of each constraint or special row name is determined. If the TYPE list is not specified, the CONDATA= data set is searched and a SAS variable with the name _TYPE_ is used. Valid keywords for the TYPE variable are given below. If there is no TYPE statement and no other method is used to furnish type information (see the DEFCONTYPE= option), all constraints are assumed to be of the type “less than or equal to” and no special rows are used. The TYPE list variable must have character values and can be used when the data in the CONDATA= data set is in either the sparse or the dense format. If the TYPE list variable value has a * as its first character, the observation is ignored because it is a comment observation.

**TYPE List Variable Values**

The following are valid TYPE list variable values. The letters in boldface denote the characters that PROC NETFLOW uses to determine what type the value suggests. You need to have at least these characters. In the following list, the minimal TYPE list variable values have additional characters to aid you in remembering these values.

- `<` less than or equal to (≤)
- `=` equal to (=)
- `>` greater than or equal to (≥)
- `CAPAC` capacity
- `COST` cost
- `EQ` equal to
- `FREE` free row (used only for linear programs solved by interior point)
- `GAIN` gain in arc flow (generalized networks)
- `GE` greater than or equal to
- `LE` less than or equal to
- `LOSS` loss in arc flow (generalized networks)
- `LOWERBD` lower flow or value bound
- `LOWblank` lower flow or value bound
- `MAXIMIZE` maximize (opposite of cost)
- `MINIMIZE` minimize (same as cost)
- `MULT` value of arc multiplier (generalized networks)
- `OBJECTIVE` objective function (same as cost)
- `RHS` rhs of constraint
- `TYPE` type of constraint
- `UPPCOST` reserved for future use
- `UNREST` unrestricted variable (used only for linear programs solved by interior point)
- `UPPER` upper value bound or capacity; second letter must not be N
The valid TYPE list variable values in function order are

- **LE** less than or equal to (≤)
- **EQ** equal to (=)
- **GE** greater than or equal to (≥)
- **COST**
  - **MINIMIZE**
  - **MAXIMIZE**
  - **OBJECTIVE**
    cost or objective function coefficient
- **CAPAC**
  - **UPPER**
    capacity or upper value bound
- **LOWERBD**
  - **LOWblank**
    lower flow or value bound
- **RHS** rhs of constraint
- **TYPE** type of constraint
- **MULT**
  - **GAIN**
  - **LOSS**
    value of arc multiplier in a generalized network

A TYPE list variable value that has the first character * causes the observation to be treated as a comment. If the first character is a negative sign, then ≤ is the type. If the first character is a zero, then = is the type. If the first character is a positive number, then ≥ is the type.

**VAR Statement**

```sas
VAR variables ;
```

The VAR variable list is used when the dense data format is used. The names of these SAS variables are also names of the arc and nonarc variables that have data in the CONDATA= data set. If no explicit VAR list is specified, all numeric variables not on other lists are put onto the VAR list. The VAR list variables must have numeric values. The values of the VAR list variables in some observations can be interpreted differently than in other observations. The values can be coefficients in the side constraints, costs and objective function coefficients, or bound data. How these numeric values are interpreted depends on the value of each observation’s TYPE or ROW list variable value. If there are no TYPE list variables, the VAR list variable values are all assumed to be side constraint coefficients.
Details: NETFLOW Procedure

Input Data Sets

PROC NETFLOW is designed so that there are as few rules as possible that you must obey when inputting a problem’s data. Raw data are acceptable. This should cut the amount of processing required to groom the data before it is input to PROC NETFLOW. Data formats are so flexible that, due to space restrictions, all possible forms for a problem’s data are not shown here. Try any reasonable form for your problem’s data; it should be acceptable. PROC NETFLOW will outline its objections.

There are several ways to supply the same piece of data. You do not have to restrict yourself to using any particular one. If you use several ways, PROC NETFLOW checks that the data are consistent each time the data are encountered. After all input data sets have been read, data are merged so that the problem is described completely. The order of the observations is not important in any of the input data sets.

ARCDATA= Data Set

See the section “Getting Started: NETFLOW Procedure” on page 314 and the section “Introductory Example” on page 315 for a description of this input data set.

**Note:** Information for an arc or nonarc variable can be specified in more than one observation. For example, consider an arc directed from node A toward node B that has a cost of 50, capacity of 100, and lower flow bound of 10 flow units. Some possible observations in the ARCDATA= data set may be

<table>
<thead>
<tr>
<th>TAIL</th>
<th>HEAD</th>
<th>COST</th>
<th>CAPAC</th>
<th>LO</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>B</td>
<td>50</td>
<td>.</td>
<td>.</td>
</tr>
<tr>
<td>A</td>
<td>B</td>
<td>.</td>
<td>100</td>
<td>.</td>
</tr>
<tr>
<td>A</td>
<td>B</td>
<td>.</td>
<td>.</td>
<td>10</td>
</tr>
<tr>
<td>A</td>
<td>B</td>
<td>50</td>
<td>100</td>
<td>.</td>
</tr>
<tr>
<td>A</td>
<td>B</td>
<td>.</td>
<td>100</td>
<td>10</td>
</tr>
<tr>
<td>A</td>
<td>B</td>
<td>50</td>
<td>.</td>
<td>10</td>
</tr>
<tr>
<td>A</td>
<td>B</td>
<td>50</td>
<td>100</td>
<td>10</td>
</tr>
</tbody>
</table>

Similarly, for a nonarc variable with upperbd=100, lowerbd=10, and objective function coefficient=50, the _TAIL_ and _HEAD_ values are missing.

CONDATA= Data Set

Regardless of whether the data in the CONDATA= data set is in the sparse or dense format, you will receive a warning if PROC NETFLOW finds a constraint row that has no coefficients. You will also be warned if any nonarc variable has no constraint coefficients.

Dense Input Format

If the dense format is used, most SAS variables in the CONDATA= data set belong to the VAR list and have names of arc and nonarc variables. These names can be values of the NAME list SAS variables in the ARCDATA= data set, or names of nonarc variables, or names in the form tail_head, or any combination of these three forms. Names in the form tail_head are default arc names, and if you use them, you must specify node names in the ARCDATA= data set (values of the TAILNODE and HEADNODE list SAS variables) using no lowercase letters.
There can be three other variables in the CONDATA= data set, belonging, respectively, to the ROW, TYPE, and RHS lists. The section “Introductory Example” on page 315 uses the dense data format.

Consider the SAS code that creates a dense format CONDATA= data set that has data for three constraints. This data set was used in the section “Introductory Example” on page 315.

```sas
data cond1;
  input m_e_ref1 m_e_ref2 thruput1 r1_gas thruput2 r2_gas
    _type_ $ _rhs_;
  datalines;
  -2 . 1 . . . >= -15
  . -2 . 1 . GE -15
  . . -3 4 . . EQ 0
  . . . -3 4 = 0
;)
```

You can use nonconstraint type values to furnish data on costs, capacities, lower flow bounds (and, if there are nonarc variables, objective function coefficients and upper and lower bounds). You need not have such (or as much) data in the ARCDATA= data set. The first three observations in the following data set are examples of observations that provide cost, capacity and lower bound data.

```sas
data cond1b;
  input m_e_ref1 m_e_ref2 thruput1 r1_gas thruput2 r2_gas
    _type_ $ _rhs_;
  datalines;
  63 81 200 . 220 . cost .
  95 80 175 140 100 100 capac .
  20 10 50 . 35 . lo .
  -2 . 1 . . . >= -15
  . -2 . 1 . GE -15
  . . -3 4 . . EQ 0
  . . . -3 4 = 0
;)
```

If a ROW list variable is used, the data for a constraint can be spread over more than one observation. To illustrate, the data for the first constraint, (which is called con1), and the cost and capacity data (in special rows called costrow and caprow, respectively) are spread over more than one observation in the following data set.

```sas
data cond1c;
  input _row_ $
    m_e_ref1 m_e_ref2 thruput1 r1_gas thruput2 r2_gas
    _type_ $ _rhs_;
  datalines;
  costrow 63 . . . . . . . .
  costrow . 81 200 . . . cost .
  . . . . . . . . . . . . . . .
  caprow . . . . . . . . . . .
  caprow 95 . 175 . 100 100 capac .
  caprow . 80 175 140 . . . .
  lorow 20 10 50 . 35 . lo .
  con1 -2 . 1 . . . . . .
  con1 . . . . . . . . . . . >= -15
  con2 . -2 . . 1 . GE -15
;)
```
Chapter 6: The NETFLOW Procedure

Using both ROW and TYPE lists, you can use special row names. Examples of these are “costrow” and “caprow” in the last data set. It should be restated that in any of the input data sets of PROC NETFLOW, the order of the observations does not matter. However, the CONDATA= data set can be read more quickly if PROC NETFLOW knows what type of constraint or special row a ROW list variable value is. For example, when the first observation is read, PROC NETFLOW does not know whether costrow is a constraint or special row and how to interpret the value 63 for the arc with the name m_e_ref1. When PROC NETFLOW reads the second observation, it learns that costrow has type cost and that the values 81 and 200 are costs. When the entire CONDATA= data set has been read, PROC NETFLOW knows the type of all special rows and constraints. Data that PROC NETFLOW had to set aside (such as the first observation 63 value and the costrow ROW list variable value, which at the time had unknown type, but is then known to be a cost special row) is reprocessed. During this second pass, if a ROW list variable value has unassigned constraint or special row type, it is treated as a constraint with DEFCONTYPE= (or DEFCONTYPE= default) type. Associated VAR list variable values as coefficients of that constraint.

Sparse Input Format

The side constraints usually become sparse as the problem size increases. When the sparse data format of the CONDATA= data set is used, only nonzero constraint coefficients must be specified. Remember to specify the SPARSECONDATA option in the PROC NETFLOW statement. With the sparse method of specifying constraint information, the names of arc and nonarc variables do not have to be valid SAS variable names.

A sparse format CONDATA= data set for the oil industry example in the section “Introductory Example” on page 315 is displayed in the following code.

title 'Setting Up Condata = Cond2 for PROC NETFLOW';
data cond2;
  input _column_ $ _row1 $ _coef1 _row2 $ _coef2 ;
datalines;
  m_e_ref1 con1 -2 . .
  m_e_ref2 con2 -2 . .
  thrput1 con1 1 con3 -3
  r1_gas . . con3 4
  thrput2 con2 1 con4 -3
  r2_gas . . con4 4
  _type_ con1 1 con2 1
  _rhs_ con3 0 con4 0
  _coef1_ con1 -15 con2 -15
;
Recall that the COLUMN list variable values “_type_” and “_rhs_” are the default values of the TYPEOBS= and RHSOBS= options. Also, the default rhs value of constraints (con3 and con4) is zero. The third to last observation has the value “_type_” for the COLUMN list variable. The _ROW1 variable value is con1, and the _COEF1_ variable has the value 1. This indicates that the constraint con1 is greater than or equal to type (because the value 1 is greater than zero). Similarly, the data in the second to last observation’s _ROW2 and _COEF2 variables indicate that con2 is an equality constraint (0 equals zero).
An alternative, using a TYPE list variable is as follows:

```plaintext
title 'Setting Up Condata = Cond3 for PROC NETFLOW';
data cond3;
    input _column_ $ _row1 $ _coef1 _row2 $ _coef2 _type_ $ ;
datalines;
    m_e_ref1 con1 -2 . . >=
    m_e_ref2 con2 -2 . . .
thruput1 con1 1 con3 -3 .
r1_gas . . con3 4 .
thruput2 con2 1 con4 -3 .
r2_gas . . con4 4 .
    . con3 . con4 . eq
    . con1 -15 con2 -15 ge
;
```

If the COLUMN list variable is missing in a particular observation (the last two observations in the data set cond3, for instance), the constraints named in the ROW list variables all have the constraint type indicated by the value in the TYPE list variable. It is for this type of observation that you are allowed more ROW list variables than COEF list variables. If corresponding COEF list variables are not missing (for example, the last observation in the data set cond3), these values are the rhs values of those constraints. Therefore, you can specify both constraint type and rhs in the same observation.

As in the previous CONDATA= data set, if the COLUMN list variable is an arc or nonarc variable, the COEF list variable values are coefficient values for that arc or nonarc variable in the constraints indicated in the corresponding ROW list variables. If in this same observation, the TYPE list variable contains a constraint type, all constraints named in the ROW list variables in that observation have this constraint type (for example, the first observation in the data set cond3). Therefore, you can specify both constraint type and coefficient information in the same observation.

Also note that DEFCONTYPE=EQ could have been specified, saving you from having to include in the data that CON3 and CON4 are of this type.

In the oil industry example, arc costs, capacities, and lower flow bounds are presented in the ARCDATA= data set. Alternatively, you could have used the following input data sets.

```plaintext
title3 'Setting Up Arcdata = Arcd2 for PROC NETFLOW';
data arcd2;
    input _from_ $11. _to_ $15. ;
datalines;
middle east refinery 1
middle east refinery 2
u.s.a. refinery 1
u.s.a. refinery 2
refinery 1 r1
refinery 2 r2
r1 refl gas
r1 refl1 diesel
r2 refl2 gas
r2 refl2 diesel
refl gas servstn1 gas
refl gas servstn2 gas
refl diesel servstn1 diesel
refl diesel servstn2 diesel
```
data cond4;
  input _column_&$27. _row1 $ _coef1 _row2 $ _coef2 _type_ $;
  datalines;
  . con1 -15 con2 -15 ge
  . costrow . . . . cost
  . . . . . caprow . . capac
  middle east_refinery 1 con1 -2 . . .
  middle east_refinery 2 con2 -2 . . .
  refinery 1_r1 con1 1 con3 -3 .
  r1_ref1 gas . . con3 4 =
  refinery 2_r2 con2 1 con4 -3 .
  r2_ref2 gas . . con4 4 eq
  middle east_refinery 1 costrow 63 caprow 95 .
  middle east_refinery 2 costrow 81 caprow 80 .
  u.s.a._refinery 1 costrow 55 . . .
  u.s.a._refinery 2 costrow 49 . . .
  refinery 1_r1 costrow 200 caprow 175 .
  refinery 2_r2 costrow 220 caprow 100 .
  r1_ref1 gas . . caprow 140 .
  r1_ref1 diesel . . caprow 75 .
  r2_ref2 gas . . caprow 100 .
  r2_ref2 diesel . . caprow 75 .
  ref1 gas_servstn1 gas costrow 15 caprow 70 .
  ref1 gas_servstn2 gas costrow 22 caprow 60 .
  ref1 diesel_servstn1 diesel costrow 18 . . .
  ref1 diesel_servstn2 diesel costrow 17 . . .
  ref2 gas_servstn1 gas costrow 17 caprow 35 .
  ref2 gas_servstn2 gas costrow 31 . . .
  ref2 diesel_servstn1 diesel costrow 36 . . .
  ref2 diesel_servstn2 diesel costrow 23 . . .
  middle east_refinery 1 . 20 . . lo
  middle east_refinery 2 . 10 . . lo
  refinery 1_r1 . 50 . . lo
  refinery 2_r2 . 35 . . lo
  ref2 gas_servstn1 gas . 5 . . lo
  ;

The first observation in the cond4 data set defines con1 and con2 as greater than or equal to (≥) constraints that both (by coincidence) have rhs values of -15. The second observation defines the special row costrow as a cost row. When costrow is a ROW list variable value, the associated COEF list variable value is interpreted as a cost or objective function coefficient. PROC NETFLOW has to do less work if constraint names and special rows are defined in observations near the top of a data set, but this is not a strict requirement. The fourth to ninth observations contain constraint coefficient data. Observations 7 and 9 have TYPE list variable values that indicate that constraints con3 and con4 are equality constraints. The last five observations contain lower flow bound data. Observations that have an arc or nonarc variable name in the COLUMN list variable, a nonconstraint type TYPE list variable value, and a value in (one of) the COEF list variables are valid.
The following data set is equivalent to the `cond4` data set.

```sas
title 'Setting Up Condata = Cond5 for PROC NETFLOW';
data cond5;
  input _column_&$27. _row1 $ _coef1 _row2 $ _coef2 _type_ $ ;
datalines;
middle east_refinery 1   con1 -2 costrow 63 .
middle east_refinery 2   con2 -2 lorow 10 .
refinery 1_r1           .   .     con3 -3 =
r1_ref1 gas             caprow 140 con3  4 .
refinery 2_r2           con2  1 con4 -3 .
r2_ref2 gas             .   .     con4  4 eq
                       .   .     CON1 -15 CON2 -15 GE
ref2 diesel_servstn1 diesel  . 36 costrow . cost
                       .   .     caprow . capac
                       .   .     lorow .  lo
middle east_refinery 1   caprow 95 lorow 20 .
middle east_refinery 2   caprow 80 costrow 81 .
usa._refinery 1          .   .     55 cost
usa._refinery 2          costrow 49 . . .
refinery 1_r1           con1  1 caprow 175 .
refinery 1_r1           lorow 50 costrow 200 .
refinery 2_r2           costrow 220 caprow 100 .
refinery 2_r2           . 35 .  lo
r1_ref1 diesel          caprow2 75 .  capac
r2_ref2 gas             .   .     caprow 100 .
rr2_ref2 diesel         caprow2 75 . . .
ref1 gas_servstn1 gas   costrow 15 caprow 70 .
ref1 gas_servstn2 gas   caprow2 60 costrow 22 .
ref1 diesel_servstn1 diesel  . costrow 18 .
ref1 diesel_servstn2 diesel costrow 17 . . .
ref2 gas_servstn1 gas   costrow 17 lorow 5 .
ref2 gas_servstn1 gas   .   .     caprow2 35 .
ref2 gas_servstn2 gas   . 31 .  cost
ref2 diesel_servstn2 diesel  . costrow 23 .
;
```

If you have data for a linear programming program that has an embedded network, the steps required to change that data into a form that is acceptable by PROC NETFLOW are

1. Identify the nodal flow conservation constraints. The coefficient matrix of these constraints (a submatrix of the LP’s constraint coefficient matrix) has only two nonzero elements in each column, -1 and 1.

2. Assign a node to each nodal flow conservation constraint.

3. The rhs values of conservation constraints are the corresponding node’s supplies and demands. Use this information to create a `NODEDATA=` data set.

4. Assign an arc to each column of the flow conservation constraint coefficient matrix. The arc is directed from the node associated with the row that has the 1 element in it and directed toward to the node associated with the row that has the -1 element in it. Set up an `ARCDATA=` data set that has two SAS variables. This data set could resemble `ARCDATA=arcd2`. These will eventually be the `TAILNODE` and `HEADNODE` list variables when PROC NETFLOW is used. Each observation consists of the tail and head node of each arc.
5. Remove from the data of the linear program all data concerning the nodal flow conservation constraints.

6. Put the remaining data into a CONDATA= data set. This data set will probably resemble CONDATA=cond4 or CONDATA=cond5.

The Sparse Format Summary

The following list illustrates possible CONDATA= data set observation sparse formats. a1, b1, b2, b3 and c1 have as a _COLUMN_ variable value either the name of an arc (possibly in the form tail_head) or the name of a nonarc variable.

- If there is no TYPE list variable in the CONDATA= data set, the problem must be constrained and there is no nonconstraint data in the CONDATA= data set.

<table>
<thead>
<tr>
<th><em>COLUMN</em></th>
<th><em>ROWx</em></th>
<th><em>COEFx</em></th>
<th><em>ROWy</em></th>
</tr>
</thead>
</table>
| a1       | variable | constraint | lhs coef | +---------+
| a2       | _TYPE_ or | constraint | -1 0 1 | |
| TYPEOBS= |         |          |        | |
| a3       | _RHS_ or | constraint | rhs value | constraint |
| RHSOBS= or |         |          |        | or |
| missing   |         |          |        | |
| a4       | _TYPE_ or | constraint | missing | |
| TYPEOBS= |         |          |        | |
| a5       | _RHS_ or | constraint | missing | |
| RHSOBS= or |         |          |        | |
| missing   |         |          |        | +---------+

Observations of the form a4 and a5 serve no useful purpose but are still allowed to make problem generation easier.

- If there are no ROW list variables in the data set, the problem has no constraints and the information is nonconstraint data. There must be a TYPE list variable and only one COEF list variable in this case. The COLUMN list variable has as values the names of arcs or nonarc variables and must not have missing values or special row names as values.

<table>
<thead>
<tr>
<th><em>COLUMN</em></th>
<th><em>TYPE</em></th>
<th><em>COEFx</em></th>
</tr>
</thead>
<tbody>
<tr>
<td>b1</td>
<td>variable</td>
<td>UPPERBD</td>
</tr>
<tr>
<td>b2</td>
<td>variable</td>
<td>LOWERBD</td>
</tr>
<tr>
<td>b3</td>
<td>variable</td>
<td>COST</td>
</tr>
</tbody>
</table>
• Using a TYPE list variable for constraint data implies the following:

<table>
<thead>
<tr>
<th><em>COLUMN</em></th>
<th><em>TYPE</em></th>
<th><em>ROWx</em></th>
<th><em>COEFx</em></th>
<th><em>ROWy</em></th>
</tr>
</thead>
<tbody>
<tr>
<td>c1 variable missing</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>c2 TYPE</td>
<td>missing</td>
<td>c</td>
<td>-1 0 1</td>
<td></td>
</tr>
<tr>
<td>TYPEOBS=</td>
<td></td>
<td>o</td>
<td></td>
<td></td>
</tr>
<tr>
<td>c3 RHS</td>
<td>missing</td>
<td>n</td>
<td>rhs value</td>
<td>constraint</td>
</tr>
<tr>
<td>or RHSOBS=</td>
<td></td>
<td>t</td>
<td></td>
<td>missing</td>
</tr>
<tr>
<td>c4 variable</td>
<td>con type</td>
<td>r</td>
<td>lhs coef</td>
<td></td>
</tr>
<tr>
<td>c5 RHS</td>
<td>con type</td>
<td>a</td>
<td>rhs value</td>
<td></td>
</tr>
<tr>
<td>missing</td>
<td>i</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>or RHSOBS=</td>
<td>n</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>c6 missing</td>
<td>TYPE</td>
<td>t</td>
<td>-1 0 1</td>
<td></td>
</tr>
<tr>
<td>c7 missing</td>
<td>RHS</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

If the observation is of the form c4 or c5, and the _COEFx_ values are missing, the constraint is assigned the type data specified in the _TYPE_ variable.

• Using a TYPE list variable for arc and nonarc variable data implies the following:

<table>
<thead>
<tr>
<th><em>COLUMN</em></th>
<th><em>TYPE</em></th>
<th><em>ROWx</em></th>
<th><em>COEFx</em></th>
<th><em>ROWy</em></th>
</tr>
</thead>
<tbody>
<tr>
<td>d1 variable</td>
<td>UPPERBD</td>
<td></td>
<td>missing</td>
<td>capacity</td>
</tr>
<tr>
<td>d2 variable</td>
<td>LOWERBD</td>
<td></td>
<td>or</td>
<td>lowerflow</td>
</tr>
<tr>
<td>d3 variable</td>
<td>COST</td>
<td></td>
<td>special</td>
<td>cost</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>row</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>name</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>d4 missing</td>
<td></td>
<td>special</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>row</td>
<td></td>
<td></td>
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<tr>
<td>d5 variable</td>
<td>missing</td>
<td></td>
<td></td>
<td>value that</td>
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<td>is interpreted</td>
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</tbody>
</table>

• Using a TYPE list variable for constraint data implies the following:
Observations with form d1 to d5 can have ROW list variable values. Observation d4 must have ROW list variable values. The ROW value is put into the ROW name tree so that when dealing with observation d4 or d5, the COEF list variable value is interpreted according to the type of ROW list variable value. For example, the following three observations define the _ROWx_ variable values up_row, lo_row and co_row as being an upper value bound row, lower value bound row, and cost row, respectively.

<table>
<thead>
<tr>
<th><em>COLUMN</em></th>
<th><em>TYPE</em></th>
<th><em>ROWx</em></th>
<th><em>COEFx</em></th>
</tr>
</thead>
<tbody>
<tr>
<td>.</td>
<td>UPPERBD</td>
<td>up_row</td>
<td>.</td>
</tr>
<tr>
<td>variable_a</td>
<td>LOWERBD</td>
<td>lo_row</td>
<td>lower flow</td>
</tr>
<tr>
<td>variable_b</td>
<td>COST</td>
<td>co_row</td>
<td>cost</td>
</tr>
</tbody>
</table>

PROC NETFLOW is now able to correctly interpret the following observation:

| _COLUMN_ _TYPE_ _ROW1_ _COEF1_ _ROW2_ _COEF2_ _ROW3_ _COEF3_ |
|----------|--------|--------|--------|
| var_c . up_row upval lo_row loval co_row cost |

If the TYPE list variable value is a constraint type and the value of the COLUMN list variable equals the value of the TYPEOBS= option or the default value _TYPE_, the TYPE list variable value is ignored.

**NODEDATA= Data Set**

See the section “Getting Started: NETFLOW Procedure” on page 314 and the section “Introductory Example” on page 315 for a description of this input data set.

**Output Data Sets**

The procedure determines the flow that should pass through each arc as well as the value assigned to each nonarc variable. The goal is that the minimum flow bounds, capacities, lower and upper value bounds, and side constraints are not violated. This goal is reached when total cost incurred by such a flow pattern and value assignment is feasible and optimal. The solution found must also conserve flow at each node.

The ARCOUXT= data set contains a solution obtained when performing optimization that does not consider any constraints. The NODEOUT= data set contains nodal dual variable information for this type of solution. You can choose to have PROC NETFLOW create the ARCOUXT= data set and the NODEOUT= data set and save the optimum of the network or the nodal dual variable values before any optimization that considers the side constraints is performed.

If there are side constraints, the CONOUT= data set can be produced and contains a solution obtained after performing optimization that considers constraints. The DUALOUT= data set contains dual variable information for nodes and side constraints from the solution obtained after optimization that considers the constraints. The CONOUT= data set and DUALOUT= data set can be used to save the constrained optimal solution.
**ARCOU T= and CONOUT= Data Sets**

The ARCOU T= and CONOUT= data sets contain the same variables. Furthermore, the variables in the output data sets depend on whether or not the problem has a network component.

If the problem has a network component, the variables and their possible values in an observation are as follows:

- **_FROM_** a tail node of an arc. This is a missing value if an observation has information about a nonarc variable.
- **_TO_** a head node of an arc. This is a missing value if an observation has information about a nonarc variable.
- **_COST_** the cost of an arc or the objective function coefficient of a nonarc variable
- **_CAPAC_** the capacity of an arc or upper value bound of a nonarc variable
- **_LO_** the lower flow bound of an arc or lower value bound of a nonarc variable
- **_NAME_** a name of an arc or nonarc variable
- **_SUPPLY_** the supply of the tail node of the arc in the observation. This is a missing value if an observation has information about a nonarc variable.
- **_DEMAND_** the demand of the head node of the arc in the observation. This is a missing value if an observation has information about a nonarc variable.
- **_FLOW_** the flow through the arc or value of the nonarc variable
- **_FCOST_** flow cost, the product of _COST_ and _FLOW_
- **_RCOST_** the reduced cost of the arc or nonarc variable
- **_ANUMB_** the number of the arc (positive) or nonarc variable (nonpositive); used for warm starting PROC NETFLOW
- **_TNUMB_** the number of the tail node in the network basis spanning tree; used for warm starting PROC NETFLOW
- **_STATUS_** the status of the arc or nonarc variable

If the problem does not have a network component, the variables and their possible values in an observation are as follows:

- **_OBJFN_** the objective function coefficient of a variable
- **_UPPERBD_** the upper value bound of a variable
- **_LOWERBD_** the lower value bound of a variable
- **_NAME_** the name of a variable
- **_VALUE_** the value of the variable
- **_FCOST_** objective function value for that variable; the product of _OBJFN_ and _VALUE_
The variables present in the ARCDATA= data set are present in an ARCOUT= data set or a CONOUT= data set. For example, if there is a variable called `tail` in the ARCDATA= data set and you specified the SAS variable list

```sas
from tail;
```

then `tail` is a variable in the ARCOUT= and CONOUT= data sets instead of `_FROM_`. Any ID list variables also appear in the ARCOUT= and CONOUT= data sets.

**NODEOUT= and DUALOUT= Data Sets**

There are two types of observations in the NODEOUT= and DUALOUT= data sets. One type of observation contains information about a node. These are called type N observations. There is one such observation of this type for each node. The `_NODE_` variable has a name of a node, and the `_CON_` variable values in these observations are missing values.

The other type of observation contains information about constraints. These are called the type C observations. There is one such observation for each constraint. The `_CON_` variable has a name of a constraint, and the `_NODE_` variable values in these observations are missing values.

Many of the variables in the NODEOUT= and DUALOUT= data sets contain information used to warm start PROC NETFLOW. The variables `_NODE_`, `_SD_`, `_DUAL_`, `_VALUE_`, `_RHS_`, `_TYPE_`, and `_CON_` contain information that might be of interest to you.

The NODEOUT= and DUALOUT= data sets look similar, as the same variables are in both. These variables and their values in an observation of each type are

- **`_NODE_`**
  - Type N: the node name
  - Type C: a missing value

- **`_SD_`**
  - Type N: the supply (positive) or demand (negative) of the node
  - Type C: a missing value

- **`_DUAL_`**
  - Type N: the dual variable value of the node in `_NODE_`
  - Type C: the dual variable value of the constraint named in `_CON_`

- **`_NNUMB_`**
  - Type N: the number of the node named in `_NODE_`
  - Type C: the number of the constraint named in `_CON_`

- **`_PRED_`**
  - Type N: the predecessor in the network basis spanning tree of the node named in `_NODE_`
  - Type C: the number of the node toward which the arc with number in `_ARCID_` is directed, or the constraint number associated with the slack, surplus, or artificial variable basic in this row

- **`_TRAV_`**
  - Type N: the traversal thread label of the node named in `_NODE_`
  - Type C: a missing value

- **`_SCESS_`**
  - Type N: the number of successors (including itself) in the network basis spanning tree of the node named in `_NODE_`
  - Type C: a missing value

- **`_ARCID_`**
  - Type N: if `_ARCID_` is nonnegative, `_ARCID_` is the number of the network basis spanning tree arc directed from the node with number `_PRED_` to the node named in `_NODE_`. If `_ARCID_` is negative, minus `_ARCID_` is the number of the network basis spanning tree arc directed from the node named in `_NODE_` to the node with number `_PRED_`. 
Converting Any PROC NETFLOW Format to an MPS-Format SAS Data Set

The MPSOUT= option enables you to convert an input data set for the NETFLOW procedure into an MPS-format SAS data set. The converted data set is readable by the OPTLP procedure.

The conversion can handle linear programs and network flow formulations. If you specify a network flow formulation, it will be converted into an equivalent linear program. When multiple objective row names are present, rows with the name encountered first are combined into the objective row. The remaining rows are marked as free rows.
Case Sensitivity

Whenever the NETFLOW procedure has to compare character strings, whether they are node names, arc names, nonarc names, or constraint names, if the two strings have different lengths, or on a character by character basis the character is different or has different cases, PROC NETFLOW judges the character strings to be different.

Not only is this rule enforced when one or both character strings are obtained as values of SAS variables in PROC NETFLOW’s input data sets, it also should be obeyed if one or both character strings were originally SAS variable names, or were obtained as the values of options or statements parsed to PROC NETFLOW. For example, if the network has only one node that has supply capability, or if you are solving a MAXFLOW or SHORTPATH problem, you can indicate that node using the SOURCE= option.

If you specify

```
proc netflow source=NotableNode
```

then PROC NETFLOW looks for a value of the TAILNODE list variable that is NotableNode.

Version 6 of the SAS System converts text that makes up statements into uppercase. The name of the node searched for would be NOTABLENODE, even if this was your SAS code:

```
proc netflow source=NotableNode
```

If you want PROC NETFLOW to behave as it did in Version 6, specify

```
options validvarname=v6;
```

If the SPARSESECONDATA option is not specified, and you are running SAS software Version 6 or have specified options validvarname=v6; using a later version, all NAME list variable values in the ARCDATA= data set are uppercased. This is because the SAS System has uppercased all SAS variable names, particularly those in the VAR list of the CONDATA= data set.

Entities that contain blanks must be enclosed in single or double quotes.

See the section “Cautions” on page 349 for additional discussion of case sensitivity.

Loop Arcs

When using the primal simplex network algorithm, loop arcs (arcs directed toward nodes from which they originate) are prohibited. Rather, introduce a dummy intermediate node in loop arcs. For example, replace arc (A,A) with (A,B) and (B,A). B is the name of a new node, and it must be distinct for each loop arc.
Multiple Arcs

Multiple arcs with the same tail and head nodes are prohibited. PROC NETFLOW checks to ensure there are no such arcs before proceeding with the optimization. Introduce a new dummy intermediate node in multiple arcs. This node must be distinct for each multiple arc. For example, if some network has three arcs directed from node A toward node B, then replace one of these three with arcs (A,C) and (C,B) and replace another one with (A,D) and (D,B). C and D are new nodes added to the network.

Pricing Strategies

The pricing strategy is the part of the simplex iteration that selects the nonbasic arc, constraint slack, surplus, or nonarc variable that should have a flow or value change, and perhaps enter the basis so that the total cost incurred is improved.

The pricing mechanism takes a large amount of computational effort, so it is important to use the appropriate pricing strategy for the problem under study. As in other large scale mathematical programming software, network codes can spend more than half of their execution time performing simplex iterations in the pricing step. Some compromise must be made between using a fast strategy and improving the quality of the flow or value change candidate selection, although more simplex iterations may need to be executed.

The configuration of the problem to be optimized has a great effect on the choice of strategy. If a problem is to be run repeatedly, experimentation on that problem to determine which scheme is best may prove worthwhile. The best pricing strategy to use when there is a large amount of work to do (for example, when a cold start is used) may not be appropriate when there is little work required to reach the optimum (such as when a warm start is used). If paging is necessary, then a pricing strategy that reduces the number of simplex iterations performed might have the advantage. The proportion of time spent doing the pricing step during stage 1 optimization is usually less than the same proportion when doing stage 2 optimization. Therefore, it is more important to choose a stage 2 pricing strategy that causes fewer, but not necessarily the fewest, iterations to be executed.

There are many similarities between the pricing strategies for optimizing an unconstrained problem (or when constraints are temporarily ignored) and the pricing mechanisms for optimizing considering constraints. To prevent repetition, options have a suffix or embedded $x$. Replace $x$ with 1 for optimization without constraint consideration and 2 for optimization with constraint consideration.

There are three main types of pricing strategies:

- **PRICETYPE$_x$=NOQ**
- **PRICETYPE$_x$=BLAND**
- **PRICETYPE$_x$=Q**

The pricing strategy that usually performs better than the others is **PRICETYPE$_x$=Q**. For this reason, **PRICETYPE$_x$=Q** is the default.
Chapter 6: The NETFLOW Procedure

PRICTYPE\_x=NOQ

PRICTYPE\_x=NOQ is the least complex pricing strategy, but it is nevertheless quite efficient. In contrast to the specification of PRICTYPE\_x=Q, a candidate queue is not set up.

The P\_xSCAN= option controls the amount of additional candidate selection work done to find a better candidate after an eligible candidate has been found.

If P\_xSCAN=FIRST is specified, the search for candidates finishes when the first eligible candidate is found, with this exception: if a node has more than one eligible arc directed toward it, the best such arc is chosen.

If P\_xSCAN=BEST is specified, everything that is nonbasic is examined, and the best candidate of all is chosen.

If P\_xSCAN=PARTIAL is specified, once an eligible candidate is found, the scan continues for another P\_xNPARTIAL= cycles in the hope that during the additional scan, a better candidate is found. Examining all nonbasic arcs directed toward a single node is counted as only one cycle.

If P\_xSCAN=FIRST or P\_xSCAN=PARTIAL is specified, the scan for entering candidates starts where the last iteration’s search left off. For example, if the last iteration’s scan terminated after examining arcs that are directed toward the node with internal number \(i\), the next iteration’s scan starts by examining arcs directed toward the node with internal number \(i + 1\). If \(i\) is the largest node number, next iterations scan begins by scanning arcs directed toward node 1 (during stage 1) or scanning constraint slack or surplus variables, if any, or nonarc variables, if any, (during stage 2). During stage 2, if the scan terminated after examining the slack or surplus of constraint \(i\), next iterations scan starts by examining the slack or surplus of the constraint with the internal number greater than \(i\) that has such a logical variable. If the scan terminated after examining the nonarc variable \(i\), the next iterations scan starts by examining the nonarc variable with internal number \(i + 1\), (or arcs directed to the node with the smallest internal number if the nonarc variable with the greatest number has been examined). This is termed a \textit{wraparound search}.

PRICTYPE\_x=Q

If PRICTYPE\_x=Q, a queue is set up. Candidates currently on the queue are tested at each iteration and either enter the basis or are removed from the queue. The size of the queue can be specified by using the QSIZE\_x= option. The default value for QSIZE1= is

\[
\text{QSIZE1=number of arcs}/200 \\
\text{if (QSIZE1<24) QSIZE1=24} \\
\text{else if (QSIZE1>100) QSIZE1=100}
\]

The default value for QSIZE2= is

\[
\text{QSIZE2=(number of arcs+number of nonarc variables)/200} \\
\text{if (QSIZE2<24) QSIZE2=24} \\
\text{else if (QSIZE2>100) QSIZE2=100}
\]

controls the amount of additional candidate selection work done to find a better candidate after an eligible candidate has been found \textit{in the queue}.

If you specify P\_xSCAN=BEST, the best eligible candidate found is removed from the queue. It can sustain a flow or value change and possibly enter the basis.
If you specify P\textsubscript{x}SCAN=FIRST, the first eligible candidate found is removed from the queue, and possibly sustains a flow or value change and enters the basis.

If you specify P\textsubscript{x}SCAN=PARTIAL, P\textsubscript{x}NPARTIAL= can then be also specified. After an eligible candidate has been found, P\textsubscript{x}NPARTIAL= more queue members are examined and the best of the eligible candidates found is chosen.

When P\textsubscript{x}SCAN=FIRST or P\textsubscript{x}SCAN=PARTIAL, the scan of the queue is wraparound. When the member last added to the queue has been examined, the scan continues from the member that was first added to the queue.

When the queue is empty, or after QSIZE\textsubscript{x}= times REFRESHQ\textsubscript{x}= iterations have been executed since the queue was last refreshed, new candidates are found and put onto the queue. Valid values for the REFRESHQ\textsubscript{x}= options are greater than 0.0 and less than or equal to 1.0. The default for REFRESHQ\textsubscript{x}= is 0.75. If the scan cannot find enough candidates to fill the queue, the procedure reduces the value of QSIZE\textsubscript{x}=. If \textit{gfound} is the number of candidates found, the new QSIZE\textsubscript{x}= value is \textit{gfound} + ((old QSIZE\textsubscript{x} - \textit{gfound}) \times REDUCEQSIZE\textsubscript{x}=). Valid values of the REDUCEQSIZE\textsubscript{x}= option are between 0.0 and 1.0, inclusive. The default for REDUCEQSIZE\textsubscript{x}= is 1.0.

The Q\textsubscript{x}FILLSCAN= option controls the amount of additional candidate selection work performed to find better candidates to put into the queue after the queue has been filled.

If you specify Q\textsubscript{x}FILLSCAN=FIRST, the nonbasic arcs, and during stage 2 optimization, nonbasic constraint slack and surplus variables, and nonbasic nonarc variables are scanned; the scan stops when the queue is filled. If a node has more than one eligible arc directed toward it, the best such arc is put onto the queue. Q\textsubscript{x}FILLSCAN=FIRST is the default.

If Q\textsubscript{x}FILLSCAN=BEST is specified, everything that is nonbasic is scanned and the best eligible candidates are used to fill the queue.

If Q\textsubscript{x}FILLSCAN=PARTIAL is specified, after the queue is full, the scan continues for another Q\textsubscript{x}FILLNPARTIAL= cycles in the hope that during the additional scan, better candidates are found to replace other candidates previously put onto the queue. Q\textsubscript{x}FILLNPARTIAL=10 is the default. If Q\textsubscript{x}FILLSCAN=FIRST or Q\textsubscript{x}FILLSCAN=PARTIAL, the scan starts where the previous iteration ended; that is, it is wraparound.

In the following section, dual variables and reduced costs are explained. These help PROC NETFLOW determine whether an arc, constraint slack, surplus, or nonarc variable should have a flow or value change. P2SCAN=ANY and the DUALFREQ= option can be specified to control stage 2 pricing, and how often dual variables and reduced costs are calculated.

What usually happens when PRICETYPE2=Q is specified is that before the first iteration, the queue is filled with nonbasic variables that are eligible to enter the basis. At the start of each iteration, a candidate on the queue is examined and its reduced cost is calculated to ensure that it is still eligible to enter the basis. If it is ineligible to enter the basis, it is removed from the queue and another candidate on the queue is examined, until a candidate on the queue is found that can enter the basis. When this happens, a minor iteration occurs. If there are no candidates left on the queue, or several iterations have been performed since the queue was refreshed, new nonbasic variables that are eligible to enter the basis are found and are placed on the queue. When this occurs, the iteration is termed a major iteration. Dual variables are calculated or maintained every iteration.

During most optimizations, if a variable is put onto the queue during a major iteration, it usually remains eligible to enter the basis in later minor iterations. Specifying P2SCAN=ANY indicates that PROC NETFLOW should choose any candidate on the queue and use that as the entering variable. Reduced costs are not
calculated. It is simply hoped that the chosen candidate is eligible. Sometimes, a candidate on the queue is chosen that has become ineligible and the optimization takes “a step backward” rather than “a step forward” toward the optimum. However, the disadvantages of incurring an occasional step backwards and the possible danger of never converging to the optimum are offset by not having to calculate reduced costs and, more importantly, not having to maintain dual variable values. The calculation of dual variables is one of two large linear equation systems that must be solved each iteration in the simplex iteration.

If P2SCAN=ANY is specified, dual variables are calculated after DUALFREQ= iterations have been performed since they were last calculated. These are used to calculate the reduced costs of all the candidates currently on the queue. Any candidate found to be ineligible to enter the basis is removed from the queue. DUALFREQ=4 is the default.

Once again, the practice of not maintaining correct dual variable values is dangerous because backward steps are allowed, so the optimization is not guaranteed to converge to the optimum. However, if PROC NETFLOW does not run forever, it can find the optimum much more quickly than when the P2SCAN= option is not ANY. Before concluding that any solution is optimal, PROC NETFLOW calculates true dual variable values and reduced costs and uses these to verify that the optimum is really at hand.

Whether P2SCAN=ANY is specified or not, dual variables are always calculated at the start of major iterations.

**PRICETYPE=x=BLAND**

PRICETYPE=x=BLAND is equivalent to specifying in the PROC NETFLOW or RESET statement all three options PRICETYPE=x=NOQ, PxSCAN=FIRST, and LRATIOx, and the scans are not wraparound. Bland (1977) proved that this pivot rule prevents the simplex algorithm from cycling. However, because the pivots concentrate on the lower indexed arcs, constraint slack, surplus, and nonarc variables, optimization with PRICETYPE=x=BLAND can make the optimization execute slowly.

**Dual Variables, Reduced Costs, and Status**

During optimization, dual variables and reduced costs are used to determine whether an arc, constraint slack, surplus, or nonarc variable should have a flow or value change. The ARCOUT= and CONOUT= data sets each have a variable called _RCOST_ that contains reduced cost values. In the CONOUT= data set, this variable also has the reduced costs of nonarc variables. For an arc, the reduced cost is the amount that would be added to the total cost if that arc were made to convey one more unit of flow. For a nonarc variable, the reduced cost is the amount that would be added to the total cost if the value currently assigned to that nonarc variable were increased by one.

During the optimization of a minimization problem, if an arc has a positive reduced cost, PROC NETFLOW takes steps to decrease the flow through it. If an arc has a negative reduced cost, PROC NETFLOW takes steps to increase the flow through it. At optimality, the reduced costs of arcs with flow at their respective lower bounds are nonnegative; otherwise, the optimizer would have tried to increase the flow, thereby decreasing the total cost. The _STATUS_ of each such nonbasic arc is LOWERBD NONBASIC. The reduced costs of arcs with flow at capacity are nonpositive. The _STATUS_ of each such nonbasic arc is UPPERBD NONBASIC. Even though it would decrease total cost, the optimizer cannot increase the flows through such arcs because of the capacity bound. Similar arguments apply for nonarc variables.
The reduced cost is also the amount that would be subtracted from the total cost if that arc was made to convey one less unit of flow. Similarly, a reduced cost is the amount subtracted from the total cost if the value currently assigned to that nonarc variable is decreased by one.

The dual variables and reduced costs can be used to detect whether multiple optimal solutions exist. A zero reduced cost of a nonbasic arc indicates the existence of multiple optimal solutions. A zero reduced cost indicates, by definition, that the flow through such arcs can be changed with zero change to the total cost. (Basic arcs and basic nonarc variables technically have zero reduced costs. A missing value is used for these so that reduced costs of nonbasic arcs and nonbasic nonarc variables that are zero are highlighted.)

The range over which costs can vary before the present solution becomes nonoptimal can be determined through examination of the reduced costs. For any nonbasic arc with assigned flow equal to its lower bound, the amount by which the cost must be decreased before it becomes profitable for this arc to convey additional flow is the value of its reduced cost. The cost reduction necessary for a nonbasic arc currently assigned capacity flow to undergo a worthwhile flow decrease is the absolute value of its reduced cost. In both cases, this minimum cost reduction changes the reduced cost to zero. Any further reduction promotes a possible basis change.

The reduced cost of an arc \((t, h)\) is \(rc_{t,h} = c_{t,h} - \pi_t + \pi_h\) where \(\pi_i\) is the dual value for node \(i\) and \(c_{t,h}\) is the cost of the arc with tail node \(t\) and head node \(h\).

If the problem has side constraints and arc \((t, h)\) has nonzero lhs coefficients, then the following term must be subtracted from \(rc_{t,h}\):

\[
\sum_i \text{condual}_i H_{i,(t,h)}
\]

where \(\text{condual}_i\) is the dual variable of constraint \(i\), and \(H_{i,(t,h)}\) is the coefficient of arc \((t, h)\) in constraint \(i\).

If \(d_n\) is the objective function coefficient of nonarc variable \(n\), the reduced cost is \(rc_n = d_n - \sum_i \text{condual}_i Q_{i,n}\), where \(Q_{i,n}\) is the coefficient of nonarc variable \(n\) in constraint \(i\).

---

**The Working Basis Matrix**

Let \(T\) be the basis matrix of NPSC. The following partitioning is done:

\[
T = \begin{bmatrix}
A & B \\
C & D
\end{bmatrix}
\]

where

- \(n\) is the number of nodes.
- \(k\) is the number of side constraints.
- \(A\) \((n \times n)\) is the network component of the basis. Most of the columns of this matrix are columns of the problem’s node-arc incidence matrix. The arcs associated with columns of \(A\), called key basic variables or key arcs, form a spanning tree. The data structures of the spanning tree of this submatrix of the basis \(T\) enable the computations involving \(T\) and the manner in which \(T\) is updated to be very efficient, especially those dealing with \(A\) (or \(A^{-1}\)).
• C \((k \times n)\) are the key arcs’ side constraint coefficient columns.

• B \((n \times k)\) are the node-arc incidence matrix columns of the nontree arcs. The columns of B having nonzero elements are associated with basic nonspanning tree arcs.

• D \((k \times k)\) are the constraint coefficient columns of nonkey basic variables. Nonkey basic variables not only include nontree basic arcs but also basic slack, surplus, artificial, or nonarc variables.

It is more convenient to factor T by block triangular matrices \(P\) and \(M\), such that \(P = TM\). The matrices \(P\) and \(M\) are used instead of \(T\) because they are less burdensome to work with. You can perform block substitution when solving the simplex iteration linear systems of equations.

\[
P = \begin{bmatrix} A & 0 \\ C & D_w \end{bmatrix}
\]

\[
M = \begin{bmatrix} I & -A^{-1}B \\ 0 & I \end{bmatrix}
\]

where \(D_w = D - CA^{-1}B\) and is called the working basis matrix.

To perform block substitution, you need the tree data structure of the A matrix, and also the C, B, and \(D_w\) matrices. Because the C matrix consists of columns of the constraint coefficient matrix, the maintenance of C from iteration to iteration simply entails changing information specifying which columns of the constraint coefficient matrix compose C.

The \(A^{-1}B\) matrix is usually very sparse. Fortunately, the information in \(A^{-1}B\) can be initialized easily using the tree structures. In most iterations, only one column is replaced by a new one. The values of the elements of the new column may already be known from preceding steps of the simplex iteration.

The working basis matrix is the submatrix that presents the most computational complexity. However, PROC NETFLOW usually can use classical simplex pivot techniques. In many iterations, only one column of \(D_w\) changes. Sometimes it is not necessary to update \(D_w\) or its inverse at all.

If INVD_2D is specified in the PROC NETFLOW statement, only one row and one column may need to be changed in the \(D_w^{-1}\) before the next simplex iteration can begin. The new contents of the changed column are already known. The new elements of the row that changes are influenced by the contents of a row of \(A^{-1}B\) that is very sparse.

If INVD_2D is not specified in the PROC NETFLOW statement, the Bartels-Golub update can be used to update the LU factors of \(D_w\). The choice must be made whether to perform a series of updates (how many depends on the number of nonzeros in a row of \(A^{-1}B\)), or refactorization.
Flow and Value Bounds

The capacity and lower flow bound of an arc can be equal. Negative arc capacities and lower flow bounds are permitted. If both arc capacities and lower flow bounds are negative, the lower flow bound must be at least as negative as the capacity. An arc (A,B) that has a negative flow of \(-f\) units can be interpreted as an arc that conveys \(f\) units of flow from node B to node A.

The upper and lower value bounds of a nonarc variable can be equal. Negative upper and lower bounds are permitted. If both are negative, the lower bound must be at least as negative as the upper bound.

Tightening Bounds and Side Constraints

If any piece of data is furnished to PROC NETFLOW more than once, PROC NETFLOW checks for consistency so that no conflict exists concerning the data values. For example, if the cost of some arc is seen to be one value and as more data are read, the cost of the same arc is seen to be another value, PROC NETFLOW issues an error message on the SAS log and stops. There are two exceptions:

- The bounds of arcs and nonarc variables are made as tight as possible. If several different values are given for the lower flow bound of an arc, the greatest value is used. If several different values are given for the lower bound of a nonarc variable, the greatest value is used. If several different values are given for the capacity of an arc, the smallest value is used. If several different values are given for the upper bound of a nonarc variable, the smallest value is used.

- Several values can be given for inequality constraint right-hand sides. For a particular constraint, the lowest rhs value is used for the rhs if the constraint is of \(\leq\) type. For a particular constraint, the greatest rhs value is used for the rhs if the constraint is of \(\geq\) type.

Reasons for Infeasibility

Before optimization commences, PROC NETFLOW tests to ensure that the problem is not infeasible by ensuring that, with respect to supplies, demands, and arc flow bounds, flow conservation can be obeyed at each node.

- Let \(IN\) be the sum of lower flow bounds of arcs directed toward a node plus the node’s supply. Let \(OUT\) be the sum of capacities of arcs directed from that node plus the node’s demand. If \(IN\) exceeds \(OUT\), not enough flow can leave the node.

- Let \(OUT\) be the sum of lower flow bounds of arcs directed from a node plus the node’s demand. Let \(IN\) be the total capacity of arcs directed toward the node plus the node’s supply. If \(OUT\) exceeds \(IN\), not enough flow can arrive at the node.
Reasons why a network problem can be infeasible are similar to those previously mentioned but apply to a set of nodes rather than for an individual node. Consider the network illustrated in Figure 6.13.

**Figure 6.13** An Infeasible Network

![Network Diagram](image)

The demand of NODE_4 is 120. That can never be satisfied because the maximal flow through arcs (NODE_1, NODE_2) and (NODE_5, NODE_6) is 117. More specifically, the implicit supply of NODE_2 and NODE_6 is only 117, which is insufficient to satisfy the demand of other nodes (real or implicit) in the network.

Furthermore, the lower flow bounds of arcs (NODE_1, NODE_2) and (NODE_5, NODE_6) are greater than the flow that can reach the tail nodes of these arcs, that, by coincidence, is the total supply of the network. The implicit demand of nodes NODE_1 and NODE_5 is 110, which is greater than the amount of flow that can reach these nodes.

When PROC NETFLOW detects that the problem is infeasible, it indicates why the solution, obtained after optimization stopped, is infeasible. It can report that the solution cannot obey flow conservation constraints and which nodes these conservation constraints are associated with. If applicable, the side constraints that the solution violates are also output.

If stage 1 optimization obtains a feasible solution to the network, stage 2 optimization can determine that the problem is infeasible and note that some flow conservation constraint is broken while all side constraints are satisfied. The infeasibility messages issued by PROC NETFLOW pertain to why the current solution is infeasible, not quite the same as the reasons why the problem is infeasible. However, the messages highlight areas in the problem where the infeasibility can be tracked down. If the problem is infeasible, make PROC NETFLOW do a stage 1 unconstrained optimization by removing the **CONDATA=** data set specification in the **PROC NETFLOW** statement. If a feasible network solution is found, then the side constraints are the source of the infeasibility in the problem.
Missing S Supply and Missing D Demand Values

In some models, you may want a node to be either a supply or demand node but you want the node to supply or demand the optimal number of flow units. To indicate that a node is such a supply node, use a missing S value in the SUPPLY list variable in the ARCDATA= data set or the SUPDEM list variable in the NODEDATA= data set. To indicate that a node is such a demand node, use a missing D value in the DEMAND list variable in the ARCDATA= data set or the SUPDEM list variable in the NODEDATA= data set.

Suppose the oil example in the section “Introductory Example” on page 315 is changed so that crude oil can be obtained from either the Middle East or U.S.A. in any amounts. You should specify that the node “middle east” is a supply node, but you do not want to stipulate that it supplies 100 units, as before. The node “u.s.a.” should also remain a supply node, but you do not want to stipulate that it supplies 80 units. You must specify that these nodes have missing S supply capabilities.

```sas
title 'Oil Industry Example';
title3 'Crude Oil can come from anywhere';
data miss_s;
  missing S;
  input _node_&$15. _sd_;
datalines;
middle east S
u.s.a. S
servstn1 gas -95
servstn1 diesel -30
servstn2 gas -40
servstn2 diesel -15
;
```

The following PROC NETFLOW run uses the same ARCDATA= and CONDATA= data sets used in the section “Introductory Example” on page 315.

```sas
proc netflow
  nodedata=miss_s /* the supply (missing S) and */
  demand data /* */
  arcdatalarcdata=arcdl /* the arc descriptions */
  condatalcondata=cond1 /* the side constraints */
  conout=solution; /* the solution data set */
  run;
print some_arcs('middle east' 'u.s.a.',_all_)/short;
proc print;
  sum _fcost_;
run;
```
The following messages appear on the SAS log:

NOTE: Number of nodes= 14.
NOTE: All supply nodes have unspecified (.S) supply capability. Number of these nodes= 2.
NOTE: Number of demand nodes= 4.
NOTE: Total supply= 0, total demand= 180.
NOTE: Number of arcs= 18.
NOTE: Number of iterations performed (neglecting any constraints)= 15.
NOTE: Of these, 0 were degenerate.
NOTE: Optimum (neglecting any constraints) found.
NOTE: Minimal total cost= 50040.
NOTE: Number of <= side constraints= 0.
NOTE: Number of >= side constraints= 2.
NOTE: Number of arc and nonarc variable side constraint coefficients= 8.
NOTE: Number of iterations, optimizing with constraints= 3.
NOTE: Of these, 0 were degenerate.
NOTE: Optimum reached.
NOTE: Minimal total cost= 50075.
NOTE: The data set WORK.SOLUTION has 18 observations and 14 variables.

The PRINT statement reports the arcs directed away from the supply nodes, shown in Figure 6.14. The amount of crude obtained from the Middle East and U.S.A. is 30 and 150 units, respectively.

Figure 6.14 Print Statement, Oil Example, Missing S Supplies

Oil Industry Example

Crude Oil can come from anywhere

The NETFLOW Procedure

<table>
<thead>
<tr>
<th><em>N</em></th>
<th><em>from</em></th>
<th><em>to</em></th>
<th><em>cost</em></th>
<th><em>capac</em></th>
<th><em>lo</em></th>
<th><em>name</em></th>
<th><em>FLOW</em></th>
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<td>20</td>
<td>m_e_ref1</td>
<td>20</td>
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<td>99999999</td>
<td>0</td>
<td></td>
<td>125</td>
</tr>
<tr>
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<td>middle east</td>
<td>refinery 2</td>
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<td>80</td>
<td>10</td>
<td>m_e_ref2</td>
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<td>4</td>
<td>u.s.a.</td>
<td>refinery 2</td>
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<td>99999999</td>
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<td>25</td>
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</tbody>
</table>
The CONOUT= data set is shown in Figure 6.15.

**Figure 6.15 Missing S SUPDEM Values in NODEDATA**

<table>
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<tr>
<th>Obs</th>
<th>from</th>
<th>to</th>
<th>cost</th>
<th>capac</th>
<th>lo</th>
<th>name</th>
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<th><em>DEMAND</em></th>
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<td>thrput1</td>
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</tr>
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<td>0</td>
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<td></td>
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<td>.</td>
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<td>0</td>
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<td>0</td>
<td></td>
<td></td>
<td>r2</td>
<td>.</td>
<td>.</td>
</tr>
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<td>100</td>
<td>0</td>
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<table>
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<th>RCOST</th>
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<td>0.00</td>
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<tr>
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<td>.</td>
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<td>9</td>
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</tr>
</tbody>
</table>

50075.00

The optimal supplies of nodes “middle east” and “u.s.a.” are 30 and 150 units, respectively. For this example, the same optimal solution is obtained if these nodes had supplies less than these values (each supplies 1 unit, for example) and the THRUNET option was specified in the PROC NETFLOW statement. With the THRUNET option active, when total supply exceeds total demand, the specified nonmissing demand values
are the lowest number of flow units that must be absorbed by the corresponding node. This is demonstrated in the following PROC NETFLOW run. The missing S is most useful when nodes are to supply optimal numbers of flow units and it turns out that for some nodes, the optimal supply is 0.

\begin{verbatim}
data miss_s_x;
  missing S;
  input _node_&$15. _sd_;
datalines;
middle east 1
u.s.a. 1
servstn1 gas -95
servstn1 diesel -30
servstn2 gas -40
servstn2 diesel -15;
proc netflow
  thrunet
    nodedata=miss_s_x /* No supply (missing S) */
    arcdatalarc1 /* the arc descriptions */
    condatalcond1 /* the side constraints */
    conout=solution; /* the solution data set */
  run;
  print some_arcs('middle east' 'u.s.a.',_all_)/short;
proc print;
  sum _fcost_;
run;
\end{verbatim}

The following messages appear on the SAS log. Note that the Total supply= 2, not 0 as in the last run.

\begin{verbatim}
NOTE: Number of nodes= 14 .
NOTE: Number of supply nodes= 2 .
NOTE: Number of demand nodes= 4 .
NOTE: Total supply= 2 , total demand= 180 .
NOTE: Number of arcs= 18 .
NOTE: Number of iterations performed (neglecting any constraints)= 20 .
NOTE: Of these, 1 were degenerate.
NOTE: Optimum (neglecting any constraints) found.
NOTE: Minimal total cost= 50040 .
NOTE: Number of \leq side constraints= 0 .
NOTE: Number of \geq side constraints= 2 .
NOTE: Number of \leq side constraints= 2 .
NOTE: Number of arc and nonarc variable side constraint coefficients= 8 .
NOTE: Number of iterations, optimizing with constraints= 3 .
NOTE: Of these, 0 were degenerate.
NOTE: Optimum reached.
NOTE: Minimal total cost= 50075 .
NOTE: The data set WORK.SOLUTION has 18 observations and 14 variables.
\end{verbatim}

The PRINT statement and the CONDATA= data set are very similar; the supplies of the supply nodes are 1, not missing S. Otherwise, the solutions are identical.
If total supply exceeds total demand, any missing S values are ignored. If total demand exceeds total supply, any missing D values are ignored.

Balancing Total Supply and Total Demand

When Total Supply Exceeds Total Demand

When total supply of a network problem exceeds total demand, PROC NETFLOW can add an extra node (called the excess node) to the problem and set the demand at that node equal to the difference between total supply and total demand. There are three ways that this excess node can be joined to the network. All three ways entail PROC NETFLOW generating a set of arcs (henceforth referred to as the generated arcs) that are directed toward the excess node. The total amount of flow in generated arcs equals the demand of the excess node. The generated arcs originate from one of three sets of nodes.

When you specify the THRUNET option, the set of nodes that generated arcs originate from are all demand nodes, even those demand nodes with unspecified demand capability. You indicate that a node has unspecified demand capability by using a missing D value instead of an actual value for demand data (discussed in the section “Missing S Supply and Missing D Demand Values” on page 401). The value specified as the demand of a demand node is in effect a lower bound of the number of flow units that node can actually demand. For missing D demand nodes, this lower bound is zero.

If you do not specify the THRUNET option, the way in which the excess node is joined to the network depends on whether there are demand nodes with unspecified demand capability (nodes with missing D demand).

If there are missing D demand nodes, these nodes are the set of nodes that generated arcs originate from. The value specified as the demand of a demand node, if not missing D, is the number of flow units that node actually demands. For a missing D demand node, the actual demand of that node may be zero or greater.

If there are no missing D demand nodes, the set of nodes that generated arcs originate from are the set of supply nodes. The value specified as the supply of a supply node is in effect an upper bound of the number of flow units that node can actually supply. For missing S supply nodes (discussed in the section “Missing S Supply and Missing D Demand Values” on page 401), this upper bound is zero, so missing S nodes when total supply exceeds total demand are transshipment nodes, nodes that neither supply nor demand flow.

When Total Supply Is Less Than Total Demand

When total supply of a network problem is less than total demand, PROC NETFLOW can add an extra node (called the excess node) to the problem and set the supply at that node equal to the difference between total demand and total supply. There are three ways that this excess node can be joined to the network. All three ways entail PROC NETFLOW generating a set of arcs (henceforth referred to as the generated arcs) that originate from the excess node. The total amount of flow in generated arcs equals the supply of the excess node. The generated arcs are directed toward one of three sets of nodes.

When you specify the THRUNET option, the set of nodes that generated arcs are directed toward are all supply nodes, even those supply nodes with unspecified supply capability. You indicate that a node has unspecified supply capability by using a missing S value instead of an actual value for supply data (discussed in the section “Missing S Supply and Missing D Demand Values” on page 401). The value specified as the supply of a supply node is in effect a lower bound of the number of flow units that node can actually supply. For missing S supply nodes, this lower bound is zero.
If you do not specify the **THRUNET** option, the way in which the excess node is joined to the network depends on whether there are supply nodes with unspecified supply capability (nodes with missing S supply).

If there are missing S supply nodes, these nodes are the set of nodes that generated arcs are directed toward. The value specified as the supply of a supply node, if not missing S, is the number of flow units that node actually supplies. For a missing S supply node, the actual supply of that node may be zero or greater.

If there are no missing S supply nodes, the set of nodes that generated arcs are directed toward are the set of demand nodes. The value specified as the demand of a demand node is in effect an upper bound of the number of flow units that node can actually demand. For missing D demand nodes, (discussed in the section “Missing S Supply and Missing D Demand Values” on page 401), this upper bound is zero, so missing D nodes when total supply is less than total demand are transshipment nodes, nodes that neither supply nor demand flow.

---

**Warm Starts**

Using a warm start can increase the overall speed of PROC NETFLOW when it is used repetitively on problems with similar structure. It is most beneficial when a solution of a previous optimization is close to the optimum of the same network with some of its parameters, for example, arc costs, changed. Whether a problem is changed or not, a nonoptimal solution resulting from a previous optimization can be used to restart optimization, thereby saving PROC NETFLOW from having to repeat work to reach the warm start already available.

Time also is saved in the data structure initialization part of the NETFLOW procedure’s execution. Information about the previous optimal solution, particularly concerning the size of the problem, a description of the basis spanning tree structure, and what is basic in constraint rows, is known. Information about which nonbasic arcs have capacity flow and which nonbasic nonarc variables are at their respective upper bounds also makes up part of the warm start. The procedure can place arc data into the internal arc length arrays in precisely defined locations, in order of ascending head node internal number. It is not necessary to have multiple passes through the data because literals such as node, nonarc variable, arc, constraint, and special row names are defined and meaning is attached to each. This also saves a considerable amount of memory. None of the pre-optimization feasibility checks need be repeated.

Warm starts also are useful if you want to determine the effect of arcs being closed to carrying flow. The costs of these arcs are set high enough to ensure that the next optimal solution never has flow through them. Similarly, the effect of opening arcs can be determined by changing the cost of such arcs from an extreme to a reasonable value.

Specify the **FUTURE1** or **FUTURE2** option to ensure that additional data about a solution to be used as a warm start are output to output data sets. If the **FUTURE1** option is specified, extra observations with information on what is to be the warm start are set up for the **NODEOUT=** and **ARCCOUT=** data sets. The warm start solution in these data sets is a solution obtained after optimization neglecting side constraints. Any cost list variable value in the **ARCCOUT=** data set (and, if there are side constraints, any constraint data in the **CONDATA=** data set) can be changed before the solution is used as a warm start in a subsequent PROC NETFLOW run. Any nonarc variable data in the **CONDATA=** data set can be changed at this time as well. New nonarc variables not present in the original problem when the warm start was generated can also be added to the **CONDATA=** data set before the problem is warm started.
If the FUTURE2 option is specified, extra variables containing information on what will be the warm start solution are set up for the DUALOUT= and CONOUT= data sets. The warm start solution in these data sets is obtained after optimization that considers side constraints has been performed. Part of the warm start is concerned with the constraint part of the basis. Only cost list variable values in the CONOUT= data set can be changed before the solution is used as a warm start in a subsequent PROC NETFLOW run.

If a primal simplex optimization is to use a warm start, the WARM option must be specified in the PROC NETFLOW statement. Otherwise, the primal simplex network algorithm processes the data for a cold start and the extra information is not used.

The ARCDATA= data set is either the ARCCOUT= data set from a previous run of PROC NETFLOW with the FUTURE1 option specified (if an unconstrained warm start is used) or the CONOUT= data set from a previous run of PROC NETFLOW with the FUTURE2 option specified (if the warm start was obtained after optimization that considers side constraints was used).

The NODEDATA= data set is the NODEOUT= data set from a previous run of PROC NETFLOW with FUTURE1 specified if an unconstrained warm start is being used. Otherwise, the DUALIN= is the DUALOUT= data sets from a previous run of PROC NETFLOW with FUTURE2 specified, if the warm start was obtained after optimization that considers side constraints was used.

You never need to alter the NODEOUT= data set or the DUALOUT= data set between the time they are generated and when they are used as a warm start. The results would be unpredictable if incorrect changes were made to these data sets, or if a NODEDATA= or a DUALIN= data set were used with an ARCDATA= data set of a different solution.

It is possible, and often useful, to specify WARM and either FUTURE1 or FUTURE2, or both, in the same PROC NETFLOW statement if a new warm start is to be generated from the present warm start.

The extent of the changes allowed to a primal simplex warm start between the time it is generated and when it is used depends on whether the warm start describes an unconstrained or constrained solution. The following list describes parts of a constrained or an unconstrained warm start that can be altered:

- **COST** list variable values
- the value of an arc’s capacity, as long as the new capacity value is not less than the lower flow bound or the flow through the arc
- any nonarc variable information, in an unconstrained warm start
- for an unconstrained warm start, any side constraint data

The changes that can be made in constraint data for a constrained warm start are more restrictive than those for an unconstrained warm start. The lhs coefficients, type, and rhs value of a constraint can be changed as long as that constraint’s slack, surplus, or artificial variable is basic. The constraint name cannot be changed.
Example of a Warm Start

The following sample SAS session demonstrates how the warm start facilities are used to obtain optimal solutions to an unconstrained network where some arc cost changes occur or optimization is halted before the optimum is found.

```sas
/* data already in data sets node0 and arc0 */
proc netflow
  nodedata=node0 /* if supply_demand information */
  /is in this SAS data set */
  arcdata=arc0;
  /* variable list specifications go here */
  /* assume that they are not necessary here */
  /* if they are, they must be included in */
  /* all the PROC NETFLOW calls that follow */
reset
  future1
  nodeout=node2 /* nodeout and arcout are necessary */
  /is when FUTURE1 is used */
  arcout=arc1;
proc print
data=arc1; /* display the optimal solution */
proc fsedit
data=arc1; /* change some arc costs */
data arc2;
reset arc1;
  oldflow=_flow_;
  oldfc=_fcost_;/* make duplicates of the flow and flowcost*/
  /* variables. If a id list was explicitly */
  /* specified, add oldflow and oldfc to this*/
  /* list so that they appear in subsequently*/
  /* created arcout= data sets */
```

The following PROC NETFLOW uses the warm start created previously, performs 250 stage 2 iterations and saves that solution, which (as FUTURE1, ARCOUT=, and NODEOUT= are specified) can be used as a warm start in another PROC NETFLOW run.

```sas
proc netflow
  warm
  nodedata=node2
  arcdatalc=arc2;
  reset
    maxit1=250
    future1;
  run;
  save
    nodeout=savelib.node3
    arcout=savelib.arc3;
    /* optimization halted because 250 iterations */
    /* were performed to resume optimization, */
    /* possibly in another session (the output */
    /* data sets were saved in a SAS library */
    /* called savelib) */
```
Using the latest warm start, PROC NETFLOW is re-invoked to find the optimal solution.

```sas
proc netflow
  warm
  nodedata=savelib.node3
  arcdata=savelib.arc3;
reset
  future1
  nodeout=node4
  arcout=arc4;
run;
```

If this problem has constraints with data in a data set called CON0, then in each of the previous PROC NETFLOW statements, specify CONDATA=CON0. Between PROC NETFLOW runs, you can change constraint data. In each of the RESET statements, you could specify the CONOUT= data set to save the last (possibly optimal) solution reached by the optimizer if it reaches stage 2. You could specify FUTURE2 and the DUALOUT= data set to generate a constrained warm start.

```sas
proc netflow
  warm
  nodedata=node4
  arcdata=arc4
  condata=con0;
reset
  maxit2=125 /* optional, here as a reason why */
  /* optimum will not be obtained */
  scratch /* optional, but warm start might be good */
  /* enough to start stage 2 optimization */
  future2
run;
/* optimization halted after 125 stage 2 iterations */
save dualout=dual1 conout=conout1;
```

Stage 2 optimization halted before optimum was reached. Now you can make cost and nonarc variable objective function coefficient changes. Then to restart optimization, use

```sas
proc netflow
  warm
  condata=con0
/* NB. NETFLOW reads constraint data only */
  dualin=dual1
  arcdata=con1;
reset
  future2
  dualout=dual2
  conout=con2;
run;
```
How to Make the Data Read of PROC NETFLOW More Efficient

Chapter 6: The NETFLOW Procedure

This section contains information useful when you want to solve large constrained network problems. However, much of this information is also useful if you have a large linear programming problem. All of the options described in this section that are not directly applicable to networks (options such as ARCS_ONLY_ARCDATA, ARC_SINGLE_OBS, NNODES=, and NARCS=) can be specified to improve the speed at which LP data are read.

Large Constrained Network Problems

Many of the models presented to PROC NETFLOW are enormous. They can be considered large by linear programming standards; problems with thousands of variables and constraints. When dealing with side constrained network programming problems, models can have not only a linear programming component of that magnitude, but also a larger, possibly much larger, network component.

The majority of a network problem’s decision variables are arcs. Like an LP decision variable, an arc has an objective function coefficient, upper and lower value bounds, and a name. Arcs can have coefficients in constraints. Therefore, an arc is quite similar to an LP variable and places the same memory demands on optimization software as an LP variable. But a typical network model has many more arcs and nonarc variables than the typical LP model has variables. And arcs have tail and head nodes. Storing and processing node names require huge amounts of memory. To make matters worse, node names occupy memory at times when a large amount of other data should also reside in memory.

While memory requirements are lower for a model with embedded network component compared with the equivalent LP once optimization starts, the same is usually not true during the data read. Even though nodal flow conservation constraints in the LP should not be specified in the constrained network formulation, the memory requirements to read the latter are greater because each arc (unlike an LP variable) originates at one node, and is directed toward another.

Paging

PROC NETFLOW has facilities to read data when the available memory is insufficient to store all the data at once. PROC NETFLOW does this by allocating memory for different purposes, for example, to store an array or receive data read from an input SAS data set. After that memory has filled, the information is sent to disk and PROC NETFLOW can resume filling that memory with new information. Often, information must be retrieved from disk so that data previously read can be examined or checked for consistency. Sometimes, to prevent any data from being lost, or to retain any changes made to the information in memory, the contents of the memory must be sent to disk before other information can take its place. This process of swapping information to and from disk is called paging. Paging can be very time-consuming, so it is crucial to minimize the amount of paging performed.

There are several steps you can take to make PROC NETFLOW read the data of network and linear programming models more efficiently, particularly when memory is scarce and the amount of paging must be reduced. PROC NETFLOW will then be able to tackle large problems in what can be considered reasonable amounts of time.
The Order of Observations

PROC NETFLOW is quite flexible in the ways data can be supplied to it. Data can be given by any reasonable means. PROC NETFLOW has convenient defaults that can save you work when generating the data. There can be several ways to supply the same piece of data, and some pieces of data can be given more than once. PROC NETFLOW reads everything, then merges it all together. However, this flexibility and convenience come at a price; PROC NETFLOW may not assume the data has a characteristic that, if possessed by the data, could save time and memory during the data read. There are several options that indicate the data has some exploitable characteristic.

For example, an arc cost can be specified once or several times in the ARCDATA= or CONDATA= data set, or both. Every time it is given in ARCDATA, a check is made to ensure that the new value is the same as any corresponding value read in a previous observation of ARCDATA. Every time it is given in CONDATA, a check is made to ensure that the new value is the same as the value read in a previous observation of CONDATA, or previously in ARCDATA. It would save PROC NETFLOW time if it knew that arc cost data would be encountered only once while reading ARCDATA, so performing the time-consuming check for consistency would not be necessary. Also, if you indicate that CONDATA contains data for constraints only, PROC NETFLOW will not expect any arc information, so memory will not be allocated to receive such data while reading CONDATA. This memory is used for other purposes and this might lead to a reduction in paging. If applicable, use the ARC_SINGLE_OBS or the CON_SINGLE_OBS option, or both, and the NON_REPLIC=COEFS specification to improve how ARCDATA and CONDATA are read.

PROC NETFLOW allows the observations in input data sets to be in any order. However, major time savings can result if you are prepared to order observations in particular ways. Time spent by the SORT procedure to sort the input data sets, particularly the CONDATA= data set, may be more than made up for when PROC NETFLOW reads them, because PROC NETFLOW has in memory information possibly used when the previous observation was read. PROC NETFLOW can assume a piece of data is either similar to that of the last observation read or is new. In the first case, valuable information such as an arc or a nonarc variable number or a constraint number is retained from the previous observation. In the last case, checking the data with what has been read previously is not necessary.

Even if you do not sort the CONDATA= data set, grouping observations that contain data for the same arc or nonarc variable or the same row pays off. PROC NETFLOW establishes whether an observation being read is similar to the observation just read.

Practically, several input data sets for PROC NETFLOW might have this characteristic, because it is natural for data for each constraint to be grouped together (dense format of CONDATA) or data for each column to be grouped together (sparse format of CONDATA). If data for each arc or nonarc is spread over more than one observation of the ARCDATA= data set, it is natural to group these observations together.

Use the GROUPED= option to indicate whether observations of the ARCDATA= data set, CONDATA= data set, or both are grouped in a way that can be exploited during data read.

Time is saved if the type data for each row appears near the top of the CONDATA= data set, especially if it has the sparse format. Otherwise, when reading an observation, if PROC NETFLOW does not know if a row is a constraint or special row, the data are set aside. Once the data set has been completely read, PROC NETFLOW must reprocess the data it set aside. By then, it knows the type of each constraint or row or, if its type was not provided, it is assumed to have a default type.
Better Memory Utilization

In order for PROC NETFLOW to make better utilization of available memory, you can now specify options that indicate the approximate size of the model. PROC NETFLOW then knows what to expect. For example, if you indicate that the problem has no nonarc variables, PROC NETFLOW will not allocate memory to store nonarc data. That memory is utilized better for other purposes. Memory is often allocated to receive or store data of some type. If you indicate that the model does not have much data of a particular type, the memory that would otherwise have been allocated to receive or store that data can be used to receive or store data of another type.

- **NNODES=** approximate number of nodes
- **NARCS=** approximate number of arcs
- **NNAS=** approximate number of nonarc variables or LP variables
- **NCONS=** approximate number of constraints
- **NCOEFS=** approximate number of constraint coefficients

These options will sometimes be referred to as Nxxxx= options.

You do not need to specify all these options for the model, but the more you do, the better. If you do not specify some or all of these options, PROC NETFLOW guesses the size of the problem by using what it already knows about the model. Sometimes PROC NETFLOW guesses the size of the model by looking at the number of observations in the ARCDATA= and CONDATA= data sets. However, PROC NETFLOW uses rough rules of thumb; that typical models are proportioned in certain ways (for example, if there are constraints, then arcs and nonarcs usually have 5 constraint coefficients). If your model has an unusual shape or structure, you are encouraged to use these options.

If you do use the options and you do not know the exact values to specify, overestimate the values. For example, if you specify NARCS=10000 but the model has 10100 arcs, when dealing with the last 100 arcs, PROC NETFLOW might have to page out data for 10000 arcs each time one of the last arcs must be dealt with. Memory could have been allocated for all 10100 arcs without affecting (much) the rest of the data read, so NARCS=10000 could be more of a hindrance than a help.

The point of these Nxxxx= options is to indicate the model size when PROC NETFLOW does not know it. When PROC NETFLOW knows the “real” value, that value is used instead of Nxxxx= .

When PROC NETFLOW is given a constrained solution warm start, PROC NETFLOW knows from the warm start information all model size parameters, so Nxxxx= options are not used. When an unconstrained warm start is used and the SAME_NONARC_DATA is specified, PROC NETFLOW knows the number of nonarc variables, so that is used instead of the value of the NNAS= option.

ARCS_ONLY_ARCDATA indicates that data for only arcs are in the ARCDATA= data set. Memory would not be wasted to receive data for nonarc and LP variables.

Use the memory usage parameters:

- The **BYTES=** option specifies the size of PROC NETFLOW main working memory in number of bytes.
• The MAXARRAYBYTES= option specifies the maximum number of bytes that an array can occupy.
• The MEMREP option indicates that memory usage report is to be displayed on the SAS log.

Specifying the BYTES= parameter is particularly important. Specify as large a number as possible, but not such a large number of bytes that will cause PROC NETFLOW (rather, the SAS System running underneath PROC NETFLOW) to run out of memory. Use the MAXARRAYBYTES= option if the model is very large or “disproportionate.” Try increasing or decreasing the MAXARRAYBYTES= option. Limiting the amount of memory for use by big arrays is good if they would take up too much memory to the detriment of smaller arrays, buffers, and other things that require memory. However, too small a value of the MAXARRAYBYTES= option might cause PROC NETFLOW to page a big array excessively. Never specify a value for the MAXARRAYBYTES= option that is smaller than the main node length array. PROC NETFLOW reports the size of this array on the SAS log if you specify the MEMREP option. The MAXARRAYBYTES= option influences paging not only in the data read, but also during optimization. It is often better if optimization is performed as fast as possible, even if the read is made slower as a consequence.

Use Defaults to Reduce the Amount of Data

Use as much as possible the parameters that specify default values. For example, if there are several arcs with the same cost value \( c \), use DEFCOST=\( c \) for arcs that have that cost. Use missing values in the COST variable in ARCDATA instead of \( c \). PROC NETFLOW ignores missing values, but must read, store, and process nonmissing values, even if they are equal to a default option or could have been equal to a default parameter had it been specified. Sometimes, using default parameters makes the need for some SAS variables in the ARCDATA= and CONDATA= data sets no longer necessary, or reduces the quantity of data that must be read. The default options are

• DEFCOST= default cost of arcs, objective function of nonarc variables or LP variables
• DEFMINFLOW= default lower flow bound of arcs, lower bound of nonarc variables or LP variables
• DEFCAPACITY= default capacity of arcs, upper bound of nonarc variables or LP variables
• DEFCONTYPE=LE DEFCONTYPE= <=
  DEFCONTYPE=EQ DEFCONTYPE= =
  DEFCONTYPE=GE DEFCONTYPE= >= (default constraint type)

The default options themselves have defaults. For example, you do not need to specify DEFCOST=0 in the PROC NETFLOW statement. You should still have missing values in the COST variable in ARCDATA for arcs that have zero costs.

If the network has only one supply node, one demand node, or both, use

• SOURCE= name of single node that has supply capability
• SUPPLY= the amount of supply at SOURCE
• SINK= name of single node that demands flow
• DEMAND= the amount of flow SINK demands
Do not specify that a constraint has zero right-hand-side values. That is the default. The only time it might be practical to specify a zero rhs is in observations of CONDATA read early so that PROC NETFLOW can infer that a row is a constraint. This could prevent coefficient data from being put aside because PROC NETFLOW did not know the row was a constraint.

Names of Things

To cut data read time and memory requirements, reduce the number of bytes in the longest node name, longest arc name, and longest constraint name to 8 bytes or less. The longer a name, the more bytes must be stored and compared with other names.

If an arc has no constraint coefficients, do not give it a name in the NAME list variable in the ARCDATA= data set. Names for such arcs serve no purpose.

PROC NETFLOW can have a default name for each arc. If an arc is directed from node \textit{tailname} toward node \textit{headname}, the default name for that arc is \textit{tailname}_\textit{headname}. If you do not want PROC NETFLOW to use these default arc names, specify NAMECTRL=1. Otherwise, PROC NETFLOW must use memory for storing node names and these node names must be searched often.

If you want to use the default \textit{tailname}_\textit{headname} name, that is, NAMECTRL=2 or NAMECTRL=3, do not use underscores in node names. If a CONDATA has a dense format and has a variable in the VAR list \textit{A_B_C_D}, or if the value \textit{A_B_C_D} is encountered as a value of the COLUMN list variable when reading CONDATA that has the sparse format, PROC NETFLOW first looks for a node named \textit{A}. If it finds it, it looks for a node called \textit{B_C_D}. It then looks for a node with the name \textit{A_B} and possibly a node with name \textit{C_D}. A search for a node named \textit{A_B_C} and possibly a node named \textit{D} is done. Underscores could have caused PROC NETFLOW to look unnecessarily for nonexistent nodes. Searching for node names can be expensive, and the amount of memory to store node names large. It might be better to assign the arc name \textit{A_B_C_D} directly to an arc by having that value as a NAME list variable value for that arc in ARCDATA and specify NAMECTRL=1.

Other Ways to Speed Up Data Reads

Use warm starts as much as possible.

- **WARM** indicates that the input SAS data sets contain a warm start.

The data read of a warm start is much faster than a cold start data read. The model size is known before the read starts. The observations of the NODEDATA= or DUALIN= data sets have observations ordered by node name and constraint name. Information is stored directly in the data structures used by PROC NETFLOW. For a cold start, much of preprocessing must be performed before the information can be stored in the same way. And using a warm start can greatly reduce the time PROC NETFLOW spends doing optimization.

- **SAME_NONARC_DATA** is an option that excludes data from processing.

This option indicates that the warm start nonarc variable data in ARCDATA is read and any nonarc variable data in CONDATA is to be ignored. Use this option if it is applicable, or when CONDATA has no nonarc variable data, or such data are duplicated in ARCDATA. ARCDATA is always read before CONDATA.

Arcs and nonarc variables can have associated with them values or quantities that have no bearing with the optimization. This information is given in ARCDATA in the ID list variables. For example, in a distribution
problem, information such as truck number and driver’s name can be associated with each arc. This is useful when a solution is saved in an output SAS data set. However, PROC NETFLOW needs to reserve memory to process this information when data are being read. For large problems when memory is scarce, it might be better to remove ancillary data from ARCDATA. After PROC NETFLOW runs, use SAS software to merge this information into the output data sets that contain the optimal solution.

Macro Variable _ORNETFL

The NETFLOW procedure creates and initializes a SAS macro variable called _ORNETFL. After exiting the procedure, you can use %put &_ORNETFL; to view details about the optimization.

When the network simplex method is used, the value of _ORNETFL consists of the following parts:

- **ERROR_STATUS**, indicating the existence or absence of any errors
- **OPT_STATUS**, the stage of the optimization, or what solution has been found

Ideally, at the end of a PROC NETFLOW run in which the network simplex method is used, _ORNETFL has the following value:

```
ERROR_STATUS=OK OPT_STATUS=OPTIMAL OBJECTIVE=x
SOLUTION=OPTIMAL
```

At the end of a PROC NETFLOW run in which the interior point algorithm is used, _ORNETFL should have the following value:

```
ERROR_STATUS=OK SOLUTION=OPTIMAL OBJECTIVE=x
ITERATIONS=x ITERATING_TIME=x SOLUTION_TIME=x
```

Nontrailing blank characters that are unnecessary are removed. If the preprocessor detects that a problem with a network component is infeasible, and you specify that the interior point algorithm should be used, _ORNETFL has the following value:

```
ERROR_STATUS=OK SOLUTION=INFEASIBLE
ITERATIONS=0 ITERATING_TIME=0 SOLUTION_TIME=0
```

The same value is assigned to the _ORNETFL macro variable if the preprocessor detects that an LP problem is infeasible.

Table 6.11 lists alternate values for the _ORNETFL value parts.
### Table 6.11 PROC NETFLOW _ORNETFL Macro Values

<table>
<thead>
<tr>
<th>Keyword</th>
<th>Value</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>ERROR_STATUS</td>
<td>OK</td>
<td>No errors</td>
</tr>
<tr>
<td>MEMORY</td>
<td></td>
<td>Memory request failed</td>
</tr>
<tr>
<td>IO</td>
<td></td>
<td>Input/output error</td>
</tr>
<tr>
<td>DATA</td>
<td></td>
<td>Error in the data</td>
</tr>
<tr>
<td>BUG</td>
<td></td>
<td>Error with PROC NETFLOW</td>
</tr>
<tr>
<td>SEMANTIC</td>
<td></td>
<td>Semantic error</td>
</tr>
<tr>
<td>SYNTAX</td>
<td></td>
<td>Syntax error</td>
</tr>
<tr>
<td>UNKNOWN</td>
<td></td>
<td>Unknown error</td>
</tr>
<tr>
<td>OPT_STATUS</td>
<td>START</td>
<td>No optimization has been done</td>
</tr>
<tr>
<td></td>
<td>STAGE_1</td>
<td>Performing stage 1 optimization</td>
</tr>
<tr>
<td></td>
<td>UNCON_OPT</td>
<td>Reached unconstrained optimum, but there are side constraints</td>
</tr>
<tr>
<td></td>
<td>STAGE_2</td>
<td>Performing stage 2 optimization</td>
</tr>
<tr>
<td></td>
<td>OPTIMAL</td>
<td>Reached the optimum</td>
</tr>
<tr>
<td>OBJECTIVE</td>
<td>objective</td>
<td>Total cost or profit</td>
</tr>
<tr>
<td>MINFLOW</td>
<td>minflow</td>
<td>If MAXFLOW and MAXIMIZE are specified at the same time</td>
</tr>
<tr>
<td>MAXFLOW</td>
<td>maxflow</td>
<td>If MAXFLOW is specified</td>
</tr>
<tr>
<td>SHORTEST_PATH</td>
<td>shortpath</td>
<td>If SHORTEST_PATH is specified</td>
</tr>
<tr>
<td>LONGEST_PATH</td>
<td>longpath</td>
<td>If SHORTEST_PATH and MAXIMIZE are specified at the same time</td>
</tr>
<tr>
<td>SOLUTION</td>
<td>NONOPTIMAL</td>
<td>More optimization is required</td>
</tr>
<tr>
<td></td>
<td>STAGE_2_REQUIRED</td>
<td>Reached unconstrained optimum, stage 2 optimization is required</td>
</tr>
<tr>
<td></td>
<td>OPTIMAL</td>
<td>Have determined the optimum</td>
</tr>
<tr>
<td></td>
<td>INFEASIBLE</td>
<td>Infeasible; no solution exists</td>
</tr>
<tr>
<td></td>
<td>UNRESOLVED_OPTIMAL_OR_FEASIBILITY</td>
<td>The optimization process stops before optimality or infeasibility can be proven.</td>
</tr>
<tr>
<td></td>
<td>MAXITERB_OPTION_STOPPED_OPTIMIZATION</td>
<td>The interior point algorithm stops after performing maximal number of iterations specified by the MAXITERB= option</td>
</tr>
</tbody>
</table>

### Memory Limit

The system option MEMSIZE sets a limit on the amount of memory used by the SAS System. If you do not specify a value for this option, then the SAS System sets a default memory limit. Your operating environment determines the actual size of the default memory limit, which is sufficient for many applications. However, to solve most realistic optimization problems, the NETFLOW procedure might require more memory. Increasing the memory limit can reduce the chance of an out-of-memory condition.
NOTE: The MEMSIZE system option is not available in some operating environments. See the documentation for your operating environment for more information.

You can specify -MEMSIZE 0 to indicate all available memory should be used, but this setting should be used with caution. In most operating environments, it is better to specify an adequate amount of memory than to specify -MEMSIZE 0. For example, if you are running PROC OPTLP to solve LP problems with only a few hundred thousand variables and constraints, -MEMSIZE 500M might be sufficient to enable the procedure to run without an out-of-memory condition. When problems have millions of variables, -MEMSIZE 1000M or higher might be needed. These are “rules of thumb”—problems with atypical structure, density, or other characteristics can increase the optimizer’s memory requirements.

The MEMSIZE option can be specified at system invocation, on the SAS command line, or in a configuration file. The syntax is described in the SAS Companion for your operating environment.

To report a procedure’s memory consumption, you can use the FULLSTIMER option. The syntax is described in the SAS Companion for your operating environment.

The Interior Point Algorithm: NETFLOW Procedure

Introduction

The simplex algorithm, developed shortly after World War II, was the main method used to solve linear programming problems. Over the last fifteen years, the interior point algorithm has been developed to also solve linear programming problems. From the start it showed great theoretical promise, and considerable research in the area resulted in practical implementations that performed competitively with the simplex algorithm. More recently, interior point algorithms have evolved to become superior to the simplex algorithm, in general, especially when the problems are large.

The interior point algorithm has been implemented in PROC NETFLOW. This algorithm can be used to solve linear programs as well as network problems. When PROC NETFLOW detects that the problem has no network component, it automatically invokes the interior point algorithm to solve the problem. The data required by PROC NETFLOW for a linear program resembles the data for nonarc variables and constraints for constrained network problems.

If PROC NETFLOW does detect a network component to the problem (the problem has arcs), you must specify the option INTPOINT in the PROC NETFLOW statement if you want to use the interior point algorithm. PROC NETFLOW first converts the constrained network model into an equivalent linear programming formulation, solves that, then converts the LP back to the network model. These models remain conceptually easy since they are based on network diagrams that represent the problem pictorially. This procedure accepts the network specification in a format that is particularly suited to networks. This not only simplifies problem description but also aids in the interpretation of the solution. The conversions to and from the equivalent LP are done “behind the scenes.”

There are many variations of interior point algorithms. PROC NETFLOW uses the Primal-Dual with Predictor-Corrector algorithm. This algorithm and related theory can be found in the texts by Roos, Terlaky, and Vial (1997), Wright (1997), and Ye (1996).
The remainder of this section is split into two parts. In the first part, how you use PROC NETFLOW’s interior point algorithm to solve network problems is described. In the second part, using PROC NETFLOW to solve linear programming problems (its interior point algorithm must be used) is described. Both parts are organized similarly:

- The way data are supplied to PROC NETFLOW is outlined in a “Getting Started” subsection.
- An “Introductory Example” is solved to demonstrate how the data are set up, how PROC NETFLOW is used to compute the solution, and how the optimum is saved.
- More sophisticated ways to use PROC NETFLOW interactively are detailed in an “Interactivity” subsection.
- A “Functional Summary” lists the statements and options that can be used to control PROC NETFLOW. Of particular interest are the options used to control the optimizer, and the way the solution is saved into output data sets or is displayed.

The Linear Programs section has additional subsections:

- “Mathematical Description of LP”
- “Interior Point Algorithmic Details,” a brief theory of the algorithm containing information about the options that can be specified to control the interior point algorithm.
- “Syntax” subsection, which is a subset of the syntax when the simplex algorithm is used. Gone are the statements and lists relevant only when the simplex algorithm is used.

### Network Models: Interior Point Algorithm

The data required by PROC NETFLOW for a network problem is identical whether the simplex algorithm or the interior point algorithm is used as the optimizer. By default, the simplex algorithm is used for problems with a network component. To use the interior point algorithm, all you need to do is specify the INTPOINT option in the PROC NETFLOW statement. You can optionally specify some options that control the interior point algorithm, of which there are only a few. The interior point algorithm is remarkably robust when reasonable choices are made during the design and implementation, so it does not need to be tuned to the same extent as the simplex algorithm.

### When to Use INTPOINT: Network Models: Interior Point Algorithm

PROC NETFLOW uses the primal simplex network algorithm and the primal partitioning algorithm to solve constrained network problems. These algorithms are fast, since they take advantage of algebraic properties of the network component of the problem.

If the network component of the model is large compared to the side constraint component, PROC NETFLOW’s optimizer can store what would otherwise be a large matrix as a spanning tree computer data structure. Computations involving the spanning tree data structure can be performed much faster than those using matrices. Only the nonnetwork part of the problem, hopefully quite small, needs to be manipulated by PROC NETFLOW as matrices.

In contrast, LP optimizers must contend with matrices that can be large for large problems. Arithmetic operations on matrices often accumulate rounding errors that cause difficulties for the algorithm. So in
addition to the performance improvements, network optimization is generally more numerically stable than LP optimization.

The nodal flow conservation constraints do not need to be specified in the network model. They are implied by the network structure. However, flow conservation constraints do make up the data for the equivalent LP model. If you have an LP that is small after the flow conservation constraints are removed, that problem is a definite candidate for solution by PROC NETFLOW’s specialized simplex method.

However, some constrained network problems are solved more quickly by the interior point algorithm than the network optimizer in PROC NETFLOW. Usually, they have a large number of side constraints or nonarc variables. These models are more like LPs than network problems. The network component of the problem is so small that PROC NETFLOW’s network simplex method cannot recoup the effort to exploit that component rather than treat the whole problem as an LP. If this is the case, it is worthwhile to get PROC NETFLOW to convert a constrained network problem to the equivalent LP and use its interior point algorithm. This conversion must be done before any optimization has been performed (specify the INTPOINT option in the PROC NETFLOW statement).

Even though some network problems are better solved by converting them to an LP, the input data and the output solution are more conveniently maintained as networks. You retain the advantages of casting problems as networks: ease of problem generation and expansion when more detail is required. The model and optimal solutions are easy to understand, as a network can be drawn.

**Getting Started: Network Models: Interior Point Algorithm**

To solve network programming problems with side constraints using PROC NETFLOW, you save a representation of the network and the side constraints in three SAS data sets. These data sets are then passed to PROC NETFLOW for solution. There are various forms that a problem’s data can take. You can use any one or a combination of several of these forms.

The **NODEDATA=** data set contains the names of the supply and demand nodes and the supply or demand associated with each. These are the elements in the column vector \( b \) in problem (NPSC).

The **ARCDATA=** data set contains information about the variables of the problem. Usually these are arcs, but there can also be data related to nonarc variables in the **ARCDATA=** data set. If there are no arcs, this is a linear programming problem.

An arc is identified by the names of its tail node (where it originates) and head node (where it is directed). Each observation can be used to identify an arc in the network and, optionally, the cost per flow unit across the arc, the arc’s lower flow bound, capacity, and name. These data are associated with the matrix \( F \) and the vectors \( c, l, \) and \( u \) in problem (NPSC).

**Note:** Although \( F \) is a node-arc incidence matrix, it is specified in the **ARCDATA=** data set by arc definitions. Do not explicitly specify these flow conservation constraints as constraints of the problem.

In addition, the **ARCDATA=** data set can be used to specify information about nonarc variables, including objective function coefficients, lower and upper value bounds, and names. These data are the elements of the vectors \( d, m, \) and \( v \) in problem (NPSC). Data for an arc or nonarc variable can be given in more than one observation.

Supply and demand data also can be specified in the **ARCDATA=** data set. In such a case, the **NODEDATA=** data set may not be needed.

The **CONDATA=** data set describes the side constraints and their right-hand sides. These data are elements of the matrices \( H \) and \( Q \) and the vector \( r \). Constraint types are also specified in the **CONDATA=** data set. You can include in this data set upper bound values or capacities, lower flow or value bounds, and costs or
objective function coefficients. It is possible to give all information about some or all nonarc variables in the CONDATA= data set.

An arc or nonarc variable is identified in this data set by its name. If you specify an arc’s name in the ARCDATA= data set, then this name is used to associate data in the CONDATA= data set with that arc. Each arc also has a default name that is the name of the tail and head node of the arc concatenated together and separated by an underscore character; \textit{tail\_head}, for example.

If you use the \texttt{dense} side constraint input format and want to use the default arc names, these arc names are names of SAS variables in the VAR list of the CONDATA= data set.

If you use the \texttt{sparse} side constraint input format (also described later) and want to use the default arc names, these arc names are values of the COLUMN list SAS variable of the CONDATA= data set.

When using the interior point algorithm, the execution of PROC NETFLOW has two stages. In the preliminary (zeroth) stage, the data are read from the NODEDATA= data set, the ARCDATA= data set, and the CONDATA= data set. Error checking is performed. The model is converted into an equivalent linear program.

In the next stage, the linear program is preprocessed. This is optional but highly recommended. Preprocessing analyzes the model and tries to determine before optimization whether variables can be “fixed” to their optimal values. Knowing that, the model can be modified and these variables dropped out. It can be determined that some constraints are redundant. Sometimes, preprocessing succeeds in reducing the size of the problem, thereby making the subsequent optimization easier and faster.

The optimal solution to the linear program is then found. The linear program is converted back to the original constrained network problem, and the optimum for this is derived from the optimum of the equivalent linear program. If the problem was preprocessed, the model is now post-processed, where fixed variables are reintroduced. The solution can be saved in the CONOUT= data set. This data set is also named in the PROC NETFLOW, RESET, and SAVE statements.

The interior point algorithm cannot efficiently be warm started, so options such as FUTURE1 and FUTURE2 options are irrelevant.

\textbf{Introductory Example: Network Models: Interior Point Algorithm}

Consider the following transshipment problem for an oil company in the section “Introductory Example” on page 315. Recall that crude oil is shipped to refineries where it is processed into gasoline and diesel fuel. The gasoline and diesel fuel are then distributed to service stations. At each stage there are shipping, processing, and distribution costs. Also, there are lower flow bounds and capacities. In addition, there are side constraints to model crude mix stipulations, and model the limitations on the amount of Middle Eastern crude that can be processed by each refinery and the conversion proportions of crude to gasoline and diesel fuel. The network diagram is reproduced in Figure 6.16.
To solve this problem with PROC NETFLOW, a representation of the model is saved in three SAS data sets that are identical to the data sets supplied to PROC NETFLOW when the simplex algorithm was used.

To find the minimum cost flow through the network that satisfies the supplies, demands, and side constraints, invoke PROC NETFLOW as follows:

```sas
proc netflow
  intpoint /* <<<----- Interior Point used */
  nodedata=noded /* the supply and demand data */
  arcdata=arcd1 /* the arc descriptions */
  condata=cond1 /* the side constraints */
  conout=solution; /* the solution data set */
run;
```

The following messages, which appear on the SAS log, summarize the model as read by PROC NETFLOW and note the progress toward a solution:
Chapter 6: The NETFLOW Procedure

The first set of messages provide statistics on the size of the equivalent linear programming problem. The number of variables may not equal the number of arcs if the problem has nonarc variables. This example has none. To convert a network to an equivalent LP problem, a flow conservation constraint must be created for each node (including an excess or bypass node, if required). This explains why the number of equality side constraints and the number of constraint coefficients change when the interior point algorithm is used.

If the preprocessor was successful in decreasing the problem size, some messages will report how well it did. In this example, the model size was cut in half!

The following set of messages describe aspects of the interior point algorithm. Of particular interest are those concerned with the Cholesky factorization of $AA^T$ where $A$ is the coefficient matrix of the final LP. It
is crucial to preorder the rows and columns of this matrix to prevent *fill-in* and reduce the number of row operations to undertake the factorization. See the section “Interior Point Algorithmic Details” on page 429 for more explanation.

Unlike PROC LP, which displays the solution and other information as output, PROC NETFLOW saves the optimum in output SAS data sets you specify. For this example, the solution is saved in the SOLUTION data set. It can be displayed with PROC PRINT as

```sas
proc print data=solution;
  var _from_ _to_ _cost_ _capac_ _lo_ _name_
    _supply_ _demand_ _flow_ _fcost_
  sum _fcost_;
title3 'Constrained Optimum';
run;
```

**Figure 6.17** CONOUT=SOLUTION

<table>
<thead>
<tr>
<th>Obs</th>
<th><em>from</em></th>
<th><em>to</em></th>
<th><em>cost</em></th>
<th><em>capac</em></th>
<th><em>lo</em></th>
<th><em>name</em></th>
<th><em>supply</em></th>
<th><em>demand</em></th>
<th><em>flow</em></th>
<th><em>fcost</em></th>
</tr>
</thead>
<tbody>
<tr>
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<td>refinery 1</td>
<td>r1</td>
<td>200</td>
<td>175</td>
<td>50</td>
<td>thruput1</td>
<td>.</td>
<td>.</td>
<td>145.000</td>
<td>29000.00</td>
</tr>
<tr>
<td>2</td>
<td>refinery 2</td>
<td>r2</td>
<td>220</td>
<td>100</td>
<td>35</td>
<td>thruput2</td>
<td>.</td>
<td>.</td>
<td>35.000</td>
<td>7700.00</td>
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<td>3</td>
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<td>75</td>
<td>0</td>
<td></td>
<td>.</td>
<td>.</td>
<td>36.250</td>
<td>0.00</td>
</tr>
<tr>
<td>4</td>
<td>r1</td>
<td>ref1 gas</td>
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<td>140</td>
<td>0</td>
<td>r1_gas</td>
<td>.</td>
<td>.</td>
<td>108.750</td>
<td>0.00</td>
</tr>
<tr>
<td>5</td>
<td>r2</td>
<td>ref2 diesel</td>
<td>0</td>
<td>75</td>
<td>0</td>
<td></td>
<td>.</td>
<td>.</td>
<td>8.750</td>
<td>0.00</td>
</tr>
<tr>
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<td>0</td>
<td>100</td>
<td>0</td>
<td>r2_gas</td>
<td>.</td>
<td>.</td>
<td>26.250</td>
<td>0.00</td>
</tr>
<tr>
<td>7</td>
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<td>20</td>
<td>m_e_ref1</td>
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<td>.</td>
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<tr>
<td>8</td>
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<td>999999999</td>
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<td>80</td>
<td>.</td>
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<td>0.00</td>
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<td></td>
<td>.</td>
<td>95</td>
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<td>446.25</td>
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<tr>
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<td>servtn2 diesel</td>
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<td>999999999</td>
<td>0</td>
<td></td>
<td>.</td>
<td>15</td>
<td>6.250</td>
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<td>servtn2 gas</td>
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<td>999999999</td>
<td>0</td>
<td></td>
<td>.</td>
<td>40</td>
<td>0.000</td>
<td>0.00</td>
</tr>
</tbody>
</table>

Notice that, in the solution data set (**Figure 6.17**), the optimal flow through each arc in the network is given in the variable named `_FLOW_`, and the cost of flow through each arc is given in the variable `_FCOST_`. As expected, the minimal total cost of the solution found by the interior point algorithm is equal to the minimal total cost of the solution found by the simplex algorithm. In this example, the solutions are the same (within several significant digits), but sometimes the solutions can be different.
Interactivity: Network Models: Interior Point Algorithm

PROC NETFLOW can be used interactively. You begin by giving the PROC NETFLOW statement with INTPOINT specified, and you must specify the ARCDATA= data set. The CONDATA= data set must also be specified if the problem has side constraints. If necessary, specify the NODEDATA= data set.

The variable lists should be given next. If you have variables in the input data sets that have special names (for example, a variable in the ARCDATA= data set named _TAIL_ that has tail nodes of arcs as values), it may not be necessary to have many or any variable lists.

So far, this is the same as when the simplex algorithm is used, except the INTPOINT option is specified in the PROC NETFLOW statement. The PRINT, QUIT, SAVE, SHOW, RESET, and RUN statements follow and can be listed in any order. The QUIT statements can be used only once. The others can be used as many times as needed.

The CONOPT and PIVOT statements are not relevant to the interior point algorithm and should not be used.

Use the RESET or SAVE statement to change the name of the output data set. There is only one output data set, the CONOUT= data set. With the RESET statement, you can also indicate the reasons why optimization should stop (for example, you can indicate the maximum number of iterations that can be performed). PROC NETFLOW then has a chance to either execute the next statement, or, if the next statement is one that PROC NETFLOW does not recognize (the next PROC or DATA step in the SAS session), do any allowed
optimization and finish. If no new statement has been submitted, you are prompted for one. Some options of the RESET statement enable you to control aspects of the interior point algorithm. Specifying certain values for these options can reduce the time it takes to solve a problem. Note that any of the RESET options can be specified in the PROC NETFLOW statement.

The RUN statement starts optimization. Once the optimization has started, it runs until the optimum is reached. The RUN statement should be specified at most once.

The QUIT statement immediately stops PROC NETFLOW. The SAVE statement has options that enable you to name the output data set; information about the current solution is put in this output data set. Use the SHOW statement if you want to examine the values of options of other statements. Information about the amount of optimization that has been done and the STATUS of the current solution can also be displayed using the SHOW statement.

The PRINT statement makes PROC NETFLOW display parts of the problem. The way the PRINT statements are specified are identical whether the interior point algorithm or the simplex algorithm is used, however there are minor differences in what is displayed for each arc, nonarc variable or constraint coefficient.

PRINT ARCS produces information on all arcs. PRINT SOME_ARCS limits this output to a subset of arcs. There are similar PRINT statements for nonarc variables and constraints:

```
PRINT NONARCS;
PRINT SOME_NONARCS;
PRINT CONSTRAINTS;
PRINT SOME_CONS;
```

PRINT CON_ARCS enables you to limit constraint information that is obtained to members of a set of arcs and that have nonzero constraint coefficients in a set of constraints. PRINT CON_NONARCS is the corresponding statement for nonarc variables.

For example, an interactive PROC NETFLOW run might look something like this:

```
proc netflow
    intpoint  /* use the Interior Point algorithm */
    arcdatal=data set
    other options;
    variable list specifications; /* if necessary */
    reset options;
    print options; /* look at problem */
    run; /* do the optimization */
    print options; /* look at the optimal solution */
    save options; /* keep optimal solution */
run;
```

If you are interested only in finding the optimal solution, have used SAS variables that have special names in the input data sets, and want to use default settings for everything, then the following statement is all you need.

```
proc netflow intpoint arcdatal= data set ;
```
**Functional Summary: Network Models, Interior Point Algorithm**

The following table outlines the options available for the NETFLOW procedure when the interior point algorithm is being used, classified by function.

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Input Data Set Options:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Arcs input data set</td>
<td>PROC NETFLOW</td>
<td>ARCDATA=</td>
</tr>
<tr>
<td>Nodes input data set</td>
<td>PROC NETFLOW</td>
<td>NODEDATA=</td>
</tr>
<tr>
<td>Constraint input data set</td>
<td>PROC NETFLOW</td>
<td>CONDATA=</td>
</tr>
<tr>
<td><strong>Output Data Set Option:</strong></td>
<td></td>
<td></td>
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<tr>
<td>Constrained solution data set</td>
<td>PROC NETFLOW</td>
<td>CONOUT=</td>
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<tr>
<td><strong>Data Set Read Options:</strong></td>
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<td></td>
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<tr>
<td>CONDATA has sparse data format</td>
<td>PROC NETFLOW</td>
<td>SPARSECONDATA=</td>
</tr>
<tr>
<td>Default constraint type</td>
<td>PROC NETFLOW</td>
<td>DEFCONTYPE=</td>
</tr>
<tr>
<td>Special COLUMN variable value</td>
<td>PROC NETFLOW</td>
<td>TYPEOBS=</td>
</tr>
<tr>
<td>Special COLUMN variable value</td>
<td>PROC NETFLOW</td>
<td>RHSOBS=</td>
</tr>
<tr>
<td>Used to interpret arc and nonarc variable names</td>
<td>PROC NETFLOW</td>
<td>NAMECTRL=</td>
</tr>
<tr>
<td>No new nonarc variables</td>
<td>PROC NETFLOW</td>
<td>SAME_NONARC_DATA=</td>
</tr>
<tr>
<td>No nonarc data in ARCDATA</td>
<td>PROC NETFLOW</td>
<td>ARCS_ONLY_ARCDATA=</td>
</tr>
<tr>
<td>Data for an arc found once in ARCDATA</td>
<td>PROC NETFLOW</td>
<td>ARC_SINGLE_OBS=</td>
</tr>
<tr>
<td>Data for a constraint found once in CONDATA</td>
<td>PROC NETFLOW</td>
<td>CON_SINGLE_OBS=</td>
</tr>
<tr>
<td>Data are grouped, exploited during data read</td>
<td>PROC NETFLOW</td>
<td>NON_REPLIC=</td>
</tr>
<tr>
<td><strong>Problem Size Specification Options:</strong></td>
<td>PROC NETFLOW</td>
<td></td>
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<td>Approximate number of nodes</td>
<td>NNODES=</td>
<td></td>
</tr>
<tr>
<td>Approximate number of arcs</td>
<td>NARCS=</td>
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</tr>
<tr>
<td>Approximate number of nonarc variables</td>
<td>NNAS=</td>
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<tr>
<td>Approximate number of coefficients</td>
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<td></td>
</tr>
<tr>
<td>Approximate number of constraints</td>
<td>NCONS=</td>
<td></td>
</tr>
<tr>
<td><strong>Network Options:</strong></td>
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<tr>
<td>Default arc cost</td>
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<td>Default arc capacity</td>
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<td>Default arc lower flow bound</td>
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<tr>
<td>Network’s only supply node</td>
<td>SOURCE=</td>
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<tr>
<td>SOURCE’s supply capability</td>
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<tr>
<td>Network’s only demand node</td>
<td>SINK=</td>
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<tr>
<td>SINK’s demand</td>
<td>DEMAND=</td>
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</tr>
<tr>
<td>Convey excess supply/demand through network</td>
<td>PROC NETFLOW</td>
<td>THRUNET=</td>
</tr>
<tr>
<td>Find maximal flow between SOURCE and SINK</td>
<td>PROC NETFLOW</td>
<td>MAXFLOW=</td>
</tr>
<tr>
<td>Cost of bypass arc for MAXFLOW problem</td>
<td>PROC NETFLOW</td>
<td>BYPASSDIVIDE=</td>
</tr>
<tr>
<td>Description</td>
<td>Statement</td>
<td>Option</td>
</tr>
<tr>
<td>-----------------------------------------------------------------------------</td>
<td>---------------</td>
<td>-----------------------------</td>
</tr>
<tr>
<td>Find shortest path from <strong>SOURCE</strong> to <strong>SINK</strong></td>
<td>PROC NETFLOW</td>
<td>SHORTPATH</td>
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<tr>
<td><strong>Memory Control Options:</strong></td>
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<tr>
<td>Issue memory usage messages to SAS log</td>
<td>PROC NETFLOW</td>
<td>MEMREP</td>
</tr>
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<td>Number of bytes to use for main memory</td>
<td>PROC NETFLOW</td>
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<td>Proportion of memory for arrays</td>
<td>PROC NETFLOW</td>
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<td>Maximum bytes for a single array</td>
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<td><strong>Interior Point Algorithm Options:</strong></td>
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<tr>
<td>Use interior point algorithm</td>
<td>PROC NETFLOW</td>
<td>INTPOINT</td>
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<tr>
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<tr>
<td>Allowed amount of primal infeasibility</td>
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<td>TOLPINF=</td>
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<tr>
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<tr>
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<tr>
<td>Cut-off tolerance for Cholesky factorization</td>
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<tr>
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<tr>
<td>Step-length multiplier</td>
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<td>Preprocessing type</td>
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<tr>
<td>Print optimization progress on SAS log</td>
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<td>PRINTLEVEL2=</td>
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<tr>
<td>Write optimization time to SAS log</td>
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<td>OPTIM_TIMER</td>
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<tr>
<td><strong>Interior Point Stopping Criteria Options:</strong></td>
<td></td>
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<tr>
<td>Maximum number of interior point iterations</td>
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<td>MAXITERB=</td>
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<tr>
<td>Primal-dual (duality) gap tolerance</td>
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<td>Stop because of complementarity</td>
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<td>STOP_C=</td>
</tr>
<tr>
<td>Stop because of duality gap</td>
<td>RESET</td>
<td>STOP_DG=</td>
</tr>
<tr>
<td>Stop because of $infeas_b$</td>
<td>RESET</td>
<td>STOP_IB=</td>
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<tr>
<td>Stop because of $infeas_c$</td>
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<td>Stop because of $infeas_d$</td>
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<td>AND_STOP_DG=</td>
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<tr>
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<td>Stop because of $infeas_c$</td>
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<td>AND_STOP_IC=</td>
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<tr>
<td>Stop because of $infeas_d$</td>
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<td>Stop because of duality gap</td>
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<td>KEEPGOING_DG=</td>
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<td>KEEPGOING_IB=</td>
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<td>Stop because of complementarity</td>
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<tr>
<td>Stop because of duality gap</td>
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<td>AND_KEEPGOING_DG=</td>
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<td>Stop because of $infeas_b$</td>
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<td>Stop because of $infeas_c$</td>
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<td>Stop because of $infeas_d$</td>
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### Description Statement Option

<table>
<thead>
<tr>
<th>PRINT Statement Options:</th>
<th>Statement</th>
<th>Option</th>
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<tbody>
<tr>
<td>Display everything</td>
<td>PRINT</td>
<td>PROBLEM</td>
</tr>
<tr>
<td>Display arc information</td>
<td>PRINT</td>
<td>ARCS</td>
</tr>
<tr>
<td>Display nonarc variable information</td>
<td>PRINT</td>
<td>NONARCS</td>
</tr>
<tr>
<td>Display variable information</td>
<td>PRINT</td>
<td>VARIABLES</td>
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<tr>
<td>Display constraint information</td>
<td>PRINT</td>
<td>CONSTRAINTS</td>
</tr>
<tr>
<td>Display information for some arcs</td>
<td>PRINT</td>
<td>SOME_ARCS</td>
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<tr>
<td>Display information for some nonarc variables</td>
<td>PRINT</td>
<td>SOME_NONARCS</td>
</tr>
<tr>
<td>Display information for some variables</td>
<td>PRINT</td>
<td>SOME_VARIABLES</td>
</tr>
<tr>
<td>Display information for some constraints</td>
<td>PRINT</td>
<td>SOME_CONS</td>
</tr>
<tr>
<td>Display information for some constraints associated with some arcs</td>
<td>PRINT</td>
<td>CON_ARCS</td>
</tr>
<tr>
<td>Display information for some constraints associated with some nonarc variables</td>
<td>PRINT</td>
<td>CON_NONARCS</td>
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<tr>
<td>Display information for some constraints associated with some variables</td>
<td>PRINT</td>
<td>CON_VARIABLES</td>
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### PRINT Statement Qualifiers:

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<td>Produce a short report</td>
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<tr>
<td>Produce a long report</td>
<td>PRINT</td>
<td>/ LONG</td>
</tr>
<tr>
<td>Display arcs/variables with zero flow/value</td>
<td>PRINT</td>
<td>/ ZERO</td>
</tr>
<tr>
<td>Display arcs/variables with nonzero flow/value</td>
<td>PRINT</td>
<td>/ NONZERO</td>
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### SHOW Statement Options:

<table>
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<tr>
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<tbody>
<tr>
<td>Show problem, optimization status</td>
<td>SHOW</td>
<td>STATUS</td>
</tr>
<tr>
<td>Show network model parameters</td>
<td>SHOW</td>
<td>NETSTMT</td>
</tr>
<tr>
<td>Show data sets that have been or will be created</td>
<td>SHOW</td>
<td>DATASETS</td>
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### Miscellaneous Options:

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<tbody>
<tr>
<td>Infinity value</td>
<td>PROC NETFLOW</td>
<td>INFINITY=</td>
</tr>
<tr>
<td>Scale constraint row, nonarc variable column coefficients, or both</td>
<td>PROC NETFLOW</td>
<td>SCALE=</td>
</tr>
<tr>
<td>Maximization instead of minimization</td>
<td>PROC NETFLOW</td>
<td>MAXIMIZE</td>
</tr>
</tbody>
</table>

### Linear Programming Models: Interior Point Algorithm

By default, the interior point algorithm is used for problems without a network component, that is, a linear programming problem. You do not need to specify the INTPOINT option in the PROC NETFLOW statement (although you will do no harm if you do).

Data for a linear programming problem resembles the data for side constraints and nonarc variables supplied to PROC NETFLOW when solving a constrained network problem. It is also very similar to the data required by the LP procedure.
Mathematical Description of LP

If the network component of NPSC is removed, the result is the mathematical description of the linear programming problem. If an LP has \( g \) variables, and \( k \) constraints, then the formal statement of the problem solved by PROC NETFLOW is

\[
\text{minimize} \quad d^T z \\
\text{subject to} \quad Qz \{\geq, =, \leq\} r \\
\quad m \leq z \leq v
\]

where

- \( d \) is the \( g \times 1 \) objective function coefficient vector
- \( z \) is the \( g \times 1 \) variable value vector
- \( Q \) is the \( k \times g \) constraint coefficient matrix for variables, where \( Q_{i,j} \) is the coefficient of variable \( j \) in the \( i \)th constraint
- \( r \) is the \( k \times 1 \) side constraint right-hand-side vector
- \( m \) is the \( g \times 1 \) variable value lower bound vector
- \( v \) is the \( g \times 1 \) variable value upper bound vector

Interior Point Algorithmic Details

After preprocessing, the linear program to be solved is

\[
\text{minimize} \quad c^T x \\
\text{subject to} \quad Ax = b \\
\quad x \geq 0
\]

This is the primal problem. The matrices \( d, z, \) and \( Q \) of NPSC have been renamed \( c, x, \) and \( A \) respectively, as these symbols are by convention used more, the problem to be solved is different from the original because of preprocessing, and there has been a change of primal variable to transform the LP into one whose variables have zero lower bounds. To simplify the algebra here, assume that variables have infinite bounds, and constraints are equalities. (Interior point algorithms do efficiently handle finite bounds, and it is easy to introduce primal slack variables to change inequalities into equalities.) The problem has \( n \) variables; \( i \) is a variable number, \( k \) is an iteration number, and if used as a subscript or superscript it denotes “of iteration \( k \)”.

There exists an equivalent problem, the dual problem, stated as

\[
\text{maximize} \quad b^T y \\
\text{subject to} \quad A^T y + s = c \\
\quad s \geq 0
\]

where \( y \) are dual variables, and \( s \) are dual constraint slacks.
The interior point algorithm solves the system of equations to satisfy the Karush-Kuhn-Tucker (KKT) conditions for optimality:

\[ Ax = b \]
\[ A^T y + s = c \]
\[ x^T s = 0 \]
\[ x \geq 0 \]
\[ s \geq 0 \]

These are the conditions for feasibility, with the complementarity condition \( x^T s = 0 \) added. Complementarity forces the optimal objectives of the primal and dual to be equal, \( c^T x_{opt} = b^T y_{opt} \), as

\[ 0 = x_{opt}^T s_{opt} = s_{opt}^T x_{opt} = (c - A^T y_{opt})^T x_{opt} \]
\[ = c^T x_{opt} - y_{opt}^T (A x_{opt}) = c^T x_{opt} - b^T y_{opt} \]

Before the optimum is reached, a solution \((x, y, s)\) may not satisfy the KKT conditions:

- Primal constraints may be violated, \( \text{infeas}_c = b - Ax \neq 0 \).
- Dual constraints may be violated, \( \text{infeas}_d = c - A^T y - s \neq 0 \).
- Complementarity may not be satisfied, \( x^T s = c^T x - b^T y \neq 0 \).

This is called the duality gap.

The interior point algorithm works by using Newton’s method to find a direction to move \((\Delta x^k, \Delta y^k, \Delta s^k)\) from the current solution \((x^k, y^k, s^k)\) toward a better solution:

\[ (x^{k+1}, y^{k+1}, s^{k+1}) = (x^k, y^k, s^k) + \alpha(\Delta x^k, \Delta y^k, \Delta s^k) \]

where \(\alpha\) is the step length and is assigned a value as large as possible but \(\leq 1.0\) and not so large that an \(x_i^{k+1}\) or \(s_i^{k+1}\) is “too close” to zero. The direction in which to move is found using the following:

\[ A \Delta x^k = -\text{infeas}_c \]
\[ A^T \Delta y^k + \Delta s^k = -\text{infeas}_d \]
\[ S^k \Delta x^k + X^k \Delta s^k = -X^k S^k e \]

where \(S = \text{diag}(s)\), \(X = \text{diag}(x)\), and \(e\) is a vector with all elements equal to 1.
To greatly improve performance, the third equation is changed to
\[ S^k \Delta x^k + X^k \Delta s^k = -X^k S^k e + \sigma_k \mu_k e \]
where \( \mu_k = 1/n X^k S^k e \), the average complementarity, and \( 0 \leq \sigma_k \leq 1 \).

The effect now is to find a direction in which to move to reduce infeasibilities and to reduce the complementarity toward zero, but if any \( x_i^k \) is too close to zero, it is “nudged out” to \( \mu \), and any \( x_i^k s_i^k \) that is larger than \( \mu \) is “nudged into” \( \mu \). A \( \sigma_k \) close to or equal to 0.0 biases a direction toward the optimum, and a value for \( \sigma_k \) close to or equal to 1.0 “centers” the direction toward a point where all pairwise products \( x_i^k s_i^k = \mu \). Such points make up the central path in the interior. Although centering directions make little, if any, progress in reducing \( \mu \) and moving the solution closer to the optimum, substantial progress toward the optimum can usually be made in the next iteration.

The central path is crucial to why the interior point algorithm is so efficient. This path “guides” the algorithm to the optimum through the interior of feasible space. Without centering, the algorithm would find a series of solutions near each other close to the boundary of feasible space. Step lengths along the direction would be small and many more iterations would probably be required to reach the optimum.

The calculation of the direction is the most time-consuming step of the interior point algorithm. Assume the \( k \)th iteration is being performed, so the subscript and superscript \( k \) can be dropped from the algebra:
\[
A \Delta x = -infeas_c \\
A^T \Delta y + \Delta s = -infeas_d \\
S \Delta x + X \Delta s = -XSe + \sigma \mu e
\]

Rearranging the second equation,
\[ \Delta s = -infeas_d - A^T \Delta y \]

Rearranging the third equation,
\[
\Delta s = X^{-1}(-S \Delta x - XSe + \sigma \mu e) \\
\Delta s = -\Theta \Delta x - Se + X^{-1} \sigma \mu e
\]
where \( \Theta = SX^{-1} \).

Equating these two expressions for \( \Delta s \) and rearranging,
\[
-\Theta \Delta x - Se + X^{-1} \sigma \mu e = -infeas_d - A^T \Delta y \\
-\Theta \Delta x = Se - X^{-1} \sigma \mu e - infeas_d - A^T \Delta y \\
\Delta x = \Theta^{-1}(-Se + X^{-1} \sigma \mu e + infeas_d + A^T \Delta y) \\
\Delta x = \rho + \Theta^{-1} A^T \Delta y
\]
where \( \rho = \Theta^{-1}(-Se + X^{-1} \sigma \mu e + infeas_d) \).
Substituting into the first direction equation,

\[ A\Delta x = -\text{infeas}_c \]
\[ A(\rho + \Theta^{-1}A^T\Delta y) = -\text{infeas}_c \]
\[ A\Theta^{-1}A^T\Delta y = -\text{infeas}_c - A\rho \]
\[ \Delta y = (A\Theta^{-1}A^T)^{-1}(-\text{infeas}_c - A\rho) \]

\( \Theta, \rho, \Delta y, \Delta x \) and \( \Delta s \) are calculated in that order. The hardest term is the factorization of the \((A\Theta^{-1}A^T)\) matrix to determine \( \Delta y \). Fortunately, although the values of \((A\Theta^{-1}A^T)\) are different for each iteration, the locations of the nonzeros in this matrix remain fixed; the nonzero locations are the same as those in the matrix \((AA^T)\). This is due to \(\Theta^{-1} = XS^{-1}\) being a diagonal matrix, which has the effect of merely scaling the columns of \((AA^T)\).

The fact that the nonzeros in \(A\Theta^{-1}A^T\) have a constant pattern is exploited by all interior point algorithms, and is a major reason for their excellent performance. Before iterations begin, \(AA^T\) is examined and its rows and columns are permuted so that during Cholesky Factorization, the number of fill-ins created is smaller. A list of arithmetic operations to perform the factorization is saved in concise computer data structures (working with memory locations rather than actual numerical values). This is called symbolic factorization. During iterations, when memory has been initialized with numerical values, the operations list is performed sequentially. Determining how the factorization should be performed again and again is unnecessary.

The Primal-Dual Predictor-Corrector Interior Point Algorithm

The variant of the interior point algorithm implemented in PROC NETFLOW is a Primal-Dual Predictor-Corrector interior point algorithm. At first, Newton’s method is used to find a direction to move \((\Delta x_{aff}^k, \Delta y_{aff}^k, \Delta s_{aff}^k)\), but calculated as if \(\mu\) is zero, that is, a step with no centering, known as an affine step:

\[ A\Delta x_{aff}^k = -\text{infeas}_c \]
\[ A^T\Delta y_{aff}^k + \Delta s_{aff}^k = -\text{infeas}_d \]
\[ S^k \Delta x_{aff}^k + X^k \Delta s_{aff}^k = -X^k S^k c \]
\[ (x_{aff}^k, y_{aff}^k, s_{aff}^k) = (x^k, y^k, s^k) + \alpha(\Delta x_{aff}^k, \Delta y_{aff}^k, \Delta s_{aff}^k) \]

where \(\alpha\) is the step length as before.

Complementarity \(x^Ts\) is calculated at \((x_{aff}^k, y_{aff}^k, s_{aff}^k)\) and compared with the complementarity at the starting point \((x^k, y^k, s^k)\), and the success of the affine step is gauged. If the affine step was successful in reducing the complementarity by a substantial amount, the need for centering is not great, and the value of \(\sigma_k\) in the following linear system is assigned a value close to zero. If, however, the affine step was unsuccessful, centering would be beneficial, and the value of \(\sigma_k\) in the following linear system is assigned a value closer to 1.0. The value of \(\sigma_k\) is therefore adaptively altered depending on the progress made toward the optimum.
A second linear system is solved to determine a centering vector \((\Delta x_c^k, \Delta y_c^k, \Delta s_c^k)\) from \((x_{aff}^k, y_{aff}^k, s_{aff}^k)\):

\[
\begin{align*}
A\Delta x_c^k &= 0 \\
A^T\Delta y_c^k + \Delta s_c^k &= 0 \\
S^k\Delta x_c^k + X^k\Delta y_c^k &= -X^k S^ke \\
S^k\Delta x_c^k + X^k\Delta s_c^k &= -X_{aff}^k s_{aff}^k e + \sigma_k \mu_k e
\end{align*}
\]

Then

\[
(\Delta x^k, \Delta y^k, \Delta s^k) = (\Delta x_{aff}^k, \Delta y_{aff}^k, \Delta s_{aff}^k) + (\Delta x_c^k, \Delta y_c^k, \Delta s_c^k)
\]

\[
(x^{k+1}, y^{k+1}, s^{k+1}) = (x^k, y^k, s^k) + \alpha (\Delta x^k, \Delta y^k, \Delta s^k)
\]

where, as before, \(\alpha\) is the step length assigned a value as large as possible but not so large that an \(x_i^{k+1}\) or \(s_i^{k+1}\) is “too close” to zero.

Although the Predictor-Corrector variant entails solving two linear system instead of one, fewer iterations are usually required to reach the optimum. The additional overhead of calculating the second linear system is small, as the factorization of the \((A\Theta^{-1}A^T)\) matrix has already been performed to solve the first linear system.

**Stopping Criteria**

There are several reasons why PROC NETFLOW stops interior point optimization. Optimization stops when

- the number of iteration equals MAXITERB\(=m\)
- the relative gap (\(duality\ gap/(c^T x)\)) between the primal and dual objectives is smaller than the value of the PDGAPTOL\(=\) option, and both the primal and dual problems are feasible. Duality gap is defined in the section “Interior Point Algorithmic Details” on page 429.

PROC NETFLOW may stop optimization when it detects that the rate at which the complementarity or duality gap is being reduced is too slow, that is, there are consecutive iterations when the complementarity or duality gap has stopped getting smaller and the infeasibilities, if nonzero, have also stalled. Sometimes, this indicates the problem is infeasible.

The reasons to stop optimization outlined in the previous paragraph will be termed the usual stopping conditions in the following explanation.

However, when solving some problems, especially if the problems are large, the usual stopping criteria are inappropriate. PROC NETFLOW might stop prematurely. If it were allowed to perform additional optimization, a better solution would be found. On other occasions, PROC NETFLOW might do too much work. A sufficiently good solution might be reached several iterations before PROC NETFLOW eventually stops.

You can see PROC NETFLOW’s progress to the optimum by specifying PRINTLEVEL2\(=2\). PROC NETFLOW will produce a table on the SAS log. A row of the table is generated during each iteration and consists of values of the affine step complementarity, the complementarity of the solution for the next iteration, the
total bound infeasibility \( \sum_{i=1}^{n} \text{infeas}_b \) (see the \text{infeas}_b array in the section “Interior Point: Upper Bounds” on page 436), the total constraint infeasibility \( \sum_{i=1}^{m} \text{infeas}_c \) (see the \text{infeas}_c array in the section “Interior Point Algorithmic Details” on page 429), and the total dual infeasibility \( \sum_{i=1}^{n} \text{infeas}_d \) (see the \text{infeas}_d array in the section “Interior Point Algorithmic Details” on page 429). As optimization progresses, the values in all columns should converge to zero.

To tailor stopping criteria to your problem, you can use two sets of parameters: the STOP_x and the KEEPGOING_x parameters. The STOP_x parameters (STOP_C, STOP_DG, STOP_IB, STOP_IC, and STOP_ID) are used to test for some condition at the beginning of each iteration and if met, to stop immediately. The KEEPGOING_x parameters (KEEPGOING_C, KEEPGOING_DG, KEEPGOING_IB, KEEPGOING_IC, and KEEPGOING_ID) are used when PROC NETFLOW would ordinarily stop but does not if some conditions are not met.

For the sake of conciseness, a set of options will be referred to as the part of the option name they have in common followed by the suffix x. For example, STOP_C, STOP_DG, STOP_IB, STOP_IC, and STOP_ID will collectively be referred to as STOP_x.

At the beginning of each iteration, PROC NETFLOW will test whether complementarity is \( \leq \text{STOP}_C \) (provided you have specified a \text{STOP}_C parameter) and if it is, PROC NETFLOW will stop. If the duality gap is \( \leq \text{STOP}_DG \) (provided you have specified a \text{STOP}_DG parameter), PROC NETFLOW will stop immediately. This is also true for the other STOP_x parameters that are related to infeasibilities, \text{STOP}_IB, \text{STOP}_IC, and \text{STOP}_ID.

For example, if you want PROC NETFLOW to stop optimizing for the usual stopping conditions, plus the additional condition, \text{complementarity} \( \leq 100 \) or \text{duality gap} \( \leq 0.001 \), then use

```plaintext
proc netflow stop_c=100 stop_dg=0.001
```

If you want PROC NETFLOW to stop optimizing for the usual stopping conditions, plus the additional condition, \text{complementarity} \( \leq 1000 \) and \text{duality gap} \( \leq 0.001 \) and constraint infeasibility \( \leq 0.0001 \), then use

```plaintext
proc netflow
    and_stop_c=1000 and_stop_dg=0.01 and_stop_ic=0.0001
```

Unlike the STOP_x parameters that cause PROC NETFLOW to stop when any one of them is satisfied, the corresponding AND_STOP_x parameters (AND_STOP_C, AND_STOP_DG, AND_STOP_IB, AND_STOP_IC, and AND_STOP_ID) cause PROC NETFLOW to stop only if all (more precisely, all that are specified) options are satisfied. For example, if PROC NETFLOW should stop when

- \text{complementarity} \( \leq 100 \) or \text{duality gap} \( \leq 0.001 \) or
- \text{complementarity} \( \leq 1000 \) and \text{duality gap} \( \leq 0.001 \) and constraint infeasibility \( \leq 0.000 \)

then use

```plaintext
proc netflow
    stop_c=100 stop_dg=0.001
    and_stop_c=1000 and_stop_dg=0.01 and_stop_ic=0.0001
```

Just as the STOP_x parameters have AND_STOP_x partners, the KEEPGOING_x parameters have AND_KEEPGOING_x partners. The role of the KEEPGOING_x and AND_KEEPGOING_x parameters is to prevent optimization from stopping too early, even though a usual stopping criterion is met.
When PROC NETFLOW detects that it should stop for a usual stopping condition, it performs the following tests:

- It will test whether complementarity is > \texttt{KEEPGOING\_C} (provided you have specified a \texttt{KEEPGOING\_C} parameter), and if it is, PROC NETFLOW will perform more optimization.

- Otherwise, PROC NETFLOW will then test whether the primal-dual gap is > \texttt{KEEPGOING\_DG} (provided you have specified a \texttt{KEEPGOING\_DG} parameter), and if it is, PROC NETFLOW will perform more optimization.

- Otherwise, PROC NETFLOW will then test whether the total bound infeasibility \( \sum_{i=1}^{n} \text{infeas}_b > \texttt{KEEPGOING\_IB} \) (provided you have specified a \texttt{KEEPGOING\_IB} parameter), and if it is, PROC NETFLOW will perform more optimization.

- Otherwise, PROC NETFLOW will then test whether the total constraint infeasibility \( \sum_{i=1}^{m} \text{infeas}_c > \texttt{KEEPGOING\_IC} \) (provided you have specified a \texttt{KEEPGOING\_IC} parameter), and if it is, PROC NETFLOW will perform more optimization.

- Otherwise, PROC NETFLOW will then test whether the total dual infeasibility \( \sum_{i=1}^{n} \text{infeas}_d > \texttt{KEEPGOING\_ID} \) (provided you have specified a \texttt{KEEPGOING\_ID} parameter), and if it is, PROC NETFLOW will perform more optimization.

- Otherwise it will test whether complementarity is > \texttt{AND\_KEEPGOING\_C} (provided you have specified an \texttt{AND\_KEEPGOING\_C} parameter), and the primal-dual gap is > \texttt{AND\_KEEPGOING\_DG} (provided you have specified an \texttt{AND\_KEEPGOING\_DG} parameter), and the total bound infeasibility \( \sum_{i=1}^{n} \text{infeas}_b > \texttt{AND\_KEEPGOING\_IB} \) (provided you have specified an \texttt{AND\_KEEPGOING\_IB} parameter), and the total constraint infeasibility \( \sum_{i=1}^{m} \text{infeas}_c > \texttt{AND\_KEEPGOING\_IC} \) (provided you have specified an \texttt{AND\_KEEPGOING\_IC} parameter) and the total dual infeasibility \( \sum_{i=1}^{n} \text{infeas}_d > \texttt{AND\_KEEPGOING\_ID} \) (provided you have specified an \texttt{AND\_KEEPGOING\_ID} parameter), and if it is, PROC NETFLOW will perform more optimization.

If all these tests to decide whether more optimization should be performed are false, optimization is stopped.

For example,

```plaintext
proc netflow
    stop_c=1000
    and_stop_c=2000 and_stop_dg=0.01
    and_stop_ib=1 and_stop_ic=1 and_stop_id=1
    keepgoing_c=1500
    and_keepgoing_c=2500 and_keepgoing_dg=0.05
    and_keepgoing_ib=1 and_keepgoing_ic=1 and_keepgoing_id=1
```

At the beginning of each iteration, PROC NETFLOW will stop if

- \texttt{complementarity} \leq 1000 or

- \texttt{complementarity} \leq 2000 and duality gap \leq 0.01 and the total bound, constraint, and dual infeasibilities are each \leq 1
When PROC NETFLOW determines it should stop because a usual stopping condition is met, it will stop only if

- complementarity ≤ 1500 or
- complementarity ≤ 2500 and duality gap ≤ 0.05 and the total bound, constraint, and dual infeasibilities are each ≤ 1

**Interior Point: Upper Bounds**

If the LP model had upper bounds (0 ≤ x ≤ u where u is the upper bound vector), then the primal and dual problems, the duality gap, and the KKT conditions would have to be expanded.

The primal linear program to be solved is

\[
\begin{align*}
\text{minimize} & \quad c^T x \\
\text{subject to} & \quad Ax = b \\
& \quad 0 \leq x \leq u
\end{align*}
\]

where 0 ≤ x ≤ u is split into x ≥ 0 and x ≤ u. Let z be primal slack so that x + z = u, and associate dual variables w with these constraints. The interior point algorithm solves the system of equations to satisfy the Karush-Kuhn-Tucker (KKT) conditions for optimality:

\[
\begin{align*}
Ax &= b \\
x + z &= u \\
A^T y + s - w &= c \\
x^T s &= 0 \\
z^T w &= 0 \\
x, s, z, w &\geq 0
\end{align*}
\]

These are the conditions for feasibility, with the complementarity conditions x^T s = 0 and z^T w = 0 added. Complementarity forces the optimal objectives of the primal and dual to be equal, c^T x_{opt} = b^T y_{opt} - u^T w_{opt}, as

\[
0 = z_{opt}^T w_{opt} = (u - x_{opt})^T w_{opt} = u^T w_{opt} - x_{opt}^T w_{opt}
\]

\[
0 = x_{opt}^T s_{opt} = s_{opt}^T x_{opt} = (c - A^T y_{opt} + w_{opt})^T x_{opt} = c^T x_{opt} - b^T y_{opt} + u^T w_{opt}
\]

Before the optimum is reached, a solution (x, y, s, z, w) might not satisfy the KKT conditions:

- Primal bound constraints may be violated, \text{infeas}_b = u - x - z \neq 0.
• Primal constraints may be violated, $\text{infeas}_c = b - Ax \neq 0$.
• Dual constraints may be violated, $\text{infeas}_d = c - A^T y - s + w \neq 0$.
• Complementarity conditions may not be satisfied, $x^T s \neq 0$ and $z^T w \neq 0$.

The calculations of the interior point algorithm can easily be derived in a fashion similar to calculations for when an LP has no upper bounds. See the paper by Lustig, Marsten, and Shanno (1992). An important point is that upper bounds can be handled by specializing the algorithm and not by generating the constraints $x + z = u$ and adding these to the main primal constraints $Ax = b$.

**Getting Started: Linear Programming Models: Interior Point Algorithm**

To solve linear programming problem using PROC NETFLOW, you save a representation of the variables and the constraints in one or two SAS data sets. These data sets are then passed to PROC NETFLOW for solution. There are various forms that a problem’s data can take. You can use any one or a combination of several of these forms.

The ARCDATA= data set contains information about the variables of the problem. Although this data set is called ARCDATA, it contains data for no arcs. Instead, all data in this data set are related to variables. The ARCDATA= data set can be used to specify information about variables, including objective function coefficients, lower and upper value bounds, and names. These data are the elements of the vectors $d$, $m$, and $v$ in problem (NPSC). Data for a variable can be given in more than one observation.

When the data for a constrained network problem is being provided, the ARCDATA= data set always contains information necessary for arcs, their tail and head nodes, and optionally the supply and demand information of these nodes. When the data for a linear programming problem is being provided, none of this information is present, as the model has no arcs. This is the way PROC NETFLOW decides which type of problem it is to solve.

PROC NETFLOW was originally designed to solve models with networks, so an ARCDATA= data set is always expected. If an ARCDATA= data set is not specified, by default the last data set created before PROC NETFLOW is invoked is assumed to be an ARCDATA= data set. However, these characteristics of PROC NETFLOW are not helpful when a linear programming problem is being solved and all data are provided in a single data set specified by the CONDATA= data set, and that data set is not the last data set created before PROC NETFLOW starts. In this case, you must specify that an ARCDATA= data set and a CONDATA= data set are both equal to the input data set. PROC NETFLOW then knows that a linear programming problem is to be solved, and the data reside in one data set.

The CONDATA= data set describes the constraints and their right-hand sides. These data are elements of the matrix $Q$ and the vector $r$.

Constraint types are also specified in the CONDATA= data set. You can include in this data set variable data such as upper bound values, lower value bounds, and objective function coefficients. It is possible to give all information about some or all variables in the CONDATA= data set.

A variable is identified in this data set by its name. If you specify a variable’s name in the ARCDATA= data set, then this name is used to associate data in the CONDATA= data set with that variable.

If you use the dense constraint input format, these variable names are names of SAS variables in the VAR list of the CONDATA= data set.
If you use the sparse constraint input format, these variable names are values of the COLUMN list SAS variable of CONDATA= data set.

When using the interior point algorithm, the execution of PROC NETFLOW has two stages. In the preliminary (zeroth) stage, the data are read from the ARCDATA= data set (if used) and the CONDATA= data set. Error checking is performed. In the next stage, the linear program is preprocessed, then the optimal solution to the linear program is found. The solution is saved in the CONOUT= data set. This data set is also named in the PROC NETFLOW, RESET, and SAVE statements.

See the section “Getting Started: Network Models: Interior Point Algorithm” on page 419 for a fuller description of the stages of the interior point algorithm.

**Introductory Example: Linear Programming Models: Interior Point Algorithm**

Consider the linear programming problem in the section “An Introductory Example” on page 171 in the chapter on the LP procedure.

```sas
data dcon1;
  input _id_ $17.
    a_light a_heavy brega naphthal naphthai
    heatingo jet_1 jet_2
  _type_ $ _rhs_;
datalines;
profit   -175 -165 -205 0 0 0 300 300 max .
naphtha_l_conv .035 .030 .045 -1 0 0 0 0 eq 0
naphtha_i_conv .100 .075 .135 0 -1 0 0 0 eq 0
heating_o_conv .390 .300 .430 0 0 -1 0 0 eq 0
recipe_1 0 0 0 0 .3 .7 -1 0 eq 0
recipe_2 0 0 0 0 .2 0 .8 0 -1 eq 0
available 110 165 80 . . . . . upperbd .
;```

To find the minimum cost solution and to examine all or parts of the optimum, you use PRINT statements.

- **print problem/short;** outputs information for all variables and all constraint coefficients. See Figure 6.19.

- **print some_variables(j:)/short;** is information about a set of variables, (in this case, those with names that start with the character string preceding the colon). See Figure 6.20.

- **print some_cons(recipe_1)/short;** is information about a set of constraints (here, that set only has one member, the constraint called recipe_1). See Figure 6.21.

- **print con_variables(_,brega)/short;** lists the constraint information for a set of variables (here, that set only has one member, the variable called brega). See Figure 6.22.

- **print con_variables(recipe:,n: jet_1)/short;** coefficient information for those in a set of constraints belonging to a set of variables. See Figure 6.23.
proc netflow
    arcdatal=dcon1
    condata=dcon1
    conout=solutn1;
run;
print problem/short;
print some_variables(j:)/short;
print some_cons(recipe_1)/short;
print con_variables(_all_,,brega)/short;
print con_variables(recipe:,n: jet_1)/short;

The following messages, which appear on the SAS log, summarize the model as read by PROC NETFLOW and note the progress toward a solution:

NOTE: ARCDATA (or the last data set created if ARCDATA was not specified) and
       CONDATA are the same data set WORK.DCON1 so will assume a Linear
       Programming problem is to be solved.
NOTE: Number of variables= 8 .
NOTE: Number of <= constraints= 0 .
NOTE: Number of == constraints= 5 .
NOTE: Number of >= constraints= 0 .
NOTE: Number of constraint coefficients= 18 .
NOTE: After preprocessing, number of <= constraints= 0 .
NOTE: After preprocessing, number of == constraints= 0 .
NOTE: After preprocessing, number of >= constraints= 0 .
NOTE: The preprocessor eliminated 5 constraints from the problem.
NOTE: The preprocessor eliminated 18 constraint coefficients from the problem.
NOTE: After preprocessing, number of variables= 0 .
NOTE: The preprocessor eliminated 8 variables from the problem.
NOTE: The optimum has been determined by the Preprocessor.
NOTE: Objective= 1544 .
NOTE: The data set WORK.SOLUTN1 has 8 observations and 6 variables.

---

Figure 6.19 PRINT PROBLEM/SHORT;

The NETFLOW Procedure

<table>
<thead>
<tr>
<th><em>N</em> <em>NAME</em></th>
<th><em>OBJFN</em> <em>UPPERBD</em> <em>LOWERBD</em> <em>VALUE</em></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>a_heavy -165 165 0 0</td>
</tr>
<tr>
<td>2</td>
<td>a_light -175 110 0 110</td>
</tr>
<tr>
<td>3</td>
<td>brega -205 80 0 80</td>
</tr>
<tr>
<td>4</td>
<td>heatingo  0 99999999 0 77.3</td>
</tr>
<tr>
<td>5</td>
<td>jet_1   300 99999999 0 60.65</td>
</tr>
<tr>
<td>6</td>
<td>jet_2   300 99999999 0 63.33</td>
</tr>
<tr>
<td>7</td>
<td>naphthal  0 99999999 0 21.8</td>
</tr>
<tr>
<td>8</td>
<td>naphthal  0 99999999 0 7.45</td>
</tr>
</tbody>
</table>
### Figure 6.19 continued

The NETFLOW Procedure

```
<table>
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<th><em>rhs</em></th>
<th>NAME</th>
<th>OBJFN</th>
<th>UPPERBD</th>
<th>LOWERBD</th>
<th>VALUE</th>
<th>COEF</th>
</tr>
</thead>
<tbody>
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<td>0</td>
<td>110</td>
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<td>0</td>
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<tr>
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<td>EQ</td>
<td>0</td>
<td>brega</td>
<td>-205</td>
<td>80</td>
<td>0</td>
<td>80</td>
</tr>
<tr>
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<td>EQ</td>
<td>0</td>
<td>heatingo</td>
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<td>110</td>
<td>0</td>
<td>77.3</td>
</tr>
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<td>EQ</td>
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<td>110</td>
<td>0</td>
<td>110</td>
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<tr>
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<td>EQ</td>
<td>0</td>
<td>aheavy</td>
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<td>165</td>
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<td>165</td>
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<td>0</td>
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<td>0</td>
<td>80</td>
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<td>80</td>
<td>0</td>
<td>80</td>
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<td>80</td>
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<td>0</td>
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<td>-205</td>
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<td>80</td>
</tr>
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<td>80</td>
<td>0</td>
<td>80</td>
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<td>-205</td>
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<td>80</td>
</tr>
<tr>
<td>18</td>
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<td>0</td>
<td>jet_2</td>
<td>300</td>
<td>99999999</td>
<td>0</td>
<td>63.33</td>
</tr>
</tbody>
</table>
```

### Figure 6.20
PRINT SOME_VARIABLES(J:)/SHORT;

The NETFLOW Procedure

```
<table>
<thead>
<tr>
<th>N</th>
<th>NAME</th>
<th>OBJFN</th>
<th>UPPERBD</th>
<th>LOWERBD</th>
<th>VALUE</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>jet_1</td>
<td>300</td>
<td>99999999</td>
<td>0</td>
<td>60.65</td>
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<td>2</td>
<td>jet_2</td>
<td>300</td>
<td>99999999</td>
<td>0</td>
<td>63.33</td>
</tr>
</tbody>
</table>
```

### Figure 6.21
PRINT SOME_CONS(RECIPE_1)/SHORT;

The NETFLOW Procedure

```
<table>
<thead>
<tr>
<th>N_id</th>
<th>type</th>
<th><em>rhs</em></th>
<th>NAME</th>
<th>OBJFN</th>
<th>UPPERBD</th>
<th>LOWERBD</th>
<th>VALUE</th>
<th>COEF</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>recipe_1</td>
<td>EQ</td>
<td>0</td>
<td>naphthai</td>
<td>0</td>
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<td>21.8</td>
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<td>recipe_1</td>
<td>EQ</td>
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<td>heatingo</td>
<td>0</td>
<td>99999999</td>
<td>0</td>
<td>77.3</td>
</tr>
<tr>
<td>3</td>
<td>recipe_1</td>
<td>EQ</td>
<td>0</td>
<td>jet_1</td>
<td>300</td>
<td>99999999</td>
<td>0</td>
<td>60.65</td>
</tr>
</tbody>
</table>
```

### Figure 6.22
PRINT CON_VARIABLES(_ALL_,BREGA)/SHORT;

The NETFLOW Procedure

```
<table>
<thead>
<tr>
<th>N_id</th>
<th>type</th>
<th><em>rhs</em></th>
<th>NAME</th>
<th>OBJFN</th>
<th>UPPERBD</th>
<th>LOWERBD</th>
<th>VALUE</th>
<th>COEF</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>heating_o_conv</td>
<td>EQ</td>
<td>0</td>
<td>brega</td>
<td>-205</td>
<td>80</td>
<td>0</td>
<td>80</td>
</tr>
<tr>
<td>2</td>
<td>naphtha_i_conv</td>
<td>EQ</td>
<td>0</td>
<td>brega</td>
<td>-205</td>
<td>80</td>
<td>0</td>
<td>80</td>
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<tr>
<td>3</td>
<td>naphtha_i_conv</td>
<td>EQ</td>
<td>0</td>
<td>brega</td>
<td>-205</td>
<td>80</td>
<td>0</td>
<td>80</td>
</tr>
</tbody>
</table>
```
Unlike PROC LP, which displays the solution and other information as output, PROC NETFLOW saves the optimum in output SAS data sets you specify. For this example, the solution is saved in the SOLUTN1 data set. It can be displayed with PROC PRINT as

```sas
proc print data=solutn1;
  var _name_ _objfn_ _upperbd _lowerbd _value_ _fcost_;
  sum _fcost_;
  title3 'LP Optimum';
run;
```

Notice, in the CONOUT=SOLUTN1 (Figure 6.24), the optimal value through each variable in the linear program is given in the variable named _VALUE_, and the cost of value for each variable is given in the variable _FCOST_.

The same model can be specified in the sparse format as in the following scon2 data set. This format enables you to omit the zero coefficients.

```sas
data scon2;
  format _type_ $8. _col_ $8. _row_ $16. ;
  input _type_ $ _col_ $ _row_ $ _coef_;
datalines;
max . . profit .
2 a_light . -175 110 0 110.00 19250
2 a_light 1 . 165 165 0 0.00 0
3 brega . -205 80 0 80.00 16400
4 heatingo 0 99999999 0 77.30 0
5 jet_1 . 300 99999999 0 60.65 18195
6 jet_2 . 300 99999999 0 63.33 18999
7 naphtha1 0 99999999 0 21.80 0
7 naphtha1 . 0 99999999 0 7.45 0
8 naphthal . 0 99999999 0 0.00 0
upperbd . available .
```

The format of the variables in the CONOUT=SOLUTN1 output is shown in Figure 6.23.
Chapter 6: The NETFLOW Procedure

To find the minimum cost solution, invoke PROC NETFLOW (note the SPARSECONDATA option which must be specified) as follows:

```plaintext
to find the minimum cost solution, invoke PROC NETFLOW (note the SPARSECONDATA option which must be specified) as follows:

proc netflow
   sparsecondata
   condata=scon2
   conout=solutn2;
run;
```

A data set that is used as an ARCDATA= data set can be initialized as follows:

```plaintext
data vars3;
   input _name_ $ profit available;
   datalines;
   a_heavy  -165 165
   a_light   -175 110
   brega     -205  80
   heatingo  0   .
   jet_1     300 .
   jet_2     300 .
   naphthai  0   .
   naphthal  0   .
;
```

The following CONDATA= data set is the original dense format CONDATA= dcon1 data set with the variable information removed. (You could have left some or all of that information in CONDATA as PROC NETFLOW “merges” data, but doing that and checking for consistency uses time.)

```plaintext
data vars3;
   input _name_ $ profit available;
   datalines;
   a_heavy  -165 165
   a_light   -175 110
   brega     -205  80
   heatingo  0   .
   jet_1     300 .
   jet_2     300 .
   naphthai  0   .
   naphthal  0   .
;```
It is important to note that it is now necessary to specify the \texttt{MAXIMIZE} option; otherwise, PROC NETFLOW will optimize to the minimum (which, incidentally, has a total objective = -3539.25). You must indicate that the SAS variable \texttt{profit} in the \texttt{ARCDATA=vars3} data set has values that are objective function coefficients, by specifying the \texttt{OBJFN} statement. The \texttt{UPPERBD} must be specified as the SAS variable \texttt{available} that has as values upper bounds.

The \texttt{ARCDATA=vars3} data set can become more concise by noting that the model variables heatingo, naphthai, and naphthal have zero objective function coefficients (the default) and default upper bounds, so those observations need not be present.

The \texttt{CONDATA=dcon3} data set can become more concise by noting that all the constraints have the same type (eq) and zero (the default) rhs values. This model is a good candidate for using the \texttt{DEFCONTYPE=} option.

The \texttt{DEFCONTYPE=} option can be useful not only when all constraints have the same type as is the case here, but also when most constraints have the same type, or if you prefer to change the default type from $\leq$ to $=$ or $\geq$. The essential constraint type data in \texttt{CONDATA=} data set is that which overrides the \texttt{DEFCONTYPE=} type you specified.
data dcon4;
   input _id_ $17.
      a_light a_heavy brega naphthal naphthai
        heatingo jet_1 jet_2;
   datalines;
   naphtha_l_conv .035 .030 .045 -1 0 0 0 0
   naphtha_i_conv .100 .075 .135 0 -1 0 0 0
   heating_o_conv .390 .300 .430 0 0 -1 0 0
   recipe_1 0 0 0 0 .3 .7 -1 0
   recipe_2 0 0 .2 0 .8 0 -1 ;
proc netflow
   maximize defcontype=eq
      ardata=vars3
      condata=dcon3
      conout=solutn3;
   objfn profit;
   upperbd available;
run;
Several different ways of using an ARCDATA= data set and a sparse format CONDATA= data set for this linear program follow. The following CONDATA= data set is the result of removing the profit and available data from the original sparse format CONDATA=scon2 data set.

data scon5;
   format _type_ $8. _col_ $8. _row_ $16. ;
   input _type_ $ _col_ $ _row_ $ _coef_;
   datalines;
   eq . napha_l_conv .
   eq . napha_i_conv .
   eq . heating_oil_conv .
   eq . recipe_1 .
   eq . recipe_2 .
   . a_light napha_l_conv .035
   . a_light napha_i_conv .100
   . a_light heating_oil_conv .390
   . a_heavy napha_l_conv .030
   . a_heavy napha_i_conv .075
   . a_heavy heating_oil_conv .300
   . brega napha_l_conv .045
   . brega napha_i_conv .135
   . brega heating_oil_conv .430
   . naphthal napha_l_conv -1
   . naphthal recipe_2 .2
   . naphthal napha_i_conv -1
   . naphthal recipe_1 .3
   . heatingo heating_oil_conv -1
   . heatingo recipe_1 .7
   . heatingo recipe_2 .8
   . jet_1 recipe_1 -1
   . jet_2 recipe_2 -1 ;
The CONDATA=scon5 data set can become more concise by noting that all the constraints have the same type (eq) and zero (the default) rhs values. Use the DEFCONTYPE= option again. Once the first 5 observations of the CONDATA=scon5 data set are removed, the _type_ SAS variable has values that are missing in the remaining observations. Therefore, this SAS variable can be removed.

```sas
proc netflow
maximize
    sparsecondata
    arcdata=vars3 /* or arcdata=vars4 */
    condata=scon5
    conout=solutn5;
    objfn profit;
    upperbd available;
run;
```

```sas
data scon6;
    input _col_ $ _row_ & $16. _coef_;
    datalines;
    a_light napha_l_conv .035
    a_light napha_i_conv .100
    a_light heating_oil_conv .390
    a_heavy napha_l_conv .030
    a_heavy napha_i_conv .075
    a_heavy heating_oil_conv .300
    brega napha_l_conv .045
    brega napha_i_conv .135
    brega heating_oil_conv .430
    naphthal napha_l_conv -1
    naphthal recipe_2 .2
    naphthal napha_i_conv -1
    naphthal recipe_1 .3
    heatingo heating_oil_conv -1
    heatingo recipe_1 .7
    heatingo recipe_2 .8
    jet_1 recipe_1 -1
    jet_2 recipe_2 -1;
    proc netflow
maximize
    defcontype=eq
    sparsecondata
    arcdata=vars3 /* or arcdata=vars4 */
    condata=scon6
    conout=solutn6;
    objfn profit;
    upperbd available;
run;
```
Interactivity: Linear Programming Models: Interior Point algorithm

PROC NETFLOW can be used interactively. You begin by giving the PROC NETFLOW statement, and you must specify the CONDATA= data set. If necessary, specify the ARCDATA= data set.

The variable lists should be given next. If you have variables in the input data sets that have special names (for example, a variable in the ARCDATA= data set named _COST_ that has objective function coefficients as values), it may not be necessary to have many or any variable lists.

The PRINT, QUIT, SAVE, SHOW, RESET, and RUN statements follow and can be listed in any order. The QUIT statements can be used only once. The others can be used as many times as needed.

The CONOPT and PIVOT are not relevant to the interior point algorithm and should not be used.

Use the RESET or SAVE statement to change the name of the output data set. There is only one output data set, the CONOUT= data set. With the RESET statement, you can also indicate the reasons why optimization should stop, (for example, you can indicate the maximum number of iterations that can be performed). PROC NETFLOW then has a chance to either execute the next statement or, if the next statement is one that PROC NETFLOW does not recognize (the next PROC or DATA step in the SAS session), do any allowed optimization and finish. If no new statement has been submitted, you are prompted for one. Some options of the RESET statement enable you to control aspects of the interior point algorithm. Specifying certain values for these options can reduce the time it takes to solve a problem. Note that any of the RESET options can be specified in the PROC NETFLOW statement.

The RUN statement starts optimization. Once the optimization has started, it runs until the optimum is reached. The RUN statement should be specified at most once.

The QUIT statement immediately stops PROC NETFLOW. The SAVE statement has options that enable you to name the output data set; information about the current solution is saved in this output data set. Use the SHOW statement if you want to examine the values of options of other statements. Information about the amount of optimization that has been done and the STATUS of the current solution can also be displayed using the SHOW statement.

The PRINT statement instructs PROC NETFLOW to display parts of the problem. The ways the PRINT statements are specified are identical whether the interior point algorithm or the simplex algorithm is used; however, there are minor differences in what is displayed for each variable or constraint coefficient.

PRINT VARIABLES produces information on all arcs. PRINT SOME_VARIABLES limits this output to a subset of variables. There are similar PRINT statements for constraints:

```
PRINT CONSTRAINTS;
PRINT SOME_CONS;
```

PRINT CON_VARIABLES enables you to limit constraint information that is obtained to members of a set of variables that have nonzero constraint coefficients in a set of constraints.

For example, an interactive PROC NETFLOW run might look something like this:

```
proc netflow
  condata=data set
  other options;
  variable list specifications; /* if necessary */
  reset options;
```
If you are interested only in finding the optimal solution, have used SAS variables that have special names in
the input data sets, and want to use default setting for everything, then the following statement is all you need:

```
proc netflow condata= data set ;
```

**Functional Summary: Linear Programming Models: Interior Point Algorithm**

The following table outlines the options available for the NETFLOW procedure when the interior point
algorithm is being used to solve a linear programming problem, classified by function.

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Input Data Set Options:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Arcs input data set</td>
<td>PROC NETFLOW</td>
<td>ARCDATA=</td>
</tr>
<tr>
<td>Constraint input data set</td>
<td>PROC NETFLOW</td>
<td>CONDATA=</td>
</tr>
<tr>
<td><strong>Output Data Set Option:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Solution data set</td>
<td>PROC NETFLOW</td>
<td>CONOUT=</td>
</tr>
<tr>
<td><strong>Data Set Read Options:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CONDATA has sparse data format</td>
<td>PROC NETFLOW</td>
<td>SPARSECONDATA</td>
</tr>
<tr>
<td>Default constraint type</td>
<td>PROC NETFLOW</td>
<td>DEFCONTYPE=</td>
</tr>
<tr>
<td>Special COLUMN variable value</td>
<td>PROC NETFLOW</td>
<td>TYPEOBS=</td>
</tr>
<tr>
<td>Special COLUMN variable value</td>
<td>PROC NETFLOW</td>
<td>RHSOBS=</td>
</tr>
<tr>
<td>Data for a constraint found once in CONDATA</td>
<td>PROC NETFLOW</td>
<td>CON_SINGLE_OBS</td>
</tr>
<tr>
<td>Data for a coefficient found once in CONDATA</td>
<td>PROC NETFLOW</td>
<td>NON_REPLIC=</td>
</tr>
<tr>
<td>Data are grouped, exploited during data read</td>
<td>PROC NETFLOW</td>
<td>GROUPED=</td>
</tr>
<tr>
<td><strong>Problem Size Specification Options:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Approximate number of variables</td>
<td>PROC NETFLOW</td>
<td>NNAS=</td>
</tr>
<tr>
<td>Approximate number of coefficients</td>
<td>PROC NETFLOW</td>
<td>NCOEFS=</td>
</tr>
<tr>
<td>Approximate number of constraints</td>
<td>PROC NETFLOW</td>
<td>NCONS=</td>
</tr>
<tr>
<td><strong>Network Options:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Default variable objective function coefficient</td>
<td>PROC NETFLOW</td>
<td>DEFCOST=</td>
</tr>
<tr>
<td>Default variable upper bound</td>
<td>PROC NETFLOW</td>
<td>DEFCAPACITY=</td>
</tr>
<tr>
<td>Default variable lower bound</td>
<td>PROC NETFLOW</td>
<td>DEFMINFLOW=</td>
</tr>
<tr>
<td><strong>Memory Control Options:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Issue memory usage messages to SAS log</td>
<td>PROC NETFLOW</td>
<td>MEMREP</td>
</tr>
</tbody>
</table>
### Chapter 6: The NETFLOW Procedure

<table>
<thead>
<tr>
<th>Description</th>
<th>Statement</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of bytes to use for main memory</td>
<td>PROC NETFLOW</td>
<td>BYTES=</td>
</tr>
<tr>
<td>Proportion of memory for arrays</td>
<td>PROC NETFLOW</td>
<td>COREFACTOR=</td>
</tr>
<tr>
<td>maximum bytes for a single array</td>
<td>PROC NETFLOW</td>
<td>MAXARRAYBYTES=</td>
</tr>
</tbody>
</table>

#### Interior Point Algorithm Options:

- Use interior point algorithm: PROC NETFLOW INTOPOINT
- Factorization method: RESET FACT_METHOD=
- Allowed amount of dual infeasibility: RESET TOLDINF=
- Allowed amount of primal infeasibility: RESET TOLPINF=
- Allowed total amount of dual infeasibility: RESET TOLTOTDINF=
- Allowed total amount of primal infeasibility: RESET TOLTOTPINF=
- Cut-off tolerance for Cholesky factorization: RESET CHOLTINYTOL=
- Density threshold for Cholesky processing: RESET DENSETHR=
- Step-length multiplier: RESET PDSTEPMULT=
- Preprocessing type: RESET PRSLTYPE=
- Print optimization progress on SAS log: RESET PRINTLEVEL2=
- Write optimization time to SAS log: RESET OPTIM_TIMER

#### Interior Point Stopping Criteria Options:

- Maximum number of interior point iterations: RESET MAXITERB=
- Primal-dual (duality) gap tolerance: RESET PDGAPTOL=
- Stop because of complementarity: RESET STOP_C=
- Stop because of duality gap: RESET STOP_DG=
- Stop because of infeasibility b: RESET STOP_IB=
- Stop because of infeasibility c: RESET STOP_IC=
- Stop because of infeasibility d: RESET STOP_ID=
- Stop because of complementarity: RESET AND_STOP_C=
- Stop because of duality gap: RESET AND_STOP_DG=
- Stop because of infeasibility b: RESET AND_STOP_IB=
- Stop because of infeasibility c: RESET AND_STOP_IC=
- Stop because of infeasibility d: RESET AND_STOP_ID=
- Stop because of complementarity: RESET KEEPGOING_C=
- Stop because of duality gap: RESET KEEPGOING_DG=
- Stop because of infeasibility b: RESET KEEPGOING_IB=
- Stop because of infeasibility c: RESET KEEPGOING_IC=
- Stop because of infeasibility d: RESET KEEPGOING_ID=

#### PRINT Statement Options:

- Display everything: PRINT PROBLEM
- Display variable information: PRINT VARIABLES
What Is a Generalized Network?

It is well known that in a pure network the sum of flows entering an arc is equal to the sum of flows leaving it. However, in a generalized network there may be a gain or a loss as flow traverses an arc. Each arc has a multiplier to represent these gains or losses.

To illustrate what is meant, consider the network shown in Figure 6.25.
You can think of this as a network representing a supply node ($N_1$), trans-shipment nodes ($N_2, N_3$), and demand nodes ($N_4, N_5$). As indicated by the legend, the number below a node represents its supdem value. Above each arc is its name, followed by the arc cost and arc multiplier in parentheses. The lower and upper bounds on flow allowed to enter an arc are represented in square brackets below it. When no bounds are specified (as in Figure 6.25), they are assumed to be $[0, 99999999]$.

Now consider the node pair ($N_1, N_2$). The information on arc $A_1$ says that it costs 2 per unit of flow to traverse it, and for each unit of flow entering the arc, four units get accumulated at node $N_2$. The corresponding component in the objective function is two times the flow through arc $A_1$ leaving node $N_1$, not two times the flow through arc $A_1$ arriving at node $N_2$.

A commonly encountered example of a generalized network is in power generation: as electricity is transmitted over wires, there is some unavoidable loss along the way. This loss is represented by a multiplier less than 1.0.

Arc multipliers need not always be less than 1.0. For instance, in financial models, a flow through an arc could represent money in a bank account earning interest. In that case, the arc would have a multiplier greater than 1.0.

Generalized networks offer convenience when flow commodity changes. For a pure network, care must be taken to ensure the flow commodity is the same throughout the entire model. For example, in a model to determine how sugar should be grown, refined, packaged, and sold, the flow commodity might be kilograms of sugar, and all numerical parameters throughout the model (all supplies, arc costs, capacities, bounds, demands, etc.) must be in terms of kilograms of sugar. Some arcs might correspond to the movement of
5-kilogram bags of sugar. If a generalized network formulation is used, the arc that represents packaging could be given a multiplier of 0.2, so flow through arcs that convey flow corresponding to bags of sugar will have arc costs in terms of dollars per bag, and capacities, bounds, demands, etc. in terms of number of bags.

In the following sections we describe in detail how to provide data for arc multipliers, how to deal with excess supply or demand in pure and generalized networks, how to model maximum flow problems, and how to handle networks with missing supply and demand nodes, and ranges on supply and demand.

---

**How to Specify Data for Arc Multipliers**

If you are familiar with using the NETFLOW procedure to solve pure network problems, then solving generalized network problems is fairly simple. You just need to provide the additional data for the arc multipliers. Arcs by default have a multiplier of 1.0, so you only need to provide arc multipliers that are not equal to 1.0. You can specify the arc multiplier data in either or both of the ARCDATA= and CONDATA= data sets. The procedure scans the SAS variables in the ARCDATA= data set, and if it finds a name _MULT_ (or a similar name with letters of different case), then it assumes that the SAS variable contains data for arc multipliers. CONDATA= is scanned for special type values that indicates data are arc multipliers.

The rest of this section describes the various ways in which you can specify data for the arc multipliers. The network in Figure 6.25 is used for illustration.

**All Arc Multiplier Data in the ARCDATA= Data Set**

You can specify all the arc multiplier data in the ARCDATA= data set. The following code creates the input SAS data sets:

```sas
/* All Arc Multiplier Data in the ARCDATA= Data Set */

data nodes;
  input _node_ $ _sd_ ;
datalines;
  N1 22
  N4 -30
  N5 -10
;)

data arcs;
  input _from_ $ _to_ $ _cost_ _mult_ ;
datalines;
  N1 N2 2 4
  N1 N3 10 0.5
  N2 N4 0 1
  N2 N5 7 3
  N3 N2 12 2
```

---

*Generalized Networks:*

* How to Specify Data for Arc Multipliers
  *
  ************************************************************
  *  Generalized Networks:                                  *
  *  How to Specify Data for Arc Multipliers                 *
  *  courageous                                              *
  ************************************************************

/* All Arc Multiplier Data in the ARCDATA= Data Set */

data nodes;
  input _node_ $ _sd_ ;
datalines;
  N1 22
  N4 -30
  N5 -10
;)

data arcs;
  input _from_ $ _to_ $ _cost_ _mult_ ;
datalines;
  N1 N2 2 4
  N1 N3 10 0.5
  N2 N4 0 1
  N2 N5 7 3
  N3 N2 12 2
```
Chapter 6: The NETFLOW Procedure

Let us first look at the data for this problem. There is a variable named _mult_ in the ARCDATA= data set, so PROC NETFLOW assumes it represents the arc multipliers. The SAS variable _sd_ represents the supdem value of a node. A positive or missing S value indicates supply, and a negative or missing D value indicates demand.

The optimal solution can be obtained from the CONOUT= data set. Note that you need to specify the CONOUT= data set even if the network has no side constraints; you cannot use the ARCOUT= data set.

You can use the following SAS code to run PROC NETFLOW:

```sas
title1 'The NETFLOW Procedure';
proc netflow
  bytes = 100000
  nodedata = nodes
  arcdata = arcs
  conout = solution;
run;
```

The optimal solution is displayed in Output 6.26.

![Output of the Example Problem](image-url)

**The NETFLOW Procedure**

<table>
<thead>
<tr>
<th>Obs</th>
<th>from</th>
<th>to</th>
<th>CAPAC</th>
<th>LO</th>
<th>mult</th>
<th>SUPPLY</th>
<th>DEMAND</th>
<th>FLOW</th>
<th>FCOST</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>N1</td>
<td>N2</td>
<td>2</td>
<td>4</td>
<td>22</td>
<td>.</td>
<td>6.0000</td>
<td>12.000</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>N3</td>
<td>N2</td>
<td>12</td>
<td>2</td>
<td>.</td>
<td>3.0000</td>
<td>36.000</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>N1</td>
<td>N3</td>
<td>10</td>
<td>0.5</td>
<td>22</td>
<td>16.0000</td>
<td>160.000</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>N2</td>
<td>N4</td>
<td>0</td>
<td>1</td>
<td>.</td>
<td>30</td>
<td>30.0000</td>
<td>0.0000</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>N5</td>
<td>N4</td>
<td>55</td>
<td>0.9</td>
<td>.</td>
<td>30</td>
<td>-0.0000</td>
<td>-0.0000</td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>N2</td>
<td>N5</td>
<td>7</td>
<td>3</td>
<td>.</td>
<td>10</td>
<td>0.0000</td>
<td>0.0000</td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>N3</td>
<td>N5</td>
<td>10</td>
<td>2</td>
<td>.</td>
<td>10</td>
<td>5.0000</td>
<td>50.000</td>
<td></td>
</tr>
</tbody>
</table>

All Arc Multiplier Data in CONDATA= Data Set

Let us now solve the same problem, but with all the arc multipliers specified in the CONDATA= data set. The CONDATA= data set can have either a sparse format or a dense format. The following code illustrates the dense format representation:

```sas
data arcs1b;
  input _from_ $ _to_ $ _cost_;
datalines;
N1 N2 2
N1 N3 10
N2 N4 0
N2 N5 7
N3 N2 12
N3 N5 10
N5 N4 55
;```
data MUdense;
    input _type_ $ N1_N2 N1_N3 N2_N4 N2_N5 N3_N2 N3_N5 N5_N4;
  datalines;
    mult 4.0 0.5 1.0 0.3 2.0 2.0 0.9
  ;

You can use the following SAS code to obtain the solution:

    proc netflow
      gennet
      nodedata = nodes
      arcdata = arcs1b
      condata = MUdense
      conout = soln1b;
    run;

Note that a new option, GENNET, has been specified in the call to PROC NETFLOW. This option is necessary when the network is generalized and there are no arc multiplier data in the ARCDATA= data set. If this option is not specified, then the procedure assumes that the network is pure (without arc multipliers) and sets up the excess supply node and the excess arcs.

The sparse format representation is as follows:

data MUsparse;
    input _type_ $ _col_ $ _coef_;
  datalines;
    mult N1_N2 4.0
    mult N1_N3 0.5
    mult N2_N4 1.0
    mult N2_N5 0.3
    mult N3_N2 2.0
    mult N3_N5 2.0
    mult N5_N4 0.9
  ;

You can use the following SAS code to obtain the solution:

    proc netflow
      gennet sparsecondata
      nodedata = nodes
      arcdata = arcs1b
      condata = MUsparse
      conout = soln1c;
    run;

Note that you need to specify the SPARSECONDATA option in the call to PROC NETFLOW.
Arc Multiplier Data in Both ARCDATA= and CONDATA= Data Sets

You can also provide some multiplier data in the ARCDATA= data set, and the rest in the CONDATA= data set as follows:

```sas
data arcs1c;
  input _from_ $ _to_ $ _cost_ _mult_;
  datalines;
  N1 N2  2  4
  N1 N3 10 .5
  N2 N4  0 .
  N2 N5  7 .
  N3 N2 12 .
  N3 N5  10 .
  N5 N4 55 .
;
data MUdense1;
  input _type_ $ N2_N4 N2_N5 N3_N2 N3_N5 N5_N4;
  datalines;
  mult 1.0 0.3 2.0 2.0 0.9
  ;
```

The procedure merges the data when all the input data sets have been read.

Specifying Arc Multiplier Data Using a List Statement

You can also specify the name of the multiplier variable in the list statement MULT, or MULTIPLIER. For example, if the name of the variable is `lossrate`, then use the following:

```sas
proc netflow
  ...
  mult lossrate;
run;
```

You may also use MULT, GAIN, or LOSS (or similar names with letters of different case) as a value of the TYPE list SAS variable.

Using the New EXCESS= Option in Pure Networks: NETFLOW Procedure

In this section we describe how to use the new EXCESS= option to solve a wide variety of problems. These include the following:

- networks with excess supply or demand
- networks containing nodes with unknown supply and demand values
- maximum flow problems
- networks with nodes having supply and demand ranges
Handling Excess Supply or Demand

The \texttt{supdem} value of a node can be specified in the following formats:

- in the \texttt{NODEDATA=} data set, using the \texttt{_supdem_} or \texttt{_sd_} list variable
- in the \texttt{ARCDATA=} data set, using the \texttt{_SUPPLY_} and \texttt{_DEMAND_} list variables

If there is only one supply (demand) node, then use the \texttt{SOURCE=} (\texttt{SINK=}) option to refer to it, and use the \texttt{SUPPLY=} (\texttt{DEMAND=}) option to specify its \texttt{supdem} value.

To ensure feasibility, there are different methods by which flow can be added to or drained from the network. This extra flow can be added to or drained from the network at either the supply or demand nodes. The new \texttt{EXCESS=} option is used to address such instances.

For pure networks there are two valid values that can be specified for the \texttt{EXCESS=} option: \texttt{EXCESS=ARCS} and \texttt{EXCESS=SLACKS}.

\texttt{EXCESS=ARCS} is the default value. An extra node, referred to as \texttt{_EXCESS_}, is added to the network and is connected to the actual network by “excess” arcs.

- If total supply exceeds total demand, then \texttt{_EXCESS_} is an extra demand node with demand equal to total supply minus total demand.
  - If the \texttt{THRUNET} option is specified, the “excess” arcs are directed away from any actual demand node (even nodes with missing D demand) and toward \texttt{_EXCESS_}.
  - Or else if there are demand nodes with missing D demands, the “excess” arcs are directed away from these nodes and toward \texttt{_EXCESS_}.
  - Or else the “excess” arcs are directed away from the supply nodes and toward \texttt{_EXCESS_}.

- If the total demand exceeds the total supply, then \texttt{_EXCESS_} is an extra supply node with supply equal to the total demand minus the total supply.
  - If the \texttt{THRUNET} option is specified, the “excess” arcs are directed away from \texttt{_EXCESS_} and toward any actual supply node (even nodes with missing S supply.)
  - Or else if there are supply nodes with missing S supplies, the “excess” arcs are directed away from \texttt{_EXCESS_} and toward these nodes.
  - Or else the “excess” arcs are directed away from \texttt{_EXCESS_} and toward the demand nodes.

The node \texttt{_EXCESS_} and the associated arcs are created to ensure that the problem presented to the optimizer has a total supply equal to the total demand. They are neither displayed in the optimal solution nor saved in any output SAS data set.

If \texttt{EXCESS=SLACKS} is specified, then slack variables are created for some flow conservation constraints instead of having the node \texttt{_EXCESS_} and “excess” arcs. The flow conservation constraint (which was an inequality) is now converted to an equality with the addition of the slack variable. Alternatively, you can think of these slacks as arcs with one of their end nodes missing — they are directed from a node but not toward any other node (or directed toward a node but not from any other node). Figure 6.27 presents a clearer picture of this.
Chapter 6: The NETFLOW Procedure

Figure 6.27  EXCESS=SLACKS, Total Supply Exceeds Total Demand, THRUNET Not Specified, No Nodes with Missing Demand

NOTE: When you specify EXCESS=SLACKS, the interior point solver is used. The output SAS data set needs to be specified by the CONOUT= data set, even if side constraints are not present. Also, when you specify the EXCESS=SLACKS option, the size of the model submitted to the optimizer is smaller than with EXCESS=ARCS since it no longer has the _EXCESS_ node and the excess arcs associated with it.

Handling Missing Supply and Demand Simultaneously

Another new feature in the NETFLOW procedure is that it enables you to specify a network containing both nodes with missing S supply values and nodes with missing D demand values. This feature is a powerful modeling tool, and we show in the later sections how to use it to formulate and solve maximum flow problems and network models with range constraints on supply and demand.

Whenever a network is detected to have both nodes with missing S supply values and nodes with missing D demand values, a special value of the EXCESS= option is assigned internally by the procedure; any value you specify for the EXCESS= option is overridden. The procedure solves the problem in the following manner:

- Nodes with positive (negative) supdem values supply (demand) the exact amount of flow specified.
- Nodes with missing S supply (missing D demand) values supply (demand) flow quantities that are determined by optimization.
Figure 6.28 displays how the slack variables are set up by the procedure internally. These variables are neither a part of the input data set nor displayed in any output SAS data set or printed output.

**Figure 6.28** A Network with Both Missing S Supply and Missing D Demand Nodes

---

**Maximum Flow Problems**

The maximum flow problem (MFP) can be stated as follows: Given a directed graph $G = (N, A)$ with capacity $u_{ij} \geq 0$ on each arc $(i, j) \in A$, a source node $s$ and a sink node $t$, find the maximum flow that can go from $s$ to $t$, while obeying the flow conservation constraints at each node. You can solve such problems using the MAXFLOW option in the call to PROC NETFLOW.

Ordinarily many, if not all, arcs in an MFP network have capacities, and it is common that these arcs have zero costs. However, the NETFLOW procedure enables you to have nonzero costs to influence the optimal solution in cases where multiple maximum flow patterns are known to exist.

The following two subsections explain the role of the EXCESS= option in solving pure and generalized maximum flow problems.

**The EXCESS=ARCS Option**

Consider a maximum flow problem involving a pure network. Assume that you do not explicitly specify the EXCESS= option (the EXCESS=ARCS option is used by the procedure by default). The NETFLOW procedure sets up the problem in the following manner:

1. The source node is assigned a `supdem` value equal to `INFINITY-1`.
2. The sink node is assigned a `supdem` value equal to $-(INFINITY-1)$. 
3. If there is no existing arc between the source node and the sink node, an arc called the bypass arc directed from the source node to the sink node is added.

4. If there is an existing arc between the source node and the sink node, a dummy node is used to break up what would have been a single bypass arc: source $\rightarrow$ sink gets transformed into two arcs, source $\rightarrow$ dummy $\rightarrow$ sink.

5. If you are maximizing, then the cost of the bypass arc(s) is equal to $-1$ if all other arcs have zero costs; otherwise the cost of the bypass arc(s) is equal to $-(\text{INFINITY} / \text{BYPASSDIV})$.

6. If you are minimizing, then the cost of the bypass arc(s) is equal to $1$ if all other arcs have zero costs; otherwise the cost of the bypass arc(s) is equal to $\text{INFINITY} / \text{BYPASSDIV}$.

You can specify the value of the INFINITY= option in the procedure statement, or you can use the default value of 99999999. You can also specify the BYPASSDIV= option. The default value for the BYPASSDIV= option is 100.

This scenario is depicted in Figure 6.29. Since the cost of the bypass arc is unattractive, the optimization process minimizes the flow through it, thereby maximizing the flow through the real network. See the first subsection in Example 6.10 for an illustration.

Figure 6.29  Pure Maximum Flow Problem, EXCESS=ARCS Option Specified

This method of setting up a maximum flow problem does come with a drawback. It is likely to produce incorrect results if the following occur:

- the maximum flow is greater than INFINITY$-1$, or
- the cost of the bypass arc is insufficiently unattractive to ensure that the entire flow traverses the real network and not through the bypass arc

Additionally, numbers of large magnitude can cause problems during optimization, including numerical instability and loss of precision. In the next section, we explain how to overcome these difficulties when solving maximum flow problems.
The EXCESS=SLACKS Option

Assume you have a pure maximum flow problem and you specify the EXCESS=SLACKS option. The NETFLOW procedure sets up the problem in the following manner:

- The source node is assigned a missing S supply value.
- The sink node is assigned a missing D demand value.

Since this network contains a node with a missing S supply value and a node with a missing D demand value, we have a situation similar to the one described in the section “Handling Missing Supply and Demand Simultaneously” on page 456. Both of these nodes have slack variables. Usually, slack variables have zero objective function coefficients, but because the MAXFLOW option is specified, one of the slack variables must be attractive enough to make it worthwhile for flow to traverse the network. Figure 6.30 presents the scenario clearly.

If you are maximizing, then the objective function coefficient of the slack variable associated with the sink node is $1$ if all other arcs have zero costs. Otherwise it is $\frac{\text{INFINITY}}{\text{BYPASSDIV}}$. If you are minimizing, then the objective function coefficient of the slack variable associated with the sink node is $1$ if all arcs have zero costs. Otherwise it is $\text{INFINITY} / \text{BYPASSDIV}$. See the second subsection in Example 6.10 for an illustration of the EXCESS=SLACKS option in pure maximum flow problems.

**NOTE:** If the MAXFLOW option is not specified, these slack variables assume zero objective function coefficients, and the MFP may not be solved properly.

**Figure 6.30** Pure Maximum Flow Problem with EXCESS=SLACKS Option Specified

When you use the MAXFLOW option, the procedure sets up the problem in such a way that maximum flow traverses the network. This enables you to transform certain types of problems into maximum flow problems. One such instance is when you have a network where the amount of flow that is supplied or demanded falls within a range of values. The following section describes how to solve such problems.
Handling Supply and Demand Ranges

Consider the scenario depicted by Figure 6.31, where the supply and demand nodes have ranges; i.e., the amounts they can supply or demand are constrained to be within certain lower and upper bounds.

To model this situation, you first need to add a supply node with missing S supply value (the Y node in Figure 6.32) and a demand node with missing D demand value (the Z node in Figure 6.32). The bounds on the supply and demand nodes get transformed into upper/lower bounds on the arcs that connect them to nodes Y and Z, respectively. It might be necessary to have costs for these arcs to make it worthwhile for flow to traverse them, and subsequently to traverse the actual network. In practice, these costs represent procurement costs, profit from sales, etc.
You could set up all your network models in this fashion, not only in scenarios in which there are supply and demand ranges. For instance, this modeling technique could be used under the following conditions:

- if there are no ranges
- if the network is generalized, and you do not know whether to specify `EXCESS=SUPPLY` or `EXCESS=DEMAND`
- if some of the lower bounds are zero or some capacities are infinite, in which case you simply do not specify the capacity

### Using the New EXCESS= Option in Generalized Networks: NETFLOW Procedure

In this section we briefly describe how to use the new `EXCESS=` option in generalized networks. We provide simple scenarios to enable you to understand what happens internally in the solver when different values for the `EXCESS=` option are specified.

### Total Supply and Total Demand: How Generalized Networks Differ from Pure Networks

For a pure network, it is easy to check for excess supply or excess demand. If the sum of positive `supdem` values exceeds (is less than) the absolute value of the sum of negative `supdem` values, then the network has excess supply (demand).

However, in a generalized network you need to specify whether the network should have excess supply or excess demand. To do that you can specify the option `EXCESS=SUPPLY` or `EXCESS=DEMAND`, respectively.
Although the total supply and total demand of a generalized network can be determined, you may not know beforehand if excess flow must be added to, removed from, or left unused by the network. For example, consider a simple network, one consisting of two nodes, A and B, connected by a single arc, A —> B. Suppose the supply of node A is 10 and the demand of node B is 30. If this is a pure network, then the network solved must be either _EXCESS_ —> A —> B if the THRUNET option is not specified and the flow through the arc between A and B is 30 units, or A —> B <— _EXCESS_ if the THRUNET option is specified and the flow through the arc from A to B is 10 units. _EXCESS_ is the name of an extra node that is set up by the procedure behind the scenes, and in both cases it would have a supply capacity of 20 units, which is the flow through the excess arc. However, if the network is generalized, and the arc from A to B has a multiplier of 3.0, then the flow through the arc from A to B would be 10 units, and the network would be feasible without any excess node and arcs. Indeed, no excess node and arcs would be created, even though total supply and total demand are unequal. Therefore, once the NETFLOW procedure detects that the network has arc multipliers that are not 1.0, it might not set up the excess node and the excess arcs.

In Example 6.11 we illustrate the use of the EXCESS= option to solve generalized networks that have total supply equal to total demand, but have arcs with varying multipliers.

In the section “Handling Missing Supply and Demand Simultaneously” on page 456, we discuss the case where a network has both nodes with missing S supply values and nodes with missing D demand values. In the next two subsections we analyze scenarios where a network has nodes with either missing S supply values or missing D demand values, but not both.

---

**The EXCESS=SUPPLY Option**

If you specify the EXCESS=SUPPLY option, then there are three possible scenarios to deal with:

**Case 1: No Node with Missing D Demand, THRUNET Not Specified (see Figure 6.33)**

Drain the excess supply from all supply nodes.

**Figure 6.33** Nodes with Missing S Supply, THRUNET Specified
Case 2: Some Nodes with Missing D Demand, THRUNET Not Specified (see Figure 6.34)
Drain the excess supply from nodes that have missing D demand values. If a node has a missing D demand value, then the amount it demands is determined by optimization. For a demand node with negative supdem value, that value negated is equal to the sum of flows on all actual arcs directed toward that node.

![Figure 6.34 Nodes with Missing D Demand](image)

Case 3: THRUNET Specified (see Figure 6.35)
Drain the excess supply from all demand nodes. If a node has a negative supdem value, that value negated is the lower bound on the sum of flows on all actual arcs directed toward that node. If a node has a missing D demand value, then the amount it demands is determined by optimization.

![Figure 6.35 Nodes with Missing D Demand, THRUNET Specified](image)
The EXCESS=DEMAND Option

If you specify the EXCESS=DEMAND option, then there are three possible scenarios to deal with:

Case 1: No Node with Missing S Supply, THRUNET Not Specified (see Figure 6.36)
Supply the excess demand to all demand nodes directly.

![Figure 6.36](image)

Case 2: Some Nodes with Missing S Supply, THRUNET Not Specified (see Figure 6.37)
Supply the excess demand by the nodes that have a missing S supply value. If a node has a missing S supply value, then the amount it supplies is determined by optimization. For a supply node with a positive supdem value, that value is equal to the sum of flows on all actual arcs directed away from that node.
The EXCESS=DEMAND Option

Case 3: THRUNET Specified (see Figure 6.38)
Supply the excess demand by all supply nodes. If a node has a positive supdem value, that value is the lower bound on the sum of flows on all actual arcs directed away from that node. If a node has a missing S supply value, then the amount it supplies is determined by optimization.

Figure 6.38 Nodes with Missing S Supply, THRUNET Specified
Examples: NETFLOW Procedure

The following examples illustrate some of the capabilities of PROC NETFLOW. These examples, together with the other SAS/OR examples, can be found in the SAS sample library.

Example 6.1: Shortest Path Problem

Whole pineapples are served in a restaurant in London. To ensure freshness, the pineapples are purchased in Hawaii and air freighted from Honolulu to Heathrow in London. The network diagram in Figure 6.39 outlines the different routes that the pineapples could take.

The cost to freight a pineapple is known for each arc. You can use PROC NETFLOW to determine what routes should be used to minimize total shipping cost. The shortest path is the least cost path that all pineapples should use. The SHORTPATH option indicates this type of network problem.

Figure 6.39 Pineapple Routes: Shortest Path Problem

The SINK= option value HEATHROW LONDON is not a valid SAS variable name so it must be enclosed in single quotes. The TAILNODE list variable is FFROM. Because the name of this variable is not _TAIL_ or _FROM_, the TAILNODE list must be specified in the PROC NETFLOW statement. The HEADNODE list must also be explicitly specified because the variable that belongs to this list does not have the name _HEAD_ or _TO_, but is TTO.
title 'Shortest Path Problem';
title2 'How to get Hawaiian Pineapples to a London Restaurant';
data aircost1;
    input ffrom$13. tto$15. _cost_;
datalines;
Honolulu   Chicago    105
Honolulu   San Francisco    75
Honolulu   Los Angeles    68
Chicago     Boston      45
Chicago     New York     56
San Francisco   Boston    71
San Francisco   New York    48
San Francisco   Atlanta   63
Los Angeles   New York     44
Los Angeles   Atlanta     57
Boston       Heathrow London    88
New York       Heathrow London    65
Atlanta       Heathrow London    76
;
proc netflow
    shortpath
    sourcenode=Honolulu
    sinknode='Heathrow London' /* Quotes for embedded blank */
    ARCDATA=aircost1
    arcout=spath;
    tail     ffrom;
    head     tto;
run;
proc print data=spath;
    sum _fcost_;
run;
The length at optimality is written to the SAS log as

NOTE: Number of nodes= 8 .
NOTE: Number of arcs= 13 .
NOTE: Number of iterations performed (neglecting any constraints)= 5 .
NOTE: Of these, 3 were degenerate.
NOTE: Optimum (neglecting any constraints) found.
NOTE: Shortest path = 177 .
NOTE: The data set WORK.SPATH has 13 observations and 13 variables.

The output data set ARCOU=SPATH in Output 6.1.1 shows that the best route for the pineapples is from Honolulu to Los Angeles to New York to Heathrow London.
Example 6.2: Minimum Cost Flow Problem

You can continue to use the pineapple example in Example 6.1 by supposing that the airlines now stipulate that no more than 350 pineapples per week can be handled in any single leg of the journey. The restaurant uses 500 pineapples each week. How many pineapples should take each route between Hawaii and London?

You will probably have more minimum cost flow problems because they are more general than maximal flow and shortest path problems. A shortest path formulation is no longer valid because the sink node does not demand one flow unit.
All arcs have the same capacity of 350 pineapples. Because of this, the **DEFCAPACITY**= option can be specified in the PROC NETFLOW statement, rather than having a **CAPACITY** list variable in **ARCDATA=aircost1**. You can have a **CAPACITY** list variable, but the value of this variable would be 350 in all observations, so using the **DEFCAPACITY**= option is more convenient. You would have to use the **CAPACITY** list variable if arcs had differing capacities. You can use both the **DEFCAPACITY**= option and a **CAPACITY** list variable.

There is only one supply node and one demand node. These can be named in the **SOURCE=** and **SINK=** options. **DEMAND=500** is specified for the restaurant demand. There is no need to specify **SUPPLY=500**, as this is assumed.

```sas
title 'Minimum Cost Flow Problem';
title2 'How to get Hawaiian Pineapples to a London Restaurant';
proc netflow
defcapacity=350
 sourcenode='Honolulu'
sinknode='Heathrow London' / * Quotes for embedded blank */
demand=500
 arcdata=aircost1
 arcout=arcout1
 nodeout=nodeout1;
tail ffrom;
head tto;
set future1;
run;
quit;

proc print data=arcout1; sum _fcost_; run;

proc print data=nodeout1;
run;
```

The following notes appear on the SAS log:

```
NOTE: SOURCENODE was assigned supply of the total network demand= 500 .
NOTE: Number of nodes= 8 .
NOTE: Number of supply nodes= 1 .
NOTE: Number of demand nodes= 1 .
NOTE: Total supply= 500 , total demand= 500 .
NOTE: Number of arcs= 13 .
NOTE: Number of iterations performed (neglecting any constraints)= 8 .
NOTE: Of these, 4 were degenerate.
NOTE: Optimum (neglecting any constraints) found.
NOTE: Minimal total cost= 93750 .
NOTE: The data set WORK.ARCOUT1 has 13 observations and 13 variables.
NOTE: The data set WORK.NODEOUT1 has 9 observations and 10 variables.
```
The routes and numbers of pineapples in each arc can be seen in the output data set `ARCOOUT=arcout1` in Output 6.2.1. `NODEOUT=NODEOUT1` is shown in Output 6.2.2.
### Output 6.2.1  ARCOUT=ARCOUT1

<table>
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<tr>
<th>Obs</th>
<th>ffrom</th>
<th>tto</th>
<th><em>cost</em></th>
<th><em>CAPAC</em></th>
<th><em>LO</em></th>
<th><em>SUPPLY</em></th>
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<tr>
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<td>.</td>
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<td>350</td>
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<td>500</td>
<td>.</td>
</tr>
<tr>
<td>6</td>
<td>Boston</td>
<td>Heathrow London</td>
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<td>350</td>
<td>0</td>
<td>.</td>
<td>500</td>
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<tr>
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<td>New York</td>
<td>Heathrow London</td>
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<td>0</td>
<td>.</td>
<td>500</td>
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<td>Heathrow London</td>
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<td>0</td>
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<td>.</td>
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<th><em>RCOST</em></th>
<th><em>ANUMB</em></th>
<th><em>TNUMB</em></th>
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</table>

### Output 6.2.2  NODEOUT=NODEOUT1

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<th>Obs</th>
<th>NODE</th>
<th>SUPDEM</th>
<th>DUAL</th>
<th><em>NNUMB</em></th>
<th><em>PRED</em></th>
<th><em>TRAV</em></th>
<th>SCESS</th>
<th><em>ARCID</em></th>
<th><em>FLOW</em></th>
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</tr>
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<td>6</td>
<td>2</td>
<td>150</td>
<td>2</td>
</tr>
</tbody>
</table>
Chapter 6: The NETFLOW Procedure

Example 6.3: Using a Warm Start

Suppose that the airlines state that the freight cost per pineapple in flights that leave Chicago has been reduced by 30. How many pineapples should take each route between Hawaii and London? This example illustrates how PROC NETFLOW uses a warm start.

In Example 6.2, the RESET statement of PROC NETFLOW is used to specify FUTURE1. A NODEOUT= data set is also specified. The warm start information is saved in the arcout1 and nodeout1 data sets.

In the following DATA step, the costs, reduced costs, and flows in the arcout1 data set are saved in variables called oldcost, oldflow, and oldfc. These variables form an implicit ID list in the following PROC NETFLOW run and will appear in ARCOUT=arcout2. Thus, it is easy to compare the previous optimum and the new optimum.

```sas
title 'Minimum Cost Flow Problem - Warm Start';
title2 'How to get Hawaiian Pineapples to a London Restaurant';
data aircost2;
  set arcout1;
  oldcost=_cost_; oldflow=_flow_; oldfc=_fcost_; 
  if ffrom='Chicago' then _cost_=_cost_-30;
proc netflow
  warm
  arcdata=aircost2
  nodedata=nodeout1
  arcout=arcout2;
  tail ffrom;
  head tto;
  run;
quit;
```

```sas
proc print data=arcout2;
  var ffrom tto _cost_ oldcost _capac_ _lo_ _flow_ oldflow _fcost_ oldfc;
  sum _fcost_ oldfc;
run;
```

The following notes appear on the SAS log:

- NOTE: Number of nodes= 8.
- NOTE: Number of supply nodes= 1.
- NOTE: Number of demand nodes= 1.
- NOTE: The greater of total supply and total demand= 500.
- NOTE: Number of iterations performed (neglecting any constraints)= 3.
- NOTE: Of these, 1 were degenerate.
- NOTE: Optimum (neglecting any constraints) found.
- NOTE: Minimal total cost= 93150.
- NOTE: The data set WORK.ARCOUT2 has 13 observations and 16 variables.
Example 6.4: Production, Inventory, Distribution Problem

Example 6.4 through Example 6.8 use data from a company that produces two sizes of televisions in order to illustrate variations in the use the NETFLOW procedure. The company makes televisions with a diagonal screen measurement of either 19 inches or 25 inches. These televisions are made between March and May at both of the company’s two factories. Each factory has a limit on the total number of televisions of each screen dimension that can be made during those months.

The televisions are distributed to one of two shops, stored at the factory where they were made and sold later, or shipped to the other factory. Some sets can be used to fill backorders from the previous months. Each shop demands a number of each type of TV for the months of March through May. The following network in Figure 6.41 illustrates the model. Arc costs can be interpreted as production costs, storage costs, backorder penalty costs, inter-factory transportation costs, and sales profits. The arcs can have capacities and lower flow bounds.
There are two similarly structured networks, one for the 19-inch televisions and the other for the 25-inch screen TVs. The minimum cost production, inventory, and distribution plan for both TV types can be determined in the same run of PROC NETFLOW. To ensure that node names are unambiguous, the names of nodes in the 19-inch network have suffix _1, and the node names in the 25-inch network have suffix _2.

The FUTURE1 option is specified because further processing could be required. Information concerning an optimal solution is retained so it can be used to warm start later optimizations. Warm start information is mostly in variables named _NUMB_, _PRED_, _TRAV_, _SCESS_, _ARCID_, and _FBQ_ and in observations for nodes named _EXCESS_ and _ROOT_, that are in the NODEOUT=NODE2 output data set. (PROC NETFLOW uses similar devices to store warm start information in the DUALOUT= data set when the FUTURE2 option is specified.) Variables _ANUMB_ and _TNUMB_ and observations for arcs directed from or toward a node called _EXCESS_ are present in ARCOOUT=arc1. (PROC NETFLOW uses similar devices to store warm start information in the CONOUT= data set when the FUTURE2 option is specified.)

The following code shows how to save the problem data in data sets and solve the model with PROC NETFLOW.

```plaintext
title 'Minimum Cost Flow problem';
title2 'Production Planning/Inventory/Distribution';
data node0;
   input _node_ $ _supdem_;
datalines;
fact1_1  1000
fact2_1  850
fact1_2  1000
fact2_2  1500
shop1_1 -900
```
data arc0;
  input _tail_ $ _head_ $ _cost_ _capac_ _lo_ diagonal factory
    key_id $10. mth_made $ _name&_17. ;
  datalines;
  fact1_1  f1_mar_1  127.9 500 50 19 1 production March prod f1 19 mar
  fact1_1  f1_apr_1  78.6 600 50 19 1 production April prod f1 19 apl
  fact1_1  f1_may_1  95.1 400 50 19 1 production May
  f1_mar_1  f1_apr_1  15 50 . 19 1 storage March.
  f1_apr_1  f1_may_1  12 50 . 19 1 storage April.
  f1_apr_1  f1_mar_1  28 20 . 19 1 backorder April back f1 19 apl
  f1_may_1  f1_apr_1  28 20 . 19 1 backorder May back f1 19 may
  f1_mar_1  f2_mar_1  11 . . 19 . f1_to_2 March.
  f1_apr_1  f2_apr_1  11 . . 19 . f1_to_2 April.
  f1_apr_1  f2_mar_1  16 . . 19 . f1_to_2 May.
  f1_mar_1  shop1_1  -327.65 250 . 19 1 sales March.
  f1_apr_1  shop1_1  -300 250 . 19 1 sales April.
  f1_may_1  shop1_1  -285 250 . 19 1 sales May.
  f1_mar_1  shop2_1  -362.74 250 . 19 1 sales March.
  f1_apr_1  shop2_1  -300 250 . 19 1 sales April.
  f1_may_1  shop2_1  -245 250 . 19 1 sales May.
  fact2_1  f2_mar_1  88.0 450 35 19 2 production March prod f2 19 mar
  fact2_1  f2_apr_1  62.4 480 35 19 2 production April prod f2 19 apl
  fact2_1  f2_may_1 133.8 250 35 19 2 production May.
  f2_mar_1  f2_apr_1  18 30 . 19 2 storage March.
  f2_apr_1  f2_may_1  17 30 . 19 2 storage April.
  f2_may_1  f2_apr_1  17 30 . 19 2 backorder April back f2 19 apl
  f2_apr_1  f2_may_1  17 30 . 19 2 backorder May back f2 19 may
  f2_mar_1  f2_apr_1  25 30 . 19 2 backorder March.
  f2_mar_1  f2_apr_1  10 40 . 19 . f2_to_1 March.
  f2_apr_1  f2_may_1  13 40 . 19 . f2_to_1 May.
  f2_may_1  shop1_1  -297.4 250 . 19 2 sales March.
  f2_apr_1  shop1_1  -290 250 . 19 2 sales April.
  f2_may_1  shop1_1  -292 250 . 19 2 sales May.
  f2_mar_1  shop2_1  -272.7 250 . 19 2 sales March.
  f2_apr_1  shop2_1  -312 250 . 19 2 sales April.
  f2_may_1  shop2_1  -299 250 . 19 2 sales May.
  fact1_2  f1_mar_2  217.9 400 40 25 1 production March prod f1 25 mar
  fact1_2  f1_apr_2  174.5 550 50 25 1 production April prod f1 25 apl
  fact1_2  f1_may_2 133.3 350 40 25 1 production May.
  f1_mar_2  f1_apr_2  20 40 . 25 1 storage March.
  f1_apr_2  f1_may_2  18 40 . 25 1 storage April.
  f1_apr_2  f1_may_2  32 60 . 25 1 backorder April back f1 25 apl
  f1_may_1  f1_apr_2  41 60 . 25 1 backorder May back f1 25 may
  f1_may_2  f1_apr_2  23 . . 25 . f1_to_2 March.
  f1_apr_2  f2_apr_2  23 . . 25 . f1_to_2 April.
  f1_mar_2  f2_apr_2  26 . . 25 . f1_to_2 May.
  f1_mar_2  shop1_2  -559.76 . . 25 1 sales March.
  f1_apr_2  shop1_2  -524.28 . . 25 1 sales April.
  f1_may_2  shop1_2  -475.02 . . 25 1 sales May.

Example 6.4: Production, Inventory, Distribution Problem  •  475
proc netflow
    nodedata=node0
    arcdatal=arc0;
set future1
    nodeout=node2
    arcout=arc1;
run;
quit;

options ls=80 ps = 50;
proc print data=arc1 heading=h width=min;
var _tail_ _head_ _cost_ _capac_ _lo_ _name_ _supply_ _demand_ _flow_ _fcost_;
sum _fcost_; 
run;

options ls=80 ps = 50;
proc print data=arc1 heading=h width=min;
var _rcost_ _anumb_ _tnumb_ _status_ diagonal factory key_id mth_made;
run;

proc print data=node2;
run;
The following notes appear on the SAS log:

NOTE: Number of nodes= 20 .
NOTE: Number of supply nodes= 4 .
NOTE: Number of demand nodes= 4 .
NOTE: Total supply= 4350 , total demand= 4150 .
NOTE: Number of arcs= 64 .
NOTE: Number of iterations performed (neglecting any constraints)= 75 .
NOTE: Of these, 1 were degenerate.
NOTE: Optimum (neglecting any constraints) found.
NOTE: Minimal total cost= -1281110.35 .
NOTE: The data set WORK.ARC1 has 68 observations and 18 variables.
NOTE: The data set WORK.NODE2 has 22 observations and 10 variables.

The solution is given in the NODEOUT=node2 and ARCOUT=arc1 data sets. In the ARCOUT= data set, shown in Output 6.4.1 and Output 6.4.2, the variables diagonal, factory, key_id, and mth_made form an implicit ID list. The diagonal variable has one of two values, 19 or 25. factory also has one of two values, 1 or 2, to denote the factory where either production or storage occurs, from where TVs are either sold to shops or satisfy backorders. PRODUCTION, STORAGE, SALES, and BACKORDER are values of the key_id variable.

Other values of this variable, F1_TO_2 and F2_TO_1, are used when flow through arcs represents the transportation of TVs between factories. The mth_made variable has values MARCH, APRIL, and MAY, the months when TVs that are modeled as flow through an arc were made (assuming that no televisions are stored for more than one month and none manufactured in May are used to fill March backorders).

These ID variables can be used after the PROC NETFLOW run to produce reports and perform analysis on particular parts of the company’s operation. For example, reports can be generated for production numbers for each factory; optimal sales figures for each shop; and how many TVs should be stored, used to fill backorders, sent to the other factory, or any combination of these, for TVs with a particular screen, those produced in a particular month, or both.
Output 6.4.1  ARCOUT=ARC1

<table>
<thead>
<tr>
<th>Obs</th>
<th>tail</th>
<th>head</th>
<th>cost</th>
<th>capac</th>
<th>lo</th>
<th>name</th>
<th>supply</th>
<th>demand</th>
<th>flow</th>
<th>fcost</th>
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Example 6.4: Production, Inventory, Distribution Problem

Output 6.4.2 continued

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Output 6.4.3 NODEOUT=NODE2

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Example 6.5: Using an Unconstrained Solution Warm Start

This example examines the effect of changing some of the arc costs. The backorder penalty costs are increased by twenty percent. The sales profit of 25-inch TVs sent to the shops in May is increased by thirty units. The backorder penalty costs of 25-inch TVs manufactured in May for April consumption is decreased by thirty units. The production cost of 19- and 25-inch TVs made in May are decreased by five units and twenty units, respectively. How does the optimal solution of the network after these arc cost alterations compare with the optimum of the original network? If you want to use the warm start facilities of PROC NETFLOW to solve this undefined problem, specify the WARM option. Notice that the FUTURE1 option was specified in the last PROC NETFLOW run.

The following SAS statements produce the new NODEOUT= and ARCOUT= data sets.

```sas
title 'Minimum Cost Flow problem- Unconstrained Warm Start';
title2 'Production Planning/Inventory/Distribution';
data arc2;
set arc1;
oldcost=_cost_;
oldfc=_fcost_;
oldflow=_flow_;;
if key_id='backorder'
   then _cost_= _cost_*1.2;
else if _tail_='f2_may_2' then _cost_= _cost_-30;
if key_id='production' & mth_made='May' then
   if diagonal=19 then _cost_= _cost_-5;
   else _cost_= _cost_-20;
proc netflow
   warm future1
   nodedata=node2
   arcdata=arc2
   nodeout=node3
   arcout=arc3;
run;
quit;
options ls=80 ps = 50;
proc print data=arc3 heading=h width=min;
sum _fcost_;
var _tail_ _head_ _capac_ _lo_ _supply_ _demand_ _name_ _cost_ _flow_ _fcost_;
run;
```

```sas
options ls=80 ps = 50;
proc print data=arc3 heading=h width=min;
sum oldfc;
var oldcost oldflow oldfc diagonal factory key_id mth_made _anumb_ _tnumb_;
run;
```

```sas
proc print data=node3;
run;
```
Example 6.5: Using an Unconstrained Solution Warm Start

The following notes appear on the SAS log:

NOTE: Number of nodes= 21.
NOTE: Number of supply nodes= 4.
NOTE: Number of demand nodes= 5.
NOTE: The greater of total supply and total demand= 4350.
NOTE: Number of iterations performed (neglecting any constraints)= 8.
NOTE: Of these, 0 were degenerate.
NOTE: Optimum (neglecting any constraints) found.
NOTE: Minimal total cost= -1285086.45.
NOTE: The data set WORK.ARC3 has 68 observations and 21 variables.
NOTE: The data set WORK.NODE3 has 22 observations and 10 variables.

The solution is displayed in Output 6.5.1 and Output 6.5.2. The associated NODEOUT data set is in Output 6.5.3.
### Output 6.5.1 ARCOUT=ARC3

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## Example 6.5: Using an Unconstrained Solution Warm Start

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Example 6.5: Using an Unconstrained Solution Warm Start

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<td>27</td>
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<tr>
<td>22</td>
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<td>-999999837.92</td>
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<td>16</td>
<td>8</td>
<td>62</td>
<td>110</td>
<td>59</td>
</tr>
</tbody>
</table>
The manufacturer of Gizmo chips, which are parts needed to make televisions, can supply only 2600 chips to factory 1 and 3750 chips to factory 2 in time for production in each of the months of March and April. However, Gizmo chips will not be in short supply in May. Three chips are required to make each 19-inch TV while the 25-inch TVs require four chips each. To limit the production of televisions produced at factory 1 in March so that the TVs have the correct number of chips, a side constraint called FACT1 MAR GIZMO is used. The form of this constraint is

\[ 3 \times \text{prod f1 19 mar} + 4 \times \text{prod f1 25 mar} \leq 2600 \]

“prod f1 19 mar” is the name of the arc directed from the node fact1_1 toward node f1_mar_1 and, in the previous constraint, designates the flow assigned to this arc. The ARCDATA= and ARCOUT= data sets have arc names in a variable called _name_.

The other side constraints (shown below) are called FACT2 MAR GIZMO, FACT1 APL GIZMO, and FACT2 APL GIZMO.

\[ 3 \times \text{prod f2 19 mar} + 4 \times \text{prod f2 25 mar} \leq 3750 \]
\[ 3 \times \text{prod f1 19 apl} + 4 \times \text{prod f1 25 apl} \leq 2600 \]
\[ 3 \times \text{prod f2 19 apl} + 4 \times \text{prod f2 25 apl} \leq 3750 \]

To maintain customer goodwill, the total number of backorders is not to exceed 50 sets. The side constraint TOTAL BACKORDER that models this restriction is:

\[ \text{back f1 19 apl} + \text{back f1 25 apl} + \text{back f2 19 apl} + \text{back f2 25 apl} + \text{back f1 19 may} + \text{back f1 25 may} + \text{back f2 19 may} + \text{back f2 25 may} \leq 50 \]

The sparse CONDATA= data set format is used. All side constraints are less than or equal type. Because this is the default type value for the DEFCONTYPE= option, type information is not necessary in the following CONDATA=CON3. Also, DEFCONTYPE= <= does not have to be specified in the PROC NETFLOW statement that follows. Notice that the _column_ variable value CHIP/BO LIMIT indicates that an observation of the CON3 data set contains rhs information. Therefore, specify RHSOBS='CHIP/BO LIMIT'.
Example 6.6: Adding Side Constraints, Using a Warm Start

CHIP/BO LIMIT  FACT1 APL GIZMO  2600
prod f2 19 apl FACT2 APL GIZMO  3
prod f2 25 apl FACT2 APL GIZMO  4
CHIP/BO LIMIT  FACT2 APL GIZMO  3750
back f1 19 apl TOTAL BACKORDER  1
back f1 25 apl TOTAL BACKORDER  1
back f2 19 apl TOTAL BACKORDER  1
back f2 25 apl TOTAL BACKORDER  1
back f1 19 may TOTAL BACKORDER  1
back f1 25 may TOTAL BACKORDER  1
back f2 19 may TOTAL BACKORDER  1
back f2 25 may TOTAL BACKORDER  1
CHIP/BO LIMIT  TOTAL BACKORDER  50
;

The four pairs of data sets that follow can be used as ARCDATA= and NODEDATA= data sets in the following PROC NETFLOW run. The set used depends on which cost information the arcs are to have and whether a warm start is to be used.

ARCDATA=arc0 NODEDATA=node0
ARCDATA=arc1 NODEDATA=node2
ARCDATA=arc2 NODEDATA=node2
ARCDATA=arc3 NODEDATA=node3

arc0, node0, arc1, and node2 were created in Example 6.4. The first two data sets are the original input data sets. arc1 and node2 were the ARCOUT= and NODEOUT= data sets of a PROC NETFLOW run with FUTURE1 specified. Now, if you use arc1 and node2 as the ARCDATA= data set and NODEDATA= data set in a PROC NETFLOW run, you can specify WARM, as these data sets contain additional information describing a warm start.

In Example 6.5, arc2 was created by modifying arc1 to reflect different arc costs. arc2 and node2 can also be used as the ARCDATA= and NODEDATA= data sets in a PROC NETFLOW run. Again, specify WARM, as these data sets contain additional information describing a warm start. This start, however, contains the optimal basis using the original costs.

If you are going to continue optimization using the changed arc costs, it is probably best to use arc3 and node3 as the ARCDATA= and NODEDATA= data sets. These data sets, created in Example 6.6 by PROC NETFLOW when the FUTURE1 option was specified, contain an optimal basis that can be used as a warm start.

PROC NETFLOW is used to find the changed cost network solution that obeys the chip limit and backorder side constraints. The FUTURE2 option is specified in case further processing is required. An explicit ID list has also been specified so that the variables oldcost, oldfc and oldflow do not appear in the subsequent output data sets.

    proc netflow
      nodedata=node3 arcdata=arc3 warm
      condata=con3 sparsecondata rhsobs='CHIP/BO LIMIT'
      future2 dualout=dual4 conout=con4;
    id diagonal factory key_id mth_made;
    run;
    quit;
Chapter 6: The NETFLOW Procedure

```sas
proc print data=con4 heading=h width=min;
  sum _fcost_;  
  var _tail_ _head_ _cost_ _capac_ _lo_ _name_ _supply_ _demand_ _flow_ _fcost_;  
run;

proc print data=con4 heading=h width=min;
  var _rcost_ _anumb_ _tnumb_ _status_ diagonal factory key_id mth_made;
run;

proc print data=dual4;
run;
```

The following messages appear on the SAS log:

```
NOTE: The following 3 variables in ARCDATA do not belong to any SAS variable list. These will be ignored.
   oldcost
   oldfc
   oldflow
NOTE: Number of nodes= 21 .
NOTE: Number of supply nodes= 4 .
NOTE: Number of demand nodes= 5 .
NOTE: The greater of total supply and total demand= 4350 .
NOTE: Number of iterations performed (neglecting any constraints)= 1 .
NOTE: Of these, 0 were degenerate.
NOTE: Optimum (neglecting any constraints) found.
NOTE: Minimal total cost= -1285086.45 .
NOTE: Number of <= side constraints= 5 .
NOTE: Number of == side constraints= 0 .
NOTE: Number of >= side constraints= 0 .
NOTE: Number of arc and nonarc variable side constraint coefficients= 16 .
NOTE: Number of iterations, optimizing with constraints= 14 .
NOTE: Of these, 1 were degenerate.
NOTE: Optimum reached.
NOTE: Minimal total cost= -1282708.625 .
NOTE: The data set WORK.CON4 has 68 observations and 18 variables.
NOTE: The data set WORK.DUAL4 has 27 observations and 14 variables.
```
### Example 6.6: Adding Side Constraints, Using a Warm Start

#### Output 6.6.1 CONOUT=CON4

<table>
<thead>
<tr>
<th>Obs</th>
<th>tail</th>
<th>head</th>
<th>cost</th>
<th>capac</th>
<th>lo</th>
<th>name</th>
<th>SUPPLY</th>
<th>DEMAND</th>
<th>FLOW</th>
<th>FCOST</th>
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<tbody>
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Output 6.6.1 continued

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-1282708.63
### Example 6.6: Adding Side Constraints, Using a Warm Start

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### Example 6.6: Adding Side Constraints, Using a Warm Start

#### Output 6.6.3 DUALOUT=DUAL4

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Example 6.7: Using a Constrained Solution Warm Start

Suppose the 25-inch screen TVs produced at factory 1 in May can be sold at either shop with an increased profit of 40 dollars each. What is the new optimal solution? Because only arc costs have been changed, information about the present solution in DUALOUT=dual4 and CONOUT=con4 can be used as a warm start in the following PROC NETFLOW run. It is still necessary to specify CONDATA=con3 SPARSECONDATA RHSOBS='CHIP/BO LIMIT', since the CONDATA= data set is always read.

```sas
title 'Using a Constrained Solution Warm Start';
title2 'Production Planning/Inventory/Distribution';
data new_con4;
  set con4;
  oldcost=_cost_;   
  oldflow=_flow_;   
  oldfc=_fcost_;    
  if _tail_='f1_may_2'
    & (_head_='shop1_2' | _head_='shop2_2')
    then _cost=_cost_-40;
run;

proc netflow
  warm
  ardata=new_con4
  dualin=dual4
  condata=con3
  sparsecondata
  rhsobs='CHIP/BO LIMIT'
  dualout=dual5
  conout=con5;
run;
quit;

proc print data=con5 heading=h width=min;
sum _fcost_;   
var _tail_ _head_ _capac_ _lo_ _supply_ _demand_ _name_ _cost_ _flow_ _fcost_; 
run;
```
Example 6.7: Using a Constrained Solution Warm Start

```
proc print data=con5 heading=h width=min;
   sum oldfc;
   var oldcost oldflow oldfc diagonal factory key_id mth_made _anumb_ _tnumb_;
run;

proc print data=dual5;
run;
```

The following messages appear on the SAS log:

```
NOTE: The following 1 variables in NODEDATA do not belong to any SAS variable list. These will be ignored.
   _VALUE_
NOTE: Number of nodes= 21 .
NOTE: Number of supply nodes= 4 .
NOTE: Number of demand nodes= 5 .
NOTE: The greater of total supply and total demand= 4350 .
NOTE: Number of <= side constraints= 5 .
NOTE: Number of == side constraints= 0 .
NOTE: Number of >= side constraints= 0 .
NOTE: Number of arc and nonarc variable side constraint coefficients= 16 .
NOTE: Number of iterations, optimizing with constraints= 6 .
NOTE: Of these, 0 were degenerate.
NOTE: Optimum reached.
NOTE: Minimal total cost= -1295661.8 .
NOTE: The data set WORK.CON5 has 68 observations and 21 variables.
NOTE: The data set WORK.DUAL5 has 25 observations and 14 variables.
```
Output 6.7.1  CONOUT=CON5

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**Example 6.7: Using a Constrained Solution Warm Start**

**Output 6.7.1 continued**

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**Example 6.8: Nonarc Variables in the Side Constraints**

Notice in DUALOUT=dual5 from Example 6.7 the FACT2 MAR GIZMO constraint (observation 24) has a _VALUE_ of 3470, which is not equal to the _RHS_ of this constraint. Not all of the 3750 chips that can be supplied to factory 2 for March production are used. It is suggested that all the possible chips be obtained in March and those not used be saved for April production. Because chips must be kept in an air-controlled environment, it costs 1 dollar to store each chip purchased in March until April. The maximum number of chips that can be stored in this environment at each factory is 150. In addition, a search of the parts inventory at factory 1 turned up 15 chips available for their March production.

Nonarc variables are used in the side constraints that handle the limitations of supply of Gizmo chips. A nonarc variable called “f1 unused chips” has as a value the number of chips that are not used at factory 1 in March. Another nonarc variable, “f2 unused chips”, has as a value the number of chips that are not used at factory 2 in March. “f1 chips from mar” has as a value the number of chips left over from March used for production at factory 1 in April. Similarly, “f2 chips from mar” has as a value the number of chips left over from March used for April production at factory 2 in April. The last two nonarc variables have objective function coefficients of 1 and upper bounds of 150. The Gizmo side constraints are

\[
3 \cdot \text{prod } f1 \text{ 19 mar} + 4 \cdot \text{prod } f1 \text{ 25 mar} + f1 \text{ unused chips} = 2615 \\
3 \cdot \text{prod } f2 \text{ 19 apl} + 4 \cdot \text{prod } f2 \text{ 25 apl} + f2 \text{ unused chips} = 3750 \\
3 \cdot \text{prod } f1 \text{ 19 apl} + 4 \cdot \text{prod } f1 \text{ 25 apl} - f1 \text{ chips from mar} = 2600 \\
3 \cdot \text{prod } f2 \text{ 19 apl} + 4 \cdot \text{prod } f2 \text{ 25 apl} - f2 \text{ chips from mar} = 3750 \\
f1 \text{ unused chips} + f2 \text{ unused chips} - \\
f1 \text{ chips from mar} - f2 \text{ chips from mar} \geq 0
\]

The last side constraint states that the number of chips not used in March is not less than the number of chips left over from March and used in April. Here, this constraint is called CHIP LEFTOVER.

The following SAS code creates a new data set containing constraint data. It seems that most of the constraints are now equalities, so you specify DEFCONTYPE=EQ in the PROC NETFLOW statements from now on and provide constraint type data for constraints that are not “equal to” type, using the default TYPEOBS value _TYPE_ as the _COLUMN_ variable value to indicate observations that contain constraint type data. Also, from now on, the default RHSOBS value is used.

```sas
title 'Nonarc Variables in the Side Constraints';
title2 'Production Planning/Inventory/Distribution';
data con6;
   input _column_ &$17. _row_ &$15. _coef_;
datalines;
prod f1 19 mar FACT1 MAR GIZMO 3
```
The nonarc variables “f1 chips from mar” and “f2 chips from mar” have objective function coefficients of 1 and upper bounds of 150. There are various ways in which this information can be furnished to PROC NETFLOW. If there were a TYPE list variable in the CONDATA= data set, observations could be in the form

```
COLUMN   TYPE    ROW    COEF
f1 chips from mar   objfn   .   1
f1 chips from mar   upperbd .   150
f2 chips from mar   objfn   .   1
f2 chips from mar   upperbd .   150
```
It is desirable to assign ID list variable values to all the nonarc variables:

```sas
data arc6;
  set con5;
  drop oldcost oldfc oldflow _flow_ _fcost_ _status_ _rcost_;
data arc6_b;
  length key_id $10;
  input _name_$ &$17. _cost_ _capac_ factory key_id $;
datalines;
f1 unused chips . . 1 chips
f2 unused chips . . 2 chips
f1 chips from mar 1 150 1 chips
f2 chips from mar 1 150 2 chips
;
proc append force nowarn
  base=arc6 data=arc6_b;
run;

proc netflow
  nodedata=node0 arcdata=arc6
  condata=con6 defcontype=eq sparsecondata
  dualout=dual7 conout=con7;
run;

print nonarcs/short;
```

The following messages appear on the SAS log:

```
NOTE: Number of nodes= 21.
NOTE: Number of supply nodes= 4.
NOTE: Number of demand nodes= 5.
NOTE: Total supply= 4350, total demand= 4350.
NOTE: Number of arcs= 68.
NOTE: Number of nonarc variables= 4.
NOTE: Number of iterations performed (neglecting any constraints)= 69.
NOTE: Of these, 1 were degenerate.
NOTE: Optimum (neglecting any constraints) found.
NOTE: Minimal total cost= -1295730.8.
NOTE: Number of <= side constraints= 1.
NOTE: Number of == side constraints= 4.
NOTE: Number of >= side constraints= 1.
NOTE: Number of arc and nonarc variable side constraint coefficients= 24.
NOTE: Number of iterations, optimizing with constraints= 13.
NOTE: Of these, 2 were degenerate.
NOTE: Optimum reached.
NOTE: Minimal total cost= -1295542.742.
NOTE: The data set WORK.CON7 has 68 observations and 18 variables.
NOTE: The data set WORK.DUAL7 has 26 observations and 14 variables.
```
The output in Output 6.8.1 is produced by

```
print nonarcs/short ;
```

**Output 6.8.1** Output of PRINT NONARCS/SHORT;

Nonarc Variables in the Side Constraints
Production Planning/Inventory/Distribution

The NETFLOW Procedure

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The optimal solution data sets, CONOUT=CON7 in Output 6.8.2 and Output 6.8.3 and DUALOUT=DUAL7 in Output 6.8.4 follow.

```
proc print data=con7;
  sum _fcost_;
proc print data=dual7;
```
### Nonarc Variables in the Side Constraints

#### Production Planning/Inventory/Distribution

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**Nonarc Variables in the Side Constraints**

Production Planning/Inventory/Distribution

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-1295542.74
### Example 6.8: Nonarc Variables in the Side Constraints

#### Output 6.8.3 CONOUT=CON7 (continued)

**Nonarc Variables in the Side Constraints**  
Production Planning/Inventory/Distribution

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### Output 6.8.3 continued

**Nonarc Variables in the Side Constraints**

Production Planning/Inventory/Distribution

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### Output 6.8.4 DUALOUT=DUAL7

#### Nonarc Variables in the Side Constraints

Production Planning/Inventory/Distribution

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The optimal value of the nonarc variable “f2 unused chips” is 280. This means that although there are 3750 chips that can be used at factory 2 in March, only 3470 are used. As the optimal value of “f1 unused chips” is zero, all chips available for production in March at factory 1 are used. The nonarc variable “f2 chips from mar” also has zero optimal value. This means that the April production at factory 2 does not need any chips that could have been held in inventory since March. However, the nonarc variable “f1 chips from mar” has value of 20. Thus, 3490 chips should be ordered for factory 2 in March. Twenty of these chips should be held in inventory until April, then sent to factory 1.

Example 6.9: Pure Networks: Using the EXCESS= Option

In this example we illustrate the use of the EXCESS= option for various scenarios in pure networks. Consider a simple network as shown in Output 6.9.1. The positive numbers on the nodes correspond to supply and the negative numbers correspond to demand. The numbers on the arcs indicate costs.

Transportation Problem, Total Supply < Total Demand

We first analyze a simple transportation problem where total demand exceeds total supply, as seen in Output 6.9.1. The EXCESS=SLACKS option is illustrated first.
The following SAS code creates the input data sets.

```sas
data parcs;
  input _from_ $ _to_ $ _cost_;
datalines;
s1 d1 1
s1 d2 8
s2 d1 4
s2 d2 2;

data SleD;
  input _node_ $ _sd_;
datalines;
s1 1
s2 10
d1 -10
d2 -5;
```

You can solve the problem using the following call to PROC NETFLOW:

```plaintext
title1 'The NETFLOW Procedure';
proc netflow
   excess  = slacks
   arcdata = parcs
   nodedata = SleD
   conout  = solex1;
run;
```

Since the EXCESS=SLACKS option is specified, the interior point method is used for optimization. Accordingly, the CONOUT= data set is specified. The optimal solution is displayed in Output 6.9.2.

**Output 6.9.2** Supply < Demand

The solution with the THRUNET option specified is displayed in Output 6.9.3.

```plaintext
title1 'The NETFLOW Procedure';
proc netflow
   thrunet
   excess  = slacks
   arcdata = parcs
   nodedata = SleD
   conout  = solex1t;
run;
```

**Output 6.9.3** Supply < Demand, THRUNET Specified

The solution with the THRUNET option specified is displayed in Output 6.9.3.

**NOTE:** If you want to use the network simplex solver instead, you need to specify the EXCESS=ARCS option and, accordingly, the ARCOUT= data set.
Missing D Demand

As shown in Output 6.9.4, node $D_1$ has a missing D demand value.

**Output 6.9.4 Missing D Demand**

The following code creates the node data set:

```plaintext
data node_missingD1;
  input _node_ $ _sd_;  
    missing D;  
  datalines;
  s1  1 
  s2 10 
  d1  D 
  d2 -1 
;  
```

![Graph showing node data set](image)
You can use the following call to PROC NETFLOW to solve the problem:

```sas
title1 'The NETFLOW Procedure';
proc netflow
  excess = slacks
  arcdata = parcs
  nodedata = node_missingD1
  conout = solex1b;
run;
```

The optimal solution is displayed in Output 6.9.5. As you can see, the flow balance at nodes with nonmissing `supdem` values is maintained. In other words, if a node has a nonmissing supply (demand) value, then the sum of flows out of (into) that node is equal to its `supdem` value.

**Output 6.9.5  THRUNET Not Specified**

The NETFLOW Procedure

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**Missing D Demand, THRUNET Specified**

Consider the previous example, but with the THRUNET option specified.

```sas
title1 'The NETFLOW Procedure';
proc netflow
  thrunet
  excess = slacks
  arcdata = parcs
  nodedata = node_missingD1
  conout = solex1c;
run;
```

The optimal solution is displayed in Output 6.9.6. By specifying the THRUNET option, we have actually obtained the minimum-cost flow through the network, while maintaining flow balance at the nodes with nonmissing supply values.

**Output 6.9.6  Missing D Demand, THRUNET Specified**

The NETFLOW Procedure

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<td>0</td>
<td>0</td>
</tr>
<tr>
<td>4</td>
<td>s2</td>
<td>d2</td>
<td>2</td>
<td>999999999</td>
<td>0</td>
<td>10</td>
<td>1</td>
<td>0</td>
<td>20</td>
</tr>
</tbody>
</table>

**NOTE:** The case with missing S supply values is similar to the case with missing D demand values.
Example 6.10: Maximum Flow Problem

Consider the maximum flow problem depicted in Output 6.10.1. The maximum flow between nodes S and T is to be determined. The minimum arc flow and arc capacities are specified as lower and upper bounds in square brackets, respectively.

Output 6.10.1 Maximum Flow Problem Example

You can solve the problem using either EXCESS=ARCS or EXCESS=SLACKS. Consider using the EXCESS=ARCS option first. You can use the following SAS code to create the input data set:

```sas
data arcs;
   input _from_ $ _to_ $ _cost_ _capac_;
   datalines;
   S a . .
   S b . .
   a c 1 7
   b c 2 9
   a d 3 5
   b d 4 8
   c e 5 15
   d f 6 20
   e g 7 11
   f g 8 6
   e h 9 12
   f h 10 4
   g T . .
   h T . .
;
```

You can use the following call to PROC NETFLOW to solve the problem:

```
title1 'The NETFLOW Procedure';
proc netflow
   intpoint
   maxflow
   excess = arcs
   arcdata = arcs
   source = S sink = T
   conout = gout3;
run;
```
With the EXCESS=ARCS option specified, the problem gets transformed internally to the one depicted in Output 6.10.2. Note that there is an additional arc from the source node to the sink node.

**Output 6.10.2** Maximum Flow Problem, EXCESS=ARCS Option Specified

The output SAS data set is displayed in Output 6.10.3.

**Output 6.10.3** Maximum Flow Problem, EXCESS=ARCS Option Specified

---

<table>
<thead>
<tr>
<th>Obs</th>
<th>from</th>
<th>to</th>
<th>cost</th>
<th>capac</th>
<th>LO</th>
<th>SUPPLY</th>
<th>DEMAND</th>
<th>FLOW</th>
<th>FCOST</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
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<td>T</td>
<td>0</td>
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<td>0</td>
<td>.</td>
<td>99999998</td>
<td>16.9996</td>
<td>0.0000</td>
</tr>
<tr>
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<td>h</td>
<td>T</td>
<td>0</td>
<td>99999999</td>
<td>0</td>
<td>.</td>
<td>99999998</td>
<td>8.0004</td>
<td>0.0000</td>
</tr>
<tr>
<td>3</td>
<td>S</td>
<td>a</td>
<td>0</td>
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<td>0</td>
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<td>.</td>
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<td>0.0000</td>
</tr>
<tr>
<td>4</td>
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<td>b</td>
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<td>99999999</td>
<td>0</td>
<td>99999998</td>
<td>.</td>
<td>13.0049</td>
<td>0.0000</td>
</tr>
<tr>
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<td>c</td>
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<td>.</td>
<td>6.9952</td>
<td>6.9952</td>
</tr>
<tr>
<td>6</td>
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<td>c</td>
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<td>9</td>
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<td>.</td>
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<td>16.0097</td>
</tr>
<tr>
<td>7</td>
<td>a</td>
<td>d</td>
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<td>5</td>
<td>0</td>
<td>.</td>
<td>.</td>
<td>4.9999</td>
<td>14.9998</td>
</tr>
<tr>
<td>8</td>
<td>b</td>
<td>d</td>
<td>4</td>
<td>8</td>
<td>0</td>
<td>.</td>
<td>.</td>
<td>5.0001</td>
<td>20.0002</td>
</tr>
<tr>
<td>9</td>
<td>c</td>
<td>e</td>
<td>5</td>
<td>15</td>
<td>0</td>
<td>.</td>
<td>.</td>
<td>15.0000</td>
<td>75.0000</td>
</tr>
<tr>
<td>10</td>
<td>d</td>
<td>f</td>
<td>6</td>
<td>20</td>
<td>0</td>
<td>.</td>
<td>.</td>
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<td>60.0000</td>
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<td>e</td>
<td>g</td>
<td>7</td>
<td>11</td>
<td>0</td>
<td>.</td>
<td>.</td>
<td>10.9996</td>
<td>76.9975</td>
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<tr>
<td>12</td>
<td>f</td>
<td>g</td>
<td>8</td>
<td>6</td>
<td>0</td>
<td>.</td>
<td>.</td>
<td>6.0000</td>
<td>48.0000</td>
</tr>
<tr>
<td>13</td>
<td>e</td>
<td>h</td>
<td>9</td>
<td>12</td>
<td>0</td>
<td>.</td>
<td>.</td>
<td>4.0004</td>
<td>36.0032</td>
</tr>
<tr>
<td>14</td>
<td>f</td>
<td>h</td>
<td>10</td>
<td>4</td>
<td>0</td>
<td>.</td>
<td>.</td>
<td>4.0000</td>
<td>40.0000</td>
</tr>
</tbody>
</table>

---

The NETFLOW Procedure

The NETFLOW Procedure
You can solve the same maximum flow problem, but this time with EXCESS=SLACKS specified. The SAS code is as follows:

```
title1 'The NETFLOW Procedure';
proc netflow
    intpoint
    excess = slacks
    arcdata = arcs
    source = S sink = T
    maxflow
    conout = gout3b;
run;
```

With the EXCESS=SLACKS option specified, the problem gets transformed internally to the one depicted in Figure 6.10.4. Note that the source node and sink node each have a single-ended “excess” arc attached to them.

**Output 6.10.4** Maximum Flow Problem, EXCESS=SLACKS Option Specified

![Network diagram showing the internal transformation of the maximum flow problem with EXCESS=SLACKS option specified.](image)

The solution, as displayed in Output 6.10.5, is the same as before. Note that the _SUPPLY_ value of the source node Y has changed from 99999998 to missing S, and the _DEMAND_ value of the sink node Z has changed from −99999998 to missing D.

**Output 6.10.5** Maximal Flow Problem

**The NETFLOW Procedure**

```
Obs  _from_  _to_  _cost_  _capac_  _LO_  _SUPPLY_  _DEMAND_  _FLOW_  _FCOST_
    1    g    T      0  999999999    0  .    D   16.9993  0.0000
    2    h    T      0  999999999    0  .    D    8.0007  0.0000
    3    S    a      0  999999999    0  S    .    11.9867  0.0000
    4    S    b    0  999999999    0  S    .    13.0133  0.0000
    5    a    c      1    7      0  .    .    6.9868   6.9868
    6    b    c      2    9      0  .    .    8.0132  16.0264
    7    a    d      3    5      0  .    .    4.9999  14.9998
    8    b    d      4    8      0  .    .    5.0001  20.0002
    9    c    e      5    15     0  .    .    15.0000  75.0000
   10    d    f      6    20     0  .    .    10.0000  60.0000
   11    e    g      7    11     0  .    .    10.9993  76.9953
   12    f    g      8    6      0  .    .    6.0000  48.0000
   13    e    h      9    12     0  .    .    4.0007  36.0661
   14    f    h    10    4      0  .    .    4.0000  40.0000
```
Example 6.11: Generalized Networks: Using the EXCESS= Option

For generalized networks you can specify either EXCESS=SUPPLY or EXCESS=DEMAND to indicate which nodal flow conservation constraints have slack variables associated with them. The default option is EXCESS=NONE.

Using the EXCESS=SUPPLY Option

Consider the simple network shown in Output 6.11.1. As you can see, the sum of positive supdem values (35) is equal to the absolute sum of the negative ones. However, the arcs connecting the supply and demand nodes have varying arc multipliers. Let us now solve the problem using the EXCESS=SUPPLY option.

Output 6.11.1  Generalized Network: Supply = Demand
You can use the following SAS code to create the input data sets:

```sas
data garcs;
   input _from_ $ _to_ $ _cost_ _mult_;
datalines;
s1 d1 1 .
s1 d2 8 .
s2 d1 4 2
s2 d2 2 2
s2 d3 1 2
s3 d2 5 0.5
s3 d3 4 0.5
;

data gnodes;
   input _node_ $ _sd_ ;
datalines;
s1 5
s2 20
s3 10
d1 -5
d2 -10
d3 -20
;
```

To solve the problem, use the following call to PROC NETFLOW:

```sas
title1 'The NETFLOW Procedure';
proc netflow
   arcdata = garcs
   nodedata = gnodes
   excess = supply
   conout = gnetout;
run;
```

The optimal solution is displayed in Output 6.11.2.

**Output 6.11.2** Optimal Solution Obtained Using the EXCESS=SUPPLY Option

**The NETFLOW Procedure**

<table>
<thead>
<tr>
<th>Obs</th>
<th>from</th>
<th>to</th>
<th>cost</th>
<th>CAPAC</th>
<th>LO</th>
<th>mult</th>
<th>SUPPLY</th>
<th>DEMAND</th>
<th>FLOW</th>
<th>FCOST</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>s1</td>
<td>d1</td>
<td>1</td>
<td>999999999</td>
<td>0</td>
<td>1.0</td>
<td>5</td>
<td>5</td>
<td>5</td>
<td>5</td>
</tr>
<tr>
<td>2</td>
<td>s2</td>
<td>d1</td>
<td>4</td>
<td>999999999</td>
<td>0</td>
<td>2.0</td>
<td>20</td>
<td>5</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>3</td>
<td>s1</td>
<td>d2</td>
<td>8</td>
<td>999999999</td>
<td>0</td>
<td>1.0</td>
<td>5</td>
<td>10</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>4</td>
<td>s2</td>
<td>d2</td>
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<td>10</td>
<td>5</td>
<td>10</td>
</tr>
<tr>
<td>5</td>
<td>s3</td>
<td>d2</td>
<td>5</td>
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<td>0</td>
<td>0.5</td>
<td>10</td>
<td>10</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>6</td>
<td>s2</td>
<td>d3</td>
<td>1</td>
<td>999999999</td>
<td>0</td>
<td>2.0</td>
<td>20</td>
<td>20</td>
<td>10</td>
<td>10</td>
</tr>
<tr>
<td>7</td>
<td>s3</td>
<td>d3</td>
<td>4</td>
<td>999999999</td>
<td>0</td>
<td>0.5</td>
<td>10</td>
<td>20</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>

**NOTE:** If you do not specify the EXCESS= option, or if you specify the EXCESS=DEMAND option, the procedure will declare the problem infeasible. Therefore, in case of real-life problems, you would need to have a little more detail about how the arc multipliers end up affecting the network — whether they tend to create excess demand or excess supply.
Using the EXCESS=DEMAND Option

Consider the previous example but with a slight modification: the arcs out of node $S_1$ have multipliers of 0.5, and the arcs out of node $S_2$ have multipliers of 1. You can use the following SAS code to create the input arc data set:

```sas
data garcs1;
  input _from_ $ _to_ $ _cost_ _mult_;
datalines;
s1 d1 1 0.5
s1 d2 8 0.5
s2 d1 4 .
s2 d2 2 .
s2 d3 1 .
s3 d2 5 0.5
s3 d3 4 0.5
; 
```

Note that the node data set remains unchanged. You can use the following call to PROC NETFLOW to solve the problem:

```sas
title1 'The NETFLOW Procedure';
proc netflow
  arcdata = garcs1
  nodedata = gnodes
  excess = demand
  conout = gnetout1;
run;
```

The optimal solution is displayed in Output 6.11.3.

**Output 6.11.3** Optimal Solution Obtained Using the EXCESS=DEMAND Option

<table>
<thead>
<tr>
<th>Obs</th>
<th><em>from</em></th>
<th><em>to</em></th>
<th><em>cost</em></th>
<th><em>CAPAC</em></th>
<th><em>LO</em></th>
<th><em>mult</em></th>
<th><em>SUPPLY</em></th>
<th><em>DEMAND</em></th>
<th><em>FLOW</em></th>
<th><em>FCOST</em></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>s1</td>
<td>d1</td>
<td>1</td>
<td>99999999</td>
<td>0</td>
<td>0.5</td>
<td>5</td>
<td>5</td>
<td>5.0000</td>
<td>5.0000</td>
</tr>
<tr>
<td>2</td>
<td>s2</td>
<td>d1</td>
<td>4</td>
<td>99999999</td>
<td>0</td>
<td>1.0</td>
<td>20</td>
<td>5</td>
<td>0.0000</td>
<td>0.0000</td>
</tr>
<tr>
<td>3</td>
<td>s1</td>
<td>d2</td>
<td>8</td>
<td>99999999</td>
<td>0</td>
<td>0.5</td>
<td>5</td>
<td>10</td>
<td>0.0000</td>
<td>0.0000</td>
</tr>
<tr>
<td>4</td>
<td>s2</td>
<td>d2</td>
<td>2</td>
<td>99999999</td>
<td>0</td>
<td>1.0</td>
<td>20</td>
<td>10</td>
<td>5.0000</td>
<td>10.0000</td>
</tr>
<tr>
<td>5</td>
<td>s3</td>
<td>d2</td>
<td>5</td>
<td>99999999</td>
<td>0</td>
<td>0.5</td>
<td>10</td>
<td>10</td>
<td>0.0000</td>
<td>0.0000</td>
</tr>
<tr>
<td>6</td>
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<td>0</td>
<td>1.0</td>
<td>20</td>
<td>20</td>
<td>15.0000</td>
<td>15.0000</td>
</tr>
<tr>
<td>7</td>
<td>s3</td>
<td>d3</td>
<td>4</td>
<td>99999999</td>
<td>0</td>
<td>0.5</td>
<td>10</td>
<td>20</td>
<td>10.0000</td>
<td>40.0000</td>
</tr>
</tbody>
</table>

**Example 6.12: Generalized Networks: Maximum Flow Problem**

Consider the generalized network displayed in Output 6.12.1. Lower and upper bounds of the flow are displayed in parentheses above the arc, and cost and multiplier, where applicable, are indicated in square brackets below the arc.
You can enter the data for the problem using the following SAS code:

```sas
data garcsM;
  input _from_ $ _to_ $ _upper_ _mult_;
datalines;
A B 2.
A C 2.
C B 1.
B D 1.
C D 2.
C E 1 3
D E 1 2
E F 5.
D F 2.
;
```

Use the following call to PROC NETFLOW:

```sas
   title1 'The NETFLOW Procedure';
   proc netflow
     arcdata = garcsM
     maxflow
     source = A sink = F
     conout = gmfpout;
   run;
```
Chapter 6: The NETFLOW Procedure

The optimal solution is displayed in Output 6.12.2.

Output 6.12.2 Generalized Maximum Flow Problem: Optimal Solution

The NETFLOW Procedure

<table>
<thead>
<tr>
<th>Obs</th>
<th>from</th>
<th>to</th>
<th>COST</th>
<th>upper</th>
<th>LO</th>
<th>mult</th>
<th>SUPPLY</th>
<th>DEMAND</th>
<th>FLOW</th>
<th>FCOST</th>
</tr>
</thead>
<tbody>
<tr>
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<td>B</td>
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<td>2</td>
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<td>0</td>
</tr>
<tr>
<td>2</td>
<td>C</td>
<td>B</td>
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<td>1</td>
<td>0</td>
<td>1</td>
<td>.</td>
<td>.</td>
<td>0.00000</td>
<td>0</td>
</tr>
<tr>
<td>3</td>
<td>A</td>
<td>C</td>
<td>0</td>
<td>2</td>
<td>0</td>
<td>1</td>
<td>S</td>
<td>.</td>
<td>2.00000</td>
<td>0</td>
</tr>
<tr>
<td>4</td>
<td>B</td>
<td>D</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>1</td>
<td>.</td>
<td>.</td>
<td>1.00000</td>
<td>0</td>
</tr>
<tr>
<td>5</td>
<td>C</td>
<td>D</td>
<td>0</td>
<td>2</td>
<td>0</td>
<td>1</td>
<td>.</td>
<td>.</td>
<td>1.00000</td>
<td>0</td>
</tr>
<tr>
<td>6</td>
<td>C</td>
<td>E</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>3</td>
<td>.</td>
<td>.</td>
<td>1.00000</td>
<td>0</td>
</tr>
<tr>
<td>7</td>
<td>D</td>
<td>E</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>2</td>
<td>.</td>
<td>.</td>
<td>1.00000</td>
<td>0</td>
</tr>
<tr>
<td>8</td>
<td>E</td>
<td>F</td>
<td>0</td>
<td>5</td>
<td>0</td>
<td>1</td>
<td>D</td>
<td>.</td>
<td>5.00000</td>
<td>0</td>
</tr>
<tr>
<td>9</td>
<td>D</td>
<td>F</td>
<td>0</td>
<td>2</td>
<td>0</td>
<td>1</td>
<td>D</td>
<td>.</td>
<td>1.00000</td>
<td>0</td>
</tr>
</tbody>
</table>

Example 6.13: Machine Loading Problem

Machine loading problems arise in a variety of applications. Consider a simple instance as described in Ahuja, Magnanti, and Orlin (1993). Assume you need to schedule the production of three products, \( P_1 \) – \( P_3 \), on four machines, \( M_1 \) – \( M_4 \). Suppose that machine 1 and machine 2 are each available for 40 hours and machine 3 and machine 4 are each available for 50 hours. Also, any of the machines can produce any product. The per-unit processing time and production cost for each product on each machine are indicated in Table 6.14.

Table 6.14 Processing Times and Production Costs

<table>
<thead>
<tr>
<th></th>
<th>M1</th>
<th>M2</th>
<th>M3</th>
<th>M4</th>
</tr>
</thead>
<tbody>
<tr>
<td>( P_1 )</td>
<td>1</td>
<td>2</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>( P_2 )</td>
<td>2</td>
<td>3</td>
<td>2</td>
<td>1</td>
</tr>
<tr>
<td>( P_3 )</td>
<td>3</td>
<td>1</td>
<td>2</td>
<td>4</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th></th>
<th>M1</th>
<th>M2</th>
<th>M3</th>
<th>M4</th>
</tr>
</thead>
<tbody>
<tr>
<td>( P_1 )</td>
<td>4</td>
<td>3</td>
<td>3</td>
<td>1</td>
</tr>
<tr>
<td>( P_2 )</td>
<td>0.5</td>
<td>2</td>
<td>0.5</td>
<td>3</td>
</tr>
<tr>
<td>( P_3 )</td>
<td>2</td>
<td>5</td>
<td>1</td>
<td>5</td>
</tr>
</tbody>
</table>

The problem is to satisfy the demands for the three products at minimum cost.

You can model this problem as a generalized network as shown in Output 6.13.1. The network has three product nodes with demands indicated by positive \texttt{supdem} values and four machine nodes with availabilities (in hours) indicated by negative \texttt{supdem} values. The multiplier on an arc between a machine and a product indicates the hours of machine capacity needed to produce one unit of the product.
You can create the input data sets with the following SAS code:

```sas
data mlarcs;
  input _from_ $ _to_ $ _cost_ _mult_;
datalines;
P1 M1  4  .
P1 M2  3  2
P1 M3  3  2
P1 M4  1  3
P2 M1 .5  2
P2 M2  2  3
P2 M3 .5  2
P2 M4  3  1
P3 M1  2  3
```

You can create the input data sets with the following SAS code:
data mlnodes;
  input _node_ $ _sd_;
datalines;
P1 10
P2 5
P3 10
M1 -40
M2 -40
M3 -50
M4 -50
;

You can solve the problem using the following call to PROC NETFLOW:

    title1 'The NETFLOW Procedure';
    proc netflow
    excess = demand
    arcdata = mlarcs
    nodedata = mlnodes
    conout = mlsol;
    run;

The optimal solution, as displayed in Output 6.13.2, can be interpreted as follows:

- Product 1: 10 units on machine 4
- Product 2: 3 units on machine 1, and 2 units on machine 3
- Product 3: 5 units on machine 3, and 5 units on machine 4

Output 6.13.2  Optimum Solution to the Machine Loading Problem

The NETFLOW Procedure

<table>
<thead>
<tr>
<th>Obs</th>
<th>from</th>
<th>to</th>
<th>_cost</th>
<th>_CAPAC</th>
<th>_LO</th>
<th>_mult</th>
<th>_SUPPLY</th>
<th>_DEMAND</th>
<th>_FLOW</th>
<th>_FCOST</th>
</tr>
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<tbody>
<tr>
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<td>M1</td>
<td>4.0</td>
<td>999999999</td>
<td>0</td>
<td>1</td>
<td>10</td>
<td>40</td>
<td>0.00000</td>
<td>0.00000</td>
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<tr>
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<td>M1</td>
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<td>0</td>
<td>3</td>
<td>10</td>
<td>40</td>
<td>0.00000</td>
<td>0.00000</td>
</tr>
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<td>M2</td>
<td>3.0</td>
<td>999999999</td>
<td>0</td>
<td>2</td>
<td>10</td>
<td>40</td>
<td>0.00000</td>
<td>0.00000</td>
</tr>
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<td>0.00000</td>
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<td>0.00000</td>
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<td>10</td>
<td>50</td>
<td>0.00000</td>
<td>0.00000</td>
</tr>
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<td>0.66072</td>
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<td>50</td>
<td>5.00000</td>
<td>5.00000</td>
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<tr>
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<td>P1</td>
<td>M4</td>
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<td>999999999</td>
<td>0</td>
<td>3</td>
<td>10</td>
<td>50</td>
<td>10.00000</td>
<td>10.00000</td>
</tr>
<tr>
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<td>M4</td>
<td>3.0</td>
<td>999999999</td>
<td>0</td>
<td>1</td>
<td>5</td>
<td>50</td>
<td>0.00000</td>
<td>0.00000</td>
</tr>
<tr>
<td>12</td>
<td>P3</td>
<td>M4</td>
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<td>999999999</td>
<td>0</td>
<td>4</td>
<td>10</td>
<td>50</td>
<td>5.00000</td>
<td>2.50000</td>
</tr>
</tbody>
</table>
Example 6.14: Generalized Networks: Distribution Problem

Consider a distribution problem (from Jensen and Bard 2003) with three supply plants \((S_1 - S_3)\) and five demand points \((D_1 - D_5)\). Further information about the problem is as follows:

- **\(S_1\)**: To be closed. Entire inventory must be shipped or sold to scrap. The scrap value is $5 per unit.
- **\(S_2\)**: Maximum production of 300 units with manufacturing cost of $10 per unit.
- **\(S_3\)**: The production in regular time amounts to 200 units and must be shipped. An additional 100 units can be produced using overtime at $14 per unit.
- **\(D_1\)**: Fixed demand of 200 units must be met.
- **\(D_2\)**: Contracted demand of 300 units. An additional 100 units can be sold at $20 per unit.
- **\(D_3\)**: Minimum demand of 200 units. An additional 100 units can be sold at $20 per unit. Additional units can be procured from \(D_4\) at $4 per unit. There is a 5% “shipping loss” on the arc connecting these two nodes.
- **\(D_4\)**: Fixed demand of 150 units must be met.
- **\(D_5\)**: 100 units left over from previous shipments. No firm demand, but up to 250 units can be sold at $25 per unit.

Additionally, there is a 5% “shipping loss” on each of the arcs between supply and demand nodes.

You can model this scenario as a generalized network. Since there are both fixed and varying supply and demand values, you can transform this to a case where you need to address missing supply and demand simultaneously. As seen from Output 6.14.1, we have added two artificial nodes, \(Y\) and \(Z\), with missing \(S\) supply value and missing \(D\) demand value, respectively. The extra production capability is depicted by arcs from node \(Y\) to the corresponding supply nodes, and the extra revenue generation capability of the demand points (and scrap revenue for \(S_1\)) is depicted by arcs to node \(Z\).
The following SAS data set has the complete information about the arc costs, multipliers, and node supply values:

```
data dnodes;
  input _node_ $ _supply_ ;
  data darc;
  input _from_ $ _to_ $ _cost_ _capac_ _mult_;
datalines;
S1  700
S2  0
S3  200
D1 -200
D2 -300
D3 -200
D4 -150
D5  100
Y   S
Z   D
```

The following SAS data set has the complete information about the arc costs, multipliers, and node supply values:

```
data dnodes;
  input _node_ $ _supply_ ;
  data darc;
  input _from_ $ _to_ $ _cost_ _capac_ _mult_;
datalines;
S1  D1  3  200  0.95
S1  D2  3  200  0.95
S1  D3  6  200  0.95
S1  D4  7  200  0.95
S2  D1  7  200  0.95
S2  D2  2  200  0.95
```
Example 6.14: Generalized Networks: Distribution Problem

You can solve this problem by using the following call to PROC NETFLOW:

```plaintext
title1 'The NETFLOW Procedure';
proc netflow
    nodedata = dnodes
    arcdata = darcs
    conout = dsol;
run;
```

The optimal solution is displayed in Output 6.14.2.

**Output 6.14.2 Distribution Problem: Optimal Solution**

<table>
<thead>
<tr>
<th>Obs</th>
<th>from</th>
<th>to</th>
<th>_cost</th>
<th>_capac</th>
<th>LO</th>
<th>mult</th>
<th>_supply</th>
<th>_demand</th>
<th>_flow</th>
<th>_FCOST</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>S1</td>
<td>D1</td>
<td>3</td>
<td>200</td>
<td>0</td>
<td>0.95</td>
<td>700</td>
<td>200</td>
<td>200.00</td>
<td>600.00</td>
</tr>
<tr>
<td>2</td>
<td>S2</td>
<td>D1</td>
<td>7</td>
<td>200</td>
<td>0</td>
<td>0.95</td>
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<td>200</td>
<td>10.526</td>
<td>73.68</td>
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<td>700</td>
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<td>200.00</td>
<td>600.00</td>
</tr>
<tr>
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<td>200.00</td>
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<tr>
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<td>0.95</td>
<td>700</td>
<td>150</td>
<td>100.00</td>
<td>700.00</td>
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<td>200</td>
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<td>0.95</td>
<td>200</td>
<td>150</td>
<td>21.053</td>
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<tr>
<td>14</td>
<td>S1</td>
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<td>0</td>
<td>1.00</td>
<td>700</td>
<td>D</td>
<td>0.00</td>
<td>0.00</td>
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<td>15</td>
<td>D2</td>
<td>Z</td>
<td>-20</td>
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<td>D</td>
<td>100.00</td>
<td>-2000.00</td>
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<tr>
<td>16</td>
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<td>Z</td>
<td>-20</td>
<td>100</td>
<td>0</td>
<td>1.00</td>
<td>.</td>
<td>D</td>
<td>0.00</td>
<td>0.00</td>
</tr>
<tr>
<td>17</td>
<td>D5</td>
<td>Z</td>
<td>-25</td>
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<td>0</td>
<td>1.00</td>
<td>100</td>
<td>D</td>
<td>250.00</td>
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</tr>
</tbody>
</table>

**-494.32**
Example 6.15: Converting to an MPS-Format SAS Data Set

This example demonstrates the use of the MPSOUT= option to convert a problem data set in PROC NETFLOW input format into an MPS-format SAS data set for use with the OPTLP procedure.

Suppose you want to solve a linear program with the following formulation:

\[
\begin{align*}
\text{min} & \quad 2x_1 - 3x_2 - 4x_3 \\
\text{subject to} & \quad -2x_2 - 3x_3 \geq -5 \\
& \quad x_1 + 2x_2 + 2x_3 \leq 4 \\
& \quad x_1 + 2x_2 + 3x_3 \geq 7 \\
& \quad 0 \leq x_1 \leq 10 \\
& \quad 0 \leq x_2 \leq 15 \\
& \quad 0 \leq x_3 \leq 20
\end{align*}
\]

You can save the LP in dense format by using the following DATA step:

```sas
data exdata;
  input x1 x2 x3 _type_ $ _rhs_;
datalines;
2 -3 -4 min .
. -2 -3 >= -5
1 1 2 <= 6
1 2 3 >= 7
10 15 20 upperbd .
;
```

If you decide to solve the problem by using the OPTLP procedure, you need to convert the data set `exdata` from dense format to MPS format. You can accomplish this by using the following statements:

```sas
/* convert to MPS format */

proc netflow condata=exdata mpsout=mpsdata bytes=100000;
  run;
```
The MPS-format SAS data set mpsdata is shown in Output 6.15.1.

**Output 6.15.1** Data Set mpsdata

The NETFLOW Procedure

<table>
<thead>
<tr>
<th>Obs</th>
<th>field1</th>
<th>field2</th>
<th>field3</th>
<th>field4</th>
<th>field5</th>
<th>field6</th>
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</tr>
</tbody>
</table>

The constraint names _OBS2_, _OBS3_, and _OBS4_ are generated by the NETFLOW procedure. If you want to provide your own constraint names, use the ROW list variable in the CONOUT= data set. If you specify the problem data in sparse format instead of dense format, the MPSOUT= option produces the same MPS-format SAS data set shown in the preceding output.

Now that the problem data are in MPS format, you can solve the problem by using the OPTLP procedure. For more information, see Chapter 12, “The OPTLP Procedure” (SAS/OR User’s Guide: Mathematical Programming).
Example 6.16: Migration to OPTMODEL: Generalized Networks

The following example shows how to solve Example 6.11 using PROC OPTMODEL. The input data sets are the same as in that example.

The following PROC OPTMODEL statements read the data sets, build the linear programming model, solve the model, and output the optimal solution to a SAS data set called GNETOUT:

```sas
proc optmodel;
   set <str> NODES;
   num _sd_ {NODES} init 0;
   read data gnodes into NODES=[_node_] _sd_;

   set <str,str> ARCS;
   num _lo_ {ARCS} init 0;
   num _capac_ {ARCS} init .;
   num _cost_ {ARCS};
   num _mult_ {ARCS} init 1;
   read data garcs nomiss into ARCS=[_from_ _to_] _cost_ _mult_;
   NODES = NODES union (union {<i,j> in ARCS} {i,j});

   var Flow {<i,j> in ARCS} >= _lo_[i,j];
   min obj = sum {<i,j> in ARCS} _cost_[i,j] * Flow[i,j];
   con balance {i in NODES}: sum {<(i),j> in ARCS} Flow[i,j] - sum {<j,(i)> in ARCS} _mult_[j,i] * Flow[j,i] = _sd_[i];
   num infinity = constant('BIG');
   /* change equality constraint to le constraint for supply nodes */
   for {i in NODES: _sd_[i] > 0} balance[i].lb = -infinity;
   solve;
   num _supply_ {<i,j> in ARCS} = (if _sd_[i] ne 0 then _sd_[i] else .);
   num _demand_ {<i,j> in ARCS} = (if _sd_[j] ne 0 then -_sd_[j] else .);
   num _fcost_ {<i,j> in ARCS} = _cost_[i,j] * Flow[i,j].sol;
   create data gnetout from [_from_ _to_] _cost_ _capac_ _lo_ _mult_ _supply_ _demand_ _flow_=Flow _fcost_;
quit;
```

To solve a generalized network flow problem, the usual balance constraint is altered to include the arc multiplier "_mult_[j,i]" in the second sum. The balance constraint is initially declared as an equality, but to mimic the PROC NETFLOW EXCESS=SUPPLY option, the sense of this constraint is changed to "≤" by relaxing the constraint’s lower bound for supply nodes. The output data set contains the same optimal solution as Output 6.11.2. The log is displayed in Output 6.16.1.
Example 6.16: Migration to OPTMODEL: Generalized Networks

Output 6.16.1  OPTMODEL Log

NOTE: There were 6 observations read from the data set WORK.GNODES.
NOTE: There were 7 observations read from the data set WORK.GARCS.
NOTE: Problem generation will use 4 threads.
NOTE: The problem has 7 variables (0 free, 0 fixed).
NOTE: The problem has 6 linear constraints (3 LE, 3 EQ, 0 GE, 0 range).
NOTE: The problem has 14 linear constraint coefficients.
NOTE: The problem has 0 nonlinear constraints (0 LE, 0 EQ, 0 GE, 0 range).
NOTE: The OPTMODEL presolver is disabled for linear problems.
NOTE: The LP presolver value AUTOMATIC is applied.
NOTE: The LP presolver removed 2 variables and 2 constraints.
NOTE: The LP presolver removed 4 constraint coefficients.
NOTE: The presolved problem has 5 variables, 4 constraints, and 10 constraint coefficients.
NOTE: The LP solver is called.
NOTE: The Dual Simplex algorithm is used.

<table>
<thead>
<tr>
<th>Objective</th>
<th>Phase</th>
<th>Iteration</th>
<th>Value</th>
<th>Time</th>
</tr>
</thead>
<tbody>
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<td></td>
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<td></td>
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<td>0</td>
</tr>
<tr>
<td></td>
<td>D 2</td>
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<td>0</td>
</tr>
<tr>
<td></td>
<td>D 2</td>
<td>3</td>
<td>2.500000E+01</td>
<td>0</td>
</tr>
</tbody>
</table>

NOTE: Optimal.
NOTE: Objective = 25.
NOTE: The Dual Simplex solve time is 0.00 seconds.
NOTE: The data set WORK.GNETOUT has 7 observations and 10 variables.

Now consider the previous example but with a slight modification to the arc multipliers, as in Example 6.11.

data garcs1;
   input _from_ $ _to_ $ _cost_ _mult_;
datalines;
s1 d1 1 0.5
s1 d2 8 0.5
s2 d1 4 .
s2 d2 2 .
s2 d3 1 .
s3 d2 5 0.5
s3 d3 4 0.5
;
The following PROC OPTMODEL statements are identical to the preceding statements, except for the balance constraint. It is still initially declared as an equality, but to mimic the PROC NETFLOW EXCESS=DEMAND option, the sense of this constraint is changed to “≥” by relaxing the constraint’s upper bound for demand nodes.

```proc optmodel;
    set <str> NODES;
    num _sd_ {NODES} init 0;
    read data gnodes into NODES=[_node_] _sd_;

    set <str,str> ARCS;
    num _lo_ {ARCS} init 0;
    num _capac_ {ARCS} init .;
    num _cost_ {ARCS};
    num _mult_ {ARCS} init 1;
    read data garcs1 nomiss into ARCS=[_from_ _to_] _cost_ _mult_;
    NODES = NODES union (union {<i,j> in ARCS} {i,j});

    var Flow {<i,j> in ARCS} >= _lo_[i,j];
    for {<i,j> in ARCS: _capac_[i,j] ne .} Flow[i,j].ub = _capac_[i,j];
    min obj = sum {<i,j> in ARCS} _cost_[i,j] * Flow[i,j];
    con balance {i in NODES}: sum {<(i),j> in ARCS} Flow[i,j]
        - sum {<j,(i)> in ARCS} _mult_[j,i] * Flow[j,i] = _sd_[i];

    num infinity = constant('BIG');
    /* change equality constraint to ge constraint */
    for {i in NODES: _sd_[i] < 0} balance[i].ub = infinity;

    solve;

    num _supply_ {<i,j> in ARCS} = (if _sd_[i] ne 0 then _sd_[i] else .);
    num _demand_ {<i,j> in ARCS} = (if _sd_[j] ne 0 then -_sd_[j] else .);
    num _fcost_ {<i,j> in ARCS} = _cost_[i,j] * Flow[i,j].sol;

    create data gnetout1 from [._from_ _to_]
            _cost_ _capac_ _lo_ _mult_ _supply_ _demand_ _flow_=Flow _fcost_;
quit;```
The output data set contains the same optimal solution as **Output 6.11.3**. The log is displayed in **Output 6.16.2**.

**Output 6.16.2** OPTMODEL Log

NOTE: There were 6 observations read from the data set WORK.GNODES.
NOTE: There were 7 observations read from the data set WORK.GARCS1.
NOTE: Problem generation will use 4 threads.
NOTE: The problem has 7 variables (0 free, 0 fixed).
NOTE: The problem has 6 linear constraints (0 LE, 3 EQ, 3 GE, 0 range).
NOTE: The problem has 14 linear constraint coefficients.
NOTE: The problem has 0 nonlinear constraints (0 LE, 0 EQ, 0 GE, 0 range).
NOTE: The OPTMODEL presolver is disabled for linear problems.
NOTE: The LP presolver value AUTOMATIC is applied.
NOTE: The LP presolver removed 2 variables and 2 constraints.
NOTE: The LP presolver removed 4 constraint coefficients.
NOTE: The presolved problem has 5 variables, 4 constraints, and 10 constraint coefficients.
NOTE: The LP solver is called.
NOTE: The Dual Simplex algorithm is used.

<table>
<thead>
<tr>
<th>Objective</th>
<th>Value</th>
<th>Time</th>
</tr>
</thead>
<tbody>
<tr>
<td>Phase Iteration</td>
<td></td>
<td></td>
</tr>
<tr>
<td>D 1</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>D 2</td>
<td>2</td>
<td>0</td>
</tr>
<tr>
<td>D 2</td>
<td>4</td>
<td>0</td>
</tr>
</tbody>
</table>

NOTE: Optimal.
NOTE: Objective = 70.
NOTE: The Dual Simplex solve time is 0.00 seconds.
NOTE: The data set WORK.GNETOUT1 has 7 observations and 10 variables.

---

**Example 6.17: Migration to OPTMODEL: Maximum Flow**

The following example shows how to solve **Example 6.10** using PROC OPTMODEL. The input data set is the same as in that example.

The following PROC OPTMODEL statements read the data sets, build the linear programming model, solve the model, and output the optimal solution to a SAS data set called GOUT3:

```
proc optmodel;
  str source = 'S';
  str sink = 'T';

  set <str> NODES;
  num _supdem_ {i in NODES} = (if i in {source, sink} then . else 0);

  set <str,str> ARCS;
  num _lo_ {ARCS} init 0;
  num _capac_ {ARCS} init .;
  num _cost_ {ARCS} init 0;
  read data arcs nomiss into ARCS=[_from_ _to_] _cost_ _capac_;
  NODES = (union {<i,j> in ARCS} {i,j});
```
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var Flow {<i,j> in ARCS} >= _lo_[i,j];
for {<i,j> in ARCS: _capac_[i,j] ne .} Flow[i,j].ub = _capac_[i,j];
max obj = sum {<i,j> in ARCS: j = sink} Flow[i,j];
con balance {i in NODES diff {source, sink}}:
    sum {<(i),j> in ARCS} Flow[i,j]
- sum {<j,(i)> in ARCS} Flow[j,i] = _supdem_[i];
solve;
num _supply_ {<i,j> in ARCS} =
    (if _supdem_[i] ne 0 then _supdem_[i] else .);
num _demand_ {<i,j> in ARCS} =
    (if _supdem_[j] ne 0 then -_supdem_[j] else .);
num _fcost_ {<i,j> in ARCS} = _cost_[i,j] * Flow[i,j].sol;
create data gout3 from [_from_ _to_] _cost_ _capac_ _lo_ _supply_ _demand_ _flow_=Flow _fcost_;
quit;

To solve a maximum flow problem, you solve a network flow problem that has a zero supply or demand at all nodes other than the source and sink nodes, as specified in the declaration of the _SUPDEM_ numeric parameter and the balance constraint. The objective declaration uses the logical condition J = SINK to maximize the flow into the sink node. The output data set contains the same optimal solution as Output 6.10.3. The log is displayed in Output 6.17.1.

Output 6.17.1 OPTMODEL Log

NOTE: There were 14 observations read from the data set WORK.ARCS.
NOTE: Problem generation will use 4 threads.
NOTE: The problem has 14 variables (0 free, 0 fixed).
NOTE: The problem has 8 linear constraints (0 LE, 8 EQ, 0 GE, 0 range).
NOTE: The problem has 24 linear constraint coefficients.
NOTE: The problem has 0 nonlinear constraints (0 LE, 0 EQ, 0 GE, 0 range).
NOTE: The OPTMODEL presolver is disabled for linear problems.
NOTE: The problem is a pure network instance. The ALGORITHM=NETWORK option is recommended for solving problems with this structure.
NOTE: The LP presolver value AUTOMATIC is applied.
NOTE: The LP presolver removed 10 variables and 6 constraints.
NOTE: The LP presolver removed 20 constraint coefficients.
NOTE: The presolved problem has 4 variables, 2 constraints, and 4 constraint coefficients.
NOTE: The LP solver is called.
NOTE: The Dual Simplex algorithm is used.

<table>
<thead>
<tr>
<th>Objective</th>
<th>Phase</th>
<th>Iteration</th>
<th>Value</th>
<th>Time</th>
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</thead>
<tbody>
<tr>
<td></td>
<td>D 1</td>
<td>1</td>
<td>0.0000000E+00</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>D 2</td>
<td>2</td>
<td>2.5000000E+01</td>
<td>0</td>
</tr>
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<td></td>
<td>P 2</td>
<td>5</td>
<td>2.5000000E+01</td>
<td>0</td>
</tr>
</tbody>
</table>

NOTE: Optimal.
NOTE: Objective = 25.
NOTE: The Dual Simplex solve time is 0.00 seconds.
NOTE: The data set WORK.GOUT3 has 14 observations and 9 variables.
Example 6.18: Migration to OPTMODEL: Production, Inventory, Distribution

The following example shows how to solve Example 6.4 using PROC OPTMODEL. The input data sets are the same as in that example.

The following PROC OPTMODEL code read the data sets, build the linear programming model, solve the model, and output the optimal solution to SAS data sets called ARC1 and NODE2:

```sas
proc optmodel;
    set <str> NODES;
    num _supdem_ {NODES} init 0;
    read data node0 into NODES=_node_ _supdem_;

    set <str,str> ARCS;
    num _lo_ {ARCS} init 0;
    num _capac_ {ARCS} init .;
    num _cost_ {ARCS};
    num diagonal {ARCS};
    num factory {ARCS};
    str key_id {ARCS};
    str mth_made {ARCS};
    str _name_ {ARCS};
    read data arc0 nomiss into ARCS=_tail_ _head_ _lo_ _capac_ _cost_
        diagonal factory key_id mth_made _name_;
    NODES = NODES union (union {<i,j> in ARCS} {i,j});

    var Flow {<i,j> in ARCS} >= _lo_[i,j];
    for {<i,j> in ARCS: _capac_[i,j] ne .} Flow[i,j].ub = _capac_[i,j];
    min obj = sum {<i,j> in ARCS} _cost_[i,j] * Flow[i,j];
    con balance {i in NODES}:
        sum {<(i),j> in ARCS} Flow[i,j]
        - sum {<j,(i)> in ARCS} Flow[j,i] = _supdem_[i];

    num infinity = constant('BIG');
    num excess = sum {i in NODES} _supdem_[i];
    if (excess > 0) then do;
        /* change equality constraint to le constraint for supply nodes */
        for {i in NODES: _supdem_[i] > 0} balance[i].lb = -infinity;
        end;
    else if (excess < 0) then do;
        /* change equality constraint to ge constraint for demand nodes */
        for {i in NODES: _supdem_[i] < 0} balance[i].ub = infinity;
        end;

    solve;

    num _supply_ {<i,j> in ARCS} =
        (if _supdem_[i] ne 0 then _supdem_[i] else .);
    num _demand_ {<i,j> in ARCS} =
```

(if _supdem_[j] ne 0 then -_supdem_[j] else .);
num _fcost_ {<i,j> in ARCS} = _cost_[i,j] * Flow[i,j].sol;

create data arcl from [_tail_ _head_]
   _cost_ _capac_ _lo_ _name_ _supply_ _demand_ _flow_=Flow _fcost优点
   _rcost_ =
   (if Flow[_tail_,_head_].rc ne 0 then Flow[_tail_,_head_].rc else .)
   _status_ = Flow.status diagonal factory key_id mth_made;
create data node2 from [_node_]
   _supdem_ = (if _supdem_[node] ne 0 then _supdem_[node] else .)
   _dual_ = balance.dual;
quit;

The statements use both single-dimensional (NODES) and multiple-dimensional (ARCS) index sets, which are populated from the corresponding data set variables in the READ DATA statements. The _SUPDEM_, _LO_, and _CAPAC_ parameters are given initial values, and the NOMISS option in the READ DATA statement tells OPTMODEL to read only the nonmissing values from the input data set. The balance constraint is initially declared as an equality, but depending on the total supply or demand, the sense of this constraint is changed to “≤” or “≥” by relaxing the constraint’s lower or upper bound, respectively. The ARC1 output data set contains most of the same information as in Example 6.4, including reduced cost, basis status, and dual values. The _ANUMB_ and _TNUMB_ values do not apply here.

The PROC PRINT statements are similar to Example 6.4.

options ls=80 ps=54;
proc print data=arc1 heading=h width=min;
   var _tail_ _head_ _cost_ _capac_ _lo_ _name_ _supply_ _demand_ _flow_ _fcost优点;
   sum _fcost优点;
run;
proc print data=arc1 heading=h width=min;
   var _rcost_ _status_ diagonal factory key_id mth_made;
run;
proc print data=node2;
run;

The output data sets contain the same optimal solution as Output 6.4.1, Output 6.4.2, and Output 6.4.3. The log is displayed in Output 6.18.1.
The following example shows how to solve Example 6.1 using PROC OPTMODEL. The input data set is the same as in that example.

The following PROC OPTMODEL statements read the data sets, build the linear programming model, solve the model, and output the optimal solution to a SAS data set called SPATH:

```sas
proc optmodel;
    str sourcenode = 'Honolulu';
    str sinknode = 'Heathrow London';

    set <str> NODES;
    num _supdem_ {i in NODES} = (if i = sourcenode then 1 else if i = sinknode then -1 else 0);

    set <str,str> ARCS;
    num _lo_ {ARCS} init 0;
    num _capac_ {ARCS} init .;
    num _cost_ {ARCS};
    read data aircost1 into ARCS=[ffrom tto] _cost_;
    NODES = (union {<i,j> in ARCS} {i,j});
```
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var Flow {<i,j> in ARCS} >= _lo_[i,j];
min obj = sum {<i,j> in ARCS} _cost_[i,j] * Flow[i,j];
con balance {i in NODES}: sum {<(i),j> in ARCS} Flow[i,j]
     - sum {<j,(i)> in ARCS} Flow[j,i] = _supdem_[i];
solve;

num _supply_ {<i,j> in ARCS} =
       (if _supdem_[i] ne 0 then _supdem_[i] else .);
num _demand_ {<i,j> in ARCS} =
       (if _supdem_[j] ne 0 then -_supdem_[j] else .);
num _fcost_ {<i,j> in ARCS} = _cost_[i,j] * Flow[i,j].sol;

create data spath from [ffrom tto]
   _cost_ _capac_ _lo_ _supply_ _demand_ _flow_=Flow _fcost_
   _rcost_ = (if Flow[ffrom,tto].rc ne 0 then Flow[ffrom,tto].rc else .)
   _status_ = Flow.status;
quit;

The statements use both single-dimensional (NODES) and multiple-dimensional (ARCS) index sets. The ARCS data set is populated from the ffrom and tto data set variables in the READ DATA statement. To solve a shortest path problem, you solve a minimum-cost network-flow problem that has a supply of one unit at the source node, a demand of one unit at the sink node, and zero supply or demand at all other nodes, as specified in the declaration of the _SUPDEM_ numeric parameter. The SPATH output data set contains most of the same information as in Example 6.1, including reduced cost and basis status. The _ANUMB_ and _TNUMB_ values do not apply here.

The PROC PRINT statements are similar to Example 6.1.

    proc print data=spath;
       sum _fcost_;
    run;

The output data set contains the same optimal solution as Output 6.1.1. The log is displayed in Output 6.19.1.

Output 6.19.1  OPTMODEL Log

NOTE: There were 13 observations read from the data set WORK.AIRCOST1.
NOTE: Problem generation will use 4 threads.
NOTE: The problem has 13 variables (0 free, 0 fixed).
NOTE: The problem has 8 linear constraints (0 LE, 8 EQ, 0 GE, 0 range).
NOTE: The problem has 26 linear constraint coefficients.
NOTE: The problem has 0 nonlinear constraints (0 LE, 0 EQ, 0 GE, 0 range).
NOTE: The OPTMODEL presolver is disabled for linear problems.
NOTE: The problem is a pure network instance. The ALGORITHM=NETWORK option is recommended for solving problems with this structure.
NOTE: The LP presolver value AUTOMATIC is applied.
NOTE: The LP presolver removed all variables and constraints.
NOTE: Optimal.
NOTE: Objective = 177.
NOTE: The data set WORK.SPATH has 13 observations and 11 variables.
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